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(11) **EP 0 903 694 A1**

(12) **EUROPEAN PATENT APPLICATION**

(43) Date of publication:
24.03.1999 Bulletin 1999/12

(51) Int. Cl.⁶: **G06T 15/00**

(21) Application number: **98107592.2**

(22) Date of filing: **27.04.1998**

(84) Designated Contracting States:
**AT BE CH CY DE DK ES FI FR GB GR IE IT LI LU
MC NL PT SE**
Designated Extension States:
AL LT LV MK RO SI

(30) Priority: **01.08.1997 US 905238**

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(54) **Real-time PC based volume rendering system**

(57) Apparatus is provided to enable real-time volume rendering on a personal computer or a desktop computer in which a technique involving blocking of voxel data organizes the data so that all voxels within a block are stored at consecutive memory addresses within a single memory model, making possible fetching an entire block or data in a burst rather than one voxel at a time. This permits utilization of DRAM memory modules which provide high capacity and low cost with substantial space savings. Additional techniques including sectioning reduces the amount of intermediate storage in a processing pipeline to an acceptable level for semiconductor implementation. A multiplexing technique takes advantage of blocking to reduce the amount of data needed to be transmitted per block, thus reducing the number of pins and the rates at which data must be transmitted across the pins connecting adjacent processing modules with each other. A mini-blocking technique saves the time needed to process sections by avoiding reading entire blocks for voxels near the boundary between a section and previously processed sections.

Description

[0001] The copy of the basic US-application SN 08/905,238 is enclosed. With respect to the disclosure of the invention it is referred to the basic US-application.

FIELD OF INVENTION

[0002] This invention relates to volume graphics and more particularly to a method and apparatus for processing voxel-based data in real time and for creating visual images of objects represented by the data.

BACKGROUND OF THE INVENTION

[0003] Volume graphics is the subfield of computer graphics that deals with the visualization of objects or phenomena represented as sampled data in three or more dimensions. These samples are called volume elements, or "voxels," and contain digital information representing physical characteristics of the objects or phenomena being studied. For example, voxel data for a particular object may represent density, type of material, temperature, velocity, or some other property at discrete points in space throughout the interior and in the vicinity of the object.

[0004] Voxel-based representations of objects occur in many situations and applications. For example, tomographic scans and nuclear magnetic resonance scans of a human body or industrial assembly produce three dimensional arrays of data representing the density and type of the material comprising the body or object. Likewise, seismic data collected from earthquakes and controlled explosions is processed into three dimensional arrays of data representing the types of soil and rock beneath the surface of the earth. In pre-natal health care, ultrasound scans of a human fetus in the womb produce 3-D sampled data for non-invasive examination and diagnostic purposes. Still another example is the modeling of the flow of air over an aircraft wing or through a jet engine, which also results in discrete samples of data at points in three dimensional space that can be used for design and analysis of the aircraft or engine.

[0005] It is natural to want to see images of objects represented by voxels. In the past, two methods have been available for this purpose. One method is to construct a series of parallel two-dimensional image slices, each representing a slightly different cross section of the object being viewed. This is the method typically used by radiologists when viewing computed tomography scans or nuclear magnetic resonance scans of the human body. Radiologists are trained to construct three-dimensional mental pictures of the internal organs of the body from these series of two-dimensional images. The slices are, in general, parallel to one of the primary dimensions or axes of the body, so that they represent the "sagittal," "axial," and "coronal" views that are familiar to radiologists. This method of visualizing voxel-based data is difficult, requires years of training, and is prone to uncertainty, even by the most expert practitioners.

[0006] Another method is to convert voxel data into representations suitable for computer graphics system to display. Most computer graphic systems today are designed to display surfaces of objects by subdividing those surfaces into small triangles or polygons. These triangles are assigned colors and levels of transparency or opacity, then converted into pixels, that is picture elements, and projected onto the computer screen. Triangles corresponding to surfaces in the foreground obscure those corresponding to surfaces in the background. Triangles can also be colored or painted with textures and other patterns to make them look more realistic. Additional realism is made possible by simulating the position and effects of lights, so that highlights and shadows appear on the resulting image. The art and science of this kind of graphics system is well-developed and described by a large body of literature such as the textbook "Computer Graphics: Principles and Practice," 2nd edition, by J. Foley, A. vanDam, S. Feiner, and J. Hughes, published by Addison-Wesley of Reading, Massachusetts, in 1990.

[0007] This kind of polygon-based graphics system is especially suitable for displaying images of objects that are represented as computer models of their surface, such as architectural or mechanical drawings. However, it is less appropriate for visualizing objects represented by 3-D sampled data or voxels, because the process of converting the sample to triangles or polygons is itself computationally expensive. Many algorithms exist for performing the conversion from voxels to polygons, including the famous Marching Cubes algorithm described by W. E. Lorensen and H. E. Cline in a paper entitled "Marching Cubes: A high-resolution 3D surface construction algorithm," presented in Computer Graphics, the Proceedings of the 1987 SIGGRAPH Conference, pages 163 - 169. All of these algorithms suffer the problem of losing detail of the surface, something that would be intolerable in applications such as medical imaging and others.

[0008] In recent years, an alternative method has emerged called volume rendering. This method is a form of digital signal processing in which the individual voxels of a voxel-based representation are assigned colors and levels of transparency or opacity. They are then projected on a two-dimensional viewing surface such as a computer screen, with opaque voxels in the foreground obscuring other voxels in the background. This accumulation of projected voxels results in a visual image of the object. Lighting calculations can be done on the individual voxels to create the appearance of highlights and shadows in a similar manner to that of conventional computer graphics.

[0009] By changing the assignment of colors and transparency to particular voxel data values, different views of the

exterior and interior of an object can be seen. For example, a surgeon needing to examine the ligaments, tendons, and bones of a human knee in preparation for surgery can utilize a tomographic scan of the knee and cause voxel data values corresponding to blood, skin, and muscle to appear to be completely transparent. In another example, a mechanic using a tomographic scan of a turbine blade or weld in a jet engine can cause voxel data values representing solid metal to appear to be transparent while causing those representing air to be opaque. This allows the viewing of internal flaws in the metal that would otherwise be hidden from the human eye.

[0010] The process of creating a viewable image from computer data is called "rendering," and the process of creating a viewable image from voxel data is called "volume rendering." The mechanism for mapping the data values of individual voxels to colors and transparencies is called a "transfer function."

a) Projection of Voxel Data

[0011] There are a number of techniques to take the data points or voxels representing an object and project them onto a flat viewing surface such as a computer screen. In each of these techniques, an object to be viewed is positioned relative to the viewing surface by translating the three dimensional sampled data representing that object to the spatial coordinates of the space in front of or behind the viewing surface. The techniques are different method of computing the color and intensity of the light at discrete points or "pixels" on that viewing surface.

[0012] One technique is to compute a series of fast Fourier transforms of the voxel data, combine them, then compute the inverse Fourier transform to obtain the resulting two-dimensional image. This is described by T. Malzbender in US Patent #5,414,803 entitled "Method Utilizing Frequency Domain Representation for Generating Two-Dimensional Views of Three-Dimensional Objects."

[0013] A second technique called "splatting" was described by L. A. Westover in a Doctoral Dissertation entitled "Splatting: A Parallel, Feed-Forward Volume Rendering Algorithm" presented to and published by the Department of Computer Science of the University of North Carolina in July 1991, Technical Report number TR91-029. In the splatting technique, each individual voxel of a set of three-dimensional sampled data is projected in the direction of the eye of the viewer. The colors and transparency of the projected voxel are mathematically combined with the pixels of the viewing surface in the immediate region surrounding the point where that projection intersects that computer screen. When all voxels are thus accumulated, the resulting image appears to be a two-dimensional picture of a three-dimensional object.

[0014] A third technique is to convert the three-dimensional set of data into a so-called "texture map" and then to store it in the texture map memory that can be found in certain types of modern computer systems. Then this texture map is used to "paint" or "color" a series of parallel planes, each perpendicular to the viewing direction, so that each appears to be a cross-section of the object in question. These planes are then mathematically combined by the graphics subsystem of the computer system to form an image of what appears to the viewer to be a three dimensional object. This method is described in detail in a paper entitled "Accelerated volume rendering and tomographic reconstruction using texture mapping hardware," presented by B. Cabral, N. Cam, and J. Foran at the "Workshop on Volume Visualization" in 1991. It is further described by T. J. Cullip and U. Neumann in a technical report number TR93-027 entitled "Accelerating volume reconstruction with 3D texture mapping hardware," published by the Department of Computer Science of the University of North Carolina at Chapel Hill.

[0015] A fourth technique is called "ray-casting." In this technique, imaginary rays are passed from the eye of the viewer through the exact center of each pixel of the viewing surface, then through the object to be viewed. Each ray which passes through the volume is "loaded up" with the visual characteristics of each point along its path. As the ray passes-through the volume, its total characteristic is the sum or mathematical integral of the characteristics of all of the points along the ray. This sum or integral is then assigned to the pixel through which the ray passes, causing a point of light to appear on the viewing surface. The accumulation of all such rays produces a visible image on the viewing surface.

[0016] When rays come through a volume, some pass between points represented by the three dimensional sampled data, not intersecting them exactly. It will be appreciated that these "missed" data points or voxels are not reflected in the color or intensity of the pixel corresponding to any ray. In order to solve this missed data-point problem, interpolation techniques are utilized to synthetically generate values from voxels in the immediate neighbourhoods of the missed points. In one example, a synthetic value is generated for each plane of sample points or voxels crossed by the ray by the mathematical method of bilinear interpolation of the values of the four nearest voxels in that plane. In another example, synthetic points are generated with uniform spacing along the ray by the mathematical method of trilinear interpolation of the eight nearest voxels surrounding each point. In these ways, as the ray passes through the object, the characteristics accumulated along the way take into account characteristics of the nearest neighbors to synthetically generate a value for the missed point. It will be appreciated that there are many possible ways of generating synthetic points and that these have a significant bearing on the quality and realism of the projected image.

[0017] In order for a two-dimensional picture to-be perceived by the human eye as the image of a three-dimensional

object or scene, it is important for the picture to include the effects of lighting and shadows. This is the subject of extensive literature in computer graphics, including the aforementioned textbook by J. Foley, *et. al.* Most techniques revolve around the notion of finding the "normal vector" or perpendicular direction to each point on each surface of the object being displayed, then making calculations based on these normal vectors and on the positions of the viewer and the light sources in order to illuminate those points, creating the effect of highlights and shadows.

[0018] Whereas in conventional computer graphics based on polygons and surface, these normal vectors can be calculated directly from the mathematical models of the surfaces, in volume graphics the normal vectors must be extracted from the sampled data itself. This must be done for each voxel, for example, by examining the values of the other voxels in its immediate neighborhood. At the boundaries of different materials, for instance different tissues, there will be significant differences or gradients in the values of the neighboring voxels. From these differences, the normal vectors can be calculated. Then whenever one type of material is transparent while an adjacent material is opaque, the projection can make clear the edges and surfaces between the different materials. Moreover, the lighting calculations based on these normal vectors can emphasize the irregularities of these surface in such a way as to be recognizable by the human eye as three dimensional. For instance, ridges in the grey matter making up the brain can be clearly displayed in this manner from a tomographic scan by simply making the skin and bone of the skull transparent.

b) Computational Requirements

[0019] It will be appreciated that all four of the above techniques for projecting voxel data onto a computing surface require massive amounts of computation and have been heretofore unsuitable for equipment of the size and cost of personal or desktop computers. Moreover, they involve the invocation of many different techniques in order to render the volume in a manner useful, for instance, in medical diagnosis. In general, each voxel of a three dimensional data set must be examined at least once to form the projected image. If the sampled data set were a cube with 256 data points on a side, this being a typical size for current tomographic and nuclear magnetic resonance scans for medical purposes, then a total of 256^3 or approximately 16 million voxels must be evaluated. If, however, the sampled data set were a cube with 4096 data points on a side, this being typical of geological data used in exploration for oil and gas, then a total of 4096^3 or approximately 64 billion voxels must be evaluated, just to render a single image.

[0020] It will be further appreciated that if rendering static images of static data is computationally expensive, this pales into insignificance when considering the computational power required to render objects that move, rotate, or change in some other way. Many applications need visualization of objects that appear to move in real time, which means rendering on the order of 30 frames per second. That is, each voxel must be re-evaluated or projected 30 times per second. For a volume of 256^3 data points, this means that data must be retrieved from the sampled data set $256^3 \times 30$ or approximately 503 million times per second. Noting that if the volume rendering were done by a computer program, between 10 and 100 computer instructions would be required per data point per frame. Therefore, the processing power to view rotating or changing volume graphics images is between five and fifty billion operations per second. Note for each doubling of the number of data points on the side of a cubic data set, the required processing power goes up by a factor of eight.

[0021] The usual compromise is to sacrifice frame rate or visual quality or cost and size. Presently, the best that one can obtain by rendering a 256^3 volume in computer software is one to two frames per second on eight ganged processors of the type found in current high-end personal computers. With very expensive computers particularly specialized for graphics and containing very large amounts of texture memory, frame rates of up to fifteen frames per second can be achieved by sacrificing lighting and shadows. Other approaches that actually achieve real-time frame rates of 30 frames per second or more without sacrificing image quality have resulted in very specialized systems that are too large and costly for personal or desktop-size equipment.

c) Reduction in Computational Requirements

[0022] In order to improve upon this rather dismal prospect for obtaining real-time volume-rendering at 30 frames per second based on the ray-casting technique, a development by Ari Kaufmann and Hanspeter Pfister at State University of New York is described in U.S. Patent #5,594,842, "Apparatus and Method for Real-time Volume Visualization." In this development, improvements can be obtained by passing a large number of rays through a volume in parallel and processing them by evaluation the volume data a slice at a time. If one can do slice-processing fast in specialized electronic hardware, as opposed to software, it has been demonstrated that one can increase from two frames per second to 30 frames per second at a modest cost.

[0023] In theory, this is accomplished in hardware through the utilization of a multiplicity of memory modules and specialized processing pipelines. Utilizing large numbers of memory modules and pipelines, one can pick out data in parallel from different memory modules in a system now dubbed "Cube-4" which was described by H. Pfister, A. Kaufmann, and T. Wessels in a paper entitled "Towards a Scalable Architecture for Real-time Volume Rendering" presented at the

10th Eurographics Workshop on Graphics Hardware at Maastricht, The Netherlands, on August 28 and 29, 1995, and further described in a Doctoral Dissertation submitted by Hanspeter Pfister to the Department of Computer Science at the State University of New York at Stony Brook in December 1996.

[0024] The essence of the Cube-4 system is that the three dimensional sampled data representing the object is distributed across the memory modules by a technique called "skewing," so that adjacent voxels in each dimension are stored in adjacent memory modules. Each memory module is associated with its own processing pipeline. Moreover, voxels are organized in the memory modules so that if there are a total of P pipelines and P memory modules, then P adjacent voxels can be fetched simultaneously, in parallel, within a single cycle of a computer memory system, independent of the viewing direction. This reduces the total time to fetch voxels from memory by a factor of P. For example, if the data set has 256^3 voxels and P has the value four, then only $256^3/4$ or approximately four million memory cycles are needed to fetch the data in order to render an image.

[0025] An additional characteristic of the Cube-4 system is that the computational processing required for volume rendering is organized into pipelines with specialized functions for this purpose. Each pipeline is capable of starting the processing of a new voxel in each cycle. Thus, in the first cycle, the pipeline fetches a voxel from its associated memory module and performs the first step of processing. Then in the second cycle, it performs the second step of processing of this first voxel, while at the same time fetching the second voxel and performing the first step of processing this voxel. Likewise, in the third cycle, the pipeline performs the third processing step of the first voxel, the second processing step of the second voxel, and the first processing step of the third voxel. In this manner, voxels from each memory module progress through its corresponding pipeline in lock-step fashion, one after the another, until they are fully processed. Thus, instead of requiring 10 to 100 computer instructions per voxel, a new voxel can be processed in every cycle.

[0026] A further innovative characteristic of the Cube-4 system is that each pipeline communicates only with its nearest neighbors. Such communication is required, for example, to transmit voxel values from one pipeline to the next for purposes of estimating gradients or normal vectors so that lighting and shadow effects can be calculated. It is also used to communicate the values of rays as they pass through the volume accumulating visual characteristics of the voxels in the vicinities of the areas through which they pass.

[0027] This approach of nearest neighbor communication provides the Cube-4 one its principal advantages, that of being "scalable." That is, in order to accommodate larger amounts of three dimensional sampled data and/or in order to process this data faster, it is only necessary to add more memory modules and pipelines. There are no common busses or other system resources to be overloaded by the expansion.

[0028] In the Cube-4 system, volume rendering proceeds as follows. Data is organized as a cube or other rectangular solid. Considering first the face of this cube or solid that is most nearly perpendicular to the viewing direction, a partial row of P voxels at the top corner is fetched from P memory modules concurrently, in one memory cycle, and inserted into the first stage of the P processing pipelines. In the second cycle these voxels are moved to the second stage of their pipelines and/or transmitted to the second stages of adjacent pipelines. At the same time, the next P voxels are fetched from the same row and inserted into the first stage of their pipelines. In each subsequent cycle, P more voxels are fetched from the top row and inserted into their pipelines, while previously fetched voxels move to later stages of their pipelines. This continues until the entire row of voxels has been fetched. Then the next row is fetched, P voxels at a time, then the next and so on, until all of the rows of the face of the volume data set have been fetched and inserted into their processing pipelines.

[0029] This face is called a "slice." Then the Cube-4 system moves again to the top corner, but this time starts fetching the P voxels in the top row immediately behind the face, that is from the second "slice." In this way, it progresses through the second slice of the data set, a row at a time and within each row, P voxels at a time. After completing the second slice, it proceeds to the third slice, then to subsequent slices in a similar manner, until all slices have been processed. The purpose of this approach is to fetch and process all of the voxels in an orderly way, P voxels at a time, until the entire volume data set has been processed and an image has been formed.

[0030] In the terminology of the Cube-4 system, a row of voxels is called a "beam" and a group of P voxels within a beam is called a "partial beam."

[0031] The processing stages of the Cube-4 system perform all of the calculations required for the ray-casting technique, including interpolation of samples, estimation of the gradients or normal vectors, assignments of colors and transparency or opacity, and calculation of lighting and shadow effects to produce the final image on the two dimensional view surface.

[0032] The Cube-4 system was designed to be capable of being implemented in semiconductor technology. However, two limiting factors prevent it from achieving the small size and low cost necessary for personal or desktop-size computers, namely the rate of accessing voxel values from memory modules and the amount of internal storage required in each processing pipeline. With regard to the rate of accessing memory, current semi-conductor memory devices suitable for storing a volume data set in a Cube-4 system are either too slow or too expensive or both. Much cheaper memory solutions are needed for a practical system usable in a personal or desktop computer. With regard to the internal storage, the Cube-4 algorithm requires that each processing pipeline store intermediate results within itself during

processing, the amount of storage being proportional to the area of the face of the volume data set being rendered. For a 256^3 data set, this amount turns out to be so large that it would increase the size of a single-chip processing pipeline by an excessive amount and therefore to an excessive cost for a personal computer system. A practical system requires a solution for reducing this amount of intermediate storage.

d) Blocking and SRAM Technology

[0033] In other experimental systems designed at about the same time as Cube-4, these limitations have been ignored. One such system is called "DIV²A," the Distributed Volume Visualization Architecture, and was described in a paper by J. Lichtermann entitled "Design of a Fast Voxel Processor for Parallel Volume Visualization" presented at the 10th Eurographics Workshop on Graphics Hardware, August 28 and 29, 1995, at Maastricht, The Netherlands. Another such system is the VIRIM system, described by M. deBoer, A. Gröpl, J. Hesser, and R. Männer in a paper entitled "Latency- and Hazard-Free Volume Memory Architecture for Direct Volume Rendering," presented at the 11th Eurographics Workshop on Graphics Hardware on August 26-27, 1996, in Poitiers, France.

[0034] The DIV²A system comprises sixteen processing pipelines connected together in a ring, so that each pipeline can communicate directly with its nearest neighbor on each side. Each processing pipeline has an associated memory module for storing a portion of the volume data set. Voxels are organized into small subcubes, and these subcubes are distributed among the memory modules so that adjacent subcubes are stored in adjacent memory modules in each of the three dimension. However, in order to achieve the required memory access rate for rendering a 256^3 data set at 30 frames per second, the DIV²A system requires eight parallel memory banks within each memory module. Moreover, each memory bank is implemented with as Static Random Access Memory or SRAM device.

[0035] In current semiconductor technology, SRAM devices are very fast, so they can support high rates of data access, but they are also very expensive, very power-hungry, and have limited capacity. Since the DIV²A system requires eight of these per processing pipeline and has sixteen processing pipelines, a total of 128 SEAM devices are needed, just to store the voxels of a 256^3 volume data set. It will be appreciated that this far exceeds the physical size and power limitations of a board that could be plugged into the back of a personal computer. Systems such as DIV²A and VIRIM are the size of a drawer of a file cabinet, not including the desktop computer to which they are connected.

SUMMARY OF THE INVENTION

[0036] In order to make real-time volume rendering practical for personal and desktop computers, the subject invention further improves upon the Cube-4 system by providing techniques including architecture modification to permit the use of high capacity, low cost Dynamic Random Access Memory or DRAM devices for memory modules. DRAM devices or "chips" are capable of storing five to ten times more information per chip than SRAM devices, cost five to ten times less per bit of information stored, and required considerably less power to operate. DRAM devices are currently available with capacities of 4, 16, and 64 megabits. Utilizing four 64-megabit DRAMs, only four chips are needed to store a data set of 256^3 voxels with sixteen bits per voxel. By coupling four DRAM modules with four custom designed semiconductor devices for processing pipelines, the subject invention makes it possible to implement a real-time volume rendering system on a board that can be plugged into the back of personal computer.

[0037] However, DRAM devices or chips are also much slower than SRAM devices. Normally, a DRAM chip can support only eight to twelve million accesses per second, versus 50 to 200 million per second for an SRAM chip. Therefore, although four DRAM devices have enough capacity to store a volume data set of 256^3 voxels, together they can support only about 32 to 48 million accesses per second, far fewer than the data rate of 503 million accesses per second needed to render the data set at 30 frames per second.

[0038] In order to achieve the benefits of the high capacity and low cost of DRAMs, the subject invention utilizes DRAM chips that support "burst mode" access. This feature is now found in some DRAM products and enables access rates as fast as those of SRAM devices, but only when accessing consecutive memory locations in rapid sequence. In order to be able to satisfy this condition and therefore to be able to take advantage of burst mode DRAMs, other architectural modifications of the Cube-4 system are required. The subject invention utilizes four techniques for this purpose.

[0039] In the first technique, called "blocking," voxel data is organized into blocks so that all voxels within a block are stored at consecutive memory addresses within a single memory module. This makes it possible to fetch an entire block of data in a burst rather than one voxel at a time. In this way, a single processing pipeline can access memory at data rates of 125 million or more voxels per second, thus making it possible for four processing pipelines and four DRAM modules to render 256^3 data sets at 30 frames per second.

[0040] A second technique to improve upon the Cube-4 system is called "sectioning." In this technique, the volume data set is subdivided into sections and rendered a section at a time. Because each section presents a face with a smaller area to the rendering pipeline, less internal storage is required. Moreover, intermediate results from processing individual sections can be stored outside the processing pipeline and later combined with each other to form a complete

image of the object being rendered. The effect of this technique is to reduce the amount of intermediate storage in a processing pipeline to an acceptable level for semiconductor implementation.

[0041] The third technique reduces the number of pins and the rates at which data must be transmitted across the pins connecting adjacent processing pipelines with each other. This is done by taking advantage of a side-effect of blocking that reduces the amount of data needed to be transmitted per block by a factor of approximately $1/B$, where B is the number of voxels on the edge of any block.

[0042] A final technique called "mini-blocking" is utilized which further refines the aforementioned sectioning technique. In this technique, the B^3 voxels of a block are further organized into small blocks or cubes called mini-blocks of size $2 \times 2 \times 2$ each. This makes it possible, when processing the voxels near the boundary between a section and previously processed sections, to avoid reading entire blocks but only read mini-blocks. This saves approximately five to seven percent of the time needed to process a volume in sections.

[0043] The overall effect of these four architectural improvements is to enable the implementation of a practical, low cost volume rendering system based on the Cube-4 architecture using DRAM memory modules, thereby reducing its size and cost from that of a small file cabinet to that of a printed circuit board that can be plugged into the back of a personal computer. An additional effect is to make it possible to further shrink the Cube-4 architecture so that a pipeline and its memory can be implemented within the same semiconductor chip. This reduces the size and power requirements of the volume rendering system even more.

[0044] More particularly with respect to blocking, current burst mode DRAM devices can operate at more than 125 million accesses per second, but only while fetching data from consecutive memory addresses. Minimum burst sizes are at least eight consecutive accesses but are often more. This data rate is sufficient for four pipelines to render a 256^3 data set at 30 frames per second, or approximately 503 million voxels per second. However, burst mode will only work if data can be organized in memory so that consecutive accesses are at consecutive addresses for at least a minimum burst size.

[0045] In Cube-4 as originally presented, this is not possible for most viewing directions. From at least one third of the viewing directions, consecutive voxels are accessed from memory locations N addresses apart, where N is the number of voxels on the edge of a cubic data set. From another third of the viewing directions, consecutive voxels are accessed from addresses N^2 apart. The result is that even a burst mode DRAM device is reduced to its slowest mode, that of accessing random addresses. In this mode, a DRAM device can support only about eight to twelve million accesses per second.

[0046] This problem can be solved by organizing voxel data in such a way that no matter from what direction the object is viewed, bursts of voxels can be fetched from consecutive memory addresses. To do this, voxel data is grouped into small cubes or blocks with B voxels on a side, so that all of the voxels of a block of size $B \times B \times B$ are stored at consecutive addresses within an single memory module. Although any value for B can be used, values of B equal to four or eight are most practical.

[0047] In order to preserve the Cube-4 characteristic that rendering is independent of the view direction, data must still be skewed across memory modules. However, instead of skewing by voxel as in Cube-4, data in the subject invention is skewed by block. In particular, adjacent blocks in any of the three dimensions of the volume data set are stored in adjacent memory modules. This makes it possible for P adjacent processing pipelines to fetch P adjacent blocks of voxels in burst mode from P adjacent memory modules, all concurrently and simultaneously. Each pipeline renders all of the voxels in a block, then they all step to their respective next blocks, in much the same way as the Cube-4 processing pipelines step to their respective next voxels. In this scheme, the order of processing individual voxels is not the same in the subject invention as the order in the Cube-4 system, so important modifications to the Cube-4 algorithm are necessary.

[0048] With regard to sectioning, this deals with the issue of the amount of storage needed for intermediate results in a processing pipeline. In both the Cube-4 system and the modifications introduced in the subject invention, the required amount of intermediate storage is approximately proportional to N^2/P , where N is the number of voxels on a side of a cubic data set and P is the number of memory modules and pipelines. The reason for this ratio is that in order to compute gradients or normal vectors according to the Cube-4 algorithm, it is necessary to mathematically combine the values of voxels of the slice being currently processed along with the values of voxels fetched in the two previous slices. Similarly, in order to compute trilinear interpolations to obtain values for "missed data points" along the rays, it is necessary to mathematically combine values of voxels from the slice being processed with values from the slice previously processed. The net effect is that each pipeline must remember the voxels from one or two previously read slices in order to complete the processing of a current slice. For a cubic data set with N voxels on a side, the number of voxel values needed to be retained is proportional to the number of voxels in a slice, that is, to N^2 . However, this data is distributed across P processing pipelines, so that this number is reduced to N^2/P . The constant of proportionality is typically more than three.

[0049] More generally, if the voxel data set represents a rectangular solid of arbitrary proportions, the amount of data that must be stored from slice to slice is proportional to the area of the face most nearly perpendicular to the view direc-

tion.

[0050] It will be appreciated that for current semiconductor technology, this is much too much data to fit economically on one processing chip. In particular, if N is 256 and P is 4, then the amount of storage required in the Cube-4 system is at least $3 \times 256^2 \times 4$, or almost 50,000 voxels, equivalent to approximately 800,000 bits for 16-bit voxel values. While this amount of storage can be easily achieved with SRAM or DRAM semiconductor technology, it would result in an excessively large semiconductor device in current technology appropriate for processing units, and therefore it would be too expensive for personal and desktop computing environments.

[0051] To solve this problem, the volume data set is partitioned into sections by subdividing it perpendicular to the face of the volume nearest to the viewing direction, each such subdivision being called a "section." Sections are rendered separately from other sections, almost as if they were independent volume data sets. When rendering a section, some rays pass through the section and out the back. The visual characteristics of these rays, i.e., color, brightness, and transparency, are assigned directly to the corresponding pixels of the viewing surface. Other rays, however, pass out of a side, top, or bottom surface of the section and into an adjacent section. The visual characteristics of these rays must be saved and utilized when rendering the continuation of the same rays in the adjacent section. To save these rays, a processing pipeline of the subject invention writes them into an external storage module. Later, as it begins processing the adjacent section, it re-reads them to initialize the visual characteristics of their continuations.

[0052] The net effect is to reduce the amount of storage required within the processing pipeline to an amount proportional to the surface area of the face of the largest section. Conversely, the size of a section can be chosen based on the amount of available memory. In the subject invention, a section is approximately one quarter to one eighth of the entire volume data set.

[0053] An additional benefit of sectioning is in rendering voxel data sets that are larger than the total amount of memory in the volume memory modules. This can be done by rendering the voxel data set a section at a time. After earlier sections are rendered and their data are no longer needed, later sections are loaded into the volume memory modules, over-writing the earlier sections. These later sections are then processed, while still others sections are loaded, etc. In this way, an entire large volume data set can be passed through a smaller volume memory during the rendering process, and the resulting image can be accumulated in the external memory modules. The size of the largest volume data set that can be thus processed is limited only by the storage capacity of the in the external memory modules.

[0054] With regard to the number of pins needed to interconnect adjacent processing pipeline chips, these represent a significant component of the cost of a semiconductor device. The Cube-4 algorithm requires several hundred pins to transmit information between adjacent pipelines. These pins carry values of voxels, values computed from several voxels, and the partial accumulation of the characteristics of each ray.

[0055] In the Cube-4 algorithm, one data element must be transmitted across each set of pins for each voxel read from memory. With voxels being read in burst mode from DRAM memory at 125 megahertz, that is 125 million voxels per second, this implies a circuit with several hundred pins at operating 125 MHz between each pair of processing pipelines. This presents a serious challenge to designer of the circuit board that contains the volume rendering system.

[0056] The solution in the subject invention is to take advantage of a side effect of the blocking algorithm, namely the reduction by a factor of approximately $1/B$ of the amount of data transmitted between adjacent pipelines. This reduction occurs because data needs only to be transmitted from the voxels on the face of each block to adjacent processing pipelines. Data from voxels interior to a block are utilized only within each block. It will be appreciated that for every B^3 voxels in a block, there are only B^2 voxels on each face of that block. Therefore, the number of pieces of information that need to be transmitted to neighboring pipelines is proportional to B^2 . This results in reduction of the communication between pipeline by a factor of approximately B^2/B^3 , that is $1/B$. This factor of $1/B$ can be applied either to reducing the bandwidth of the transmitted data on individual pins or to reducing the number of pins by multiplexing. Note that any of a number of widely know multiplexing techniques may be utilized in this regard.

[0057] It will be appreciated that in order to process a section, the values of immediately adjacent voxels of previously processed sections must be utilized. These are combined mathematically with voxels values of the section being processed to obtain gradients or normal vectors in the vicinity of the edge of the section and to obtain values for "missed points" between two sections. One way to obtain these values is to re-read the voxel data of previously processed sections directly from the memory modules holding the volume data set. However, as a result of the aforementioned blocking technique, voxel values are read in bursts of a block at a time. If the value of B, the number of voxels on a side of a block, is greater than two, this causes the sectioning mechanism to re-read too many voxels, thereby wasting time and processing power.

[0058] This leads to the fourth technique for improving the Cube-4 system, namely the utilization of mini-blocks and taking advantage of the fact that in some DRAM products, the minimum burst size is eight accesses. In the subject invention, each block is subdivided into mini-blocks of size $2 \times 2 \times 2$ voxels such that each mini-block of a block is also stored in consecutive memory locations within its volume memory module. Then as the sectioning mechanism re-reads voxels from previously processed adjacent sections, it needs to re-read only the mini-blocks at the exact boundaries of those adjacent sections, not the entire blocks. It is estimated that this technique saves approximately five to seven per-

cent of the processing time of a volume data set, although the actual savings depends upon the areas of the boundaries of the sections.

[0059] It will be appreciated that an apparent simplification of the subject invention would be to set value of B, the number of voxels on an edge of a block, to two. This would appear to obviate the need for a separate mini-blocking mechanism. However, this simplification is illusory, because the savings in number of data pins between adjacent processing pipelines is determined by the factor $1/B$. If B were set to two, this savings would only one-half, an amount insufficient for a low cost implementation. Thus, the economics of semiconductor design and production indicate that B should be set to a larger value, such as eight, and that a separate mini-block scheme should be implemented to avoid wasting time re-reading unnecessary voxels at the boundaries of sections.

[0060] In summary, apparatus is provided to enable real-time volume rendering on a personal computer or a desktop computer in which a technique involving blocking of voxel data organizes the data so that all voxels within a block are stored at consecutive memory addresses within a single memory model, making possible fetching an entire block of data in a burst rather than one voxel at a time. This permits utilization of DRAM of memory models which provide high capacity and low cost with substantial space savings. Additional techniques including sectioning reducing the amount of intermediate storage in a processing pipeline to an acceptable level for semiconductor implementation. A multiplexing technique takes advantage of blocking to reduce the amount of data needed to be transmitted per block, thus rendering the number of pins and the rates at which data must be transmitted across the pins connecting adjacent processing modules with each other. Mini blocking saves the time needed to process and sections by avoiding reading entire blocks for voxels near the boundary between a section and previously processed sections.

BRIEF DESCRIPTION OF THE DRAWINGS

[0061] These and other features of the Subject Invention will be better understood in connection with the Detailed Description taken in conjunction with the Drawing of which:

- Figure 1 is a diagrammatic illustration of a view of a volume data set being projected onto an image plane by means of ray-casting.
- Figure 2 is a diagrammatic illustration the processing of an individual ray by ray-casting.
- Figure 3 is a diagrammatic illustration several methods of paralleling the processing of rays in a ray-casting system.
- Figure 4 is a diagrammatic illustration the skewing of voxels among memory modules in the prior art Cube-4 system.
- Figure 5 is a diagrammatic illustration slice parallel rendering as implemented in a Cube-4 system.
- Figure 6 is a diagrammatic illustration the order of fetching and processing voxels from two consecutive slices in a Cube-4 system.
- Figure 7 is a block diagram of a Cube-4 system, showing the connection of processing units in a ring.
- Figure 8 is a block diagram of the processing pipeline of a Cube-4 system, showing the principal components of the pipeline.
- Figure 9 is a diagrammatic illustration the memory addresses of voxels on the XY face of a volume data set in the Cube-4 system.
- Figure 10 is a diagrammatic illustration the memory addresses of voxels on the YZ face of a volume data set in the Cube-4 system.
- Figure 11 is a diagrammatic illustration the organization of voxels by blocks and the skewing of blocks among memory modules in the subject invention.
- Figure 12 is a block diagram of a processing pipeline and its associated memory in one embodiment of the subject invention.

Figure 13 is a diagrammatic illustration the determination of the rendering coordinates and the selected "front" face for rendering, based on the angle of a ray from the viewing surface.

Figure 14 is a diagrammatic illustration the base plane of a volume data set and its relation to the image plane.

Figure 15 is a diagrammatic illustration the calculation of samples from a block of B^3 voxels and voxels forwarded from previously processes blocks.

Figure 16 is a diagrammatic illustration the forwarding of information from a block to support the processing of adjacent blocks in the rightward, downward, and rearward directions.

Figure 17 is a diagrammatic illustration the calculation of gradients from a block of B^3 samples and samples forwarded from previously processed blocks.

Figure 18 is a diagrammatic illustration of three volume data sets, each subdivided into sections.

Figure 19 is a block diagram of modification to the illustration of Figure 12 showing changes needed to implement the technique of sectioning.

DETAILED DESCRIPTION

[0062] Referring now to Figure 1, a two-dimensional view of a three-dimensional volume data set 10 is shown. The third dimension of volume data set 10 is perpendicular to the printed page so that only a cross section of the data set can be seen in the figure. Voxels are illustrated by dots 12 in the figure and are data values that represent some characteristic of a three dimensional object 14 at fixed points of a rectangular grid in three dimensional space. Also illustrated in Figure 1 is a one-dimensional view of a two-dimensional image plane 16 onto which an image of object 14 is to be formed. In this illustration, the second dimension of image plane 16 is also perpendicular to the printed page.

[0063] In the technique of ray-casting, rays 18 are extended from pixels 22 the image plane 16 through the volume data set 10. Each ray accumulates color, brightness, and transparency or opacity at sample points 20 along that ray. This accumulation of light determines the brightness and color of the corresponding pixels 22.

[0064] It will be appreciated that although Figure 1 suggests that the third dimension of volume data set 10 and the second dimension of image plane 16 are both perpendicular to the printed page and therefore parallel to each other, in general this is not the case. The image plane may have any orientation with respect to the volume data set, so that rays 18 may pass through volume data set 10 at any angle in all three dimensions.

[0065] It will also be appreciated that sample points 20 do not necessarily intersect exactly with the fixed points represented by voxels 12. Therefore, the value of each sample point must be synthesized from the values of voxels nearby. That is, the intensity of light, color, and transparency or opacity at each sample point 20 must be calculated by a mathematical function of the values of nearby voxels 12. The sample points 20 of each ray 18 are then accumulated by another mathematical function to produce the brightness and color of the pixel 22 corresponding to that ray. The resulting set of pixels 22 forms a visual image of the object 14 in the image plane 16.

[0066] In both the Cube-4 system and in the subject invention, the calculation of the color, brightness or intensity, and transparency of sample points 20 is done in two parts. First, the mathematical function of trilinear interpolation is utilized to take the weighted average of the values of the eight voxels in a cubic arrangement immediately surrounding the sample point 20. The resulting average is then used to assign a color and opacity or transparency to the sample point by some transfer function. Second, the mathematical gradient of the sample values at each sample point 20 is estimated by taking the differences between nearby sample points: This gradient is then used in a lighting calculation to determine the brightness of the sample point.

[0067] Figure 2 illustrates the processing of an individual ray. Ray 18 passes through the three dimensional volume data set 10 at some angle, passing near voxels 12. Each sample point is calculated by an interpolation unit 24, and its gradient is calculated by a gradient estimation unit 26. The outputs of these are then applied to a transfer function 28 which assigns color, brightness or intensity, and transparency or opacity to each sample. Finally, the colors, levels of brightness, and transparencies assigned to all of the samples along all of the rays are applied to a compositing unit 30 that mathematically combines their values into pixels depicting the resulting image 32 on image plane 16.

a) Parallel Ray-casting

[0068] In order to form different points of view of an object, image plane 16 is moved or re-oriented relative to volume data set 10. It is the goal of the field of interactive volume graphics to recalculate images from volume data sets fast

enough from different points of view so that objects appear to move, as if in a motion picture. In addition, the mathematical functions for converting voxels 12 to samples 20 and for accumulating samples into pixels 22 can be modified to provide the appearance of a dynamically changing or transforming three-dimensional object. A typical requirement is to be able to recalculate an image thirty or more times per second.

5 [0069] It will be appreciated that the magnitude of recalculation is enormous, even for a small data set of 256^3 voxels. Therefore, most systems implementing the ray-casting technique utilize parallel processing units and cast a multiplicity of rays through the volume at the same time. Figure 3 illustrates some potential ways of implementing parallel ray-casting. In Figure 3A, individual rays 18 are cast through the volume data set 10 independently, stepping through the data set from the front to back accumulating color, intensity, and opacity as they proceed. Parallelism is achieved by assign-
10 ing separate rays to separate processing units. For example rays labeled "a" through "g" might be assigned to separate processing units for processing in parallel. This is called the "ray-parallel approach."

[0070] The problem with the ray-parallel approach is that the same voxel values are needed to process different rays, often at the same time. For example, the voxel labeled 34 in Figure 3A is needed in order to process both ray "c" and ray "d." If two independent processing units proceed at their own pace, then the voxel must be fetched from volume data set 10 at least twice. In general, the value of each individual voxel contributes to several rays that pass near it, so each value of the volume data set needs to be fetched several times by separate processors. Since fetching data from a memory module is a time-consuming operation relative to processing data, this approach is slow and expensive. More-
15 over, even if voxels were distributed across memory modules, it is likely that several processors would be trying to access the same module at the same time. Thus, memory access is the bottleneck to rendering the volume data set to an image.

20 [0071] In Figure 3B, this problem is partly alleviated by casting several rays in parallel through the volume data set 10, with each ray assigned to a processing unit and with all processing units working in lock step. In this technique, called the "beam parallel" approach, the processing units all together fetch a row or "beam" 36 of voxels at the same time. Each processing unit synthesizes sample points and calculates color, intensity, and transparency from the voxel that it has fetched and from the values fetched by its neighbors to the left and right. Then all processing units step forward to the next beam, each processing corresponding voxels of that beam and sharing values with its neighbors. Then they step forward to the next beam, then the next, etc., until all rays have emerged from the volume data set. This is repeated for other beams, starting on the front face of the volume data set until all of the voxels of have been processed.

25 [0072] In order to avoid memory conflicts, the processing units for separate rays should have independent memory modules, and the volume data set should be distributed across the memory modules. For example, the vertical "slice" 38 of voxels in Figure 3B would be assigned to a separate memory module from the slices on each side. Therefore, its processor could fetch voxels from that memory module while adjacent processing units fetch adjacent voxels from adjacent memory modules concurrently, without memory conflicts. Processing units would, of course, share voxel values with each other in order to synthesize "missed" sample points, calculate normal vectors, and pass rays through the volume at an angle.

35 [0073] This approach works well provided that the rays are roughly parallel to the vertical slices. If, however, the volume is to be viewed from another direction, as illustrated in Figure 3C, then beam parallel processing fails. In this case, a beam of voxels 36 and the vertical slice 38 are parallel to each other. The result is that all of the voxels of the beam are in the same vertical slice, and therefore they are stored in the same memory module. Thus it would not be possible
40 for a multiplicity of parallel processors to access them all at the same time without clashing over access the that memory module.

[0074] Some ray-casting system solve this problem by storing three copies of the volume data set at any given time, one for each orientation or major view direction. One copy is partitioned among memory modules in slices front to back, a second copy is partitioned among memory module side to side, and a third is partitioned among memory modules top
45 to bottom. It will be appreciated that this triples the amount of memory needed to store the volume data set, and it also imposes a burden upon applications to keep all three copies consistent with each other.

b) Slice-parallel Ray-casting in Cube-4

50 [0075] Referring now to Figure 4, the problem of requiring three copies of a volume data set is solved in the Cube-4 System by "skewing" the volume data set across memory modules in all three dimensions simultaneously. That is, adjacent voxels are stored in adjacent memory modules, so that no matter which way rays enter the volume data set, adjacent rays pass near adjacent voxels assigned to different memory modules.

55 [0076] Figure 4 illustrates this skewing by showing the detail of a portion of a volume data set near one corner, for a system with four memory modules. Each voxel in the figure is illustrated by a small cube 54, and the patterns on the cubes depict the assignment of voxels to memory modules. As can be seen from the illustration, adjacent voxels on the three visible faces of the volume data set have different shaded patterns and therefore are assigned to different memory modules. It will be appreciated that the same is true for the three faces of the volume data set that are not shown in

Figure 4, that is, the three back faces. In the terminology of the Cube-4 System, this arrangement is called "skewing" and it is the essence of Cube-4 invention.

[0077] The arrangement of voxels among memory modules can be described mathematically. If there are P memory modules and processing units, then a voxel located at position (x, y, z) within the volume data set is assigned to the memory module numbered

$$(x + y + z) \bmod P, \quad (1)$$

where x, y, and z are integers that represent the position of the voxel within the data set in terms of the three dimensions, and where the symbol "mod" represents the mathematical operation of dividing the quantity on the left by the integer on the right and keeping only the remainder. That is, the memory module number can be obtained via Formula 1 by adding up the three positional coordinates of the voxel, dividing by the number of memory modules P, and taking the remainder, this remainder having values ranging from zero to (P - 1). Although the x, y, and z coordinates of a voxel are typically counted from a designated corner of the data set, it is also possible, without loss of generality, to count from some designated point, this point being referred to as the "origin."

[0078] It will be appreciated from Formula 1 that the voxels of every slice through each of the three dimensions of the volume data set are skewed across memory modules in exactly the same way, but starting with a different memory module. Therefore, if one of the slices were peeled away from any face of the volume data set of Figure 4, it would reveal an identically colored or shaded slice immediately behind it, but with the patterns shifted by one voxel. Moreover, it will be appreciated that voxels of a particular memory module are always bracketed by voxels of the same two other modules, one module on one side and one on the other. Thus, a particular processing unit associated with a memory module has exactly two neighbors.

[0079] This organization has a profound effect on the ability to parallelize the casting of rays. A group of P rays can be cast in any direction through any face of the volume data set, with each ray being assigned to one processing unit, and they can always be processed in parallel without memory conflicts. Each processing unit fetches a voxel near its ray from its own memory module, so that P adjacent voxels are fetched simultaneously and concurrently. Thus, the skewed memory organization enables full parallelism in rendering a volume data set from any view direction.

[0080] Referring now to Figures 5 and 6, the Cube-4 system renders a volume data set a slice at a time, casting all rays through that slice and accumulating the visual characteristics of all sample points within the slice, before proceeding to the next slice. This technique is called "slice parallel" rendering. Figure 5 is a diagrammatic illustration depicting a multiplicity of rays 18 entering the face of a slice 55 of the volume data set. It will be appreciated that in actual practice, there are far more rays than can be illustrated in this simple figure.

[0081] In the slice parallel technique, each ray 18 entering slice 55 is partially rendered. That is, the visual characteristics including color, brightness, and transparency of each ray is assigned so far as possible from the data available in slice 55. Only after all of the rays have accumulated visual characteristics from slice 55 does the Cube-4 system peel away that slice and step forward to the next slice 56. Because of the skewing of voxels across memory, slice 56 is identical to slice 55, but with its memory module assignments shifted by one voxel.

[0082] Figure 6 is an illustration of the actual order of fetching voxels in the Cube-4 system. In this illustration, P is assumed to be four, so there are four memory modules and four processing pipelines. Voxels 54 are fetched from the top row of the slice in groups of P voxels, starting in the upper left corner. Once these P voxels are inserted into the processing pipeline, the next P voxels from the same row are fetched, then the next, etc., until the row is completed. Then the system steps down to the next row, also fetching in groups of P voxels until that row is also completed. This processing is repeated for all rows of slice 55 until that slice is completed. Then processing continues with the next slice 56, also in groups of P voxels starting from its upper left corner.

[0083] It will be appreciated that variations of the Cube-4 algorithm are possible in which processing begins with some other corner or some other designated point, but it always proceeds in groups of P voxels at a time through the beams of a slice and through the slices of a volume data set.

[0084] Figure 7 is an idealized block diagram of the prior art Cube-4 system and illustrates the interconnection of the processing elements and memory modules. In Figure 7, a multiplicity of processing pipelines 40 are each coupled to their own volume memory modules 42. Processing pipelines 40 are coupled to each other via a multiplicity of communication channels 44, each communication channel providing a means for transmitting data in either direction between two processing pipelines. The outputs 46 of the processing elements are coupled to a bus or other mechanism 48 for purpose of conveying pixels of the rendered image to a display surface 50, such as a computer screen. Input voxels are written to volume memory modules 42 via an input bus 52 which is coupled to each module.

[0085] It will be appreciated from Figure 7 that there is no "first" or "master" processing pipeline. All pipelines have equal status and operate in lock step with each other.

[0086] Figure 8 depicts a block diagram of internal elements of Cube-4 processing pipeline, along with a more

detailed view of the communications channels between the pipelines. In the figure are five processing pipelines 40 arranged side-by-side for illustration purpose only. That is, the rightmost processing unit in the figure is connected to the leftmost processing unit so that the entire system form a ring of processing units as in Figure 7. In Figure 8, each memory module 42 is coupled to FIFO storage unit 60 and to trilinear interpolation unit 62 of its own pipeline. Memory module 42 is coupled via communication lines 44 to the trilinear interpolation units 62 of the two neighboring pipelines to the left and to one trilinear interpolation unit 62 of the neighboring pipeline to the right. FIFO storage unit 62 is coupled to one trilinear interpolation unit 62 in its own processing pipeline and via communication lines 44 to one trilinear interpolation unit 52 in the neighboring processing pipeline to the left and to trilinear interpolation units 62 in each of the two neighboring pipelines to the right. By these connections, each processing pipeline can synthesize sample points 20 from the eight surround voxels. FIFO storage units 60 are First-in, First-out storage circuits that provide internal storage necessary to hold copies of voxel values from one beam to the next and one slice to the next.

[0087] Trilinear interpolation unit 62 is coupled both to FIFO storage unit 64 and to shader unit 66. FIFO storage unit 64 is coupled to shader unit 66 of its own pipeline and, via communication lines 44, to shader units 66 of the two neighboring pipelines to the right. Shader unit 66 of a pipeline is also coupled via communication lines 44 to shader units 66 of the nearest neighboring pipelines on either side and also to the shader unit 66 of the second neighboring pipeline to the right.

[0088] The output of shader unit 66 is coupled to compositing unit 68, which is also couple via communication lines 44 to compositing units 68 of the neighboring pipeline to the left and to the three neighboring pipelines to the right.

[0089] Detailed operation of the Cube-4 system, along with the descriptions of the signals passing across communication lines 44 is given in the aforementioned Doctoral Dissertation by Hanspeter Pfister and also in a Master's thesis (i.e., "Diplomarbeit im Fach Informatik") by Urs Kanus and Michael Meissner entitled "Cube-4, a Volume Rendering Architecture for Real-time Visualization of High-resolution Volumetric Datasets," submitted to Eberhard-Karls-Universität Tübingen, in Tübingen, Germany, on September 30, 1996. In general, P voxels are fetched from memory modules 42 and forwarded to a multiplicity of trilinear interpolation units 62 to synthesize samples 20. Since each sample is synthesized from the eight voxels surrounding it, and since these voxels reside in adjacent rows and adjacent slices, it will be appreciated that some voxel values must be "held up" or delayed to wait for others to be fetched. This delay is provided by FIFO storage units 60. Once samples 20 have been synthesized, they are forwarded to shader units 66 where gradients are calculated.

[0090] Each gradient depends upon the values of samples on either side of it and on samples above and below it and on samples in front of and behind it. It will be appreciated that some samples are computed before others, so the earlier sample values must be held up or delayed, just like voxel values, FIFO storage units 64 provide two levels of delay, one level for a single slice and one level for a second slice.

[0091] Finally, after gradients calculated, the color, brightness, and transparency of the samples can be calculated. These visual characteristics are forwarded to compositing units 68 where they are combined with the colors, levels of brightness, and transparencies already accumulated in their respective rays for previously processed voxels and samples. It will be appreciated that a ray may pass through the volume data set at an angle, so that when it emerges from a slice in the vicinity of a voxel, it may enter the next slice in the vicinity of any of nine voxels. These nine voxels are skewed across as many as five memory modules. Therefore, the values of partially accumulated rays must be forwarded to any of five processing pipelines 40 and the compositing units 68, depending upon the view direction, for continued accumulation of color, brightness, and transparency values of additional slices.

[0092] When a ray is finally completed, it is forwarded to the viewing surface via pixel bus 48 for display.

c) Limitations of Memory Access Rates in Cube-4

[0093] Looking in more detail at the assignment of voxels to memory modules, it is possible to see the order in which voxel values are fetched from memory during slice parallel processing. If a volume data set is organized as a cube with N voxels on each edge so that it has a total of N^3 voxels, and if N is evenly divisible by p, then the address of each voxel within its memory module in the Cube-4 system is given by the mathematical formula

$$\left[\begin{array}{c} x \\ - \\ p \end{array} \right] + y \cdot x \cdot \frac{N}{p} + z \cdot x \cdot \frac{N^2}{p}, \quad (2)$$

where x, y, and z are the integer coordinates of the voxel with respect to a corner or some other origin of the volume data set and where the symbol

$$\left\lfloor \frac{x}{P} \right\rfloor$$

denotes the result of dividing the integer x by the number P and discarding the remainder.

[0094] Figure 9 illustrates the shading of voxels on the XY face of Figure 4, along with the memory address of each voxel for P equal to four. It will be appreciated from the figure that within any row, groups of P adjacent voxels have the same memory address within their respective memory modules. Moreover, when a processing unit fetches voxels consecutively according to the Cube-4 algorithm, it fetches successive voxels of the same shading from the same row. It can be seen from Figure 9 that these voxels have consecutive memory addresses within their memory modules. More generally, it will be appreciated from Formula 2 that for any slice of the volume data set parallel to the XY face, consecutive voxels have consecutive memory addresses. In theory, it would be possible to use a burst mode DRAM module to fetch these voxels more quickly, provided the view direction was such that rays enter the XY face of the volume.

[0095] However, Figure 10 illustrates the assignment of memory addresses to voxels on the YZ face of the same volume data set with P equals four. On this face, it can be seen from the figure that consecutive voxels having the same shading within the same row differ in their memory addresses by the amount N . Moreover, the last voxel of a row having a given shading and the first voxel of the next row having the same shading differ in their memory addresses by the amount $3xN \div 4$.

[0096] Therefore, it would not be possible to use burst mode of a DRAM module to fetch consecutive voxels for rays entering the YZ face. A processing unit fetching voxels according to the Cube-4 algorithm would be limited to fetching them in ordinary mode, that is, not in burst mode, at a data rate as slow as if it were fetching memory locations at random.

[0097] It will be appreciated from Formula 2 that in the ZX face, consecutive voxels of any row having the same shading would differ in their memory addresses by N^2 . Therefore, burst mode could not be applied to processing rays entering this face, either.

[0098] More generally, if the volume data set is a rectangular solid with dimensions L , M , and N , where each of L , M , and N is evenly divisible by P , then it has a total of $LxMxN$ voxels. The address of each voxel in the Cube-4 system is given by the formula

$$\left\lfloor \frac{x}{P} \right\rfloor + yx \frac{L}{P} + zx \frac{L \times M}{P}, \quad (3)$$

[0099] It will be appreciated from Formulas 1 and 3 that consecutive voxels within a row having the same shading on the XY face are stored at consecutive memory addresses, but consecutive voxels within a row having the same shading on the YZ face are stored at addresses differing by L and that consecutive voxels within a row having the same shading on the ZX face are stored at addresses differing by LxM . Thus, burst mode can be used to speed up the fetching of voxels when rays enter the XY face, but it cannot be used when they enter the YZ or ZX faces.

d) Blocking and the Utilization of Burst-mode Dram

[0100] Referring now to Figure 11, in order to group voxels in such a way that they can be fetched from consecutive memory addresses, regardless of viewing direction, the subject invention utilizes a technique called blocking. By doing so, it becomes possible to use burst mode to access voxels from DRAM modules for all viewing directions. In this technique, voxels are organized into subcubes or blocks, and blocks are skewed across memory modules rather than individual voxels being skewed. The shading of a block in the figure indicates the memory module in which it is stored, with all of the voxels of that block being stored in that same memory module.

[0101] In particular, if each block has B voxels along each of its edges, then the assignment of a voxel with coordinates (x, a, z) is given by the formula.

$$\left(\begin{bmatrix} x \\ - \\ B \end{bmatrix} + \begin{bmatrix} y \\ - \\ B \end{bmatrix} + \begin{bmatrix} z \\ - \\ B \end{bmatrix} \right) \bmod P, \quad (4)$$

where P is the number of memory modules and processing units and x, y, and z are integer coordinates of the voxel relative to the corner or other origin of the volume data set in each of the three dimensions. That is, the memory module to which voxel (x, y, z) is assigned can be determined by dividing each coordinate by B, throwing away the remainder, taking the sum of these three divisions, then dividing the resulting sum by P and taking the remainder. This is the same formula described by Lichtermann in the aforementioned description of the DIV²A system.

[0102] Blocks are numbered within the volume data set in the subject invention in the same way as voxels are numbered in the Cube-4 system, that is by counting blocks in each of the three dimensions from the corner or other origin. It will be appreciated from Formula 4 that a voxel at position (x, y, z) is stored in a block with block coordinates (B_x, B_y, B_z) given by the formulas.

$$B_x = \left\lfloor \frac{x}{B} \right\rfloor, \quad B_y = \left\lfloor \frac{y}{B} \right\rfloor, \quad B_z = \left\lfloor \frac{z}{B} \right\rfloor \quad (5)$$

[0103] If the volume data set represents a cube with N³ voxels, and if PxB evenly divides N, the number of voxels on a side of the cubic data set, then the starting address of the block with coordinates (B_x, B_y, B_z) within its memory module is given by the formula

$$\frac{B_x \times B^3 + B_y \times N \times B^2 + B_z \times N^2 \times B}{P} \quad (6)$$

[0104] Within each block, the voxels are stored at consecutive memory addresses. It will be appreciated that many possible arrangements of voxels within a block are possible. In one embodiment, voxel memory addresses relative to the beginning of the block are given by the formula

$$x \bmod B + B * (y \bmod B) + B^2 * (z \bmod B). \quad (7)$$

[0105] That is, the position of voxel (x, y, z) within its block can be found by taking the remainders from x, y, and z after dividing by B, then adding the remainder from x to B times the remainder from y and then adding that to B² times the remainder from z. It will be appreciated that Formula 7 describes consecutive locations with a range of B³ memory addresses, where B³ is the number of voxels in a block.

[0106] Referring now to Figure 12, a diagrammatic illustration is of the pipeline processor 40 of one embodiment of the subject invention along with its associated memory module 42. Like Cube-4, the subject invention comprises a multiplicity of processing pipelines 40 and memory modules 42 connected in a ring, as illustrated in Figure 7. Referring again to Figure 12, memory module 42 is coupled to two block buffers 72, each of which has capacity to store B³ voxels, where B is the number of voxels on the edge of a block. Each block buffer 72 is coupled both to interpolation unit 82 and to two tri-state interfaces 74. Each tri-state interface 74 is coupled to a voxel communication line 76, one being coupled to the nearest neighboring pipeline 40 in the clockwise direction around the ring and the other being coupled to the nearest neighboring pipeline in the counter-clockwise direction around the ring.

[0107] It will be appreciated that in electronic design, a tristate interface is one which serves as either an input or output interface. In particular, in a semiconductor implementation of the present embodiment, the pins connecting tri-state interface 74 to communication line 76 are both input and output pins. Therefore, each voxel communication line 76 can

carry data in either direction, so that processing pipeline 40 can either receive data from or transmit data to either of its nearest neighbors. In this embodiment, both voxel communication lines 76 carry data in the same direction around the ring, that is, either both are configured for clockwise signaling or both are configured for counterclockwise signaling at any given instant.

[0108] Tri-state interface 74 are also coupled to beam FIFO storage unit 78, to slice FIFO storage unit 80 and to optional delay unit 73. Beam FIFO storage unit 78, slice FIFO storage unit 80, and optional delay unit 73 are all coupled to interpolation unit 82. For rendering a volume data set L voxels wide, M voxels high, and N voxels deep, beam FIFO storage unit 78 is configured to hold $L \div (B \times P)$ elements, where each element is an array of $(B + 1)^2$ voxels. Likewise, slice FIFO storage unit 80 is configured to hold $(L \times M) \div (B^2 \times P)$ elements, where each element is an array of an array of $B \times (B + 1)$ samples. Optional delay unit 73 is configured to hold B^2 voxels and to delay them either zero fundamental cycles or B^3 fundamental cycles, depending upon whether the pipeline is at the left end of its partial beam or not. As will be shown below, beam and slice FIFO storage units 78 and 80 hold voxels forwarded from immediately above and in front of the block being processed, respectively. Optional delay unit 73 holds voxels forwarded from the pipeline immediately to the left.

[0109] Interpolation unit 82 calculates the values of sample points based on the immediately surrounding voxels. In general, to calculate B^3 sample points, $(B + 1)^3$ voxel values are needed. These are obtained from the B^3 voxels read from voxel memory 42 into block buffer 72, plus an array of B^2 voxels from optional delay unit 73, an array of $(B + 1)^2$ voxels from beam FIFO storage unit 78, and an array of $B \times (B + 1)$ voxels from slice FIFO storage unit 80.

[0110] Interpolation unit 82 is coupled to gradient estimation and shading unit 92 and to tri-state interfaces 84. Tri-state interfaces 84 are coupled to sample communication lines 86, which are in turn coupled to the nearest neighbor pipelines in the clockwise and counterclockwise directions, respectively. Like voxel communication lines 76, sample communication lines 86 are bidirectional and may carry sample data in either direction around the ring. Tri-state interfaces 84 are also coupled to beam FIFO storage unit 88, slice FIFO storage unit 90, and optional delay unit 83. Optional delay unit 83 and beam and slice FIFO storage units 88 and 90 are all coupled to gradient estimation and shading unit 92.

[0111] For rendering a volume data set L voxels wide, M voxels high, and N voxels deep, beam FIFO storage unit 88 is configured to hold $L \div (B \times P)$ elements, where each element is an array of $2 \times (B + 2)^2$ samples. Likewise, slice FIFO storage unit 90 is configured to hold $(L \times M) \div (B^2 \times P)$ elements, where each element is an array of $2 \times B \times (B + 2)$ samples. Optional delay unit 83 is configured to hold B^2 sample values for a delay of either zero fundamental cycles or B^3 fundamental cycles, depending upon whether the pipeline is at the left end of its partial beam or not. As will be shown below, beam and slice FIFO storage units 88 and 90 hold samples forwarded from immediately above and in front of the block being processed, respectively. Optional delay unit 83 holds samples forwarded from the pipeline immediately to the left.

[0112] Gradient estimation and shading unit 92 is coupled directly to compositing unit 102. Compositing unit 102 is coupled to tri-state interfaces 94, which in turn are coupled to composition element communication lines 96. As with voxel communication lines 76 and sample communication lines 86, composition element communication lines 96 are bi-directional communication lines to the nearest neighboring pipeline in each of the clockwise and counterclockwise direction around the ring. Tri-state interfaces 94 are also beam FIFO storage unit 98, slice FIFO storage unit 100, and optional delay unit 93. Beam FIFO storage unit 98, slice FIFO storage unit 100, and optional delay unit 93 are all coupled to compositing unit 102. Finally, compositing unit 102 is coupled to pixel output bus 48, which is in turn coupled to a viewing surface such as a computer screen.

[0113] For rendering a volume data set L voxels wide, M voxels high, and N voxels deep, beam FIFO storage unit 98 is configured to hold $L \div (B \times P)$ elements, where each element is an array of $(B + 1)^2$ pixel values of partially accumulated rays, that is, visual characteristics containing color, opacity, and depth information. Likewise, slice FIFO storage unit 100 is configured to hold $(L \times M) \div (B^2 \times P)$ elements, where each element is an array of $B \times (B + 1)$ pixel values of partially accumulated rays. Optional delay unit is configured to hold B^2 pixel values of partially accumulated rays with a delay of either zero fundamental cycles or B^2 fundamental cycles. As will be shown below, beam and slice FIFO storage units 98 and 100 hold pixel values of partially accumulated rays forwarded from immediately above and in front of the block being processed, respectively. Optional delay unit 93 holds pixel values of partially accumulated rays from the pipeline immediately to the left.

[0114] In other words, in the present embodiment of the subject invention, a processing unit 40 comprises four major functional stages connected together in pipeline fashion, namely, a block buffering stages, an interpolation stage, a gradient estimation and shading stage, and a compositing stage. Each stage is separated from the next by a pair of bi-directional communication lines to the neighboring pipelines and by beam and slice FIFO storage units capable of holding values forwarded from the previous beam and the previous slice.

e) Method of Operation

[0115] The method of operation of this embodiment of the subject invention will now be described. Referring to Figure

13, the view direction is determined. A single ray 110 is cast perpendicularly from the view surface through the volume data set, that is from image 10, so that it strikes the center of face 12 that is nearest and most nearly perpendicular to the view surface. In general, the ray will strike the view surface at some angle 116 less than 45 degrees from the normal vector of face 112, that is, from a line perpendicular to face 112. It will be appreciated that if the angle 116 is greater than 45 degrees, a different face of the volume data set would be nearer and more nearly perpendicular to the ray 110. If the angle 116 to normal vector line 114 is exactly 45 degrees, then either of two view surfaces can be chosen arbitrarily. Moreover, if ray 110 strikes a corner of the volume data set, then angle 116 will be 45 degrees from each of three normal vectors will be 45 degrees, and any of the three faces can be chosen arbitrarily.

[0116] Having selected a face 112, ray 110 is projected onto the face, making a "shadow" 118 of the ray. In general, this shadow will land in one of the four quadrants of the face. The quadrant 120 containing shadow 118 will be the selected quadrant. If shadow 118 lands on a line between two quadrants, then either quadrant can be selected. If shadow 118 is a point exactly in the center of face 112, then ray 110 is perpendicular to the face and any quadrant may be selected.

[0117] Having selected a quadrant 120 of a face 112, the volume data set may now be rotated in three dimensions so that face 112 is at the "front" and quadrant 120 is in the upper left corner. It will be appreciated that in "rotating" the volume data set, no data has to be moved. Instead, an appropriate transformation matrix can be applied to voxel and block coordinates to translate these coordinates into coordinate system in which the corner of the selected quadrant is the origin and is in the upper left corner of the front face. The theory of transformation matrices is explained in graphics textbooks, including the aforementioned reference by J. Foley, *et al.*

[0118] In the following discussion, coordinates relative to the volume data set itself are denoted as x, y, and z, while coordinates relative to the selected quadrant 120 are denoted u, v, and w. These are called "rendering coordinates." The terms "left," "right," "above," "below," "back," and "front" are defined in terms in rendering coordinates as follows:

"Left"	"in the direction of decreasing values of u."
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"Right"	"in the direction of increasing values of u."
"Above" and "top"	"in the direction of decreasing values of v."
"Below" and "bottom"	"in the direction of increasing values of v."
"Front"	"in the direction of decreasing values of w."
"Back"	"in the direction of increasing values of w."

[0119] Moreover, the front, left, top corner of the volume data set in rendering coordinates is designated as the "origin," that is, the voxel with $(u, v, w) = (0, 0, 0)$. In rendering coordinates, rays always pass through a volume from front to back and in a downward and rightward direction, unless they happen to be perpendicular to the face.

[0120] It will be appreciated from the definition of block skewing in Formula 4 that the association of the terms "left,"

"right," "above," "below," "front," and "back" with particular neighboring pipelines depends upon the viewing direction. For one viewing direction, the pipelines in front, to the left, and above may all be the pipeline in the counterclockwise direction in Figure 7, while in other viewing directions, some or all of them may be the pipeline in the clockwise direction in Figure 7.

[0121] In the current embodiment of the subject invention, the processing order is exactly that of Figure 6 except that it references blocks, not individual voxels. That is, processing begins at the origin in rendering coordinates and proceeds from left to the right in groups of P blocks across each beam of blocks, then beam by beam down the slice blocks, and then slice by slice from the front of the volume to the back. As the preprocessing pipelines step across the volume in groups of P blocks, rays will always exit blocks in the direction still to be processed, that is, either to the back, the bottom, or the right. In all cases, already processed data will come from above, to the front, and to the left of a block currently being processed.

[0122] Referring again to Figure 12, the fundamental processing cycle in the current embodiment of the subject invention is the cycle time of reading one voxel from DRAM memory in burst mode. These fundamental cycles are grouped into block cycles of B^3 fundamental cycles each. At the beginning of a block cycle, B^3 voxels are fetched from consecutive addresses of memory module 42, starting at the beginning of the block under consideration and continuing for B^3 fundamental cycles. Voxels are fetched into one of the two block buffers 72. During the next block cycle, those B^3 voxels will be processed while a new block of B^3 voxels is fetched into the other block buffer 72. Then during the following block cycle, the roles of the two buffers are reversed again, in an application of the familiar technique of "double buffering."

[0123] Referring now to Figure 14, in both Cube-4 and the subject invention, the spacing of rays 18 is determined not by pixels 22 on image plane 16, but by base pixels 130 on the base plane 132. Figure 14 depicts a two-dimensional illustration of a three-dimensional volume data set and image plane as in Figure 1. The "base plane" of Figure 14 is a mathematical plane parallel the selected face 112 of the volume data set and passing through the origin (u, v, w) = (0, 0, 0) in rendering coordinates. "Base pixels" 130 of base plane 132 are coterminous with voxels on face 112, and they extend in all directions with the same spacing as voxels. Rays 18 are cast in a direction perpendicular to image plane 16 but passing through the exact centers of base pixels 130 in base plane 132. The resulting image is then rendered into the base plane, not the image plane. It will be appreciated that, in general, rays passing through base pixels will not line up exactly with pixels 22 of image plane 16. Therefore, a postprocessing step is required to "warp" the base plane image into a final image.

[0124] It will also be appreciated that for rays 18 that are parallel to each other, sample points are offset in space from their neighboring voxels by the same amount whenever they lie in the same plane parallel to the base plane. This simplifies the Cube-4 algorithm considerably. In particular, it means that adjacent sample points are surrounded by adjacent groups of eight neighboring voxels, with four of those eight being shared between the two sample points.

[0125] The flow of data among pipelines during the operation of the current embodiment will now be described. First, an array of B^3 sample values along rays 18 is calculated from the B^3 voxels of a block plus other voxels forwarded from neighboring pipelines. Since samples are interpolated from their nearest voxels, it will be appreciated that it takes an array of $(B + 1)^3$ voxels to generate B^3 samples. Second, an array of B^3 gradients is calculated and pixel values representing colors, brightness or shading levels, and transparency levels are assigned. Since it requires the values of samples on all sides of a given sample in order to estimate its gradient, a total of $(B + 2)^3$ samples is needed to generate B^3 gradients and pixel values. Finally, the B^3 pixel values are composited with previously accumulated pixel values to form partially rendered rays. This also requires an array of $(B + 1)^3$ pixel values to accumulate the visual characteristics of the rays passing through a block.

[0126] Figure 15 illustrates three views of a three-dimensional array of $(B + 1)^3$ voxels needed by a pipeline to calculate a block of B^3 sample points. Figure 15A represents a cross-section of the array for values of $w > 0$, that is, all voxels except the front face of the array. Figure 15B represents the right face of the array. Figure 15C depicts a perspective view of the three dimensional array from a view below, in front of, and to the right of the array.

[0127] The voxels of the cubic array in Figure 15 come from four sources. A block of B^3 voxels 140 is fetched from volume memory into block buffer 72. An array of B^2 voxels 142 is forwarded from the pipeline on the left of the current block via communication lines 76 and optional delay unit 73. An array of $(B + 1)^2$ voxels 144 is taken from the output side of beam FIFO storage unit 78, and an array of $B \times (B + 1)$ voxels 146 is taken from the output side of slice FIFO storage unit 80. It will be appreciated that the total of these four groups of voxels is $(B + 1)^3$. The array 150 of B^3 samples, represented in the figure by crosses, is calculated by trilinear interpolation or some other mathematical function. It will be appreciated that, in general, the array 150 of B^3 samples calculated by this process is offset to the left, front, and above the array 140 of B^3 voxels originally fetched from volume memory 42 via block buffer 72. The amount of the offset is always less than the spacing between voxels, but it may be zero in the case of view directions that are perpendicular to one of the axes of the rendering coordinates.

[0128] Since P processing pipelines are operating in parallel, voxel array 142 will, in general, be the right face of the block of B^3 voxels currently being processed immediately to the left. Therefore, as voxels of a block are being fetched into a block buffer 72, its rightmost B^2 voxels must immediately be forwarded to the processing element on the right and

inserted into optional delay unit 73, then forwarded to interpolation unit 82. This forwarding must be completed before the voxels are needed for calculating the sample points 150 at the left most edge of block 140. The exception is when block 140 is the leftmost block of a partial beam. In this case, the block to the left was read during the preceding block cycle, so the array of voxels 142 needs to be delayed by one block cycle, that is, by B^3 fundamental cycles. This delay is represented by optional delay unit 73 in Figure 12. In the case that a pipeline is at the left end of its partial beam, the delay value is set to B^3 cycles, but otherwise it is set to zero, meaning no delay at all.

[0129] In addition to forwarding the rightmost face of block 140 for immediate use by the processing pipeline to the right, it is also necessary to prepare arrays for the processing pipelines below and behind block 140. Referring now to Figure 16, array 242 mimics array 142. This will be needed during the processing of the next beam, that is, $L \div (B \times P)$ block cycles later. This array is formed from the bottom face of block 140, the bottom row of array 142, and the bottom row of array 146. It is forwarded to the processing pipeline of the block below for storage in its beam FIFO storage unit 78. Likewise, an array 246 mimicking array 146 must be prepared for the processing pipeline of the block behind. This is formed from the back face of block 140 and the back vertical row of array 142. It is forwarded to the slice FIFO storage unit 80 of the processing pipeline of the block behind, to be ready for use one slice later, that is $L \div M \div (B^2 \times P)$ block cycles later.

[0130] The calculation of gradients and the compositing of rays follows roughly the same pattern. Interpolation unit 82 produces an array of B^3 samples. In general, as illustrated in Figure 15, these are offset slightly above, to the left of, and in front of the B^3 voxels of block 140. In order to calculate B^3 gradients from these samples, a cubic array of $(B + 2)^3$ samples is required. This is because each gradient is calculated by taking the central differences or some other mathematical function of the adjacent samples in each of the three dimensions.

[0131] Referring now to Figure 17, gradients 158 can be calculated at sample points that not at the boundary of the $(B + 2)^3$ group of samples. The voxels of the original block 140 are illustrated by dots. Samples calculated by interpolation unit 82 are illustrated by crosses. The original group calculated as part of processing block 140 is the B^3 array 150 of samples. In addition, an array 152 of $2 \times B^2$ samples is needed from the block immediately to the left, an array 154 of $2 \times (B + 2)^2$ samples is needed from the processing of the block above, and an array 156 of $2 \times B \times (B + 2)$ samples is needed from the block immediately in front. As with voxel array 142, array 152 is being calculated by the processing pipeline immediately to the left during the same pipeline cycle, unless block 140 is at the left of a partial beam. Therefore, sample array 152 is forwarded to interpolation unit 82 optional delay unit 83. The delay value is set to zero except when the pipeline is at the left end of its partial beam, in which case the delay value is set to B^3 fundamental cycles, that is, one block cycle. Arrays 154 and 156, by contrast, are obtained from the beam and slice FIFO storage units 88 and 90, respectively.

[0132] Likewise, following the calculation of samples, the interpolation unit 82 must therefore forward arrays mimicking arrays 154 and 156 to the beam and slice FIFO storage units 88 and 90, respectively, for processing in the next beam and slice.

[0133] It will be appreciated that the processing pipeline that originally fetched block 140 of voxels calculates gradients on samples that are offset to the left, above, and in front by more than the spacing of one voxel. That is, that it calculates gradients for some of the samples synthesized on earlier block cycles. The reason for this is that no processing unit can calculate a gradient that is dependent upon voxels and samples that are synthesized later. In particular, the processing unit at the right end of a partial beam cannot calculate gradients for the B^2 the samples nearest the right face of its block. Moreover, no processing pipeline can calculate gradients for the samples on the bottom face of its block. Therefore, these have to be calculated later, but to compensate, the processing pipeline must calculate previously uncalculated gradients for samples above, to the left, and in front of its block.

[0134] Following the calculation of gradients, pixel values representing the color, brightness, and transparency or opacity of a sample can be assigned. These are then passed by gradient estimate and shader unit 92 to the final set of stages for compositing. These follow the pattern of Figure 15, but offset in sample space to the positions of the calculated gradients in Figure 17. B^3 pixel values are forwarded directly from gradient estimation and shading unit 92 to compositing unit 102. An array of pixel values of partially accumulated rays mimicking voxel array 142 is forwarded to the processing pipeline to the right, where it is inserted into optional delay unit 93. Likewise, array of compositing elements mimicking voxel arrays 144 and 146 are forwarded to the beam and slice FIFO storage units 98 and 100, respectively, of the neighboring pipelines to the rear and below. As before, these arrays are formed from the bottom and rear slices of the B^3 compositing elements calculated from the gradients in the same block cycle, plus the bottom rows of voxels obtained from the left neighbor and from the slice FIFO storage unit 100.

[0135] In this way, all of the voxels can be processed in the groups of P blocks at a time, stepping right across a beam of blocks, then stepping beams down a slice of blocks, and stepping slices through the volume data set.

[0136] It will be observed that in some embodiments, the processing of each block within a pipeline is carried out in serial fashion in B^3 fundamental cycles. When accessing volume memory at burst mode rate of 125 megahertz or 133.3 megahertz, the length of a fundamental cycle is 8 nanoseconds or 7.5 nanoseconds respectively. This is very demanding upon the designer of the circuitry that calculates samples, estimates gradients, and composites pixel values in par-

tially accumulated rays. Therefore, in preferred embodiments, processing with a pipeline is carried out in parallel by a multiplicity of processing units operating at a slower rate. For example, if B equals 8, then processing can be carried out by a single set of processing stages operating with 7.5 nanosecond to 8 nanosecond cycle times, or by two sets of processing stages operating at 15 to 16 nanosecond cycle times, or by four sets of processing stages operating at 30 to 32 nanosecond cycle times, or by eight sets of processing stages operating at 60 to 64 nanosecond processing times, or by even more stages. It will be appreciated that the selection of the number of processing stages is an implementation choice left to a practitioner skilled in the art of electronic circuit design.

[0137] It will be appreciated from the foregoing description that the introduction of blocking and the associated changes to the architecture and processing order of voxels have the effect of making it possible for a system based on Cube-4 to utilize burst mode for accessing DRAM. That is, it becomes possible in the subject invention to implement the large amounts of memory required to hold volume data sets utilizing inexpensive, readily available DRAM devices. This leads to substantial savings in cost, size, and power over previously implemented real-time volume rendering systems, and it makes it possible to implement practical and affordable real-time volume rendering systems for personal and desktop computing environments.

[0138] It will also be appreciated that as semiconductor technology advances and as it becomes possible to combine processing logic and DRAM on the same device or chip, the same architectural changes needed to enable burst mode DRAM access will be needed to enable direct, on-chip access by a processing pipeline to volume memory in an efficient and effective manner.

f) Communication between processing pipelines

[0139] From Figure 12, and the discussion above, it can be seen that three kinds of data must be passed from one pipeline to its neighbor in the current embodiment. These are voxels, samples, and partially accumulated pixel values. These are transmitted between pipelines via communication lines 76, 86, and 96, respectively. Moreover, for each kind of data there are two kinds of FIFO storage units, namely, beam FIFO storage units 78, 88, and 98 for voxels, samples, and pixels, respectively, and slice FIFO storage units 80, 90, and 100, respectively.

[0140] During every block cycle, B^3 voxels are fetched from volume memory 42. At the same time, B^2 voxels of array 142, $(B + 1)^2$ voxels of array 144, and $Bx(B + 1)$ voxels of array 146 must be transmitted between two pipelines. That is,

$$\begin{aligned} B^2 + (B + 1)^2 + Bx(B + 1) &= 3B^2 + 3B + 1 \\ &= (B + 1)^3 - B^3 \end{aligned} \quad (5)$$

voxels must be transmitted.

[0141] Similarly, during every block cycle, B^3 samples are obtained from the sample calculation stage of the pipeline, but B^2 samples of array 152, $2x(B + 2)^2$ of array 154, and $2xBx(B + 2)$ samples of array 156 are transmitted between pipelines. This is, a total of

$$\begin{aligned} 2xB^2 + 2x(B + 2)^2 + 2xBx(B + 2) &= 6B^2 + 12B + 8 \\ &= (B + 2)^3 - B^3 \end{aligned} \quad (6)$$

samples must be transmitted.

[0142] Finally, during every block cycle, B^3 pixel values are calculated within the pipeline, but B^2 pixels values representing partially accumulated rays are needed from the left, $(B + 1)^2$ pixels values representing partially accumulated rays are needed from above, and $Bx(B + 1)$ pixel values are needed representing partially accumulated rays from the front. Thus, a total of

$$\begin{aligned} B^2 + (B + 1)^2 + Bx(B + 1) &= 3B^2 + 3B + 1 \\ &= (B + 1)^3 - B^3 \end{aligned} \quad (7)$$

pixels values must be transmitted between pipelines. It will be seen from Equations 5, 6, and 7 that the total number of items of data that must be transmitted between pipelines for each B^3 block of voxels is approximately proportional to B^2 .

[0143] The following table displays values for Equations 5, 6, and 7 for block sizes ranging from 2 to 16.

B	B^3	$(B + 1)^3 - B^3$	$(B + 2)^3 - B^3$
2	8	19	56
4	64	61	152
8	512	217	488
16	4096	817	1736

[0144] As can be seen from the table, as B grows, B^3 grows rapidly but Equations 5, 6, and 7 grow much more slowly. This is because for each cubic array of data fetched from memory or a previous stage, only a quadric number of voxels need to be transmitted between pipelines. For example, if a block has two voxels on each edge, then 2^3 or eight voxels must be fetched during a block cycle, but 19 voxels, 56 samples, and 19 pixels must be transmitted to the neighboring pipelines during the same block cycle. This is almost twelve times as much information communicated as fetched.

[0145] On the other hand, for $B = 8$, for each 512 voxels fetched during a block cycle, 217 voxels, 488 samples, and 217 pixels must be transmitted to neighboring pipelines. The ratio of communicated values to fetched values in this case is about 1.8.

[0146] Therefore, a side effect of blocking is the reduction in the amount of information that must be transmitted between pipelines. This has the added benefit to the design of a semiconductor implementation of a processing pipeline because a reduction in the amount of communication is a reduction in the number of pins.

[0147] It is also possible to reduce the bandwidths of pins rather than their number.

[0148] From Figure 8, it will be appreciated that the prior art Cube-4 system requires communication lines between adjacent processing pipelines, pipelines that are a distance of two from each other, and in the case of the compositing unit 68, pipelines that are a distance of three from each other. The total number of pins required is slightly under two hundred for eight-bit voxels and nearly four hundred for sixteen-bit voxels. By contrast, in the current embodiment with $B = 8$, and assuming 16-bit voxels and samples and 48-bit pixels, the total number of pins required is 192, that is, 96 pins leading to the pipeline on each side.

[0149] It will be appreciated from the method of block skewing in the subject invention that once rendering coordinates have been chosen, a ray may passing through a particular block will exit that block and may enter any one of seven other blocks, namely the three adjacent blocks to the right, below, or behind the given block, the three blocks with edges adjacent to the right bottom, right back, and bottom back edges of the given block, or the block with a top, left, front corner adjacent to the bottom, right, rear corner of the given block. These seven blocks are processed by at least three different processing modules, but possibly as many as five.

[0150] Whereas in the Cube-4 system, each processing pipeline requires direct connections to all five, in the subject invention this is not necessary. Instead, all communication necessary to forward voxel and sample values and partially accumulated rays is accomplished by the forwarding of arrays of these values to nearest neighbors. Values needed by more distant pipelines, that is by pipelines that are not nearest neighbors, are forwarded in several steps, but will always arrive at the destination pipeline in time.

g) Sectioning

[0151] In the subject invention, each processing pipeline requires internal storage or memory to hold data values transmitted from one pipeline to the next. These data values are retained in this memory until needed for processing a subsequent beam or subsequent slice of blocks. In the current embodiment, this internal memory takes the form of beam FIFO storage units 78, 88, and 98 and slice FIFO storage units 80, 90, and 100. Each FIFO storage unit is an internal memory unit that implements the well-known technique of First-In, First-Out memory management. That is, new data is always written to unused memory locations. When previously stored data is read, its memory locations become unused again and are available for new data. The control of a FIFO storage unit guarantees that data items can only be read in the order that they are written.

[0152] In the current embodiment, each beam FIFO storage unit requires a capacity to store data for $L \times (B \times P)$ blocks to be processed later, where L is the width of the volume data set being rendered, B is the number of voxels on the edge

of a block, and P is the number of processing pipelines in the volume rendering system. The amount of data stored per block in FIFO storage units 78 and 98 are arrays of size $(B + 1)^2$ data elements, the amount of data stored per block in FIFO storage unit 88 is an array of size $2 \times (B + 2)^2$ data elements. Thus the total amount of internal storage for beam FIFO storage units is approximately $L \times B \times P$.

5 [0153] In the case of slice FIFO storage units 80, 90, and 100, each requires a capacity for $L \times M \times (B^2 \times P)$ blocks to be processed later, where M is the height of the volume data set. The amount of data stored per block in FIFO storage units 80 and 100 arrays of size $B \times (B + 1)$ data elements, the amount of data stored per block in FIFO storage unit 88 is an array of size $2 \times B \times (B + 2)$ data elements. Thus the total amount of internal storage for beam FIFO storage units is approximately $L \times M \times P$.

10 [0154] In other words, the storage capacities of beam FIFO storage units must be proportional to the width of the volume data set, while the capacities of slice FIFO storage units must be proportional the area of the face of the volume data. In the case of cubic volume data sets, that is volume data sets with the same number of elements on each edge, these storage requirements are independent of view direction. But in the cases of general volume data sets shaped like rectangular solids of arbitrary proportions, the storage requires vary with view direction.

15 [0155] It will be appreciated that in the prior art Cube-4 system and in other embodiments of the subject invention, the internal storage requirements are approximately the same. That is, beam storage is proportional to the width of the volume data set, and slice storage is proportional to the area of the face of the volume data set. It will also be appreciated that the storage requirements for slice FIFO units dominates all others.

20 [0156] Moreover, the total amount of storage can be very large. In the current embodiment, with voxels and samples needing 16 bits of storage and partially accumulated pixels need 32 bits of storage, more than 1.5 megabits of internal storage are required per pipeline to render a 256^3 data set with four processing pipelines. In current semiconductor technology suitable for implementing processing elements, this would result in a very large and therefore very expensive chip.

25 [0157] To alleviate this problem, the subject invention renders a volume data set in pieces or "sections" in such a way as to reduce the area of the face of each section to a more manageable value. This reduces the amount of internal storage needed because each section is rendered as a separate volume data set. Figure 18 depicts three example volume data sets in rendering coordinates, each to be rendered from view direction 110. Figure 18A is partitioned into equal horizontal sections 200. Each section is a "slab" of data from front to back in the rendering coordinates. The amount of internal storage required for slice FIFO units is proportional to the area of each section face 202.

30 [0158] In Figure 18B, the volume data set 10 is partitioned in both the u and v dimensions into rectangular sections that extend from front to back. Again, the amount of slice FIFO storage required for rendering each section is proportional to the area of the face. In Figure 18C, the volume data set is a long, thin rectangular solid to be rendered from its long side. In the case, the data set is partitioned into sections with square faces side-by-side. In all three cases, the amount of internal storage required for rendering is reduced to an amount proportional to the areas of the faces 202 of the sections.

35 [0159] If the view direction 110 is exactly perpendicular to each section face 202, then the images resulting from rendering each section can be placed side-by-side or one above the other to produce a correctly rendered image of the entire volume data set. That is, in the case a perpendicular view direction, rendering in sections is exactly equivalent to rendering the data set as a whole.

40 [0160] However, if the view direction is not perpendicular to each face, then some rays will pass through the boundaries 204 between sections. In this case, partially composited or accumulated rays that exit the side or bottom of a section and into an adjacent section must be stored temporarily until the rendering of that section is complete. They must then be used to continue the accumulation of rays in the adjacent sections.

45 [0161] In the subject invention, partially accumulated rays are stored outside of rendering pipelines in external storage modules. Referring now to Figure 19, a modification of the lower portion of Figure 12 is shown. In this modification, compositing unit 102 is coupled to external storage module 104 via tri-state unit 106. Tri-state units 94 connecting pixel communication lines 96 are also coupled to tri-state interface 106. External storage module 104 is then coupled to rendering output 48.

50 [0162] During rendering operation, when compositing unit 102 sends a partially accumulated pixel value to its neighboring pipeline below or to the right, if that pixel value represents a ray leaving right or bottom side of the section currently being rendered and if that ray will enter the left or top side of an adjacent section, then the neighboring pipeline writes the pixel value to external storage module 104 via tri-state interface 106. Then, when rendering the adjacent section, pixel values of partially accumulated rays that enter the section from the left or above must be read from the external storage unit 104 instead of from optional delay 93 or beam FIFO storage 98. Pixel values representing rays that leave the entire volume data set are also written to external storage module 104, then forwarded to pixel output lines 48.

55 [0163] In the subject invention, external storage is implemented utilizing burst mode DRAM chips. The amount of storage required is proportional to the areas of the bottom and right faces forming the boundaries of sections. For example, if a cubic data set with N voxels on each edge is divided into horizontal sections as in Figure 18A, then each boundary

204 will have at most N^2 pixels. The actual number of pixels needing to be stored between sections depends upon the viewing angle. Perpendicular viewing directions require no pixels to be stored externally, which viewing angles at 45 degrees to the boundary of a section require that N^2 pixels be stored.

[0164] It will be appreciated that to correctly accumulate rays at the boundaries of sections 204, sample points must be calculated between the right or bottom plane of voxels of one section and the top or left plane of the adjacent section. The calculation of these samples requires voxel values from both sections. Similarly, gradients must be estimated for sample values both between sections and for the sample values within each section nearest the boundary 204. This estimation requires sample values from both sections.

[0165] In some embodiments of the subject invention, these voxel and sample values required for the calculations near the section boundaries are stored in external storage 104 along with pixel values of partially accumulated rays. In preferred embodiments, however, these voxel and sample values are obtained by re-reading and re-rendering the voxels near the boundary of the section. This has the effect of refilling the beam FIFO storage units with the appropriate intermediate values needed to calculate the samples and gradients near a section boundary 204.

[0166] It will be appreciated that the technique of sectioning can be utilized for rendering volume data sets that are too large to fit into volume memory all at once. A large data set would be subdivided into sections, each of which is small enough to fit into volume memory and each of which has a face that is small enough to render within the limits of internal storage. Then each section is rendered separately, and its rendered image is accumulated in external storage modules 104. After a section is rendered, it is replaced in volume memory with an adjacent section which is then rendered separately. Pixel values of partially accumulated rays are passed from one section to the next via the same mechanism as described above, including the re-reading and re-processing of voxels near the boundary. This process is repeated until the entire volume data set is rendered. It will be appreciated that in cases of very large data sets, it is impractical to achieve the full real-time rendering rate of 30 frames per second.

h) Mini-blocking

[0167] In the subject invention as described thus far, voxels are read from voxel memory a block at a time. That is, each read operation fetches B^3 voxels in one block cycle. This is more than needed to re-process the voxels near the boundary of a section. For example, if B equals 8, then 512 voxels are read in a block cycle. However, only two or three planes of voxels are needed along the boundary for reprocessing, that is, only 128 or 192 voxels. The requirement to read 512 voxels at a time in order to process only 128 or 192 voxels is a waste of time.

[0168] To reduce this waste, the subject invention utilizes a technique called "mini-blocking." In this technique, voxels are stored in with a block in smaller blocks of "mini-blocks" of size $2 \times 2 \times 2$ voxels each, that is a total of eight voxels in a mini-block. The entire block is then a cubic array of mini-blocks. Each mini-block is stored at consecutive locations in volume memory, so that it can be fetched in burst mode. The mini-block size is chosen to be at least as large as the minimum burst size of some burst mode DRAM products. Therefore, the mini-blocks of a block can be read from volume memory in any order, and a subset of a block can be read whenever appropriate.

[0169] This technique is utilized when re-reading the voxels near the boundary of a section. Only as many mini-blocks as containing the voxels needed for re-processing are fetched.

[0170] It will also be appreciated that the sizes of block buffers can be reduced slightly by fetching mini-blocks in the order that voxels are processed within a block. That is, the rendering of a block begins at one side as soon as those voxels have been fetched. So long as fetching proceeds as fast as the processing of individual voxels, the two can proceed in lock step. Then, new voxels can be fetched into buffer areas for which processing is completed. This reduces the total amount of block buffer storage 72 needed for rendering.

[0171] A program listing of one embodiment of the subject invention is presented in the Appendix hereto.

[0172] Having now described a few embodiments of the invention, and some modifications and variations thereto, it should be apparent to those skilled in the art that the foregoing is merely illustrative and not limiting, having been presented by way of example only. Numerous modifications and other embodiments are within the scope of one of ordinary skill in the art and are contemplated as falling within the scope of the invention as limited only by appended claims and equivalents thereto.

APPENDIX

Functional Simulator for volume rendering
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 Technology Center America, Inc., 1997, All rights
 reserved.

```

15  ::::::::::::::
    cube4/AddressGenerator.C
    ::::::::::::::
    // AddressGenerator.C
    // (c) Ingmar Bitter '97

    // AddressGenerator
    // in : uvw Dataset coordinates
    // out: index into corresponding memory module

    // Copyright, Mitsubishi Electric Information Technology Center
    // America, Inc., 1997, All rights reserved.

25  #include "AddressGenerator.h"

void AddressGenerator::Demo()
{
30      AddressGenerator addr;
      cout << endl << "Demo of class " << typeid(addr).name();
      cout << endl << "size : " << sizeof(AddressGenerator) << " Bytes";
      cout << endl << "public member functions:";
      cout << endl << "AddressGenerator addr; = " << addr;
      cout << endl << "End of demo of class " << typeid(addr).name() << endl;
35  } // Demo

    //////////////////////////////////////
    // constructors & destructors

40  // static first init
    int AddressGenerator::numOfChips          = 0;
    int AddressGenerator::numOfPipelinesPerChip = 0;
    int AddressGenerator::blockSize           = 0;
    int AddressGenerator::blockEdge           = 0;
45  int AddressGenerator::blockFace            = 0;
    int AddressGenerator::blockVolume         = 0;

    AddressGenerator::AddressGenerator()
    {
50      results.address = new int [numOfPipelinesPerChip];
      results.weightsXYZ = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];
      results.perPipelineControlFlags = new PerPipelineControlFlags
[ numOfPipelinesPerChip];

```

```

} // constructor

5
AddressGenerator::~AddressGenerator()
{
    if (results.address) { delete results.address; results.address=0; }
    if (results.weightsXYZ) { delete results.weightsXYZ; results.weightsXYZ=0; }
}
10
    if (results.perPipelineControlFlags) {
        delete results.perPipelineControlFlags;
        results.perPipelineControlFlags=0;
    }
} // destructor

15
////////////////////////////////////
// show/set data & data properties
//
// - local show/set functions

20
ostream & AddressGenerator::Ostream(ostream & os) const
{
    // append Control info to os
    os << typeid(*this).name() << "@" << (void *) this;
    os <<endl<<" blockEdge      = "<<blockFace;
25
    os <<endl<<" blockFace      = "<<blockFace;
    os <<endl<<" blockVolume    = "<<blockVolume;
    os <<endl<<" datasetSizeUVW = "<<datasetSizeUVW;
    os <<endl<<" rowOfBlocks    = "<<rowOfBlocks;
    os <<endl<<" sliceOfBlocks   = "<<sliceOfBlocks;
    os <<endl<<" U_step      = "<<U_step;
30
    os <<endl<<" V_step      = "<<V_step;
    os <<endl<<" W_step      = "<<W_step;
    os <<endl<<" u_step      = "<<u_step;
    os <<endl<<" v_step      = "<<v_step;
    os <<endl<<" w_step      = "<<w_step;

35
    // return complete os
    return os;
} // Ostream

40
void AddressGenerator::GlobalSetup(const int setNumOfChips,
                                   const int setNumOfPipelinesPerChip,
                                   const int setBlockSize)
45
{
    numOfChips          = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    blockSize           = setBlockSize;
}
50

55

```

```

3
    blockEdge = blockSize;
    blockFace = blockEdge * blockEdge;
5    blockVolume = blockFace * blockEdge;
} // GlobalSetup

void AddressGenerator::PerFrameSetup(const Vector3D<int> & setDatasetSizeUVW,
10    const Matrix4x4<int> &
    setPipelineToDatasetMatrix)
{
    datasetSizeUVW = setDatasetSizeUVW;
    pipelineToDatasetMatrix = setPipelineToDatasetMatrix;
15    rowOfBlocks = blockVolume * datasetSizeUVW.U();
    sliceOfBlocks = rowOfBlocks * (datasetSizeUVW.V()/blockEdge);

    // linear address offset in u,v,w for complete blocks
    U_step = blockVolume;
20    V_step = rowOfBlocks / (blockEdge*numOfChips); // division because of
storage
    W_step = sliceOfBlocks / (blockEdge*numOfChips); // distributed over
numOfChips

25    // linear address offset in u,v,w for voxels inside a block
    u_step = 1;
    v_step = blockEdge;
    w_step = blockFace;

    // reset pipeline registers
30    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        results.address[p] = 0;
        results.perPipelineControlFlags[p].Reset();
    }
    results.perChipControlFlags.Reset();

35    // print debug info
    // static bool first(true); if (first) { cout<<this<<endl; first =
false; }
} // PerFrameSetup

40
////////////////////////////////////
// local computation functions

45 void AddressGenerator::RunForOneClockCycle()
{
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        results.address[p] = MemoryAddress(inputs.voxelPosXYZ[p].X(),
50            inputs.voxelPosXYZ[p].Y(),

55

```

50

```

// (c) Ingmar Bitter '97

5 // AddressGenerator
// in : uvw dataset coordinates
// out: index into corresponding memory module

// Copyright, Mitsubishi Electric Information Technology Center
10 // America, Inc., 1997, All rights reserved.

#ifndef _AddressGenerator_h_ // prevent multiple includes
#define _AddressGenerator_h_

15 #include "Object.h"
#include "Vector3D.h"
#include "Matrix4x4.h"
#include "Control.h"
#include "FixPointNumber.h"

20 class AddressGeneratorInputs {
public: // pointers
    Vector3D<int> *voxelPosXYZ;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags *perChipControlFlags;
25 PerPipelineControlFlags *perPipelineControlFlags;
};

class AddressGeneratorResults {
30 public: // arrays
    int *address;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
35 };

class AddressGenerator : virtual public Object {
public:

40     static void Demo ();

    // constructors & destructors
    AddressGenerator();
    ~AddressGenerator();
45 // show/set data & data properties
    virtual ostream & Ostream (ostream & ) const;

    static void GlobalSetup (const int setNumOfChips,
50     const int setNumOfPipelinesPerChip,
        const int setBlockSize);

```

55


```

        6
virtual void PerFrameSetup(const Vector3D<int> & setDatasetSizeUVW,
5      const Matrix4x4<int> & setPipelineToDatasetMatrix);

    // local computation functions
    virtual void RunForOneClockCycle();
    virtual /*inline*/ int ChipIndex      (const int u, const int v, const
10   int w);
    virtual /*inline*/ int BlockStartAddress (const int u, const int v, const
    int w);
    virtual /*inline*/ int VoxelBlockOffset (const int u, const int v, const
    int w);
    virtual /*inline*/ int MemoryAddress     (const int x, const int y, const
15   int z);

public:
    AddressGeneratorInputs inputs;
    AddressGeneratorResults results;

protected:
20   Matrix4x4<int> pipelineToDatasetMatrix;
    static int numOfChips, numOfPipelinesPerChip, blockSize;
    static int blockEdge, blockFace, blockVolume;
    int rowOfBlocks, sliceOfBlocks;
    int U_step, V_step, W_step;
25   int u_step, v_step, w_step;
    Vector3D<int> datasetSizeUVW;
    int lineExtend; // this many addresses are needed per line
    int sliceExtend; // this many addresses are needed per slice
};

30   #endif // _AddressGenerator_h_
    ::::::::::::::
    cube4/ColorLUT.C
    ::::::::::::::
    // ColorLUT.C
35   // (c) Ingmar Bitter '97 / Urs Kanus '97

    // Copyright, Mitsubishi Electric Information Technology Center
    // America, Inc., 1997, All rights reserved.

    #include "Cube4.h"
40   #include "ColorLUT.h"

    //////////////////////////////////////
    // Construction/Destruction
    //////////////////////////////////////

45   ColorLUT::ColorLUT()
    {
        pLookupTable = 0;
    }

50

55

```

7

```

ColorLUT::~ColorLUT()
{
5
}

void ColorLUT::WriteTable(const char * fileName)
{
10
    cout << fileName;
}

void ColorLUT::ReadTable (const char * fileName)
{
15
    int index;
    int red, green ,blue, alpha;

    if (pLookupTable) delete [] pLookupTable;

20
    pLookupTable = new LUT[256];

    //cout << endl << "lookup Table \"" << fileName << "\"\n";

    ifstream lutFile(fileName);

25
    lutFile >> index;
    while (index < 255){
        lutFile >> alpha;
        lutFile >> red;
        lutFile >> green;
30
        lutFile >> blue;
        pLookupTable[index].red = red;
        pLookupTable[index].green = green;
        pLookupTable[index].blue = blue;
        pLookupTable[index].alpha = alpha;
        lutFile >> index;
35
    }

}

////////////////////////////////////
40
// show/set data & data properties
//

ostream & ColorLUT::Ostream(ostream & os) const
{
45
    // append Light info to os
    os << "not there yet, sorry\n";

    // return complete os
    return os;

50
} // Ostream

```

55

```

5      FixPointNumber ColorLUT::Red(int index) const { return pLookupTable[index].red;
      }

      FixPointNumber ColorLUT::Green(int index) const { return
      pLookupTable[index].green; }

      FixPointNumber ColorLUT::Blue(int index) const { return
10     pLookupTable[index].blue; }

      FixPointNumber ColorLUT::Alpha(int index) const { return
      pLookupTable[index].alpha; }

      FixPointNumber ColorLUT::Kd(int index) const { return pLookupTable[index].kd; }
15     FixPointNumber ColorLUT::Ks(int index) const { return pLookupTable[index].ks; }

      void ColorLUT::ComputeLUT(int param) const { cout << param; }
      ::::::::::::::
      cube4/ColorLUT.h
20     ::::::::::::::
      // ColorLUT.h
      // (c) Ingmar Bitter '97 / Urs Kanus '97

      // Copyright, Mitsubishi Electric Information Technology Center
      // America, Inc., 1997, All rights reserved.
25

      #ifndef _ColorLUT_h_    // prevent multiple includes
      #define _ColorLUT_h_

      #include "Misc.h"
      #include "Object.h"
30     #include "FixPointNumber.h"

      struct LUT {
          FixPointNumber red;
          FixPointNumber green;
35         FixPointNumber blue;
          FixPointNumber alpha;
          FixPointNumber kd;
          FixPointNumber ks;
      };

40     class ColorLUT : virtual public Object {
      public:

          static void      Demo ();

          // constructors & destructors
45         ColorLUT ();
          ~ColorLUT ();

          // show/set data & data properties
50
55

```

55

```

5  // constructors & destructors

// static first init
int ComposBufferPipeline::numOfChips          = 0;
int ComposBufferPipeline::numOfPipelinesPerChip = 0;
10 int ComposBufferPipeline::blockSize         = 0;
Cube4 *ComposBufferPipeline::cube4           = 0;

ComposBufferPipeline::ComposBufferPipeline()
{
} // constructor

15 ComposBufferPipeline::~ComposBufferPipeline()
{
} // destructor

20 // show/set data & data properties

ostream & ComposBufferPipeline::Ostream(ostream & os) const
25 {
    // append ComposBufferPipeline info to os
    os << typeid(*this).name() << "@" << (void *) this;
    os << endl << "    numOfChips          = " << numOfChips;
    os << endl << "    numOfPipelinesPerChip    = " << numOfPipelinesPerChip;
30    os << endl << "    chipIndex              = " << chipIndex;
    os << endl << "    blockSliceCoxelFiFo.Size() = "
    << blockSliceCoxelFiFo.Size();
    os << endl << "    volumeSliceCoxelFiFo.Size() = "
    << volumeSliceCoxelFiFo.Size();

35    // return complete os
    return os;

} // Ostream

40 // show/set data & data properties
//
// - local show/set functions

45 void ComposBufferPipeline::GlobalSetup(const int setNumOfChips,
                                         const int setNumOfPipelinesPerChip,
                                         const int setBlockSize)
50
55

```

```

11
{
    numOfChips          = setNumOfChips;
5    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    blockSize          = setBlockSize;
} // GlobalSetup

10 void ComposBufferPipeline::LocalSetup(const int setChipIndex,
                                       const int setPipelineIndex,
                                       ComposBufferStage & composBufferStage)
{
15    chipIndex = setChipIndex;
    pipelineIndex = setPipelineIndex;

    inputs.coxel = &(composBufferStage.inputs.coxel[pipelineIndex]);
    inputs.perChipControlFlags
20     = composBufferStage.inputs.perChipControlFlags;

    results.coxel = &(composBufferStage.results.coxel[pipelineIndex]);

    cube4 = composBufferStage.cube4;
} // LocalSetup

25 void ComposBufferPipeline::PerFrameSetup()
{
    // reset pipeline registers already done in SliceVoxelFiFoStage

30    // resize fifo's according to dataset size
    // step delay for a z-step within a block
    blockSliceDelay = (cube4->datasetSizeXYZ.X()*blockSize
                      ) /
    (numOfChips*numOfPipelinesPerChip);

35    // step delay for a z-step between blocks
    volumeSliceDelay = (cube4->datasetSizeXYZ.X()*cube4->datasetSizeXYZ.Y()
                      ) /
    (numOfChips*numOfPipelinesPerChip);

40    blockSliceCoxelFiFo.SetSize(blockSliceDelay);
    volumeSliceCoxelFiFo.SetSize(volumeSliceDelay);

    *(inputs.coxel) = cube4->backgroundCoxel;
    blockSliceCoxelFiFo.Preset(*(inputs.coxel));
45    volumeSliceCoxelFiFo.Preset(*(inputs.coxel));

    readBigFiFoCounter = readSmallFiFoCounter =
        writeBigFiFoCounter = writeSmallFiFoCounter = -1;
} // PerFrameSetup

50

55

```

```

5  //////////////////////////////////////
// local computation functions

void ComposBufferPipeline::RunForOneClockCycle()
{
    // reset counters
    if (cube4->composBuff[0].inputs.perChipControlFlags->volumeStart ||
10      inputs.perChipControlFlags->volumeStart ||
        ((readBigFiFoCounter == 0) &&
         (readSmallFiFoCounter == 0) &&
         (writeBigFiFoCounter == 0) &&
         (writeSmallFiFoCounter == 0))) {

15      readBigFiFoCounter = blockSliceDelay;
      readSmallFiFoCounter = (blockSize-1) * readBigFiFoCounter;

      writeBigFiFoCounter = readBigFiFoCounter;
      writeSmallFiFoCounter = readSmallFiFoCounter;
20    }

    //////////////////////////////////////
    // first read from FiFos into results register

25    // at start of block read from big FiFo
    if (readBigFiFoCounter > 0) {
        volumeSliceCoxelFiFo.Read(*(results.coxel));
        --readBigFiFoCounter;
        // if (this == &cube4->sliceCoxelFiFo1[0].sliceCoxelFiFoPipeline[0])
        cout<<"R"<<*(results.coxel)<<volumeSliceCoxelFiFo<<endl;
30    }

    // in middle and at end of block read from small FiFo
    else if (readSmallFiFoCounter > 0) {
        blockSliceCoxelFiFo.Read(*(results.coxel));
        --readSmallFiFoCounter;
35        //if (pipelineIndex == 0)      cout<<"r"<<*(results.coxel);
    }

    //////////////////////////////////////
    // now write to FiFos from inputs register

40    // at start and in middle of block write to small FiFo
    if (writeSmallFiFoCounter > 0) {
        blockSliceCoxelFiFo.Write( *(inputs.coxel) );
        --writeSmallFiFoCounter;
        // if (this == &cube4->sliceCoxelFiFo0[0].sliceCoxelFiFoPipeline[0])
45    cout<<"w";
    }

    // at end of block write to big FiFo of next chip
50

55

```

```

13
    else if (writeBigFiFoCounter > 0) {
        ModInt c(chipIndex+1, numOfChips);
        int p(pipelineIndex);
        cube4->composBuff[c].composBufferPipeline[p].
            volumeSliceCoxelFiFo.Write(*(inputs.coxel) );
        --writeBigFiFoCounter;
        //if (this == &cube4->sliceCoxelFiFo[0].sliceCoxelFiFoPipeline[0])
        cout<<"W";
    }
} // RunForOneClockCycle

//////////////////////////////////////
// internal utility functions

// end of ComposBufferPipeline.C
:::::::::::::
cube4/ComposBufferPipeline.h
:::::::::::::
// ComposBufferPipeline.h
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#ifndef _ComposBufferPipeline_h_    // prevent multiple includes
#define _ComposBufferPipeline_h_

#include "Misc.h"
#include "Object.h"
#include "Voxel.h"
#include "Coxel.h"
#include "Control.h"
#include "FiFo.h"

class ComposBufferStage;
class Cube4;

class ComposBufferPipelineInputs {
public: // pointers
    Coxel *coxel;
    PerChipControlFlags *perChipControlFlags;
};

class ComposBufferPipelineResults {
public: // pointers
    Coxel *coxel;
};

class ComposBufferPipeline : virtual public Object {

```



```

public:
5      static void      Demo ();

        // constructors & destructors
        ComposBufferPipeline ();
        ~ComposBufferPipeline ();

10     // show/set data & data properties
        // - class Object requirements
        virtual ostream & Ostream (ostream & )    const;

        // - local show/set functions
15     static void GlobalSetup (const int setNumOfChips,

        const int setNumOfPipelinesPerChip,

        const int setBlockSize);
        virtual void LocalSetup (const int setChipIndex,
20     const int setPipelineIndex,

        ComposBufferStage & composBufferStage);
        virtual void PerFrameSetup ();
        // local computation functions
25     virtual void RunForOneClockCycle();

public:
        ComposBufferPipelineInputs inputs;
        ComposBufferPipelineResults results;

30     protected:
        FiFo<Coxel> blockSliceCoxelFiFo;
        FiFo<Coxel> volumeSliceCoxelFiFo;

        int blockSliceDelay, volumeSliceDelay;

35     int  readSmallFiFoCounter,  readBigFiFoCounter;
        int  writeSmallFiFoCounter, writeBigFiFoCounter;

        static int  numOfChips, numOfPipelinesPerChip, blockSize;
        static Cube4 *cube4;
40     int      chipIndex, pipelineIndex;    // only for debugging purpose
    };

#include "ComposBufferStage.h"
#include "Cube4.h"

45     #endif      // _ComposBufferPipeline_h_
        ::::::::::::::
        cube4/ComposBufferStage.C
        ::::::::::::::
        // ComposBufferStage.C
50

55

```

```

// (c) Ingmar Bitter '97

5 // Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include "ComposBufferStage.h"

void ComposBufferStage::Demo()
10 {
    ComposBufferStage composBuffer;
    cout << endl << "Demo of class " << typeid(composBuffer).name();
    cout << endl << "size : " << sizeof(ComposBufferStage) << " Bytes";
    cout << endl << "public member functions:";
    cout << endl << "ComposBufferStage composBuffer; = " << composBuffer;
15 cout << endl << "End of demo of class " << typeid(composBuffer).name() <<
endl;
} // Demo

20 ///////////////////////////////////////////////////////////////////
// constructors & destructors

// static first init
int ComposBufferStage::numOfChips = 0;
int ComposBufferStage::numOfPipelinesPerChip = 0;
25 Cube4 *ComposBufferStage::cube4 = 0;

ComposBufferStage::ComposBufferStage() : composBufferPipeline(0)
{
    composBufferPipeline = new ComposBufferPipeline [numOfPipelinesPerChip];
    results.coxel = new Coxel [numOfPipelinesPerChip + 1];
30 } // constructor

ComposBufferStage::~ComposBufferStage()
{
    if (composBufferPipeline) { delete composBufferPipeline;
35 composBufferPipeline=0; }
    if (results.coxel) { delete results.coxel; results.coxel=0; }
} // destructor

40 ///////////////////////////////////////////////////////////////////
// show/set data & data properties

ostream & ComposBufferStage::Ostream(ostream & os) const
{
45 // append ComposBufferStage info to os
os << typeid(*this).name() << "@" << (void *) this;
    os << endl << "    numOfChips          = " << numOfChips;
    os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
    os << endl << "    chipIndex            = " << chipIndex;
50
55

```

```

5      // return complete os
      return os;

} // Ostream

10  ///////////////////////////////////////////////////////////////////
    // show/set data & data properties
    //
    // - local show/set functions

15  void ComposBufferStage::GlobalSetup(const int setNumOfChips,

                                     const int setNumOfPipelinesPerChip,

                                     const int setBlockSize,

20      Cube4 *setCube4)
    {
        numOfChips          = setNumOfChips;
        numOfPipelinesPerChip = setNumOfPipelinesPerChip;
        cube4                = setCube4;
        ComposBufferPipeline::GlobalSetup(numOfChips, numOfPipelinesPerChip,
25      setBlockSize);
    } // GlobalSetup

30  void ComposBufferStage::LocalSetup(const int setChipIndex)
    {
        chipIndex = setChipIndex;
        for (int p=0; p<numOfPipelinesPerChip; ++p) {
            composBufferPipeline[p].LocalSetup(chipIndex,p,*this);
        }
35  } // LocalSetup

void ComposBufferStage::PerFrameSetup()
{
    int p;
40    // reset pipeline registers
    for (p=0; p<numOfPipelinesPerChip; ++p) {
        results.coxel[p] = cube4->backgroundCoxel;
    }

    for (p=0; p<numOfPipelinesPerChip; ++p) {
45        composBufferPipeline[p].PerFrameSetup();
    }

    // print debug info
    //static bool first(true); if (first) { cout<<this<<endl; first=false; }
50

55

```

40

```

static void      Demo ();

5          // constructors & destructors
          ComposBufferStage ();
          ~ComposBufferStage ();

10         // show/set data & data properties
          // - class Object requirements
          virtual ostream & Ostream (ostream & )    const;

          // - local show/set functions
          static void GlobalSetup (const int setNumOfChips,

15          const int setNumOfPipelinesPerChip,

          const int setBlockSize,

20          Cube4 *setCube4);

          virtual void LocalSetup (const int setChipIndex);
          virtual void PerFrameSetup();
          // local computation functions
          virtual void RunForOneClockCycle();

25

public:
          ComposBufferPipeline *composBufferPipeline;
          ComposBufferStageInputs inputs;
          ComposBufferStageResults results;

30

protected:
          static int      numOfChips, numOfPipelinesPerChip;
          static Cube4 *cube4;
          int              chipIndex; // only for debugging purpose

35          friend class ComposBufferPipeline;
};

#ifdef      // _ComposBufferStage_h_
          ::::::::::::::
40          cube4/ComposLinXPipeline.C
          ::::::::::::::
          // ComposLinXPipeline.C
          // (c) Ingmar Bitter '97

          // Copyright, Mitsubishi Electric Information Technology Center
          // America, Inc., 1997, All rights reserved.

          #include "ComposLinXPipeline.h"

50          void ComposLinXPipeline::Demo()
          {
              ComposLinXPipeline composLinX;

55

```

19

```

    cout << endl << "Demo of class " << typeid(composLinX).name();
    cout << endl << "size : " << sizeof(ComposLinXPipeline) << " Bytes";
5    cout << endl << "public member functions:";
    cout << endl << "ComposLinXPipeline composLinX; = " << composLinX;
    cout << endl << "End of demo of class " << typeid(composLinX).name() <<
endl;
} // Demo

10
////////////////////////////////////
// constructors & destructors

// static first init
int ComposLinXPipeline::numOfChips          = 0;
15 int ComposLinXPipeline::numOfPipelinesPerChip = 0;
int ComposLinXPipeline::blockSize          = 0;
Cube4 *ComposLinXPipeline::cube4          = 0;

ComposLinXPipeline::ComposLinXPipeline()
20 {
    // Number of clock cycles to process a partial beam inside a block
    int partialBeamDelay = blockSize / numOfPipelinesPerChip;

    // Delay for communication: 16 bits, 4 bits / cycle, double frequency => 2
cycles
25    int communicationDelay = 2;

    partialBeamCoxelFiFo.SetSize(partialBeamDelay);
    partialBeamWeightsFiFo.SetSize(partialBeamDelay);
    partialBeamPerPipelineControlFlagsFiFo.SetSize(partialBeamDelay);
30    partialBeamPerChipControlFlagsFiFo.SetSize(partialBeamDelay);

    communicationDelayCoxelFiFo.SetSize(communicationDelay);
    communicationDelayWeightsFiFo.SetSize(communicationDelay);
    communicationDelayPerPipelineControlFlagsFiFo.SetSize(communicationDelay);
    communicationDelayPerChipControlFlagsFiFo.SetSize(communicationDelay);
35 } // constructor

ComposLinXPipeline::~ComposLinXPipeline()
{
} // destructor
40

////////////////////////////////////
// show/set data & data properties

45 ostream & ComposLinXPipeline::Ostream(ostream & os) const
{
    // append ComposLinXPipeline info to os
    os << typeid(*this).name() << "@" << (void *) this;
    os << endl << "    numOfChips          = " << numOfChips;
50
55

```

```

20
    os <<endl<< "          numOfPipelinesPerChip = " <<
numOfPipelinesPerChip;
5    os <<endl<< " chipIndex          = " << chipIndex;

    // return complete os
    return os;

} // Ostream
10

////////////////////////////////////
// show/set data & data properties
//
// - local show/set functions
15

void ComposLinXPipeline::GlobalSetup(const int setNumOfChips,

                                     const int setNumOfPipelinesPerChip,
                                     const int setBlockSize)
20
{
    numOfChips = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    blockSize = setBlockSize;
} // GlobalSetup
25

void ComposLinXPipeline::LocalSetup(const int setChipIndex,

                                     const int setPipelineIndex,

                                     ComposLinXStage & composLinXStage)
30
{
    chipIndex = setChipIndex;
    pipelineIndex(setPipelineIndex, numOfPipelinesPerChip+1);

    inputs.coxelLeft = &(composLinXStage.computation.coxel[pipelineIndex-1]);
35    inputs.coxelMiddle = &(composLinXStage.computation.coxel[pipelineIndex]);
    inputs.weightsXYZ =
    &(composLinXStage.computation.weightsXYZ[pipelineIndex]);
    inputs.perChipControlFlags
        = &composLinXStage.computation.perChipControlFlags;
    inputs.perPipelineControlFlags
40    =
    &(composLinXStage.computation.perPipelineControlFlags[pipelineIndex]);

    results.coxel = &(composLinXStage.results.coxel[pipelineIndex]);
    results.weightsXYZ = &(composLinXStage.results.weightsXYZ[pipelineIndex]);
    results.perPipelineControlFlags
45    = &(composLinXStage.results.perPipelineControlFlags[pipelineIndex]);
    results.perChipControlFlags
        = &(composLinXStage.results.perChipControlFlags);

50

55

```

21

```

    cube4 = composLinXStage.cube4;
} // LocalSetup

5

void ComposLinXPipeline::PerFrameSetup()
{
    // reset pipeline registers already done in ComposLinXStage
    partialBeamCoxelFiFo.Preset(*(inputs.coxelMiddle));
    partialBeamWeightsFiFo.Preset(*(inputs.weightsXYZ));
10
    partialBeamPerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineControlFlags));
    ;
    partialBeamPerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFlags));

15
    communicationDelayCoxelFiFo.Preset(*(inputs.coxelMiddle));
    communicationDelayWeightsFiFo.Preset(*(inputs.weightsXYZ));

    communicationDelayPerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineControl
Flags));

20
    communicationDelayPerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFlags));
} // PerFrameSetup

////////////////////////////////////
25
// local computation functions

void ComposLinXPipeline::RunForOneClockCycle()
{
    if (cube4->cubeMode == Cube4Classic) {

30
        // complete selection from ComposSelX

        if (inputs.perChipControlFlags->xStep == Left) {
            // data comes from the right (which happens in ComposSelX)
            // L      M      R
            // o      o<---o
35
            *(results.coxel) = *(inputs.coxelMiddle);
        }
        else if (inputs.perChipControlFlags->xStep == Right) {
            // data comes from the left
            // L      M      R
            // o---->o      o
40
            *(results.coxel) = *(inputs.coxelLeft);
        }
        else if (inputs.perChipControlFlags->xStep == Middle) {
            // data goes straight
            // L      M      R
            // o      o      o
45
            *(results.coxel) = *(inputs.coxelMiddle);
        }
        else { ERROR( "Wrong xstep in ComposLinXPipeline!" ); }
    }

50

55

```



```

5      else if (cube4->cubeMode == Cube4Light) {
      // interpolating between coxels,
      // interpolation weights depending on x weight
      FixPointNumber interpolationWeight;
10      if (inputs.weightsXYZ->X() < 0) {
          // weight pointing left, starting at middle coxel
          // L      M
          // o  <-o    // dx < 0
          interpolationWeight = 1.0 + inputs.weightsXYZ->X();
15      }
      else {
          // weight pointing right, starting at left coxel
          // L      M
          // o->  o    // dx > 0
20      interpolationWeight = inputs.weightsXYZ->X();
      }

      ////////////////////////////////////////////
      // Linear interpolation
      // c = w(b-a)+a
25      //
      // w=0 -> c=a
      // w=1 -> c=b

      a = *inputs.coxelLeft;
30      b = *inputs.coxelMiddle;

      // if current pipeline is working on a starting ray
      // set out of volume samples to background color
      if (inputs.perPipelineControlFlags->startOfRay) {
          if (inputs.weightsXYZ->X() < 0) a = cube4->backgroundCoxel;
35      else b = cube4->backgroundCoxel;
      }

      results.coxel->r = interpolationWeight * (b.r - a.r) + a.r;
      results.coxel->g = interpolationWeight * (b.g - a.g) + a.g;
40      results.coxel->b = interpolationWeight * (b.b - a.b) + a.b;
      results.coxel->a = interpolationWeight * (b.a - a.a) + a.a;
      }
  } // RunForOneClockCycle

45  ////////////////////////////////////////////
  // internal utility functions

  // end of ComposLinXPipeline.C
  :::::::::::::::
50

55

```

23

```

cube4/ComposLinXPipeline.h
:::::::::::::
// ComposLinXPipeline.h
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#ifndef _ComposLinXPipeline_h_           // prevent multiple includes
#define _ComposLinXPipeline_h_

#include "Misc.h"
#include "Object.h"
#include "FiFo.h"
#include "Coxel.h"
#include "ModInt.h"
#include "Control.h"
#include "FixPointNumber.h"
#include "Vector3D.h"

typedef Vector3D<FixPointNumber> FixPointVector3D;

class ComposLinXStage;
class Cube4;

class ComposLinXPipelineInputs {
public: // pointers
    Coxel *coxelLeft;
    Coxel *coxelMiddle;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags      *perChipControlFlags;
    PerPipelineControlFlags  *perPipelineControlFlags;
};

class ComposLinXPipelineResults {
public: // pointers
    Coxel *coxel;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags      *perChipControlFlags;
    PerPipelineControlFlags  *perPipelineControlFlags;
};

class ComposLinXPipeline : virtual public Object {
public:

    static void      Demo ();

    // constructors & destructors
    ComposLinXPipeline ();
    ~ComposLinXPipeline ();

```

24

```

// show/set data & data properties
// - class Object requirements
5   virtual ostream & Ostream (ostream & ) const;

// - local show/set functions
static void GlobalSetup (const int setNumOfChips,
10   const int setNumOfPipelinesPerChip,
        const int setBlockSize);

virtual void LocalSetup(const int setChipIndex,
        const int setPipelineIndex,
15   ComposLinXStage & composLinXStage);
virtual void PerFrameSetup();
// local computation functions
virtual void RunForOneClockCycle();

20   public:
        ComposLinXPipelineInputs inputs;
        ComposLinXPipelineResults results;

protected:
25   FiFo<Coxel>                partialBeamCoxelFiFo;
        FiFo<FixPointVector3D> partialBeamWeightsFiFo;
        FiFo<PerPipelineControlFlags> partialBeamPerPipelineControlFlagsFiFo;
        FiFo<PerChipControlFlags>    partialBeamPerChipControlFlagsFiFo;

        FiFo<Coxel>                communicationDelayCoxelFiFo;
30   FiFo<FixPointVector3D>      communicationDelayWeightsFiFo;
        FiFo<PerPipelineControlFlags> communicationDelayPerPipelineControlFlagsFiFo;
        FiFo<PerChipControlFlags>    communicationDelayPerChipControlFlagsFiFo;

        static int    numOfChips, numOfPipelinesPerChip, blockSize;
35   static Cube4 *cube4;
        int    chipIndex;
                ModInt    pipelineIndex;
                Coxel      a,b;

        friend class ComposLinXStage;
40   friend class Cube4;
};

#include "ComposLinXStage.h"
#include "Cube4.h"

45   #endif // _ComposLinXPipeline_h_
        ::::::::::::::
        cube4/ComposLinXStage.C
        ::::::::::::::
        // ComposLinXStage.C
50   // (c) Ingmar Bitter '97

```

55

```

5 // Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include "ComposLinXStage.h"

void ComposLinXStage::Demo()
{
10     ComposLinXStage composLinX;
    cout << endl << "Demo of class " << typeid(composLinX).name();
    cout << endl << "size : " << sizeof(ComposLinXStage) << " Bytes";
    cout << endl << "public member functions:";
    cout << endl << "ComposLinXStage composLinX; = " << composLinX;
    cout << endl << "End of demo of class " << typeid(composLinX).name() <<
15 endl;
} // Demo

////////////////////////////////////
// constructors & destructors

20 // static first init
int ComposLinXStage::numOfChips      = 0;
int ComposLinXStage::numOfPipelinesPerChip = 0;
Cube4 *ComposLinXStage::cube4 = 0;

25 ComposLinXStage::ComposLinXStage()
{
    composLinXPipeline = new ComposLinXPipeline [numOfPipelinesPerChip];

    computation.coxel
30     = new Coxel [numOfPipelinesPerChip+1];
    computation.weightsXYZ
        = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];
    computation.perPipelineControlFlags
        = new PerPipelineControlFlags [numOfPipelinesPerChip+1]; // +1 just
for debugging

35     results.coxel
        = new Coxel [numOfPipelinesPerChip];
    results.weightsXYZ
        = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];
    results.perPipelineControlFlags
40     = new PerPipelineControlFlags [numOfPipelinesPerChip];
} // defaultconstructor

ComposLinXStage::~ComposLinXStage()
{
45     if (composLinXPipeline) { delete composLinXPipeline; composLinXPipeline=0;
    }

    if (computation.coxel) {
50
55

```

```

26
        delete computation.coxel;
        computation.coxel=0;
5      }
      if (computation.weightsXYZ) {
        delete computation.weightsXYZ;
        computation.weightsXYZ=0;
      }
      if (computation.perPipelineControlFlags) {
10      delete computation.perPipelineControlFlags;
        computation.perPipelineControlFlags=0;
      }

      if (results.coxel) { delete results.coxel; results.coxel=0; }
      if (results.weightsXYZ) { delete results.weightsXYZ; results.weightsXYZ=0;
15  }
      if (results.perPipelineControlFlags) {
        delete results.perPipelineControlFlags;
        results.perPipelineControlFlags=0;
      }
20  } // destructor

////////////////////////////////////
// show/set data & data properties

25
ostream & ComposLinXStage::Ostream(ostream & os) const
{
  // append ComposLinXStage info to os
  os << typeid(*this).name() << "@" << (void *) this;
  os <<endl<< "  numOfChips          = " << numOfChips;
30  os <<endl<< "  numOfPipelinesPerChip = " << numOfPipelinesPerChip;
  os <<endl<< "  chipIndex          = " << chipIndex;

  // return complete os
  return os;
35  } // Ostream

////////////////////////////////////
// show/set data & data properties
40  //
  // - local show/set functions

void ComposLinXStage::GlobalSetup(const int setNumOfChips,
45      const int setNumOfPipelinesPerChip,
      Cube4 *setCube4)
{
  numOfChips          = setNumOfChips;
50
55

```

```

27
numOfPipelinesPerChip =      setNumOfPipelinesPerChip;
cube4      = setCube4;
5   ComposLinXPipeline::GlobalSetup(numOfChips,
                                   numOfPipelinesPerChip,
                                   cube4->blockSize);
10  } // GlobalSetup

void ComposLinXStage::LocalSetup(const int setChipIndex)
{
    chipIndex(setChipIndex,numOfChips);
15    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        composLinXPipeline[p].LocalSetup(chipIndex,p,*this);
    }
} // LocalSetup

20
void ComposLinXStage::PerFrameSetup()
{
    // reset pipeline registers
    int p;
25    readBufferCoxel = 0;
    communicationCoxel = 0;
    for (p=0; p<numOfPipelinesPerChip; ++p) {
        computation.coxel[p] = 0;
        computation.weightsXYZ[p](0,0,0);
        computation.perPipelineControlFlags[p].Reset();
30    }
    computation.coxel[numOfPipelinesPerChip] = 0;

    for (p=0; p<numOfPipelinesPerChip; ++p) {
        results.coxel[p] = cube4->backgroundCoxel;
35        results.weightsXYZ[p](0,0,0);
        results.perPipelineControlFlags[p].Reset();
    }
    results.perChipControlFlags.Reset();

    for (p=0; p<numOfPipelinesPerChip; ++p) {
40        composLinXPipeline[p].PerFrameSetup();
    }
} // PerFrameSetup

45  //////////////////////////////////////
// local computation functions

void ComposLinXStage::CommunicateForOneClockCycle()
{
50    //////////////////////////////////////
    // fill communication register

55

```

```

28
// only sent data at beginning of a block
if (inputs.perChipControlFlags->xBlockEnd) {
5
    // write readbuffer to communication register
    cube4->composLinX[chipIndex+1].communicationCoxel =
        cube4->composLinX[chipIndex+1].readBufferCoxel;
    cube4->composLinX[chipIndex+1].communicationPerPipelineControlFlags =
        cube4->composLinX[chipIndex+1].readBufferPerPipelineControlFlags;
10
    // leftmost chip sends data as early as possible
    if (inputs.perChipControlFlags->rightmostChip) {
        cube4->composLinX[chipIndex+1].readBufferCoxel =
            inputs.coxel[0];
15
        cube4->composLinX[chipIndex+1].readBufferPerPipelineControlFlags =
            inputs.perPipelineControlFlags[0];
    }
    // remaining chips send (blockSize/numOfPipelinesPerChip) later
    else {
20
        cube4->composLinX[chipIndex+1].readBufferCoxel =
            composLinXPipeline[0].partialBeamCoxelFiFo.Peek(0);
        cube4->composLinX[chipIndex+1].readBufferPerPipelineControlFlags =
            composLinXPipeline[0].partialBeamPerPipelineControlFlagsFiFo.Peek(0);
    }
}

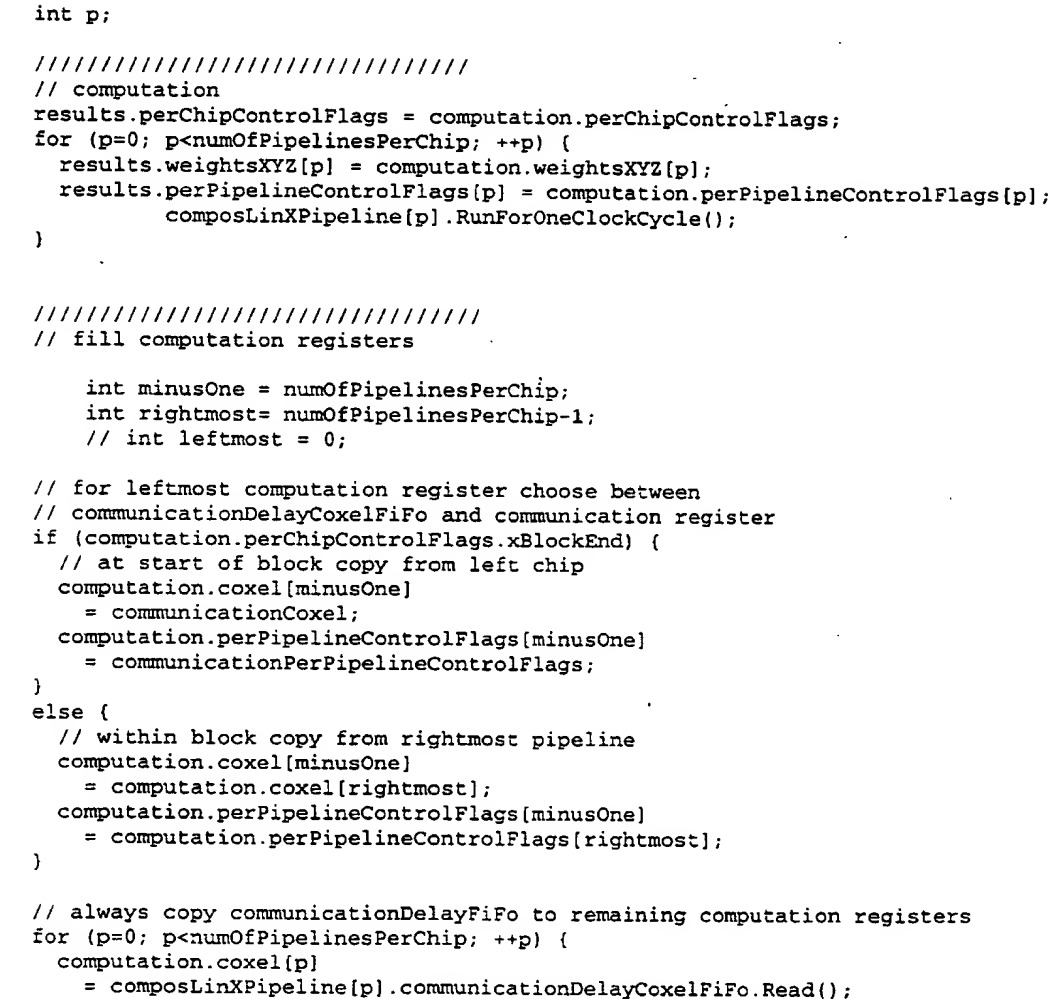
25 } // CommunicateForOneClockCycle

```

```

void ComposLinXStage::RunForOneClockCycle()
{
30
    /*
        +---+---+---+---+
        | 8 | 8 | 8 | 8 |
        +---+---+---+---+
        |
        +---+
        +--> | ? | ---> | 5 |
        +---+
        +---+
        | 3 |
        +---+
        |
        +---+---+---+---+
        | 7 | 7 | 7 | 7 |
        +---+---+---+---+
        | 6 | 6 | 6 | 6 |
        +---+---+---+---+
        |
        +---+---+---+---+
        | 5 | 5 | 5 | 5 |
        +---+---+---+---+
        | 4 | 4 | 4 | 4 |
        +---+---+---+---+
        |
        +---+---+---+---+
        | 7 | 7 | 7 | 7 |
        +---+---+---+---+
        | 6 | 6 | 6 | 6 |
        +---+---+---+---+
        |
        +---+---+---+---+
        | 5 | 5 | 5 | 5 |
        +---+---+---+---+
        | 4 | 4 | 4 | 4 |
        +---+---+---+---+
        |
        +---+
    */
    inputs
    read
    buffer
    communication
    register
    partial
    beam
    FiFo
    communication
    delay
    FiFo
50
55

```



30

```

    computation.weightsXYZ[p]
    = composLinXPipeline[p].communicationDelayWeightsFiFo.Read();
5    computation.perPipelineControlFlags[p]
    =
composLinXPipeline[p].communicationDelayPerPipelineControlFlagsFiFo.Read();
    }
    computation.perChipControlFlags
    = composLinXPipeline[0].communicationDelayPerChipControlFlagsFiFo.Read();
10
    //////////////////////////////////////
    // Write to communication delay FiFo
    for (p=0; p<numOfPipelinesPerChip; ++p) {
        composLinXPipeline[p].communicationDelayCoxelFiFo.Write
15        (composLinXPipeline[p].partialBeamCoxelFiFo.Read());
        composLinXPipeline[p].communicationDelayWeightsFiFo.Write
        (composLinXPipeline[p].partialBeamWeightsFiFo.Read());
        composLinXPipeline[p].communicationDelayPerPipelineControlFlagsFiFo.Write
        (composLinXPipeline[p].partialBeamPerPipelineControlFlagsFiFo.Read());
    }
20    composLinXPipeline[0].communicationDelayPerChipControlFlagsFiFo.Write
    (composLinXPipeline[0].partialBeamPerChipControlFlagsFiFo.Read());

    //////////////////////////////////////
    // Write to partial beam FiFo
25    for (p=0; p<numOfPipelinesPerChip; ++p) {
        composLinXPipeline[p].partialBeamCoxelFiFo.Write
        (inputs.coxel[p]);
        composLinXPipeline[p].partialBeamWeightsFiFo.Write
        (inputs.weightsXYZ[p]);
        composLinXPipeline[p].partialBeamPerPipelineControlFlagsFiFo.Write
30        (inputs.perPipelineControlFlags[p]);
    }
    composLinXPipeline[0].partialBeamPerChipControlFlagsFiFo.Write
    (*inputs.perChipControlFlags);

35    } // RunForOneClockCycle

    // end of ComposLinXStage.C
    :::::::::::::::
cube4/ComposLinXStage.h
    :::::::::::::::
40    // ComposLinXStage.h
    // (c) Ingmar Bitter '97

    // Copyright, Mitsubishi Electric Information Technology Center
    // America, Inc., 1997, All rights reserved.

45    #ifndef _ComposLinXStage_h_    // prevent multiple includes
    #define _ComposLinXStage_h_

    #include "Misc.h"
    #include "Object.h"
50    #include "Coxel.h"

```

55

```

#include "Control.h"
#include "ComposLinXPipeline.h"
5  #include "FixPointNumber.h"
#include "Cube4.h"

class Cube4;

10 class ComposLinXStageInputs {
public: // pointers
    Coxel *coxel;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags      *perChipControlFlags;
15   PerPipelineControlFlags *perPipelineControlFlags;
};

class ComposLinXStageResults {
public: // arrays
20   Coxel *coxel;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags      perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

25

class ComposLinXStage : virtual public Object {
public:

30   static void      Demo ();

    // constructors & destructors
    ComposLinXStage ();
    ~ComposLinXStage ();

35   // show/set data & data properties
    // - class Object requirements
    virtual ostream & Ostream (ostream & ) const;

    // - local show/set functions
40   static void GlobalSetup (const int setNumOfChips,

        const int setNumOfPipelinesPerChip,

        Cube4 *setCube4);
45   virtual void LocalSetup (const int setChipIndex);
    virtual void PerFrameSetup ();
    // local computation functions
    virtual void CommunicateForOneClockCycle();
    virtual void RunForOneClockCycle();

50 public:
    ComposLinXPipeline *composLinXPipeline;
    ComposLinXStageInputs inputs;

55

```

```

ComposLinXStageResults computation;
ComposLinXStageResults results;

5
protected:
    static int    numOfChips, numOfPipelinesPerChip;
    static Cube4 *cube4;

    ModInt        chipIndex;
10    Coxel        readBufferCoxel;
    PerPipelineControlFlags readBufferPerPipelineControlFlags; // only for
debugging
    Coxel        communicationCoxel;
    PerPipelineControlFlags communicationPerPipelineControlFlags; // only for
15 debugging

    friend class ComposLinXPipeline;
    friend class Cube4;
};

20 #endif // _ComposLinXStage_h_
    ::::::::::::::
cube4/ComposLinYPipeline.C
    ::::::::::::::
// ComposLinYPipeline.C
25 // (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include "ComposLinYPipeline.h"

30
void ComposLinYPipeline::Demo()
{
    ComposLinYPipeline composLinY;
    cout << endl << "Demo of class " << typeid(composLinY).name();
35    cout << endl << "size : " << sizeof(ComposLinYPipeline) << " Bytes";
    cout << endl << "public member functions:";
    cout << endl << "ComposLinYPipeline composLinY; = " << composLinY;
    cout << endl << "End of demo of class " << typeid(composLinY).name() <<
endl;
} // Demo

40

////////////////////////////////////
// constructors & destructors

45 // static first init
int ComposLinYPipeline::numOfChips          = 0;
int ComposLinYPipeline::numOfPipelinesPerChip = 0;
int ComposLinYPipeline::blockSize           = 0;
Cube4 *ComposLinYPipeline::cube4            = 0;

50 ComposLinYPipeline::ComposLinYPipeline()

```

55

33

```

{
} // constructor
5

ComposLinYPipeline::~ComposLinYPipeline()
{
} // destructor
10

////////////////////////////////////
// show/set data & data properties

15
ostream & ComposLinYPipeline::Ostream(ostream & os) const
{
    // append ComposLinYPipeline info to os
    os << typeid(*this).name() << "@" << (void *) this;
    os <<endl<< "    numOfChips          = " << numOfChips;
20    os <<endl<< "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
    os <<endl<< "    chipIndex          = " << chipIndex;

    // return complete os
    return os;
25
} // Ostream

////////////////////////////////////
// show/set data & data properties
30
//
// - local show/set functions

void ComposLinYPipeline::GlobalSetup(const int setNumOfChips,
35
                                   const int setNumOfPipelinesPerChip,
                                   const int setBlockSize)
{
    numOfChips          = setNumOfChips;
40    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    blockSize          = setBlockSize;
} // GlobalSetup

45
void ComposLinYPipeline::LocalSetup(const int setChipIndex,
                                   const int setPipelineIndex,
                                   ComposLinYStage & composLinYStage)
{
50
    chipIndex = setChipIndex;
    pipelineIndex = setPipelineIndex;
55

```

```

5      inputs.coxel = &(composLinYStage.inputs.coxel[pipelineIndex]);
      inputs.weightsXYZ = &(composLinYStage.inputs.weightsXYZ[pipelineIndex]);
      inputs.perChipControlFlags
          = composLinYStage.inputs.perChipControlFlags;
      inputs.perPipelineControlFlags
          = &(composLinYStage.inputs.perPipelineControlFlags[pipelineIndex]);

10     results.coxel = &(composLinYStage.results.coxel[pipelineIndex]);
      results.weightsXYZ = &(composLinYStage.results.weightsXYZ[pipelineIndex]);
      results.perPipelineControlFlags
          = &(composLinYStage.results.perPipelineControlFlags[pipelineIndex]);
      results.perChipControlFlags
          = &(composLinYStage.results.perChipControlFlags);

15     cube4 = composLinYStage.cube4;
    } // LocalSetup

20    void ComposLinYPipeline::PerFrameSetup()
    {
        // resize fifo's according to dataset size
        // step delay for a y-step within a block
        beamDelay = (cube4->datasetSizeXYZ.X()
25        (numOfChips*numOfPipelinesPerChip);

        // step delay for a y-step between blocks
        blockBeamDelay = beamDelay * blockSize;

        beamCoxelFiFo.SetSize(beamDelay);
30     blockBeamCoxelFiFo.SetSize(blockBeamDelay);

        beamCoxelFiFo.Preset(*(inputs.coxel));
        blockBeamCoxelFiFo.Preset(*(inputs.coxel));

        readBigFiFoCounter = readSmallFiFoCounter =
35     writeBigFiFoCounter = writeSmallFiFoCounter = -1;
    } // PerFrameSetup

    ////////////////////////////////////////
40    // local computation functions

    void ComposLinYPipeline::RunForOneClockCycle()
    {
        // reset counters
        if (inputs.perChipControlFlags->volumeStart ||
45         ((readBigFiFoCounter == 0) &&
          (readSmallFiFoCounter == 0) &&
          (writeBigFiFoCounter == 0) &&
          (writeSmallFiFoCounter == 0))) {
50
55

```

```

35
    readBigFiFoCounter =      beamDelay;
    readSmallFiFoCounter = (blockSize-1) * readBigFiFoCounter;
5
    writeBigFiFoCounter = readBigFiFoCounter;
    writeSmallFiFoCounter = readSmallFiFoCounter;
}

//////////
10 // first read from FiFos into results register

    // at start of block read from big FiFo
    if (readBigFiFoCounter > 0) {
        blockBeamCoxelFiFo.Read(fifoCoxel);
        --readBigFiFoCounter;
15        // if (chipIndex == 0 && pipelineIndex == 0)
        cout<<"R"<<*(results.coxel)<<volumeSliceGradientFiFo<<endl;
    }
    // in middle and at end of block read from small FiFo
    else if (readSmallFiFoCounter > 0) {
20        beamCoxelFiFo.Read(fifoCoxel);
        --readSmallFiFoCounter;
        // if (chipIndex == 0 && pipelineIndex == 0)    cout<<"r";
    }

    // control allways goes the same way as data with weight 0 (step middle)
25 // thus control comes from the input registers
    *results.weightsXYZ = *inputs.weightsXYZ;
    *results.perPipelineControlFlags = *inputs.perPipelineControlFlags;
    *results.perChipControlFlags = *inputs.perChipControlFlags;

30
    //////////
    // buffer writing

    //////////
    // now write to FiFos from inputs register
35

    // at start and in middle of block write to small FiFo
    if (writeSmallFiFoCounter > 0) {
        beamCoxelFiFo.Write(*(inputs.coxel));
        --writeSmallFiFoCounter;
40        // if (chipIndex == 0 && pipelineIndex == 0) cout<<"w";
    }

    // at end of block write to big FiFo of next chip
    else if (writeBigFiFoCounter > 0) {
        ModInt c(chipIndex+1, numOfChips);
        int p(pipelineIndex);
45        ComposLinYPipeline *next(&cube4-
>composLinY[c].composLinYPipeline[p]);
        next->blockBeamCoxelFiFo.Write(*inputs.coxel);
        --writeBigFiFoCounter;
        //if (chipIndex == 0 && pipelineIndex == 0) cout<<"W";
50

```

55

```

    }

5
    ///////////////////////////////////////////////////////////////////
    // select/interpolate results from FiFo or inputs
    // depending on yStep or y-weight

10    if (cube4->cubeMode == Cube4Classic) {

        if (inputs.perChipControlFlags->yStep == Down) {
            // data comes from the top
            // T      M      B (data src)
            // D      M      U (ray step)
15            // o---->o      o
            *(results.coxel) = fifoCoxel;
        }
        else if (inputs.perChipControlFlags->yStep == Up) {
            // data comes from the bottom
20            // T      M      B (data src)
            // D      M      U (ray step)
            // o      o<----o
            *(results.coxel) = *(inputs.coxel);
        }
25        if (inputs.perChipControlFlags->yStep == Middle) {
            // data goes straight
            // T      M      B (data src)
            // D      M      U (ray step)
            // o      o      o
30            *(results.coxel) = fifoCoxel;
        }
        else { ERROR( "Wrong ystep in ComposLinYPipeline!" ); }

            if (inputs.perPipelineControlFlags->startOfRay) {
35                *(results.coxel) = cube4->backgroundCoxel;
            }

        }

        else if (cube4->cubeMode == Cube4Light) {

40            FixPointNumber interpolationWeight;

            if (inputs.weightsXYZ->Y() <= 0) {
                // data comes from the top or goes straight
                // T      M      B (weight / data src)
45                // o---->o      o
                interpolationWeight = 1.0 + inputs.weightsXYZ->Y();
            }
            else { // inputs.weightsXYZ->Y() > 0
                // data comes from the bottom
50                // T      M      B (weight / data src)
                // o      o<----o
                interpolationWeight = inputs.weightsXYZ->Y();
            }
        }

55

```

```

5          // Linear interpolation
          // c = w(b-a)+a
          //
          // w=0 -> c=a
          // w=1 -> c=b

10         Coxel a(fifoCoxel);
         Coxel b(*inputs.coxel);

          // if current pipeline is working on a starting ray
          // set out of volume samples to background color
15         if (inputs.perPipelineControlFlags->startOfRay) {
             if (inputs.weightsXYZ->Y() < 0) a = cube4->backgroundCoxel;
             else b = cube4->backgroundCoxel;
         }

20         results.coxel->r = interpolationWeight * (b.r - a.r) + a.r;
         results.coxel->g = interpolationWeight * (b.g - a.g) + a.g;
         results.coxel->b = interpolationWeight * (b.b - a.b) + a.b;
         results.coxel->a = interpolationWeight * (b.a - a.a) + a.a;
     }
} // RunForOneClockCycle

25

// internal utility functions

30 // end of ComposLinYPipeline.C
:~::~:~::~:~::~:~::~:~::~:
cube4/ComposLinYPipeline.h
:~::~:~::~:~::~:~::~:~::~:
// ComposLinYPipeline.h
// (c) Ingmar Bitter '97

35 // Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#ifdef _ComposLinYPipeline_h_ // prevent multiple includes
40 #define _ComposLinYPipeline_h_

#include "Misc.h"
#include "Object.h"
#include "FiFo.h"
#include "Coxel.h"
45 #include "Control.h"
#include "FixPointNumber.h"

typedef Vector3D<FixPointNumber> FixPointVector3D;

50 class ComposLinYStage;

55

```



```

class Cube4;

5      class ComposLinYPipelineInputs {
      public: // pointers
          Coxel *coxel;
          Vector3D<FixPointNumber> *weightsXYZ;
          PerChipControlFlags      *perChipControlFlags;
10      PerPipelineControlFlags *perPipelineControlFlags;
      };

      class ComposLinYPipelineResults {
15      public: // pointers
          Coxel *coxel;
          Vector3D<FixPointNumber> *weightsXYZ;
          PerChipControlFlags      *perChipControlFlags;
          PerPipelineControlFlags *perPipelineControlFlags;
20      };

      class ComposLinYPipeline : virtual public Object {
      public:

25          static void      Demo ();

          // constructors & destructors
          ComposLinYPipeline ();
          ~ComposLinYPipeline ();
30

          // show/set data & data properties
          // - class Object requirements
          virtual ostream & Ostream (ostream & ) const;

          // - local show/set functions
35          static void GlobalSetup (const int setNumOfChips,

          const int setNumOfPipelinesPerChip,

          const int setBlockSize);
40

          virtual void LocalSetup(const int setChipIndex,

          const int setPipelineIndex,

          ComposLinYStage & composLinYStage);
45          virtual void PerFrameSetup();
          // local computation functions
          virtual void RunForOneClockCycle();

50      public:
          ComposLinYPipelineInputs inputs;
          ComposLinYPipelineResults results;

55

```

```

protected:
    FiFo<Coxel> beamCoxelFiFo;
    FiFo<Coxel> blockBeamCoxelFiFo;

    Coxel fifoCoxel;

    int beamDelay, blockBeamDelay;

    int readSmallFiFoCounter, readBigFiFoCounter;
    int writeSmallFiFoCounter, writeBigFiFoCounter;

    static int    numOfChips, numOfPipelinesPerChip, blockSize;
    static Cube4 *cube4;
    int         chipIndex, pipelineIndex;

    friend class ComposLinYStage;
    friend class Cube4;
};

#include "ComposLinYStage.h"
#include "Cube4.h"

#ifdef _ComposLinYPipeline_h_
::::::::::::::::::
cube4/ComposLinYStage.C
::::::::::::::::::
// ComposLinYStage.C
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include "ComposLinYStage.h"

void ComposLinYStage::Demo()
{
    ComposLinYStage composLinY;
    cout << endl << "Demo of class " << typeid(composLinY).name();
    cout << endl << "size : " << sizeof(ComposLinYStage) << " Bytes";
    cout << endl << "public member functions:";
    cout << endl << "ComposLinYStage composLinY; = " << composLinY;
    cout << endl << "End of demo of class " << typeid(composLinY).name()
<< endl;
} // Demo

////////////////////////////////////
// constructors & destructors

// static first init
int ComposLinYStage::numOfChips      = 0;
int ComposLinYStage::numOfPipelinesPerChip = 0;
Cube4 *ComposLinYStage::cube4 = 0;

```

40

```

ComposLinYStage::ComposLinYStage()
{
5   composLinYPipeline = new ComposLinYPipeline [numOfPipelinesPerChip];
   results.coxel = new Coxel [numOfPipelinesPerChip];
   results.weightsXYZ = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];
   results.perPipelineControlFlags = new PerPipelineControlFlags
10  [numOfPipelinesPerChip];
} // defaultconstructor

ComposLinYStage::~ComposLinYStage()
{
15   if (composLinYPipeline) { delete composLinYPipeline; composLinYPipeline=0;
   if (results.coxel) { delete results.coxel; results.coxel=0;
   if (results.weightsXYZ) { delete results.weightsXYZ; results.weightsXYZ=0;
20   if (results.perPipelineControlFlags) {
       delete results.perPipelineControlFlags;
       results.perPipelineControlFlags=0;
   }
} // destructor

25  //////////////////////////////////////
// show/set data & data properties

ostream & ComposLinYStage::Ostream(ostream & os) const
30  {
    // append ComposLinYStage info to os
    os << typeid(*this).name() << "@" << (void *) this;
    os <<endl<< "    numOfChips          = " << numOfChips;
    os <<endl<< "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
    os <<endl<< "    chipIndex            = " << chipIndex;
35   // return complete os
    return os;
} // Ostream

40  //////////////////////////////////////
// show/set data & data properties
//
// - local show/set functions

45  void ComposLinYStage::GlobalSetup(const int setNumOfChips,
                                     const int setNumOfPipelinesPerChip,
50
55

```

```

const int setBlockSize,
5      Cube4 *setCube4)
{
    numOfChips      = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    cube4           = setCube4;
10    ComposLinYPipeline::GlobalSetup(numOfChips, numOfPipelinesPerChip,
                                     setBlockSize);
} // GlobalSetup

15 void ComposLinYStage::LocalSetup(const int setChipIndex)
{
    chipIndex = setChipIndex;
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        composLinYPipeline[p].LocalSetup(chipIndex,p,*this);
20    }
} // LocalSetup

void ComposLinYStage::PerFrameSetup()
{
25    int p;
    // reset pipeline registers
    for (p=0; p<numOfPipelinesPerChip; ++p) {
        results.coxel[p] = cube4->backgroundCoxel;
        results.weightsXYZ[p](0,0,0);
        results.perPipelineControlFlags[p].Reset();
30    }
    results.perChipControlFlags.Reset();

    for (p=0; p<numOfPipelinesPerChip; ++p) {
        composLinYPipeline[p].PerFrameSetup();
35    }

    // print debug info
    //static bool first(true); if (first) { cout<<this<<endl; first=false; }
} // PerFrameSetup

40
////////////////////////////////////
// local computation functions

void ComposLinYStage::RunForOneClockCycle()
45 {
    // communication

    // computation
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        composLinYPipeline[p].RunForOneClockCycle();
50    }
}

```

55

```

    }
    } // RunForOneClockCycle

5

////////////////////////////////////
// internal utility functions

10
// end of ComposLinYStage.C
:::::::::::::
cube4/ComposLinYStage.h
:::::::::::::
// ComposLinYStage.h
15 // (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

20 #ifndef _ComposLinYStage_h_ // prevent multiple includes
#define _ComposLinYStage_h_

#include "Misc.h"
#include "Object.h"
25 #include "Vector3D.h"
#include "Coxel.h"
#include "Control.h"
#include "ComposLinYPipeline.h"
#include "FixPointNumber.h"
30 #include "Cube4.h"

class ComposLinYStageInputs {
public: // pointers
    Coxel *coxel;
    Vector3D<FixPointNumber> *weightsXYZ;
35     PerChipControlFlags     *perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

40 class ComposLinYStageResults {
public: // arrays
    Coxel *coxel;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags     perChipControlFlags;
45     PerPipelineControlFlags *perPipelineControlFlags;
};

class ComposLinYStage : virtual public Object {
public:

50     static void     Demo ();

```

```

5      // constructors & destructors
      ComposLinYStage ();
      ~ComposLinYStage ();

      // show/set data & data properties
      // - class Object requirements
      virtual ostream & Ostream (ostream & )    const;

10     // - local show/set functions
      static void GlobalSetup (const int setNumOfChips,

      const int setNumOfPipelinesPerChip,

15     const int setBlockSize,

      Cube4 *setCube4);
      virtual void LocalSetup (const int setChipIndex);
      virtual void PerFrameSetup ();
20     // local computation functions
      virtual void RunForOneClockCycle();

      public:
      ComposLinYPipeline *composLinYPipeline;
25     ComposLinYStageInputs inputs;
      ComposLinYStageResults results;

      protected:
      static int    numOfChips, numOfPipelinesPerChip;
30     static Cube4 *cube4;
      int          chipIndex; // only for debugging purpose

      friend class ComposLinYPipeline;
};

35 #endif // _ComposLinYStage_h_
      ::::::::::::::
      cube4/ComposPipeline.C
      ::::::::::::::
      // ComposPipeline.C
40     // (c) Ingmar Bitter '97

      // Copyright, Mitsubishi Electric Information Technology Center
      // America, Inc., 1997, All rights reserved.

45     // Premultiplied Colors (C implies A*C)
      //
      // Back-to-Front
      // Cacc = (1-Anew)Cacc + Cnew
      // Aacc = (1-Anew)Aacc + Anew
50     //
      // Front-to-Back
      // Cacc = (1-Aacc)Cnew + Cacc
      // Aacc = (1-Aacc)Anew + Aacc

```

```

#include "ComposPipeline.h"

5 void ComposPipeline::Demo()
{
    ComposPipeline compos;
    cout << endl << "Demo of class " << typeid(compos).name();
    cout << endl << "size : " << sizeof(ComposPipeline) << " Bytes";
10    cout << endl << "public member functions:";
    cout << endl << "ComposPipeline compos; = " << compos;
    cout << endl << "End of demo of class " << typeid(compos).name() << endl;
} // Demo

15 ///////////////////////////////////////////////////////////////////
// constructors & destructors

// static first init
int ComposPipeline::numOfChips          = 0;
20 int ComposPipeline::numOfPipelinesPerChip = 0;
Cube4 *ComposPipeline::cube4           = 0;

ComposPipeline::ComposPipeline()
{
} // constructor

25

ComposPipeline::~ComposPipeline()
{
} // destructor

30

/////////////////////////////////////////////////////////////////
// show/set data & data properties

35 ostream & ComposPipeline::Ostream(ostream & os) const
{
    // append ComposPipeline info to os
    os << typeid(*this).name() << "@" << (void *) this;
    os << endl << "    numOfChips          = " << numOfChips;
    os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
40    os << endl << "    chipIndex          = " << chipIndex;
    os << endl << "    results.coxel      = " << results.coxel;

    // return complete os
    return os;

45 } // Ostream

/////////////////////////////////////////////////////////////////
// show/set data & data properties

50

55

```

45

```

//
// - local show/set functions
5

void ComposPipeline::GlobalSetup(const int setNumOfChips,
                                const int setNumOfPipelinesPerChip)
{
10     numOfChips      = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
} // GlobalSetup

void ComposPipeline::LocalSetup(const int setChipIndex,
15     const int setPipelineIndex,
                                ComposStage & composStage)
{
20     chipIndex = setChipIndex;
    pipelineIndex = setPipelineIndex;

    inputs.shadel = &(composStage.inputs.shadel[pipelineIndex]);
    inputs.coxel = &(composStage.inputs.coxel[pipelineIndex]);
    inputs.weightsXYZ = &(composStage.inputs.weightsXYZ[pipelineIndex]);
25     inputs.perChipControlFlags
        = composStage.inputs.perChipControlFlags;
    inputs.perPipelineControlFlags
        = &(composStage.inputs.perPipelineControlFlags[pipelineIndex]);

    results.coxel = &(composStage.tempResults.coxel[pipelineIndex]);
30     results.perPipelineControlFlags
        = &(composStage.tempResults.perPipelineControlFlags[pipelineIndex]);
    results.perChipControlFlags
        = &(composStage.tempResults.perChipControlFlags);

    cube4 = composStage.cube4;
35 } // LocalSetup

void ComposPipeline::PerFrameSetup()
{
40     // reset pipeline registers already done in ComposStage
} // PerFrameSetup

////////////////////////////////////
// local computation functions
45

void ComposPipeline::RunForOneClockCycle()
{
    if (cube4->compositingStyle == BackToFront) {
50

55

```



```

                                46
                                results.coxel->r = (1.0-      inputs.shadel->a)*inputs.coxel->r +
inputs.shadel->r;
5      results.coxel->g = (1.0-inputs.shadel->a)*inputs.coxel->g +
inputs.shadel->g;
      results.coxel->b = (1.0-inputs.shadel->a)*inputs.coxel->b +
inputs.shadel->b;
      results.coxel->a = (1.0-inputs.shadel->a)*inputs.coxel->a +
10     inputs.shadel->a;
    }

    if (cube4->compositingStyle == FrontToBack) {
        results.coxel->r = (1.0-inputs.coxel->a)*inputs.shadel->r +
inputs.coxel->r;
15     results.coxel->g = (1.0-inputs.coxel->a)*inputs.shadel->g +
inputs.coxel->g;
        results.coxel->b = (1.0-inputs.coxel->a)*inputs.shadel->b +
inputs.coxel->b;
        results.coxel->a = (1.0-inputs.coxel->a)*inputs.shadel->a +
20     inputs.coxel->a;
    }

    // if debug: hand inputs through without change
    results.coxel->r = inputs.shadel->r;
    results.coxel->g = inputs.shadel->g;
25     results.coxel->b = inputs.shadel->b;
    results.coxel->a = inputs.shadel->a;
} // RunForOneClockCycle

//////////////////////////////////////
30 // internal utility functions

// end of ComposPipeline.C
::::::::::::
35 cube4/ComposPipeline.h
::::::::::::
// ComposPipeline.h
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
40 // America, Inc., 1997, All rights reserved.

// Premultiplied Colors (C implies A*C)
//
// Back-to-Front
45 // Cacc = (1-Anew)Cacc + Cnew
// Aacc = (1-Anew)Aacc + Anew
//
// Front-to-Back
// Cacc = (1-Aacc)Cnew + Cacc
50 // Aacc = (1-Aacc)Anew + Aacc

```

55

```

5      #ifndef _ComposPipeline_h_          //          47      prevent multiple includes
      #define _ComposPipeline_h_

      #include "Misc.h"
      #include "Object.h"
      #include "Shadel.h"
      #include "Coxel.h"
10     #include "Control.h"

      class ComposStage;
      class Cube4;

15     class ComposPipelineInputs {
      public: // pointers
          Shadel *shadel;
          Coxel *coxel;
          Vector3D<FixPointNumber> *weightsXYZ;
          PerChipControlFlags      *perChipControlFlags;
20     PerPipelineControlFlags *perPipelineControlFlags;
      };

      class ComposPipelineResults {
25     public: // pointers
          Coxel *coxel;
          PerChipControlFlags      *perChipControlFlags;
          PerPipelineControlFlags *perPipelineControlFlags;
      };

30     class ComposPipeline : virtual public Object {
      public:

          static void      Demo ();

35          // constructors & destructors
          ComposPipeline ();
          ~ComposPipeline ();

40          // show/set data & data properties
          // - class Object requirements
          virtual ostream & Ostream (ostream & ) const;

          // - local show/set functions
          static void GlobalSetup (const int setNumOfChips,
45          const int setNumOfPipelinesPerChip);

          virtual void LocalSetup(const int setChipIndex,
50          const int setPipelineIndex,
          ComposStage & composStage);

```

55

48

```

    virtual void PerFrameSetup();
    // local computation functions
5    virtual void RunForOneClockCycle();

public:
    ComposPipelineInputs inputs;
    ComposPipelineResults results;

10 protected:
    static int    numOfChips, numOfPipelinesPerChip;
    static Cube4 *cube4;
    int          chipIndex, pipelineIndex;    // only for debugging purpose
};

15 #include "ComposStage.h"
#include "Cube4.h"

#ifdef    // _ComposPipeline_h_
:::
20 cube4/ComposSelXPipeline.C
:::
// ComposSelXPipeline.C
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
25 // America, Inc., 1997, All rights reserved.

#include "ComposSelXPipeline.h"

void ComposSelXPipeline::Demo()
{
30    ComposSelXPipeline composSelX;
    cout << endl << "Demo of class " << typeid(composSelX).name();
    cout << endl << "size : " << sizeof(ComposSelXPipeline) << " Bytes";
    cout << endl << "public member functions:";
    cout << endl << "ComposSelXPipeline composSelX; = " << composSelX;
35    cout << endl << "End of demo of class " << typeid(composSelX).name() << endl;
} // Demo

////////////////////////////////////
// constructors & destructors

40 // static first init
int ComposSelXPipeline::numOfChips          = 0;
int ComposSelXPipeline::numOfPipelinesPerChip = 0;
int ComposSelXPipeline::blockSize           = 0;
45 Cube4 *ComposSelXPipeline::cube4          = 0;

ComposSelXPipeline::ComposSelXPipeline()
{
    // Number of clock cycles to process a partial beam inside a block
    int partialBeamDelay = blockSize / numOfPipelinesPerChip;
50
55

```

```

// Delay for communication: 16 bits, 4 bits / cycle, double frequency => 2
5 cycles
  int communicationDelay = 2;

  partialBeamCoxelFifo.SetSize(partialBeamDelay);
  partialBeamWeightsFifo.SetSize(partialBeamDelay);
  partialBeamPerPipelineControlFlagsFifo.SetSize(partialBeamDelay);
10 partialBeamPerChipControlFlagsFifo.SetSize(partialBeamDelay);

  communicationDelayCoxelFifo.SetSize(communicationDelay);
  communicationDelayWeightsFifo.SetSize(communicationDelay);
  communicationDelayPerPipelineControlFlagsFifo.SetSize(communicationDelay);
15 communicationDelayPerChipControlFlagsFifo.SetSize(communicationDelay);
} // constructor

ComposSelXPipeline::~ComposSelXPipeline()
{
20 } // destructor

////////////////////////////////////
// show/set data & data properties

25

ostream & ComposSelXPipeline::Ostream(ostream & os) const
{
  // append ComposSelXPipeline info to os
  os << typeid(*this).name() << "@" << (void *) this;
30 os << endl << "  numOfChips          = " << numOfChips;
  os << endl << "  numOfPipelinesPerChip = " << numOfPipelinesPerChip;
  os << endl << "  chipIndex            = " << chipIndex;

  // return complete os
35 return os;
} // Ostream

////////////////////////////////////
40 // show/set data & data properties
//
// - local show/set functions

void ComposSelXPipeline::GlobalSetup(const int setNumOfChips,
45 const int setNumOfPipelinesPerChip,
const int setBlockSize)
{
  numOfChips          = setNumOfChips;
  numOfPipelinesPerChip = setNumOfPipelinesPerChip;
50 blockSize          = setBlockSize;

```

50

```

    } // GlobalSetup

5   void ComposSelXPipeline::LocalSetup(const int setChipIndex,
                                       const int setPipelineIndex,
                                       ComposSelXStage & composSelXStage)
    {
        chipIndex = setChipIndex;
10     pipelineIndex = setPipelineIndex;

        inputs.coxelMiddle = &(composSelXStage.computation.coxel[pipelineIndex]);
        inputs.coxelRight = &(composSelXStage.computation.coxel[pipelineIndex+1]);
        inputs.weightsXYZ = &(composSelXStage.computation.weightsXYZ[pipelineIndex]);
        inputs.perChipControlFlags
15         = & composSelXStage.computation.perChipControlFlags;
        inputs.perPipelineControlFlags
            = &(composSelXStage.computation.perPipelineControlFlags[pipelineIndex]);

        results.coxel = &(composSelXStage.results.coxel[pipelineIndex]);
        results.weightsXYZ = &(composSelXStage.results.weightsXYZ[pipelineIndex]);
20     results.perPipelineControlFlags
            = &(composSelXStage.results.perPipelineControlFlags[pipelineIndex]);
        results.perChipControlFlags
            = &(composSelXStage.results.perChipControlFlags);

        cube4 = composSelXStage.cube4;
25     } // LocalSetup

    void ComposSelXPipeline::PerFrameSetup()
    {
        // reset pipeline registers already done in TriLinXStage
30     partialBeamCoxelFiFo.Preset(*(inputs.coxelMiddle));
        partialBeamWeightsFiFo.Preset(*(inputs.weightsXYZ));

        partialBeamPerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineControlFlags))
        ;
35     partialBeamPerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFlags));

        communicationDelayCoxelFiFo.Preset(*(inputs.coxelMiddle));
        communicationDelayWeightsFiFo.Preset(*(inputs.weightsXYZ));

        communicationDelayPerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineControl
40     Flags));

        communicationDelayPerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFlags));
    } // PerFrameSetup

45     ////////////////////////////////////////////
    // local computation functions

    void ComposSelXPipeline::RunForOneClockCycle()

```

50

55

51

```

(
  if (cube4->cubeMode == Cube4Classic) {
5
    if (inputs.perChipControlFlags->xStep == Right) {
      // data comes from the left (which happens in ComposLinX)
      // L      M      R (data src)
      // R      M      L (step)
      // o---->o      o
10
      *(results.coxel) = *(inputs.coxelMiddle);
    }
    else if (inputs.perChipControlFlags->xStep == Left) {
      // data comes from the right
      // L      M      R (data src)
      // R      M      L (step)
15
      // o      o<----o
      *(results.coxel) = *(inputs.coxelRight);
    }
    else if (inputs.perChipControlFlags->xStep == Middle) {
20
      // data goes straight
      // L      M      R (data src)
      // R      M      L (step)
      // o      o      o
      *(results.coxel) = *(inputs.coxelMiddle);
25
    }
    else { ERROR( "Wrong xstep in ComposSelXPipeline!" ); }
  }

  else if (cube4->cubeMode == Cube4Light) {
30
    // selecting either the left or right coxel,
    // depending on sign of x weight

    if (inputs.weightsXYZ->X() <= 0) {
      // data comes from the left or goes straight
35
      // L      M      R (weight / data src)
      // o---->o      o
      *(results.coxel) = *(inputs.coxelMiddle);
    }
    else { // inputs.weightsXYZ->X() > 0
40
      // data comes from the right
      // L      M      R (weight / data src)
      // o      o<----o
      *(results.coxel) = *(inputs.coxelRight);
    }
  }
45
} // RunForOneClockCycle

////////////////////////////////////
50
// internal utility functions

// end of ComposSelXPipeline.C

```

55

```

5  :::::::::::::::
   cube4/ComposSelXPipeline.h
   :::::::::::::::
   // ComposSelXPipeline.h
   // (c) Ingmar Bitter '97

   // Copyright, Mitsubishi Electric Information Technology Center
10  // America, Inc., 1997, All rights reserved.

   #ifndef _ComposSelXPipeline_h_      // prevent multiple includes
   #define _ComposSelXPipeline_h_

   #include "Misc.h"
15  #include "Object.h"
   #include "ModInt.h"
   #include "Coxel.h"
   #include "FiFo.h"
   #include "Control.h"
20  #include "FixPointNumber.h"
   #include "Vector3D.h"

   typedef Vector3D<FixPointNumber> FixPointVector3D;

25  class ComposSelXStage;
   class Cube4;

   class ComposSelXPipelineInputs {
   public: // pointers
30     Coxel *coxelMiddle;
     Coxel *coxelRight;
     Vector3D<FixPointNumber> *weightsXYZ;
     PerChipControlFlags      *perChipControlFlags;
     PerPipelineControlFlags *perPipelineControlFlags;
35  };

   class ComposSelXPipelineResults {
   public: // pointers
40     Coxel *coxel;
     Vector3D<FixPointNumber> *weightsXYZ;
     PerChipControlFlags      *perChipControlFlags;
     PerPipelineControlFlags *perPipelineControlFlags;
   };

45  class ComposSelXPipeline : virtual public Object {
   public:

       static void      Demo ();

50     // constructors & destructors
       ComposSelXPipeline ();
       ~ComposSelXPipeline ();

55

```

```

5      // show/set data & data properties
      // - class Object requirements
      virtual ostream & Ostream (ostream & ) const;

      // - local show/set functions
      static void GlobalSetup (const int setNumOfChips,
10          const int setNumOfPipelinesPerChip,
          const int setBlockSize);

      virtual void LocalSetup(const int setChipIndex,
          const int setPipelineIndex,
          ComposSelXStage & composSelXStage);
15      virtual void PerFrameSetup();
      // local computation functions
      virtual void RunForOneClockCycle();

public:
20      ComposSelXPipelineInputs inputs;
      ComposSelXPipelineResults results;

protected:
      FiFo<Coxel> partialBeamCoxelFiFo;
      FiFo<FixPointVector3D> partialBeamWeightsFiFo;
25      FiFo<PerPipelineControlFlags> partialBeamPerPipelineControlFlagsFiFo;
      FiFo<PerChipControlFlags> partialBeamPerChipControlFlagsFiFo;

      FiFo<Coxel> communicationDelayCoxelFiFo;
      FiFo<FixPointVector3D> communicationDelayWeightsFiFo;
      FiFo<PerPipelineControlFlags> communicationDelayPerPipelineControlFlagsFiFo;
30      FiFo<PerChipControlFlags> communicationDelayPerChipControlFlagsFiFo;

      static int numOfChips, numOfPipelinesPerChip, blockSize;
      static Cube4 *cube4;
      int chipIndex, pipelineIndex;

35      friend class ComposSelXStage;
      friend class Cube4;
};

#include "ComposSelXStage.h"
40      #include "Cube4.h"

#ifdef // _ComposSelXPipeline_h_
      ::::::::::::::
      cube4/ComposSelXStage.C
      ::::::::::::::
45      // ComposSelXStage.C
      // (c) Ingmar Bitter '97

      // Copyright, Mitsubishi Electric Information Technology Center
      // America, Inc., 1997, All rights reserved.

```

50

55


```

#include "ComposSelXStage.h"

5 void ComposSelXStage::Demo()
{
    ComposSelXStage composSelX;
    cout << endl <<"Demo of class " << typeid(composSelX).name();
    cout << endl <<"size : " << sizeof(ComposSelXStage) << " Bytes";
    cout << endl <<"public member functions:";
10    cout << endl <<"ComposSelXStage composSelX; = " << composSelX;
    cout << endl << "End of demo of class " << typeid(composSelX).name() << endl;
} // Demo

15 ///////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
// constructors & destructors

// static first init
int ComposSelXStage::numOfChips          = 0;
int ComposSelXStage::numOfPipelinesPerChip = 0;
20 Cube4 *ComposSelXStage::cube4 = 0;

ComposSelXStage::ComposSelXStage()
{
    composSelXPipeline = new ComposSelXPipeline [numOfPipelinesPerChip];

25    computation.coxel
        = new Coxel [numOfPipelinesPerChip+1];
    computation.weightsXYZ
        = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];
    computation.perPipelineControlFlags
        = new PerPipelineControlFlags [numOfPipelinesPerChip+1]; // +1 just
30 for debugging

    results.coxel
        = new Coxel [numOfPipelinesPerChip];
    results.weightsXYZ
        = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];
35    results.perPipelineControlFlags
        = new PerPipelineControlFlags [numOfPipelinesPerChip];
} // defaultconstructor

40 ComposSelXStage::~ComposSelXStage()
{
    if (composSelXPipeline) { delete composSelXPipeline; composSelXPipeline=0; }

    if (computation.coxel) {
        delete computation.coxel;
45    computation.coxel=0;
    }

    if (computation.weightsXYZ) {
        delete computation.weightsXYZ;
        computation.weightsXYZ=0;
50
55

```

55

```

    }
    if (computation.perPipelineControlFlags) {
5      delete computation.perPipelineControlFlags;
      computation.perPipelineControlFlags=0;
    }

    if (results.coxel) { delete results.coxel; results.coxel=0; }
    if (results.weightsXYZ) { delete results.weightsXYZ; results.weightsXYZ=0; }
10    if (results.perPipelineControlFlags) {
        delete results.perPipelineControlFlags;
        results.perPipelineControlFlags=0;
    }
} // destructor

15

////////////////////////////////////
// show/set data & data properties

20 ostream & ComposSelXStage::Ostream(ostream & os) const
{
    // append ComposSelXStage info to os
    os << typeid(*this).name() << "@" << (void *) this;
    os << endl << "    numOfChips          = " << numOfChips;
    os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
25    os << endl << "    chipIndex            = " << chipIndex;

    // return complete os
    return os;

30 } // Ostream

////////////////////////////////////
// show/set data & data properties
//
35 // - local show/set functions

void ComposSelXStage::GlobalSetup(const int setNumOfChips,
                                   const int setNumOfPipelinesPerChip,
                                   Cube4 *setCube4)
40 {
    numOfChips          = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    cube4               = setCube4;
    ComposSelXPipeline::GlobalSetup(numOfChips,
45                                   numOfPipelinesPerChip,
                                   cube4->blockSize);
} // GlobalSetup

50

55

```

```

void ComposSelXStage::LocalSetup(const int setChipIndex)
5 {
    chipIndex(setChipIndex,numOfChips);
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        composSelXPipeline[p].LocalSetup(chipIndex,p,*this);
    }
10 } // LocalSetup

void ComposSelXStage::PerFrameSetup()
{
    // reset pipeline registers
15 int p;
    readBufferCoxel = 0;
    communicationCoxel = 0;
    for (p=0; p<numOfPipelinesPerChip; ++p) {
        computation.coxel[p] = 0;
        computation.weightsXYZ[p](0,0,0);
20 computation.perPipelineControlFlags[p].Reset();
    }
    computation.coxel[numOfPipelinesPerChip] = 0;

    for (p=0; p<numOfPipelinesPerChip; ++p) {
25 results.coxel[p] = cube4->backgroundCoxel;
        results.weightsXYZ[p](0,0,0);
        results.perPipelineControlFlags[p].Reset();
    }
    results.perChipControlFlags.Reset();

30 for (p=0; p<numOfPipelinesPerChip; ++p) {
    composSelXPipeline[p].PerFrameSetup();
} // PerFrameSetup

35 ///////////////////////////////////////////////////////////////////
// local computation functions

void ComposSelXStage::CommunicateForOneClockCycle()
{
40 ///////////////////////////////////////////////////////////////////
    // fill communication register

    // *****
    // scrap following for loop when ComposBuffer is ok !!!!!!!!
    // *****
45 for (int p=0; p<numOfPipelinesPerChip; ++p) {
    inputs.coxel[p].r = inputs.perPipelineControlFlags[p].voxelPosXYZ.X();
    inputs.coxel[p].g = inputs.perPipelineControlFlags[p].voxelPosXYZ.Y();
    inputs.coxel[p].b = inputs.perPipelineControlFlags[p].voxelPosXYZ.Z();
50 inputs.coxel[p].a = inputs.perPipelineControlFlags[p].voxelPosXYZ.Z();
}

```

```

5 // only sent data at beginning of a block
  if (inputs.perChipControlFlags->xBlockStart) {

    // write readbuffer to communication register
    cube4->composSelX[chipIndex-1].communicationCoxel =
      cube4->composSelX[chipIndex-1].readBufferCoxel;
10    cube4->composSelX[chipIndex-1].communicationPerPipelineControlFlags =
      cube4->composSelX[chipIndex-1].readBufferPerPipelineControlFlags;

    // leftmost chip sends data as early as possible
    if (inputs.perChipControlFlags->leftmostChip) {
      cube4->composSelX[chipIndex-1].readBufferCoxel =
15      inputs.coxel[0];
      cube4->composSelX[chipIndex-1].readBufferPerPipelineControlFlags =
        inputs.perPipelineControlFlags[0];
    }
    // remaining chips send (blockSize/numOfPipelinesPerChip) later
20    else {
      cube4->composSelX[chipIndex-1].readBufferCoxel =
        composSelXPipeline[0].partialBeamCoxelFiFo.Peek(0);
      cube4->composSelX[chipIndex-1].readBufferPerPipelineControlFlags =
        composSelXPipeline[0].partialBeamPerPipelineControlFlagsFiFo.Peek(0);
25    }
  }

} // CommunicateForOneClockCycle

```

```

30 void ComposSelXStage::RunForOneClockCycle()
{
  /*
35   +---+ +---+ +---+ +---+
   | 8 | 8 | 8 | 8 |
   +---+ +---+ +---+ +---+

                                     +---+ +---+
                                     | 8 | 8 | 8 | 8 |
                                     +---+ +---+
                                     inputs

                                     +---+ +---+
                                     | 5 | <---| ? | <---+
                                     +---+ +---+
                                     | 3 |
                                     +---+
40                                     read
                                     buffer

                                     +---+ +---+
                                     | 5 |
                                     +---+
                                     | 3 |
                                     +---+
                                     communication
                                     register

                                     +---+ +---+ +---+ +---+
                                     | 7 | 7 | 7 | 7 |
                                     +---+ +---+ +---+ +---+
45                                     | 6 | 6 | 6 | 6 |
                                     +---+ +---+ +---+ +---+

                                     +---+ +---+ +---+ +---+
                                     | 7 | 7 | 7 | 7 |
                                     +---+ +---+ +---+ +---+
                                     | 6 | 6 | 6 | 6 |
                                     +---+ +---+ +---+ +---+
                                     partial
                                     beam
                                     FiFo

                                     +---+ +---+ +---+ +---+
                                     | 5 | 5 | 5 | 5 |
                                     +---+ +---+ +---+ +---+
50                                     | 4 | 4 | 4 | 4 |
                                     +---+ +---+ +---+ +---+
                                     communication
                                     delay
                                     FiFo

```



59

```

    =
    composSelXPipeline[p].communicationDelayWeightsFiFo.Read();
5      computation.perPipelineControlFlags[p]
    =
    composSelXPipeline[p].communicationDelayPerPipelineControlFlagsFiFo.Read();
  }
  computation.perChipControlFlags
10    = composSelXPipeline[0].communicationDelayPerChipControlFlagsFiFo.Read();

  //////////////////////////////////////
  // Write to communication delay FiFo
  for (p=0; p<numOfPipelinesPerChip; ++p) {
    composSelXPipeline[p].communicationDelayCoxelFiFo.Write
15    (composSelXPipeline[p].partialBeamCoxelFiFo.Read());
    composSelXPipeline[p].communicationDelayWeightsFiFo.Write
    (composSelXPipeline[p].partialBeamWeightsFiFo.Read());
    composSelXPipeline[p].communicationDelayPerPipelineControlFlagsFiFo.Write
    (composSelXPipeline[p].partialBeamPerPipelineControlFlagsFiFo.Read());
  }
20  composSelXPipeline[0].communicationDelayPerChipControlFlagsFiFo.Write
    (composSelXPipeline[0].partialBeamPerChipControlFlagsFiFo.Read());

  //////////////////////////////////////
  // Write to partial beam FiFo
25  for (p=0; p<numOfPipelinesPerChip; ++p) {
    composSelXPipeline[p].partialBeamCoxelFiFo.Write
    (inputs.coxel[p]);
    composSelXPipeline[p].partialBeamWeightsFiFo.Write
    (inputs.weightsXYZ[p]);
    composSelXPipeline[p].partialBeamPerPipelineControlFlagsFiFo.Write
30    (inputs.perPipelineControlFlags[p]);
  }
  composSelXPipeline[0].partialBeamPerChipControlFlagsFiFo.Write
    (*inputs.perChipControlFlags);

35  } // RunForOneClockCycle

  // end of ComposSelXStage.C
  :::::::::::::::
  cube4/ComposSelXStage.h
  :::::::::::::::
40  // ComposSelXStage.h
  // (c) Ingmar Bitter '97

  // Copyright, Mitsubishi Electric Information Technology Center
  // America, Inc., 1997, All rights reserved.

45  #ifndef _ComposSelXStage_h_ // prevent multiple includes
  #define _ComposSelXStage_h_

  #include "Misc.h"
  #include "Object.h"
50  #include "Coxel.h"

```

55

```

5      #include "Control.h"
      #include "ComposSelXPipeline.h"
      #include "FixPointNumber.h"

      class Cube4;

      class ComposSelXStageInputs {
10     public: // pointers
          Coxel *coxel;
          Vector3D<FixPointNumber> *weightsXYZ;
          PerChipControlFlags      *perChipControlFlags;
          PerPipelineControlFlags *perPipelineControlFlags;
15     };

      class ComposSelXStageResults {
      public: // arrays
20     Coxel *coxel;
          Vector3D<FixPointNumber> *weightsXYZ;
          PerChipControlFlags      perChipControlFlags;
          PerPipelineControlFlags *perPipelineControlFlags;
          };

25     class ComposSelXStage : virtual public Object {
      public:

          static void      Demo ();

30     // constructors & destructors
          ComposSelXStage ();
          ~ComposSelXStage ();

35     // show/set data & data properties
          // - class Object requirements
          virtual ostream & Ostream (ostream & )    const;

          // - local show/set functions
40     static void GlobalSetup (const int setNumOfChips,
                                const int setNumOfPipelinesPerChip,
                                Cube4 *setCube4);
          virtual void LocalSetup (const int setChipIndex);
          virtual void PerFrameSetup ();
45     // local computation functions
          virtual void CommunicateForOneClockCycle();
          virtual void RunForOneClockCycle();

      public:
50     ComposSelXPipeline *composSelXPipeline;
          ComposSelXStageInputs inputs;
          ComposSelXStageResults computation;
          ComposSelXStageResults results;

55

```

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```

protected:
    static int    numOfChips, numOfPipelinesPerChip;
    static Cube4 *cube4;

    ModInt        chipIndex;
    Coxel          readBufferCoxel;
    PerPipelineControlFlags readBufferPerPipelineControlFlags; // only for
debugging
    Coxel          communicationCoxel;
    PerPipelineControlFlags communicationPerPipelineControlFlags; // only for
debugging

    friend class ComposSelXPipeline;
    friend class Cube4;
};

#include "Cube4.h"

#endif // _ComposSelXStage_h_
:
:
cube4/ComposSelYPipeline.C
:
:
// ComposSelYPipeline.C
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include "ComposSelYPipeline.h"

void ComposSelYPipeline::Demo()
{
    ComposSelYPipeline composSelY;
    cout << endl << "Demo of class " << typeid(composSelY).name();
    cout << endl << "size : " << sizeof(ComposSelYPipeline) << " Bytes";
    cout << endl << "public member functions:";
    cout << endl << "ComposSelYPipeline composSelY; = " << composSelY;
    cout << endl << "End of demo of class " << typeid(composSelY).name() << endl;
} // Demo

////////////////////////////////////
// constructors & destructors

// static first init
int ComposSelYPipeline::numOfChips          = 0;
int ComposSelYPipeline::numOfPipelinesPerChip = 0;
int ComposSelYPipeline::blockSize           = 0;
Cube4 *ComposSelYPipeline::cube4            = 0;

ComposSelYPipeline::ComposSelYPipeline()
{
} // constructor

```



```

5  ComposSelyPipeline::~ComposSelyPipeline()
   {
   } // destructor

10  //////////////////////////////////////
   // show/set data & data properties

   ostream & ComposSelyPipeline::Ostream(ostream & os) const
   {
15     // append ComposSelyPipeline info to os
       os << typeid(*this).name() << "@" << (void *) this;
       os << endl << "    numOfChips          = " << numOfChips;
       os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
       os << endl << "    chipIndex          = " << chipIndex;

20     // return complete os
       return os;

   } // Ostream

25  //////////////////////////////////////
   // show/set data & data properties
   //
   // - local show/set functions

30

   void ComposSelyPipeline::GlobalSetup(const int setNumOfChips,
                                         const int setNumOfPipelinesPerChip,
                                         const int setBlockSize)
   {
35     numOfChips          = setNumOfChips;
       numOfPipelinesPerChip = setNumOfPipelinesPerChip;
       blockSize          = setBlockSize;
   } // GlobalSetup

40

   void ComposSelyPipeline::LocalSetup(const int setChipIndex,
                                        const int setPipelineIndex,
                                        ComposSelyStage & composSelyStage)
   {
45     chipIndex = setChipIndex;
       pipelineIndex = setPipelineIndex;

       inputs.coxel = &(composSelyStage.inputs.coxel[pipelineIndex]);
       inputs.weightsXYZ = &(composSelyStage.inputs.weightsXYZ[pipelineIndex]);
       inputs.perChipControlFlags
50         = composSelyStage.inputs.perChipControlFlags;
       inputs.perPipelineControlFlags

55

```

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```

    =
    &(composSelYStage.inputs.perPipelineControlFlags[pipelineIndex]);
5
    results.coxel = &(composSelYStage.results.coxel[pipelineIndex]);
    results.weightsXYZ = &(composSelYStage.results.weightsXYZ[pipelineIndex]);
    results.perPipelineControlFlags
        = &(composSelYStage.results.perPipelineControlFlags[pipelineIndex]);
    results.perChipControlFlags
10    = &(composSelYStage.results.perChipControlFlags);

    cube4 = composSelYStage.cube4;
} // LocalSetup

15
void ComposSelYPipeline::PerFrameSetup()
{
    // resize fifo's according to dataset size
    // step delay for a y-step within a block
    beamDelay = (cube4->datasetSizeXYZ.X()
20    ) /
    (numOfChips*numOfPipelinesPerChip);

    // step delay for a y-step between blocks
    blockBeamDelay = beamDelay * blockSize;

25
    beamCoxelFiFo.SetSize(beamDelay);
    beamWeightsFiFo.SetSize(beamDelay);
    beamPerPipelineControlFlagsFiFo.SetSize(beamDelay);
    beamPerChipControlFlagsFiFo.SetSize(beamDelay);

    blockBeamCoxelFiFo.SetSize(blockBeamDelay);
30    blockBeamWeightsFiFo.SetSize(blockBeamDelay);
    blockBeamPerPipelineControlFlagsFiFo.SetSize(blockBeamDelay);
    blockBeamPerChipControlFlagsFiFo.SetSize(blockBeamDelay);

    beamCoxelFiFo.Preset(*(inputs.coxel));
35    beamWeightsFiFo.Preset(*(inputs.weightsXYZ));
    beamPerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineControlFlags));
    beamPerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFlags));

    blockBeamCoxelFiFo.Preset(*(inputs.coxel));
    blockBeamWeightsFiFo.Preset(*(inputs.weightsXYZ));
40
    blockBeamPerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineControlFlags));
    blockBeamPerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFlags));

    readBigFiFoCounter = readSmallFiFoCounter =
45    writeBigFiFoCounter = writeSmallFiFoCounter = -1;
} // PerFrameSetup

////////////////////////////////////
// local computation functions
50

```

55

```

void ComposSelyPipeline::RunForOneClockCycle()
{
5   // reset counters
   if (inputs.perChipControlFlags->volumeStart ||
       ((readBigFiFoCounter == 0) &&
        (readSmallFiFoCounter == 0) &&
        (writeBigFiFoCounter == 0) &&
10      (writeSmallFiFoCounter == 0))) {

       readBigFiFoCounter = beamDelay;
       readSmallFiFoCounter = (blockSize-1) * readBigFiFoCounter;

       writeBigFiFoCounter = readBigFiFoCounter;
15      writeSmallFiFoCounter = readSmallFiFoCounter;
   }

   //////////////////////////////////////
   // first read from FiFos into results register

20   // at start of block read from big FiFo
   if (readBigFiFoCounter > 0) {
       blockBeamCoxelFiFo.Read(fifoCoxel);
       blockBeamWeightsFiFo.Read(*(results.weightsXYZ));

25      blockBeamPerPipelineControlFlagsFiFo.Read(*(results.perPipelineControlFlag
s));

       blockBeamPerChipControlFlagsFiFo.Read(*(results.perChipControlFlags));
       --readBigFiFoCounter;
       // if (chipIndex == 0 && pipelineIndex == 0)
30      cout<<"R"<<*(results.coxel)<<volumeSliceGradientFiFo<<endl;
   }
   // in middle and at end of block read from small FiFo
   else if (readSmallFiFoCounter > 0) {
       beamCoxelFiFo.Read(fifoCoxel);
       beamWeightsFiFo.Read(*(results.weightsXYZ));

35      beamPerPipelineControlFlagsFiFo.Read(*(results.perPipelineControlFlags));
       beamPerChipControlFlagsFiFo.Read(*(results.perChipControlFlags));
       --readSmallFiFoCounter;
       // if (chipIndex == 0 && pipelineIndex == 0)    cout<<"r";
40      }

   //////////////////////////////////////
   // buffer writing

45   //////////////////////////////////////
   // now write to FiFos from inputs register

   // at start and in middle of block write to small FiFo
   if (writeSmallFiFoCounter > 0) {
50
55

```

65

```

5      beamCoxelFifo.Write(*(inputs.coxel));
      beamWeightsFifo.Write(*(inputs.weightsXYZ) );

      beamPerPipelineControlFlagsFifo.Write(*(inputs.perPipelineControlFlags));
      beamPerChipControlFlagsFifo.Write(
10      *(inputs.perChipControlFlags));
      --writeSmallFifoCounter;
      // if (chipIndex == 0 && pipelineIndex == 0) cout<<"w";
    }

    // at end of block write to big Fifo of next chip
    else if (writeBigFifoCounter > 0) {
15      ModInt c(chipIndex+1, numOfChips);
      int p(pipelineIndex);
      ComposSelYPipeline *next(&cube4-
>composSelY[c].composSelYPipeline[p]);
      next->blockBeamCoxelFifo.Write(*(inputs.coxel));
      next->blockBeamWeightsFifo.Write(*(inputs.weightsXYZ) );
      next-
20 >blockBeamPipelineControlFlagsFifo.Write(*(inputs.perPipelineControlFlags));
      next-
>blockBeamPerChipControlFlagsFifo.Write(*(inputs.perChipControlFlags));
      --writeBigFifoCounter;
      //if (chipIndex == 0 && pipelineIndex == 0) cout<<"W";
25    }

    //////////////////////////////////////
    // select results from Fifo or inputs depending on yStep or y-weight

30    if (cube4->cubeMode == Cube4Classic) {

    if (inputs.perChipControlFlags->yStep == Down) {
      // data comes from the top
      // T      M      B (data src)
      // B      M      T (step)
35      // o---->o      o
      *(results.coxel) = fifoCoxel;
    }
    else if (inputs.perChipControlFlags->yStep == Up) {
      // data comes from the bottom
40      // T      M      B (data src)
      // B      M      T (step)
      // o      o<----o
      *(results.coxel) = *(inputs.coxel);
    }
    if (inputs.perChipControlFlags->yStep == Middle) {
45      // data goes straight
      // T      M      B (data src)
      // B      M      T (step)
      // o      o      o
      *(results.coxel) = fifoCoxel;
50
55

```

66

```

    }
    else { ERROR( "Wrong ystep in ComposSelYPipeline!" ); }
5      }

      else if (cube4->cubeMode == Cube4Light) {

          if (inputs.weightsXYZ->Y() <= 0) {
10         // data comes from the top or goes straight
          // T      M      B (weight / data src)
          // o---->o      o
          *(results.coxel) = fifoCoxel;
          }

          else { // inputs.weightsXYZ->Y() > 0
15         // data comes from the bottom
          // T      M      B (weight / data src)
          // o      o<----o
          *(results.coxel) = *(inputs.coxel);
          }
20      }
    } // RunForOneClockCycle

//////////////////////////////////////
25  // internal utility functions

// end of ComposSelYPipeline.C
::::::::::::::::::
cube4/ComposSelYPipeline.h
30  ::::::::::::::::::::
// ComposSelYPipeline.h
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
35  // America, Inc., 1997, All rights reserved.

#ifndef _ComposSelYPipeline_h_      // prevent multiple includes
#define _ComposSelYPipeline_h_

40  #include "Misc.h"
#include "Object.h"
#include "FiFo.h"
#include "Coxel.h"
#include "Control.h"
#include "FixPointNumber.h"
45

typedef Vector3D<FixPointNumber> FixPointVector3D;

class ComposSelYStage;
class Cube4;

50  class ComposSelYPipelineInputs {
public: // pointers

55

```

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```

    Coxel *coxel;
    Vector3D<FixPointNumber> *weightsXYZ;
5    PerChipControlFlags      *perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

10    class ComposSelyPipelineResults {
public: // pointers
    Coxel *coxel;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags      *perChipControlFlags;
15    PerPipelineControlFlags *perPipelineControlFlags;
};

class ComposSelyPipeline : virtual public Object {
20 public:

    static void      Demo ();

    // constructors & destructors
    ComposSelyPipeline ();
25    ~ComposSelyPipeline ();

    // show/set data & data properties
    // - class Object requirements
    virtual ostream & Ostream (ostream & ) const;

30    // - local show/set functions
    static void GlobalSetup (const int setNumOfChips,
                             const int setNumOfPipelinesPerChip,
                             const int setBlockSize);

35    virtual void LocalSetup(const int setChipIndex,
                             const int setPipelineIndex,
                             ComposSelyStage & composSelyStage);
    virtual void PerFrameSetup();
    // local computation functions
40    virtual void RunForOneClockCycle();

public:
    ComposSelyPipelineInputs inputs;
    ComposSelyPipelineResults results;

45    protected:
        FiFo<Coxel>                beamCoxelFiFo;
        FiFo<FixPointVector3D>     beamWeightsFiFo;
        FiFo<PerPipelineControlFlags> beamPerPipelineControlFlagsFiFo;
50        FiFo<PerChipControlFlags> beamPerChipControlFlagsFiFo;

        FiFo<Coxel>                blockBeamCoxelFiFo;
        FiFo<FixPointVector3D>     blockBeamWeightsFiFo;

55

```

```

68
    FiFo<PerPipelineControlFlags>      blockBeamPerPipelineControlFlagsFiFo;
    FiFo<PerChipControlFlags>         blockBeamPerChipControlFlagsFiFo;

5   Coxel fifoCoxel;

        int beamDelay, blockBeamDelay;

        int readSmallFiFoCounter, readBigFiFoCounter;
10   int writeSmallFiFoCounter, writeBigFiFoCounter;

        static int   numOfChips, numOfPipelinesPerChip, blockSize;
        static Cube4 *cube4;
        int          chipIndex, pipelineIndex;

15   friend class Cube4;
}; // ComposSelYPipeline

#include "ComposSelYStage.h"
#include "Cube4.h"

20   #endif          // _ComposSelYPipeline_h_
        ::::::::::::::
        cube4/ComposSelYStage.C
        ::::::::::::::
        // ComposSelYStage.C
25   // (c) Ingmar Bitter '97

        // Copyright, Mitsubishi Electric Information Technology Center
        // America, Inc., 1997, All rights reserved.

        #include "ComposSelYStage.h"

30   void ComposSelYStage::Demo()
    {
        ComposSelYStage composSelY;
        cout << endl <<"Demo of class " << typeid(composSelY).name();
        cout << endl <<"size : " << sizeof(ComposSelYStage) << " Bytes";
35   cout << endl <<"public member functions:";
        cout << endl <<"ComposSelYStage composSelY; = " << composSelY;
        cout << endl << "End of demo of class " << typeid(composSelY).name() <<
        endl;
    } // Demo

40

        //////////////////////////////////////
        // constructors & destructors

        // static first init
45   int ComposSelYStage::numOfChips      = 0;
        int ComposSelYStage::numOfPipelinesPerChip = 0;
        Cube4 *ComposSelYStage::cube4 = 0;

        ComposSelYStage::ComposSelYStage()

50

55

```

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```

{
    composSelyPipeline = new ComposSelyPipeline [numOfPipelinesPerChip];
    results.coxel = new Coxel [numOfPipelinesPerChip + 1];
    results.weightsXYZ = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];
    results.perPipelineControlFlags = new PerPipelineControlFlags
{numOfPipelinesPerChip};
} // defaultconstructor

ComposSelyStage::~ComposSelyStage()
{
    if (composSelyPipeline) { delete composSelyPipeline; composSelyPipeline=0;
    if (results.coxel)      { delete results.coxel;      results.coxel=0;
    if (results.weightsXYZ) { delete results.weightsXYZ; results.weightsXYZ=0;
    if (results.perPipelineControlFlags) {
        delete results.perPipelineControlFlags;
        results.perPipelineControlFlags=0;
    }
} // destructor

////////////////////////////////////
// show/set data & data properties

ostream & ComposSelyStage::Ostream(ostream & os) const
{
    // append ComposSelyStage info to os
    os << typeid(*this).name() << "@" << (void *) this;
    os <<endl<< "    numOfChips          = " << numOfChips;
    os <<endl<< "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
    os <<endl<< "    chipIndex            = " << chipIndex;

    // return complete os
    return os;
} // Ostream

////////////////////////////////////
// show/set data & data properties
//
// - local show/set functions

void ComposSelyStage::GlobalSetup(const int setNumOfChips,
    const int setNumOfPipelinesPerChip,
    const int setBlockSize,

```



```

Cube4 *setCube4)
5  {
    numOfChips          = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    ComposSelYPipeline::GlobalSetup(numOfChips, numOfPipelinesPerChip,
        setBlockSize);
10    cube4 = setCube4;
} // GlobalSetup

void ComposSelYStage::LocalSetup(const int setChipIndex)
15 {
    chipIndex = setChipIndex;
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        composSelYPipeline[p].LocalSetup(chipIndex,p,*this);
    }
} // LocalSetup
20

void ComposSelYStage::PerFrameSetup()
{
    int p;
    // reset pipeline registers
25    for (p=0; p<numOfPipelinesPerChip; ++p) {
        results.coxel[p] = cube4->backgroundCoxel;
        results.weightsXYZ[p](0,0,0);
        results.perPipelineControlFlags[p].Reset();
    }
    results.perChipControlFlags.Reset();
30
    for (p=0; p<numOfPipelinesPerChip; ++p) {
        composSelYPipeline[p].PerFrameSetup();
    }

35    // print debug info
    //static bool first(true); if (first) { cout<<this<<endl; first=false; }
} // PerFrameSetup

40 ///////////////////////////////////////////////////////////////////
// local computation functions

void ComposSelYStage::RunForOneClockCycle()
{
    // communication
45
    // computation
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        composSelYPipeline[p].RunForOneClockCycle();
    }
} // RunForOneClockCycle
50

55

```

```

5  ///////////////////////////////////////////////////////////////////
   // internal utility functions

   // end of ComposSelYStage.C
   ::::::::::::::
10  cube4/ComposSelYStage.h
   ::::::::::::::
   // ComposSelYStage.h
   // (c) Ingmar Bitter '97

15  // Copyright, Mitsubishi Electric Information Technology Center
   // America, Inc., 1997, All rights reserved.

   #ifndef _ComposSelYStage_h_ // prevent multiple includes
   #define _ComposSelYStage_h_

20  #include "Misc.h"
   #include "Object.h"
   #include "Vector3D.h"
   #include "Coxel.h"
   #include "Control.h"
25  #include "ComposSelYPipeline.h"
   #include "FixPointNumber.h"
   #include "Cube4.h"

   class Cube4;

30  class ComposSelYStageInputs {
public: // pointers
       Coxel *coxel;
       Vector3D<FixPointNumber> *weightsXYZ;
       PerChipControlFlags      *perChipControlFlags;
35  PerPipelineControlFlags      *perPipelineControlFlags;
   };

   class ComposSelYStageResults {
40 public: // arrays
       Coxel *coxel;
       Vector3D<FixPointNumber> *weightsXYZ;
       PerChipControlFlags      perChipControlFlags;
       PerPipelineControlFlags *perPipelineControlFlags;
45  };

   class ComposSelYStage : virtual public Object {
public:

50  static void      Demo ();

55

```

```

// constructors & destructors
ComposSelyStage ();
5  -ComposSelyStage {};

// show/set data & data properties
// - class Object requirements
virtual ostream & Ostream (ostream & ) const;

10 // - local show/set functions
static void GlobalSetup (const int setNumOfChips,

const int setNumOfPipelinesPerChip,

15 const int setBlockSize,

Cube4 *setCube4);
virtual void LocalSetup (const int setChipIndex);
virtual void PerFrameSetup ();
20 // local computation functions
virtual void RunForOneClockCycle();

public:
ComposSelyPipeline *composSelyPipeline;
ComposSelyStageInputs inputs;
25 ComposSelyStageResults results;

protected:
static int numOfChips, numOfPipelinesPerChip;
static Cube4 *cube4;
30 int chipIndex; // only for debugging purpose

friend class ComposSelyPipeline;
};

#endif // _ComposSelyStage_h_
35 :::::::::::::::
cube4/Coxel.C
:::::::::::::
// Coxel.C
// (c) Ingmar Bitter '97

40 // Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include"Coxel.h"

45 Coxel::Coxel(FixPointNumber setR, FixPointNumber setG, FixPointNumber setB,
FixPointNumber setA)
: r(setR),g(setG),b(setB),a(setA)
{
} // constructor
50

```

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```

Coxel::Coxel(const Coxel & coxel)
    : r(coxel.r),g(coxel.g),b(coxel.b),a(coxel.a)
5   {
    } // constructor

Coxel::Coxel(const double & equalSet)
    : r(equalSet),g(equalSet),b(equalSet),a(equalSet)
10  {
    } // constructor

// friend output function
ostream & operator << (ostream & os, const Coxel & c)
15  { return os<<"("<<c.r<<","<<c.g<<","<<c.b<<","<<c.a<<")"; }
    : : : : : : : : : :
cube4/ComposStage.C
    : : : : : : : : : :
// ComposStage.C
20  // (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

// Premultiplied Colors (C implies A*C)
25  //
// Back-to-Front
// Cacc = (1-Anew)Cacc + Cnew
// Aacc = (1-Anew)Aacc + Anew
//
// Front-to-Back
30  // Cacc = (1-Aacc)Cnew + Cacc
// Aacc = (1-Aacc)Anew + Aacc

#include "ComposStage.h"

35  void ComposStage::Demo()
    {
        ComposStage compos;
        cout << endl <<"Demo of class " << typeid(compos).name();
        cout << endl <<"size : " << sizeof(ComposStage) << " Bytes";
        cout << endl <<"public member functions:";
40  cout << endl <<"ComposStage compos; = " << compos;
        cout << endl << "End of demo of class " << typeid(compos).name() << endl;
    } // Demo

45  //////////////////////////////////////
// constructors & destructors

// static first init
int ComposStage::numOfChips      = 0;
int ComposStage::numOfPipelinesPerChip = 0;
50

55

```

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```

Cube4 *ComposStage::cube4 = 0;

5 ComposStage::ComposStage()
{
    composPipeline = new ComposPipeline [numOfPipelinesPerChip];
    tempResults.coxel = new Coxel [numOfPipelinesPerChip];
    tempResults.perPipelineControlFlags = new PerPipelineControlFlags
[numOfPipelinesPerChip];
10    results.coxel = new Coxel [numOfPipelinesPerChip];
    results.perPipelineControlFlags = new PerPipelineControlFlags
[numOfPipelinesPerChip];
} // defaultconstructor

15 ComposStage::~ComposStage()
{
    if (composPipeline) { delete composPipeline; composPipeline=0; }
    if (tempResults.coxel) { delete tempResults.coxel; tempResults.coxel=0; }
    if (tempResults.perPipelineControlFlags) {
20         delete tempResults.perPipelineControlFlags;
        tempResults.perPipelineControlFlags=0;
    }
    if (results.coxel) { delete results.coxel; results.coxel=0; }
    if (results.perPipelineControlFlags) {
25         delete results.perPipelineControlFlags;
        results.perPipelineControlFlags=0;
    }
} // destructor

30 ///////////////////////////////////////////////////////////////////
// show/set data & data properties

ostream & ComposStage::Ostream(ostream & os) const
{
    // append ComposStage info to os
35    os << typeid(*this).name() << "@" << (void *) this;
    os << endl << "    numOfChips          = " << numOfChips;
    os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
    os << endl << "    chipIndex            = " << chipIndex;

    // return complete os
40    return os;
} // Ostream

45 ///////////////////////////////////////////////////////////////////
// show/set data & data properties
//
// - local show/set functions

```

50

55

```

void ComposStage::GlobalSetup(const int setNumOfChips,
5
    const int setNumOfPipelinesPerChip,
    Cube4 *setCube4)
{
    numOfChips          = setNumOfChips;
10    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    cube4               = setCube4;
    ComposPipeline::GlobalSetup(numOfChips, numOfPipelinesPerChip);
} // GlobalSetup

15 void ComposStage::LocalSetup(const int setChipIndex)
{
    chipIndex = setChipIndex;
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        composPipeline[p].LocalSetup(chipIndex,p,*this);
20    }
} // LocalSetup

void ComposStage::PerFrameSetup()
{
25    int p;
    // reset pipeline registers
    for (p=0; p<numOfPipelinesPerChip; ++p) {
        results.coxel[p] = cube4->backgroundCoxel;
        results.perPipelineControlFlags[p].Reset();
    }
30    results.perChipControlFlags.Reset();

    for (p=0; p<numOfPipelinesPerChip; ++p) {
        composPipeline[p].PerFrameSetup();
    }

35    // print debug info
    //static bool first(true); if (first) { cout<<this<<endl; first=false; }
} // PerFrameSetup

40 ///////////////////////////////////////////////////////////////////
// local computation functions

void ComposStage::RunForOneClockCycle()
{
45    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        composPipeline[p].RunForOneClockCycle();
        tempResults.perPipelineControlFlags[p] =
inputs.perPipelineControlFlags[p];
    }
    tempResults.perChipControlFlags = *(inputs.perChipControlFlags);
50
55

```

```

} // RunForOneClockCycle

5
void ComposStage::WriteResultsToPipelineRegister()
{
    results.perChipControlFlags = tempResults.perChipControlFlags;
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        results.coxel[p] =      tempResults.coxel[p];
10        results.perPipelineControlFlags[p] =
            tempResults.perPipelineControlFlags[p];
    }
} // WriteResultsToPipelineRegister

15
////////////////////////////////////
// internal utility functions

20
// end of ComposStage.C
:::::::::::::
cube4/ComposStage.h
:::::::::::::
// ComposStage.h
// (c) Ingmar Bitter '97

25
// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

// Premultiplied Colors (C implies A*C)
30
//
// Back-to-Front
// Cacc = (1-Anew)Cacc + Cnew
// Aacc = (1-Anew)Aacc + Anew
//
35
// Front-to-Back
// Cacc = (1-Aacc)Cnew + Cacc
// Aacc = (1-Aacc)Anew + Aacc

#ifndef _ComposStage_h_ // prevent multiple includes
40
#define _ComposStage_h_

#include "Misc.h"
#include "Object.h"
#include "Voxel.h"
45
#include "Coxel.h"
#include "Control.h"
#include "ComposPipeline.h"

class ComposStageInputs {
50
public: // pointers
    Shadel *shadel;
    Coxel *coxel;

55

```

```

5
    Vector3D<FixPointNumber>      77      *weightsXYZ;
    PerChipControlFlags      *perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

class ComposStageResults {
10 public: // arrays
    Coxel *coxel;
    PerChipControlFlags      perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

15

class ComposStage : virtual public Object {
public:

    static void      Demo ();

20
    // constructors & destructors
    ComposStage ();
    ~ComposStage ();

25
    // show/set data & data properties
    // - class Object requirements
    virtual ostream & Ostream (ostream & )      const;

    // - local show/set functions
30
    static void GlobalSetup (const int setNumOfChips,

        const int setNumOfPipelinesPerChip,

        Cube4 *setCube4);
    virtual void LocalSetup (const int setChipIndex);
35
    virtual void PerFrameSetup ();
    // local computation functions
    virtual void RunForOneClockCycle();
    virtual void WriteResultsToPipelineRegister();

40
public:
    ComposPipeline *composPipeline;
    ComposStageInputs inputs;
    ComposStageResults tempResults;
    ComposStageResults results;

45

protected:
    static int      numOfChips, numOfPipelinesPerChip;
    static Cube4 *cube4;
    int      chipIndex; // only for debugging purpose

50
    friend class ComposPipeline;

};

55

```



```

5      #endif // _ComposStage_h_
      : : : : : : : : : :
      cube4/Control.C
      : : : : : : : : : :
      // Control.C
      // (c) Ingmar Bitter '97

10     // Copyright, Mitsubishi Electric Information Technology Center
      // America, Inc., 1997, All rights reserved.

      #include "Control.h"
      #include "Cube4.h"

15     void Control::Demo()
      {
          Control control;
          cout << endl << "Demo of class " << typeid(control).name();
          cout << endl << "size : " << sizeof(Control) << " Bytes";
20         cout << endl << "public member functions:";
          cout << endl << "Control control; = " << control;
          cout << endl << "End of demo of class " << typeid(control).name() << endl;
      } // Demo

25     PerChipControlFlags::PerChipControlFlags()
      {
          Reset();
      } // constructor

30     PerChipControlFlags::PerChipControlFlags(PerChipControlFlags & src)
      : volumeStart(src.volumeStart),
        sliceSlabStart(src.sliceSlabStart),
        beamSlabStart(src.beamSlabStart),
35         xBlockStart(src.xBlockStart),
        xBlockEnd(src.xBlockEnd),
        yBlockStart(src.yBlockStart),
        zBlockStart(src.zBlockStart),
        xStep(src.xStep),
40         yStep(src.yStep),
        endFace(src.endFace),
        leftmostChip(src.leftmostChip),
        rightmostChip(src.rightmostChip)
      {
45     } // copy constructor

      void PerChipControlFlags::Reset()
      {
50         volumeStart      = false;
          sliceSlabStart   = false;
          beamSlabStart    = false;

55

```

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```

    xBlockStart    = false;
    xBlockEnd      = false;
5   yBlockStart    = false;
    zBlockStart    = false;
    xStep          = Middle;
    yStep          = Middle;
    endFace        = None;
10  leftmostChip   = false;
    rightmostChip  = false;
} // Reset

ostream & PerPipelineControlFlags::Ostream(ostream & os) const
15 {
    // append Control info to os
    os << typeid(*this).name() << "@" << (void *) this;

    // return complete os
    return os;
20 } // Ostream

PerPipelineControlFlags::PerPipelineControlFlags()
{
    Reset();
25 } // constructor

PerPipelineControlFlags::PerPipelineControlFlags(PerPipelineControlFlags & src)
:   valid(src.valid), startOfRay(src.startOfRay), endOfRay(src.endOfRay),
    voxelPosXYZ(src.voxelPosXYZ)
30 {
} // constructor

void PerPipelineControlFlags::Reset()
35 {
    valid = false;
    startOfRay = false;
    endOfRay = false;
    voxelPosXYZ(0,0,0);
40 } // Reset

ostream & PerPipelineControlFlags::Ostream(ostream & os) const
{
    // append Control info to os
45  os << typeid(*this).name() << "@" << (void *) this;

    // return complete os
    return os;
} // Ostream

50

55

```

```

////////////////////////////////////
5 // class Control implementation

// static first init
int Control::numOfChips = 0;
int Control::numOfPipelinesPerChip = 0;
int Control::blockSize = 0;
10 Cube4 *Control::cube4 = 0;

////////////////////////////////////
// constructors & destructors

15 Control::Control()
{
    results.voxelPosXYZ = new Vector3D<int> [numOfPipelinesPerChip];
    results.weightsXYZ = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];
    results.perPipelineControlFlags = new PerPipelineControlFlags
[numOfPipelinesPerChip];
20 } // constructor

Control::~Control()
{
25     if (results.voxelPosXYZ) {
        delete results.voxelPosXYZ;
        results.voxelPosXYZ=0;
    }
    if (results.weightsXYZ) {
        delete results.weightsXYZ;
        results.weightsXYZ=0;
30     }
    if (results.perPipelineControlFlags) {
        delete results.perPipelineControlFlags;
        results.perPipelineControlFlags=0;
35     }
} // destructor

////////////////////////////////////
// show/set data & data properties
40

ostream & Control::Ostream(ostream & os) const
{
    // append Control info to os
    os << typeid(*this).name() << " " << (void *) this;
45     os << endl << "    numOfChips      = " << numOfChips;
    os << endl << "    chipIndex      = " << chipIndex;
    os << endl << "    datasetSizeXYZ = " << datasetSizeXYZ;

    // return complete os
50     return os;
}
55

```

```

5      } // Ostream

      //////////////////////////////////////
      // show/set data & data properties
      //
10     // - local show/set functions

void Control::GlobalSetup(const int setNumOfChips,
                          const int setNumOfPipelinesPerChip,
                          const int setBlockSize,
15     Cube4 *setCube4)
{
    numOfChips          = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    blockSize           = setBlockSize;
    cube4 = setCube4;
20 } // GlobalSetup

void Control::LocalSetup(const int setChipIndex)
{
25     chipIndex      = setChipIndex;
} // LocalSetup

void Control::PerFrameSetup(const Vector3D<int> & setDatasetSizeXYZ,
                             const Vector3D<int> startVoxelPos,
30     const Vector3D<FixPointNumber> & setViewPointXYZ,
                             const CompositingStyles & setCompositingStyle,
                             const ProjectionStyles & setProjectionStyle,
                             const CubeModes & setCubeMode)
{
35     int X,Y,Z;
    datasetSizeXYZ = setDatasetSizeXYZ;
    X = setDatasetSizeXYZ.X();
    Y = setDatasetSizeXYZ.Y();
    Z = setDatasetSizeXYZ.Z();
    voxelPos(ModInt(startVoxelPos.X(), X),
40         ModInt(startVoxelPos.Y(), Y),
         ModInt(startVoxelPos.Z(), Z));
    leftRightDistance = 1;
    viewPointXYZ = setViewPointXYZ;
    normalizedSightRay(0,0,0);
    samplePosIncrement(0,0,0);
45     samplePosXYZ(0,0,0);
    compositingStyle = setCompositingStyle;
    projectionStyle = setProjectionStyle;
    cubeMode = setCubeMode;
    leftmostChipIndex(-2,numOfChips); // -2 because there will be 2
50     ++leftmostChipIndex

```

55

```

82
    rightmostChipIndex(-3,numOfChips); // while computing the first IntVoxelPos()

5    zDepth = 4;

    x_voxelStep(ModInt(1,X),ModInt(0,Y),ModInt(0,Z));
    y_voxelStep(ModInt(0,X),ModInt(1,Y),ModInt(0,Z));
    z_voxelStep(ModInt(0,X),ModInt(-blockSize,Y),ModInt(1,Z)); // includes y
    corection
10    x_blockStep(ModInt(blockSize*(numOfChips-1),X),ModInt(0,Y),ModInt(0,Z)); //
    compute this is on each chip
    y_blockStep(ModInt(-blockSize,X),ModInt(blockSize,Y),ModInt(-blockSize,Z)); //
    consider skewing and z-correction
    z_blockStep(ModInt(-blockSize,X),ModInt(0,Y),ModInt(blockSize,Z)); // consider
    skewing
15    x_partialBlockBeamStep(ModInt(blockSize*(numOfChips),X),ModInt(0,Y),ModInt(0,Z))
    ;

    // reset pipeline registers
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
20        results.voxelPosXYZ[p](0,0,0);
        results.perPipelineControlFlags[p].Reset();
    }
    results.perChipControlFlags.Reset();

25    if (projectionStyle == parallel) {
        sightRay = datasetSizeXYZ;
        sightRay /= 2.0;
        sightRay -= viewPointXYZ;

        // normalize by z component
30        FixPointNumber norm(sightRay.Z().Abs());
        normalizedSightRay(sightRay.X() / norm,
                           sightRay.Y() / norm,
                           0);

        if (compositingStyle == FrontToBack)
35            samplePosIncrement = normalizedSightRay;
        else if (compositingStyle == BackToFront)
            samplePosIncrement = -normalizedSightRay;

        if (chipIndex ==0)
40            cout << "normalizedSightRay:" << normalizedSightRay
                << "samplePosIncrement:" << samplePosIncrement << endl;
    }

    // print debug info
    //static bool first(true); if (first) { cout<<this<<endl; first=false; }
45    } // PerFrameSetup

    //////////////////////////////////////
    // local computation functions

```

50

55

```

void Control::RunForOneClockCycle()
{
    // walk left to right within beams
    //   "   top   " bottom   "   slices
    //   "   front " back    "   volume cube

    // do this for whole blocks and within blocks

    // init flags to defaults within volume
    results.perChipControlFlags.Reset();
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        results.perPipelineControlFlags[p].Reset();
    }

    // compute integer voxel read positions (in pipeline xyz coords)
    IntVoxelPos();

    // compute weights for TriLin associated with voxel pos
    TriLinWeights();

} // RunForOneClockCycle

void Control::IntVoxelPos()
{
    // compute integer voxel read positions (in pipeline xyz coords)

    int p;
    static int volNum(-1);
    // go to next voxel to the right
    voxelPos += x_voxelStep;

    if ((voxelPos.X()+numOfPipelinesPerChip*x_voxelStep.X()) % blockSize == 0) {
        // will run over block boundary in next cycle
        results.perChipControlFlags.xBlockEnd = true;
    }
    if (voxelPos.X() % blockSize == 0) {
        // just ran over block boundary,
        // need to go to next partial beam in next block
        voxelPos += x_blockStep;
        results.perChipControlFlags.xBlockStart = true;
    }
    if (voxelPos.X()%blockSize == 0 &&
        voxelPos.X() <  blockSize*numOfChips) {
        // just ran out of volume, need to go to next beam of voxels
        voxelPos += y_voxelStep;
    }
    if (voxelPos.Y() % blockSize == 0) {
        // just ran over block boundary, need to go to next z-beam inside block
        voxelPos += z_voxelStep;
        results.perChipControlFlags.blockSliceStart = true;
    }
}

```

```

84
//if (voxelPos.Z() == datasetSizeXYZ.Z() - 3)
//results.perChipControlFlags.startReadingMiniblocks;

5
if (voxelPos.Z() % blockSize == 0) {
    // just ran too deep in z, need to come back and step one block in y
    voxelPos += y_blockStep;
    if (chipIndex == leftmostChipIndex)
        voxelPos += x_partialBlockBeamStep;
10
    ++leftmostChipIndex;
    ++rightmostChipIndex;
    results.perChipControlFlags.yBlockStart = true;
    if (chipIndex == 0) { cout<<"Y"; cout.flush(); }

15
    if (voxelPos.Y() == 0) {
        // just ran out of volume, need to go to next slice of blocks
        voxelPos += z_blockStep;
        if (chipIndex == leftmostChipIndex)
            voxelPos += x_partialBlockBeamStep;
        ++leftmostChipIndex;
20
        ++rightmostChipIndex;
        results.perChipControlFlags.volumeSlabStart = true;
        results.perChipControlFlags.zBlockStart = true;
        // debug info
        if (chipIndex == 0) cout << "S";

25
        if (voxelPos.Z() == 0) {
            // just ran out of volume, need to wrap back to volume start
            // assuming that skewing has made a full cycle and doesn't
            // need to be corrected this time
            results.perChipControlFlags.volumeStart = true;
30
            ++volNum;
        }
    }
}
}
}
35
}

// write voxel positions into pipeline registers
// now at first correct voxel
// following voxels are guaranteed to be within the same block
40
results.voxelPosXYZ[0] = voxelPos;
for (p=1; p<numOfPipelinesPerChip; ++p) {
    voxelPos += x_voxelStep;
    results.voxelPosXYZ[p] = voxelPos; // for debugging
    // make image generation easier by not wrapping the z coordinate
    results.voxelPosXYZ[p].SetZ(voxelPos.Z() +
45
    volNum*datasetSizeXYZ.Z());
}

// send pos also as control
// only for debugging purpose
50
for (p=0; p<numOfPipelinesPerChip; ++p) {

```

55

```

results.perPipelineControlFlags[p].voxelPosXYZ = results.voxelPosXYZ[p];
// in case one wants to see the voxel time stamps, uncomment next
5 line
  //results.perPipelineControlFlags[p].voxelPosXYZ.SetZ(cube4->clk+1);
}

results.perChipControlFlags.leftmostChip = (chipIndex == leftmostChipIndex);
10 results.perChipControlFlags.rightmostChip = (chipIndex == rightmostChipIndex);
} // IntVoxelPos

void Control::TriLinWeights()
{
15 ////////////////////////////////////////////////////////////////////
// compute weights for TriLin associated with voxel pos

if (cubeMode == Cube4Light) {

20   for (int p=0; p<numOfPipelinesPerChip; ++p) {

      if (projectionStyle == perspective) {
        samplePosXYZ = results.voxelPosXYZ[p];

        sightRay = samplePosXYZ - viewPointXYZ;

25        // normalize by z component
        FixPointNumber norm(sightRay.Z().Abs());
        normalizedSightRay(sightRay.X() / norm,
                           sightRay.Y() / norm,
                           0);

30        if (compositingStyle == FrontToBack)
          samplePosIncrement = normalizedSightRay;
        else if (compositingStyle == BackToFront)
          samplePosIncrement = -normalizedSightRay;
      }

35      results.weightsXYZ[p] = samplePosIncrement;
    }

    // set x/y steps (in perspective more xsteps might have to be reset later)
    // X/Y steps mean where rays go (eg, if xstep > 0, ray makes step to the
    right)
    // CHANGE ACCORDINGLY!!!!!!
40    if (samplePosIncrement.X() > 0) xStep = Left;
    else if (samplePosIncrement.X() < 0) xStep = Right;
    else xStep = Middle;
    if (samplePosIncrement.Y() > 0) yStep = Up;
    else if (samplePosIncrement.Y() < 0) yStep = Down;
45    else yStep = Middle;

    samplePosXYZ(0,0,0); // local pos of trilin weights used in endOfRay
    computation
  } // cubeMode == Cube4Light

```

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55


```

else if (cubeMode == Cube4Classic) {
5   if (results.perChipControlFlags.blockSliceStart) {
        // advance samplePos by samplePosIncrement at beginning
        // of every slice of voxels in a block
        samplePosXYZ += samplePosIncrement;

10        // at z-block step update blockStartSamplePos
        if (results.perChipControlFlags.zBlockStart) {
            blockStartSamplePos = samplePosXYZ;
        }

        // at y-block step restore samplePos of previous
15   blockStartSamplePos
        if (results.perChipControlFlags.yBlockStart) {
            samplePosXYZ = blockStartSamplePos;
        }

        // at start of volume set initial samplePosXYZ
20   if (results.perChipControlFlags.volumeStart) {
            samplePosXYZ(0,0,0);
            blockStartSamplePos(0,0,0);
        }

        // set x/y-steps to defaults
25   xStep = Middle;
        yStep = Middle;

        // reset x/y-steps if necessary
        // X/Y steps mean where rays go (eg. if xstep > 0, ray makes step to the
30   right)
        if (samplePosXYZ.X() >= 1) { samplePosXYZ += Vector3D<FixPointNumber>(-
            1,0,0); xStep = Right; }
        if (samplePosXYZ.X() < 0) { samplePosXYZ += Vector3D<FixPointNumber>(
            1,0,0); xStep = Left; }
        if (samplePosXYZ.Y() >= 1) { samplePosXYZ += Vector3D<FixPointNumber>(0,-
35   1,0); yStep = Down; }
        if (samplePosXYZ.Y() < 0) { samplePosXYZ += Vector3D<FixPointNumber>(0,
            1,0); yStep = Up; }
    }

    // assign same weight to all pipelines (parallel projection only)
40   for (int p=0; p<numOfPipelinesPerChip; ++p) {
        results.weightsXYZ[p] = samplePosXYZ;
    }
    // assign same x/y-steps to all pipelines (parallel projection only)
    results.perChipControlFlags.xStep = xStep;
45   results.perChipControlFlags.yStep = yStep;
} // cubeMode == Cube4Classic

```

```

////////////////////////////////////

```

50

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87

```

// set startOfRay bits

5 // preset with default
for (int p=0; p<numOfPipelinesPerChip; ++p) {
    results.perPipelineControlFlags[p].startOfRay = false;
}

// check for first (front) face
10 if (results.voxelPosXYZ[0].Z() == 0) {
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        results.perPipelineControlFlags[p].startOfRay = true;
    }
}

15 // check for top or bottom overflow
else if (// check for top overflow
        results.voxelPosXYZ[0].Y() == 0
        && yStep == Down
        || // check for bottom overflow
20 results.voxelPosXYZ[0].Y() == datasetSizeXYZ.Y()-1
        && yStep == Up ) {

    for (p=0; p<numOfPipelinesPerChip; ++p) {
        results.perPipelineControlFlags[p].startOfRay = true;
25 }
}

// check for left/right overflow
else {
    // check for left overflow
30 //if (cubeMode == Cube4Light && projectionStyle == perspective) {
        //if (results.weightsXYZ[0].X() > 0) xStep = Left;
        //else if (results.weightsXYZ[0].X() < 0) xStep = Right;
        //else
            xStep = Middle;

    //}
35 if (results.voxelPosXYZ[0].X() == 0 && xStep == Right) {
        results.perPipelineControlFlags[0].startOfRay = true;
    }
    else {
        // check for right overflow
40 //if (cubeMode == Cube4Light && projectionStyle == perspective) {
            //if (results.weightsXYZ[numOfPipelinesPerChip-1].X() >
0) xStep = Left;
            //else if (results.weightsXYZ[numOfPipelinesPerChip-1].X() <
0) xStep = Right;
            //else
45 xStep = Middle;
        //}
        if (results.voxelPosXYZ[numOfPipelinesPerChip-1].X()
            == datasetSizeXYZ.X() - 1
            && xStep == Left) {
50
55

```

```

5      results.perPipelineControlFlags[numOfPipelinesPerChip-1].startOfRay    = true;
      }
    }

    //////////////////////////////////////
    // set endOfRay and endFace bits

10    // preset with default
    results.perChipControlFlags.endFace = None;
    for (p=0; p<numOfPipelinesPerChip; ++p) {
        results.perPipelineControlFlags[p].endOfRay = false;
15    }

    // check for final (back) face
    if (results.voxelPosXYZ[0].Z() == datasetSizeXYZ.Z()-1) {
        results.perChipControlFlags.endFace = BackFace;
        for (int p=0; p<numOfPipelinesPerChip; ++p) {
20            results.perPipelineControlFlags[p].endOfRay = true;
        }
    }

    // check for top or bottom overflow
    if (// check for top overflow
25        results.voxelPosXYZ[0].Y() == 0
        && samplePosXYZ.Y()+samplePosIncrement.Y() < 0
        || // check for bottom overflow
        results.voxelPosXYZ[0].Y() == datasetSizeXYZ.Y()-1
        && ((cubeMode==Cube4Classic && (samplePosXYZ.Y()
30            +samplePosIncrement.Y() >= 1)) ||
            (cubeMode==Cube4Light &&
results.weightsXYZ[0].Y() > 0) ) ) {

        results.perChipControlFlags.endFace = TopBottomFace;
        for (p=0; p<numOfPipelinesPerChip; ++p) {
35            results.perPipelineControlFlags[p].endOfRay = true;
        }
    }

    // check for left/right overflow
    if (// check for left overflow
40        results.voxelPosXYZ[0].X() == 0
        && ((cubeMode==Cube4Classic && (samplePosXYZ.X()
            + samplePosIncrement.X() < 0))
            ||
45        (cubeMode==Cube4Light &&
results.weightsXYZ[0].X() < 0) ) ) {
        results.perChipControlFlags.endFace
            = results.perChipControlFlags.endFace | SideFace;
        results.perPipelineControlFlags[0].endOfRay = true;
50
55

```

```

89
}
else if (// check for right overflow
5      results.voxelPosXYZ[numOfPipelinesPerChip-1].X()
        == datasetSizeXYZ.X()-1
        && ((cubeMode==Cube4Classic && (samplePosXYZ.X()
                                +samplePosIncrement.X() >= 1))
10      ||
        (cubeMode==Cube4Light &&
            results.weightsXYZ[numOfPipelinesPerChip-1].X() > 0) ) ) {
    results.perChipControlFlags.endFace
        = results.perChipControlFlags.endFace | SideFace;
    results.perPipelineControlFlags[numOfPipelinesPerChip-1].endOfRay
15      = true;
}

////////////////////////////////////
// valid flag computation, same for all cube modes
20 for (p=0; p<numOfPipelinesPerChip; ++p) {
    // set valid flag, if not at volume boundary
    if (results.voxelPosXYZ[p].X() > 0 &&
        results.voxelPosXYZ[p].Y() > 0 &&
        results.voxelPosXYZ[p].Z() > 0 &&
25      results.voxelPosXYZ[p].X() < datasetSizeXYZ.X()-2 &&
        results.voxelPosXYZ[p].Y() < datasetSizeXYZ.Y()-2 &&
        results.voxelPosXYZ[p].Z() < datasetSizeXYZ.Z()-2 ) {
        results.perPipelineControlFlags[p].valid = true;
    }
    // set valid flag to false, if weights are suggesting non local
30 access
        else if (normalizedSightRay.X().Abs() > 1 ||
                normalizedSightRay.Y().Abs() > 1) {
            results.perPipelineControlFlags[p].valid = false;
            cout <<"x"; cout.flush();
        }
    }
35 } // TriLinWeights

// end of Control.C
:::::::::::::
cube4/Control.h
:::::::::::::
// Control.h
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

45 #ifndef _Control_h_          // prevent multiple includes
#define _Control_h_

```

```

#include "Misc.h"
#include "Object.h"
#include "ModInt.h"
5  #include "FixPointNumber.h"
#include "Vector3D.h"
#include "Matrix4x4.h"

class Cube4;

10 class PerChipControlFlags {
public:
    bool volumeStart; // need bool, because SliceVoxelFiFo wants pointer to it
    unsigned sliceSlabStart : 1;
    unsigned beamSlabStart : 1;
15    unsigned xBlockStart : 1;
    unsigned xBlockEnd : 1;
    unsigned yBlockStart : 1;
    unsigned zBlockStart : 1;
    unsigned xStep : 2;
    unsigned yStep : 2;
20    unsigned endFace : 3;
    unsigned leftmostChip : 1;
    unsigned rightmostChip : 1;

    unsigned blockSliceStart : 1; // kill
    unsigned volumeSlabStart : 1;
25    unsigned blockStart : 1;
public:
    PerChipControlFlags();
    PerChipControlFlags(PerChipControlFlags & src);
    //void PerFrameSetup();
    void Reset();
30    virtual ostream & Ostream (ostream & ) const;
}; // PerChipControlFlags

class PerPipelineControlFlags {
public:
35    unsigned valid : 1;
    unsigned startOfRay : 1;
    unsigned endOfRay : 1;
    Vector3D<int> voxelPosXYZ; // only for debugging purpose
public:
    PerPipelineControlFlags();
40    PerPipelineControlFlags(PerPipelineControlFlags & src);
    // void PerFrameSetup();
    void Reset();
    virtual ostream & Ostream (ostream & ) const;
}; // PerPipelineControlFlags

45 class ControlResults {
public: // arrays
    Vector3D<int> *voxelPosXYZ;
    Vector3D<FixPointNumber> *weightsXYZ;
50
55

```

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```

    PerChipControlFlags          perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
5   }; // ControlResults

class Control : virtual public Object {
public:

10   static void      Demo ();

        // constructors & destructors
        Control ();
        ~Control ();

15   // show/set data & data properties
        // - class Object requirements
        virtual ostream & Ostream (ostream & )    const;

20   // - local show/set functions
        static void GlobalSetup (const int setNumOfChips,

        const int setNumOfPipelinesPerChip,

25   const int setBlockSize,

        Cube4 *cube4);
        virtual void LocalSetup(const int setChipIndex);
        virtual void PerFrameSetup(const Vector3D<int> & setDatasetSizeXYZ,

30   const Vector3D<int> startVoxelPos,

        const Vector3D<FixPointNumber> & setViewPointXYZ,

        const CompositingStyles & setCompositingStyle,

35   const ProjectionStyles & setProjectionStyle,

        const CubeModes & setCubeMode);
        // local computation functions
        virtual void RunForOneClockCycle();
40   virtual void IntVoxelPos();
        virtual void TriLinWeights();

public:
45   ControlResults results;

protected:
        static int      numOfChips, numOfPipelinesPerChip, blockSize;
        int      chipIndex;
        ModInt leftmostChipIndex, rightmostChipIndex;
50   Vector3D<int> datasetSizeXYZ; // pipeline coordinates
        Vector3D<ModInt> voxelPos;
        Vector3D<ModInt> x_voxelStep, y_voxelStep, z_voxelStep;

55

```

```

92
    Vector3D<ModInt>                x_blockStep,y_blockStep,z_blockStep;
    Vector3D<ModInt> x_partialBlockBeamStep;
    Vector3D<FixPointNumber> viewPointXYZ;
5   Vector3D<FixPointNumber> samplePosXYZ, blockStartSamplePos;
    Vector3D<FixPointNumber> sightRay;
    Vector3D<FixPointNumber> normalizedSightRay;
    Vector3D<FixPointNumber> samplePosIncrement;
    int xStep, yStep;
10   int leftRightDistance, zDepth;
    static Cube4 *cube4;

    CompositingStyles compositingStyle;
    ProjectionStyles projectionStyle;
15   CubeModes         cubeMode;

    friend class Cube4;
};

#ifdef      // _Control_h_
20   ::::::::::::::
    cube4/CoxMem.C
    ::::::::::::::
    // CoxMem.C
    // (c) Ingmar Bitter '97

25   // Copyright, Mitsubishi Electric Information Technology Center
    // America, Inc., 1997, All rights reserved.

    // DRAM Coxel Memory of one pipeline
    // in : 1/numOfPipeline fraction of the final image
30   // out: random access to any of these coxels

#include "CoxMem.h"

void CoxMem::Demo()
{
35   CoxMem mem;
    cout << endl <<"Demo of class " << typeid(mem).name();
    cout << endl <<"size : " << sizeof(CoxMem) << " Bytes";
    cout << endl <<"public member functions:";
    mem(3)=65; cout << endl <<" mem(3)=65          = " << mem(3);
40   cout << endl <<"CoxMem::Demo() end" << endl;
} // Demo

////////////////////////////////////
45 // constructors & destructors

CoxMem::CoxMem()
    : size(0), mem(0)
{
} // constructor

50

55

```

```

CoxMem::~CoxMem()
5 {
    if (mem) { delete mem; mem=0; }
} // destructor

10 //////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
// show/set data & data properties

ostream & CoxMem::Ostream(ostream & os) const
{
    // append Control info to os
15 os << typeid(*this).name() << "@" << (void *) this;
    os <<endl<< " size = " << size;

    // return complete os
    return os;
20 } // Ostream

//
// - local show/set functions
25

bool CoxMem::SetSize (unsigned int setSize)
{
    size = setSize;
    if (mem) delete mem;
30 mem = new Coxel [size];
    if (!mem) ERROR("OutOfMemoryError");
    return true;
} // SetSize

35

Coxel & CoxMem::operator () (unsigned int index)
{
    // subscript a array value
    // check that index is valid
    if (index >= size) {
40         cout <<index<<"index:size"<<size;
        ERROR("TooLargeArrayIndexError!");
    }

    // return reference to requested element
45     return mem[index];
} // operator ()

// end of CoxMem.C
:::
50 cube4/CoxMem.h
:::
55

```



```

// CoxMem.h
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

// DRAM Coxel Memory of one pipeline
// in : 1/numOfChips fraction of the final image
// out: bustmode access to blocks of voxels

#ifndef _CoxMem_h_      // prevent multiple includes
#define _CoxMem_h_

#include "Object.h"
#include "Misc.h"
#include "Coxel.h"

class CoxMem : virtual public Object {
public:

    static void      Demo ();

    // constructors & destructors
    CoxMem();
    virtual ~CoxMem();

    // show/set data & data properties
    // - class Object requirements
    virtual          ostream &  Ostream (ostream & )    const;

    virtual          bool      SetSize      (unsigned int setSize);
    virtual /*inline*/ Coxel & operator () (unsigned int index);

    // local computation functions

protected:
    Coxel *mem;
    unsigned int size;
};

#endif      // _CoxMem_h_
:::
cube4/Coxel.h
:::
// Coxel.h
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#ifndef _Coxel_h_ // prevent multiple includes
#define _Coxel_h_

```

```

#include <iostream.h> // cout
#include "FixPointNumber.h"

5
class Coxel {
public: // data
    FixPointNumber r,g,b,a;
public: // member functions
    Coxel(FixPointNumber r=0, FixPointNumber g=0, FixPointNumber b=0,
10         FixPointNumber a=0);
    Coxel(const Coxel & coxel);
    Coxel(const double & equalSet);
public: // friend functions
    friend ostream & operator << (ostream & os, const Coxel & c);
15 }; // Coxel

#endif // _Coxel_h_
:::::::::::::
cube4/Cube4.C
20 :::::::::::::::
// Cube4.C
// (c) Ingmar Bitter '97 / Urs Kanus '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.
25

// Cube4 complete parallel rendering pipeline
// in : dataset, colorTable, illumTable
// out: baseplane image

30
#include "Cube4.h"
#include "Cube4Interface.C"
#include "Cube4Debug.C"

////////////////////////////////////
35 // constructors & destructors

Cube4::Cube4(int argc, char *argv[])
: cubeMode(Cube4Classic), projectionStyle(parallel),
  numOfChips(4), numOfPipelinesPerChip(4), blockSize(8),
  numOfFramesInAnimation(0),
40  trilinearWeightBits(8), gradientBits(8), .
  shaderMode(Phong),
  colorTableLoaded(false), alphaTableLoaded(false),
  reflectanceTableLoaded(false),
  viewPointSet(false), phongExponent(50),
45  IAmbient(1.0, 1.0, 1.0),
  Ka(0.6), Kd(0.5), Ks(1.0),
  threshold(0.6), maxWidth(1.5), mulAlpha(2.0),
  shadeColorBits(8), shadeAlphaBits(8),
  compositingStyle(BackToFront),
50  coxelColorBits(8), coxelAlphaBits(8),
  singleImagePerFrameMode(false),
  distortionCompensation(true),

55

```

```

constantAngularResolution(true),
    reflectanceMapIP(true),
    reflectanceMapBits(3),
    mapWeightBits(3)
{
    int c;

    strcpy(datasetFileName, "bulb.slc");
    strcpy(imageRootFileName, "Image");
    strcpy(colorTableFileName, "RGBA-LookupTable");
    alphaTableFileName[0] = 0;
    reflectanceTableFileName[0] = 0;

    ReadCube4PipelineParametersFromFile("Cube4PipelineParameter.dat");
    ReadCube4PipelineParametersFromCommandLine(argc, argv);

    if (cubeMode == Cube4Classic && projectionStyle == perspective) {
        cout << "\n sorry Cube4Classic && perspective not jet possible \n";
        exit(1);
    }

    //////////////////////////////////////
    // allocate memory for pipeline objects

    voxMem = new VoxMem [numOfChips];
    coxMem = new CoxMem [numOfChips];

    Control::GlobalSetup
    (numOfChips, numOfPipelinesPerChip, blockSize, this);
    AddressGenerator::GlobalSetup
    (numOfChips, numOfPipelinesPerChip, blockSize);
    MemoryCtrl::GlobalSetup      (numOfChips, numOfPipelinesPerChip);
    SliceVoxelFiFoStage::GlobalSetup(numOfChips, numOfPipelinesPerChip, blockSize, this);
    TriLinZStage::GlobalSetup      (numOfChips, numOfPipelinesPerChip, this);
    TriLinYStage::GlobalSetup
    (numOfChips, numOfPipelinesPerChip, blockSize, this);
    TriLinXStage::GlobalSetup      (numOfChips, numOfPipelinesPerChip, this);
    GradYStage::GlobalSetup
    (numOfChips, numOfPipelinesPerChip, blockSize, this);
    GradXStage::GlobalSetup      (numOfChips, numOfPipelinesPerChip, this);
    GradZStage::GlobalSetup      (numOfChips, numOfPipelinesPerChip, this);
    GradZLinZStage::GlobalSetup
    (numOfChips, numOfPipelinesPerChip, blockSize, this);
    GradZLinYStage::GlobalSetup
    (numOfChips, numOfPipelinesPerChip, blockSize, this);
    GradZLinXStage::GlobalSetup
    (numOfChips, numOfPipelinesPerChip, blockSize, this);
    ShaderStage::GlobalSetup      (numOfChips, numOfPipelinesPerChip, this);
    DataSyncStage::GlobalSetup
    (numOfChips, numOfPipelinesPerChip, blockSize, this);
    ComposBufferStage::GlobalSetup
    (numOfChips, numOfPipelinesPerChip, blockSize, this);

```

```

        ComposStage::GlobalSetup
(numOfChips,numOfPipelinesPerChip,this);
5      ComposSelXStage::GlobalSetup      (numOfChips,numOfPipelinesPerChip,this);
        ComposSelYStage::GlobalSetup
(numOfChips,numOfPipelinesPerChip,blockSize,this);
        ComposLinXStage::GlobalSetup      (numOfChips,numOfPipelinesPerChip,this);
        ComposLinYStage::GlobalSetup
10      (numOfChips,numOfPipelinesPerChip,blockSize,this);
        FinalCoxelBuffer::GlobalSetup
(numOfChips,numOfPipelinesPerChip,blockSize,this);

        control          = new Control          [numOfChips];
        addrGen           = new AddressGenerator [numOfChips];
15      memCtrl           = new MemoryCtrl       [numOfChips];
        sliceVoxelFiFo0   = new SliceVoxelFiFoStage[numOfChips];
        sliceVoxelFiFo1   = new SliceVoxelFiFoStage[numOfChips];
        triLinZ           = new TriLinZStage     [numOfChips];
        triLinY           = new TriLinYStage     [numOfChips];
        triLinX           = new TriLinXStage     [numOfChips];
20      gradY             = new GradYStage       [numOfChips];
        gradX             = new GradXStage       [numOfChips];
        gradZ             = new GradZStage       [numOfChips];
        gradZLinZ         = new GradZLinZStage   [numOfChips];
        gradZLinY         = new GradZLinYStage   [numOfChips];
        gradZLinX         = new GradZLinXStage   [numOfChips];
25      shader            = new ShaderStage      [numOfChips];
        dataSync          = new DataSyncStage    [numOfChips];
        composBuff        = new ComposBufferStage[numOfChips];
        compos            = new ComposStage      [numOfChips];
        composSelX        = new ComposSelXStage  [numOfChips];
30      composSelY        = new ComposSelYStage  [numOfChips];
        composLinX        = new ComposLinXStage  [numOfChips];
        composLinY        = new ComposLinYStage  [numOfChips];
        finalCoxelBuff    = new FinalCoxelBuffer[numOfChips];

        //////////////////////////////////////
35      // setup pipeline connections

        for (c=0; c<numOfChips; ++c) {
                control[c].LocalSetup(c);
        }

40      for (c=0; c<numOfChips; ++c) {
                addrGen[c].inputs.voxelPosXYZ = control[c].results.voxelPosXYZ;
                addrGen[c].inputs.weightsXYZ = control[c].results.weightsXYZ;
                addrGen[c].inputs.perChipControlFlags
45                = &(control[c].results.perChipControlFlags);
                addrGen[c].inputs.perPipelineControlFlags
                = control[c].results.perPipelineControlFlags;
        }

        for (c=0; c<numOfChips; ++c) {
50      memCtrl[c].inputs.address = addrGen[c].results.address;

```

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```

memCtrl[c].inputs.weightsXYZ =
addrGen[c].results.weightsXYZ;
5      memCtrl[c].inputs.perChipControlFlags
        = &(addrGen[c].results.perChipControlFlags);
        memCtrl[c].inputs.perPipelineControlFlags
        = addrGen[c].results.perPipelineControlFlags;
        memCtrl[c].LocalSetup(c, &(voxMem[c]));
    }
10
    for (c=0; c<numOfChips; ++c) {
        sliceVoxelFiFo0[c].inputs.voxel = memCtrl[c].results.voxel;
        sliceVoxelFiFo0[c].inputs.weightsXYZ =
memCtrl[c].results.weightsXYZ;
        sliceVoxelFiFo0[c].inputs.perChipControlFlags
15          = &(memCtrl[c].results.perChipControlFlags);
        sliceVoxelFiFo0[c].inputs.perPipelineControlFlags
        = memCtrl[c].results.perPipelineControlFlags;
        sliceVoxelFiFo0[c].startReadWriteCounters
        = &(memCtrl[c].results.perChipControlFlags.volumeStart);
20      sliceVoxelFiFo0[c].LocalSetup(c, sliceVoxelFiFo0);
    }

    for (c=0; c<numOfChips; ++c) {
        sliceVoxelFiFo1[c].inputs.voxel = sliceVoxelFiFo0[c].results.voxel;
        sliceVoxelFiFo1[c].inputs.weightsXYZ =
25      sliceVoxelFiFo0[c].results.weightsXYZ;
        sliceVoxelFiFo1[c].inputs.perChipControlFlags
        = &(sliceVoxelFiFo0[c].results.perChipControlFlags);
        sliceVoxelFiFo1[c].inputs.perPipelineControlFlags
        = sliceVoxelFiFo0[c].results.perPipelineControlFlags;
        sliceVoxelFiFo1[c].startReadWriteCounters
30      =
        &(memCtrl[c].results.delayedPerChipControlFlags.volumeStart);
        sliceVoxelFiFo1[c].LocalSetup(c, sliceVoxelFiFo1);
    }

    for (c=0; c<numOfChips; ++c) {
35      triLinZ[c].inputs.voxel0 = sliceVoxelFiFo0[c].results.voxel;
        triLinZ[c].inputs.voxel1 = sliceVoxelFiFo1[c].results.voxel;
        triLinZ[c].inputs.weightsXYZ =
        sliceVoxelFiFo1[c].results.weightsXYZ;
        triLinZ[c].inputs.perChipControlFlags
40          = &(sliceVoxelFiFo1[c].results.perChipControlFlags);
        triLinZ[c].inputs.perPipelineControlFlags
        = sliceVoxelFiFo1[c].results.perPipelineControlFlags;
        triLinZ[c].LocalSetup(c);
    }

    for (c=0; c<numOfChips; ++c) {
45      triLinY[c].inputs.voxel = triLinZ[c].results.voxel;
        triLinY[c].inputs.weightsXYZ = triLinZ[c].results.weightsXYZ;
        triLinY[c].inputs.perChipControlFlags
        = &(triLinZ[c].results.perChipControlFlags);
50
55

```

```

triLinY[c].inputs.perPipelineControlFlags
5      = triLinZ[c].results.perPipelineControlFlags;
      triLinY[c].LocalSetup(c);
    }

    for (c=0; c<numOfChips; ++c) {
10      triLinX[c].inputs.voxel = triLinY[c].results.voxel;
      triLinX[c].inputs.weightsXYZ = triLinY[c].results.weightsXYZ;
      triLinX[c].inputs.perChipControlFlags
          = &(triLinY[c].results.perChipControlFlags);
      triLinX[c].inputs.perPipelineControlFlags
15      = triLinY[c].results.perPipelineControlFlags;
      triLinX[c].LocalSetup(c);
    }

    for (c=0; c<numOfChips; ++c) {
20      gradY[c].inputs.voxel = triLinX[c].results.voxel;
      gradY[c].inputs.weightsXYZ = triLinX[c].results.weightsXYZ;
      gradY[c].inputs.perChipControlFlags
          = &(triLinX[c].results.perChipControlFlags);
      gradY[c].inputs.perPipelineControlFlags
25      = triLinX[c].results.perPipelineControlFlags;
      gradY[c].LocalSetup(c);
    }

    for (c=0; c<numOfChips; ++c) {
      gradX[c].inputs.voxel = gradY[c].results.voxel;
      gradX[c].inputs.gy = gradY[c].results.gy;
30      gradX[c].inputs.weightsXYZ = gradY[c].results.weightsXYZ;
      gradX[c].inputs.perChipControlFlags
          = &(gradY[c].results.perChipControlFlags);
      gradX[c].inputs.perPipelineControlFlags
          = gradY[c].results.perPipelineControlFlags;
35      gradX[c].LocalSetup(c);
    }

    for (c=0; c<numOfChips; ++c) {
      gradZ[c].inputs.voxel0 = memCtrl[c].results.voxel;
      gradZ[c].inputs.voxel1 = sliceVoxelFiFo1[c].results.voxel;
40      gradZ[c].inputs.weightsXYZ = sliceVoxelFiFo0[c].results.weightsXYZ;
      gradZ[c].inputs.perChipControlFlags
          = &(sliceVoxelFiFo0[c].results.perChipControlFlags);
      gradZ[c].inputs.perPipelineControlFlags
          = sliceVoxelFiFo0[c].results.perPipelineControlFlags;
45      gradZ[c].LocalSetup(c);
    }

    for (c=0; c<numOfChips; ++c) {
      gradZLinZ[c].inputs.gz = gradZ[c].results.gz;
50      gradZLinZ[c].inputs.weightsXYZ = gradZ[c].results.weightsXYZ;
      gradZLinZ[c].inputs.perChipControlFlags
          = &(gradZ[c].results.perChipControlFlags);

```

```

gradZLinZ[c].inputs.perPipelineControlFlags
5      = gradZ[c].results.perPipelineControlFlags;
      gradZLinZ[c].LocalSetup(c);
    }

    for (c=0; c<numOfChips; ++c) {
      gradZLinY[c].inputs.gz = gradZLinZ[c].results.gz;
10      gradZLinY[c].inputs.weightsXYZ = gradZLinZ[c].results.weightsXYZ;
      gradZLinY[c].inputs.perChipControlFlags
        = &(gradZLinZ[c].results.perChipControlFlags);
      gradZLinY[c].inputs.perPipelineControlFlags
        = gradZLinZ[c].results.perPipelineControlFlags;
15      gradZLinY[c].LocalSetup(c);
    }

    for (c=0; c<numOfChips; ++c) {
      gradZLinX[c].inputs.gz = gradZLinY[c].results.gz;
      gradZLinX[c].inputs.weightsXYZ = gradZLinY[c].results.weightsXYZ;
20      gradZLinX[c].inputs.perChipControlFlags
        = &(gradZLinY[c].results.perChipControlFlags);
      gradZLinX[c].inputs.perPipelineControlFlags
        = gradZLinY[c].results.perPipelineControlFlags;
      gradZLinX[c].LocalSetup(c);
25    }

    /*
    for (c=0; c<numOfChips; ++c) {
      shader[c].inputs.voxel = gradX[c].results.voxel;
      shader[c].inputs.gx = gradX[c].results.gx;
      shader[c].inputs.gy = gradX[c].results.gy;
30      shader[c].inputs.gz = gradZLinX[c].results.gz;
      shader[c].inputs.weightsXYZ = gradX[c].results.weightsXYZ;
      shader[c].inputs.perChipControlFlags
        = &(gradX[c].results.perChipControlFlags);
      shader[c].inputs.perPipelineControlFlags
        = gradX[c].results.perPipelineControlFlags;
35      shader[c].LocalSetup(c);
    }

    */

    for (c=0; c<numOfChips; ++c) {
      shader[c].inputs.voxel = triLinX[c].results.voxel;
40      shader[c].inputs.gx = gradX[c].results.gx;
      shader[c].inputs.gy = gradX[c].results.gy;
      shader[c].inputs.gz = gradZLinX[c].results.gz;
      shader[c].inputs.weightsXYZ = triLinX[c].results.weightsXYZ;
      shader[c].inputs.perChipControlFlags
        = &(triLinX[c].results.perChipControlFlags);
45      shader[c].inputs.perPipelineControlFlags
        = triLinX[c].results.perPipelineControlFlags;
      shader[c].LocalSetup(c);
    }

50    for (c=0; c<numOfChips; ++c) {

```

55

```

101
dataSync[c].inputs.shadel = shader[c].results.shadel;
dataSync[c].inputs.weightsXYZ = shader[c].results.weightsXYZ;
5 dataSync[c].inputs.perPipelineControlFlags
    = shader[c].results.perPipelineControlFlags;
dataSync[c].inputs.perChipControlFlags
    = &(shader[c].results.perChipControlFlags);
dataSync[c].LocalSetup(c);
}
10
/*
for (c=0; c<numOfChips; ++c) {
    compos[c].inputs.shadel = dataSync[c].results.shadel;
    compos[c].inputs.coxel = composLinY[c].results.coxel;
    compos[c].inputs.weightsXYZ = composLinY[c].results.weightsXYZ;
15 compos[c].inputs.perPipelineControlFlags
    = composLinY[c].results.perPipelineControlFlags;
    compos[c].inputs.perChipControlFlags
    = &(composLinY[c].results.perChipControlFlags);
    compos[c].LocalSetup(c);
}
20 */
for (c=0; c<numOfChips; ++c) {
    compos[c].inputs.shadel = dataSync[c].results.shadel;
    compos[c].inputs.coxel = composLinY[c].results.coxel;
    compos[c].inputs.weightsXYZ = dataSync[c].results.weightsXYZ;
25 compos[c].inputs.perPipelineControlFlags
    = dataSync[c].results.perPipelineControlFlags;
    compos[c].inputs.perChipControlFlags
    = &(dataSync[c].results.perChipControlFlags);
    compos[c].LocalSetup(c);
}
30
for (c=0; c<numOfChips; ++c) {
    composBuff[c].inputs.coxel = compos[c].results.coxel;
    composBuff[c].inputs.perChipControlFlags
    = &(compos[c].results.perChipControlFlags);
35 composBuff[c].LocalSetup(c);
}

for (c=0; c<numOfChips; ++c) {
    composSelX[c].inputs.coxel = composBuff[c].results.coxel;
    composSelX[c].inputs.weightsXYZ = shader[c].results.weightsXYZ;
40 composSelX[c].inputs.perPipelineControlFlags
    = shader[c].results.perPipelineControlFlags;
    composSelX[c].inputs.perChipControlFlags
    = &(shader[c].results.perChipControlFlags);
    composSelX[c].LocalSetup(c);
}
45
for (c=0; c<numOfChips; ++c) {
    composLinX[c].inputs.coxel = composSelX[c].results.coxel;
    composLinX[c].inputs.weightsXYZ = composSelX[c].results.weightsXYZ;
    composLinX[c].inputs.perPipelineControlFlags
50
55

```


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```

    =
    composSelX[c].results.perPipelineControlFlags;
5      composLinX[c].inputs.perChipControlFlags
        = &(composSelX[c].results.perChipControlFlags);
        composLinX[c].LocalSetup(c);
    }

    for (c=0; c<numOfChips; ++c) {
10      composSelY[c].inputs.coxel = composLinX[c].results.coxel;
        composSelY[c].inputs.weightsXYZ = composLinX[c].results.weightsXYZ;
        composSelY[c].inputs.perPipelineControlFlags
            = composLinX[c].results.perPipelineControlFlags;
        composSelY[c].inputs.perChipControlFlags
            = &(composLinX[c].results.perChipControlFlags);
15      composSelY[c].LocalSetup(c);
    }

    for (c=0; c<numOfChips; ++c) {
        composLinY[c].inputs.coxel = composLinX[c].results.coxel;
        composLinY[c].inputs.weightsXYZ = composLinX[c].results.weightsXYZ;
20      composLinY[c].inputs.perPipelineControlFlags
            = composLinX[c].results.perPipelineControlFlags;
        composLinY[c].inputs.perChipControlFlags
            = &(composLinX[c].results.perChipControlFlags);
        composLinY[c].LocalSetup(c);
25    }

    for (c=0; c<numOfChips; ++c) {
        finalCoxelBuff[c].inputs.coxel = compos[c].results.coxel;
        finalCoxelBuff[c].inputs.perPipelineControlFlags
            = compos[c].results.perPipelineControlFlags;
30      finalCoxelBuff[c].inputs.perChipControlFlags
            = &(compos[c].results.perChipControlFlags);
        finalCoxelBuff[c].LocalSetup(&(coxMem[c]));
    }

35    // setup geometry stuff
    Mdp[ViewFront](1,0,0,0,
                   0,1,0,0,
                   0,0,1,0,
                   0,0,0,1);

40    Mdp[ViewFront](1,0,0,0,
                   0,1,0,0,
                   0,0,1,0,
                   0,0,0,1);

45    Mdp[ViewLeft](0,0,1,0,
                  1,0,0,0,
                  0,1,0,0,
                  0,0,0,1);

    Mdp[ViewLeft](0,1,0,0,
50
55

```

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```

5                                     0,0,1,0,
                                     1,0,0,0,
                                     0,0,0,1);

    Mpd[ ViewTop ](0,1,0,0,

                                     0,0,1,0,
                                     1,0,0,0,
10                                     0,0,0,1);

    Mdp[ ViewTop ](0,0,1,0,

                                     1,0,0,0,
                                     0,1,0,0,
15                                     0,0,0,1);

} // constructor

Cube4::~Cube4()
{
20     if (dataset)      { delete dataset;      dataset      =0; }
    if (voxMem)         { delete voxMem;        voxMem        =0; }
    if (coxMem)         { delete coxMem;        coxMem        =0; }
    if (control)        { delete control;       control       =0; }
    if (addrGen)        { delete addrGen;       addrGen       =0; }
25     if (memCtrl)      { delete memCtrl;       memCtrl       =0; }
    if (sliceVoxelFiFo0){ delete sliceVoxelFiFo0; sliceVoxelFiFo0=0; }
    if (sliceVoxelFiFo1){ delete sliceVoxelFiFo1; sliceVoxelFiFo1=0; }
    if (triLinZ)        { delete triLinZ;       triLinZ       =0; }
    if (triLinY)        { delete triLinY;       triLinY       =0; }
    if (triLinX)        { delete triLinX;       triLinX       =0; }
30     if (gradY)        { delete gradY;        gradY         =0; }
    if (gradX)          { delete gradX;        gradX          =0; }
    if (gradZ)          { delete gradZ;        gradZ          =0; }
    if (gradZLinZ)      { delete gradZLinZ;    gradZLinZ      =0; }
    if (gradZLinY)      { delete gradZLinY;    gradZLinY      =0; }
35     if (gradZLinX)    { delete gradZLinX;    gradZLinX      =0; }
    if (shader)         { delete shader;       shader         =0; }
    if (dataSync)       { delete dataSync;     dataSync       =0; }
    if (composBuff)     { delete composBuff;   composBuff     =0; }
    if (compos)         { delete compos;       compos         =0; }
40     if (composSelX)   { delete composSelX;   composSelX     =0; }
    if (composSelY)     { delete composSelY;   composSelY     =0; }
    if (composLinX)     { delete composLinX;   composLinX     =0; }
    if (composLinY)     { delete composLinY;   composLinY     =0; }
    if (finalCoxelBuff) { delete finalCoxelBuff; finalCoxelBuff =0; }
} // destructor
45

////////////////////////////////////
// local computation functions

50 bool Cube4::RenderAnimation()
{
55

```

```

char str[500];

5   if (numOfFramesInAnimation == 0) {
        RenderImage();
        // MakePSfile("");
        // sprintf(str,"display img/%s.miff \n", imageRootFileName);
        // system(str);
        return true;
10  }

        PerFrameSetup();
int km=numOfFramesInAnimation,
        x=datasetSizeUVW.X(), y=datasetSizeUVW.Y(), z=datasetSizeUVW.Z();
        int imgX = km * 3*x * 2, imgY = 2* 3*y;
15  if (km>8) { imgX = 8* 3*x *2; imgY = 2* 3*y * int((km+7)/8); }

        singleImagePerFrameMode = true;
        viewPointSet = true;
        system("/usr/bin/rm -f img/ani*.miff & \n");
        sprintf(str,"convert -geometry %ix%i! img/white.miff img/dummy.miff \n",
20  imgX, imgY);

        system(str);
        system("display -delay 1 img/dummy.miff & \n");
        double twoPi=2.0*M_PI, t=twoPi;
        for (int k=0; k < km; k++) {
25  t = k/double(km-1);
        //viewPointUVW(x/2.0 + 50*cos(t*twoPi), y/2.0 + 50*sin(t*twoPi),
z/2.0+75); // circle
        //viewPointUVW(x*t, y/2.0 , z*1.5); // leftRight
        //viewPointUVW(x/2.0 , y*t, z*1.5); // upDown
        viewPointUVW(x/2.0 , y/2.0, z/2.0 + 1/(t/z)); // near / far
30  //viewPointUVW(x/2.0 - 100*sin(t*twoPi/8.5),
        //
        // y/2.0 - 100*sin(t*twoPi/8.5),
        // z/2.0 + 100*cos(t*twoPi/8.5));
        // 35deg circle
        cout << x<< " "<<y<< " "<<z<< " "<<"new view point: "<< viewPointUVW <<
endl;
35  RenderImage();
        sprintf(str,"convert img/baseplaneImage.miff img/ani_%02i.miff",k);
        system(str);
        sprintf(str,"convert -draw 'image %i,%i img/baseplaneImage.miff' %s
%s",
40  (k%8)*2*3*x, (k/8)*2*3*y, "img/dummy.miff",
        "img/dummy.miff");
        system(str);
        }
        sprintf(str,"animate img/ani*.miff & \n",k);
        system(str);
45  sprintf(str,"cp img/dummy.miff img/baseplaneImage.miff \n");
        system(str);
        sprintf(str,"diagonal view point sweep x=0...%i y=0...%i in %i
steps",x,y,km);
        MakePSfile(str);
50
55

```

```

105
    sprintf(str,"cp img/%s* ani/ \n", imageRootFileName);
    system(str);
    sprintf(str,"cp img/ani_*.miff ani/ \n");
5    system(str);
    return true;
} // RenderAnimation

10 void Cube4::RenderImage()
{
    Timer timer;
    PerFrameSetup();
    RunPipeline();
15    cout << "last projection " << timer << endl;
} // RenderImage

void Cube4::PerFrameSetup()
{
20    int c,k;

    backgroundCoxel.r = 1;
    backgroundCoxel.g = 1;
    backgroundCoxel.b = 1;
25    backgroundCoxel.a = 0;

    backgroundShadel.r = 1;
    backgroundShadel.g = 1;
    backgroundShadel.b = 1;
    backgroundShadel.a = 0;
30

    // make sure that the right dataset is in on board DRAM
    if (!datasetLoaded) {
        dataset = new LinearDataset(datasetFileName);

        // global control information
35        cout << endl << "dataset.sizeUVW = "<<dataset->sizeUVW<<endl;
        Vector3D<int> one(1,1,1);
        // make each direction a multiple of (numOfChips*blockSize)
        datasetSizeUVW = (one + (dataset->sizeUVW-
one)/(numOfChips*blockSize))
40        * (numOfChips*blockSize);
        cout << "datasetSizeUVW = "<<datasetSizeUVW
            << " number of chips = "<<numOfChips
            << " pipelines per chip = "<<numOfPipelinesPerChip
            << " block size = "<<blockSize
            << endl;
45

        // initialize memory modules
        for (c=0; c<numOfChips; ++c) {
            voxMem[c].Init((datasetSizeUVW.U() *
50            datasetSizeUVW.V() *
55

```

```

datasetSizeUVW.W() ) / numOfChips);
5      }

      datasetToPipelineMatrix = Mpd[ViewFront];
      pipelineToDatasetMatrix = Mdp[ViewFront];

10     // initialize address generator for writing data
      for (c=0; c<numOfChips; ++c) {
          addrGen[c].PerFrameSetup(datasetSizeUVW,
pipelineToDatasetMatrix);
      }

15     // move dataset into memory modules
      int index,address;
      int v_step(dataset->sizeUVW.U());
      int w_step(v_step * dataset->sizeUVW.V());
      for (int w=0; w<datasetSizeUVW.W(); ++w) {
          for (int v=0; v<datasetSizeUVW.V(); ++v) {
20             for (int u=0; u<datasetSizeUVW.U(); ++u) {
                index = addrGen[0].ChipIndex(u,v,w);
                address = addrGen[0].MemoryAddress(u,v,w);
                if (u < dataset->sizeUVW.U() &&
                    v < dataset->sizeUVW.V() &&
                    w < dataset->sizeUVW.W() )
25                 voxMem[index](address) = dataset-
>voxelData[u + v*v_step + w*w_step];
                else
                    voxMem[index](address) = 0;
                    //voxMem[index](address) = u + v*32 + w*32*32;
                    //voxMem[index](address) = index*256/numOfChips;
                    //if (v==w) voxMem[index](address) = 200;
30             }
          }
      }
      datasetLoaded = true;

35     // free temporary storage
      delete dataset; dataset=0;
  }

  //////////////////////////////////////
40  // get the viewdependent global variables

  if (!viewPointSet) {
      if (compositingStyle == BackToFront) {
          viewPointUVW(datasetSizeUVW.X()/2.0,
45                      datasetSizeUVW.Y()/2.0,
                      2.0*datasetSizeUVW.Z());
      }
      else if (compositingStyle == FrontToBack) {
          viewPointUVW(datasetSizeUVW.X()/2.0,
50                      datasetSizeUVW.Y()/2.0,
                      2.0*datasetSizeUVW.Z());
      }
  }

```

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```

datasetSizeUVW.Y()/2.0,
5          }
          }
          }

Vector3D<FixPointNumber> sightRay(datasetSizeUVW);
sightRay /= 2.0;
10 cout << "datasetCenter:"<<sightRay<< " viewPointUVW:"<<viewPointUVW;
sightRay -= viewPointUVW;
Vector3D<FixPointNumber> absSightRay(sightRay.U().Abs(),
                                     sightRay.V().Abs(),
15                                     sightRay.W().Abs());

int maxDirection, maxIndex(0);
if (absSightRay[maxIndex] < absSightRay[1]) maxIndex = 1;
20 if (absSightRay[maxIndex] < absSightRay[2]) maxIndex = 2;

switch (maxIndex) {
case 0: maxDirection = ViewLeft ; break;
case 1: maxDirection = ViewTop ; break;
25 case 2: maxDirection = ViewFront; break;
}

datasetToPipelineMatrix = Mdp[maxDirection];
pipelineToDatasetMatrix = Mpd[maxDirection];

30 datasetSizeXYZ = datasetToPipelineMatrix * datasetSizeUVW;
viewPointXYZ = datasetToPipelineMatrix * viewPointUVW;

if (viewPointXYZ.Z() > datasetSizeXYZ.Z()/2.0) {
    // view point behind dataset
    compositingStyle = BackToFront;
35 }
else {
    // view point in front of dataset
    compositingStyle = FrontToBack;
}

40 cout << " sightRay:"<<sightRay
    << " viewPointXYZ:"<<viewPointXYZ
    << " Processing:"<<TypeStr::MajorViewDirection[maxDirection]
    << " Compos:"<<TypeStr::CompositingStyle[compositingStyle]
    << endl;

45 // transform light sources
lightSourceXYZ = lightSourceUVW;
for (k=0; k<lightSourceXYZ.Size(); ++k) {
    lightSourceXYZ[k].TransformDirection(datasetToPipelineMatrix);
50 }

```

55

```

// initialize address generator for reading data
5 for (c=0; c<numOfChips; ++c) {
    addrGen[c].PerFrameSetup(datasetSizeUVW, pipelineToDatasetMatrix);
}

// initialize on chip control
// last voxel of volume=>wrap around to first
10 // (reverse control IntVoxelPos computation)
Vector3D<int> startVoxelPos(-(1+blockSize)*(blockSize*numOfChips),-1,-1);

int nextX;
for (c=0; c<numOfChips; ++c) {
15     control[c].PerFrameSetup(datasetSizeXYZ, startVoxelPos,

    viewPointXYZ, compositingStyle,

    projectionStyle, cubeMode);
    nextX = startVoxelPos.X()+blockSize;
    startVoxelPos.SetX(nextX);
20 }

#define ForAllChips for (c=0; c<numOfChips; ++c)

ForAllChips memCtrl[c].PerFrameSetup();
25 ForAllChips sliceVoxelFiFo0[c].PerFrameSetup();
ForAllChips sliceVoxelFiFo1[c].PerFrameSetup();
ForAllChips triLinZ[c].PerFrameSetup();
ForAllChips triLinY[c].PerFrameSetup();
ForAllChips triLinX[c].PerFrameSetup();
ForAllChips gradY[c].PerFrameSetup();
30 ForAllChips gradX[c].PerFrameSetup();
ForAllChips gradZ[c].PerFrameSetup();
ForAllChips gradZLinZ[c].PerFrameSetup();
ForAllChips gradZLinY[c].PerFrameSetup();
ForAllChips gradZLinX[c].PerFrameSetup();
35 ForAllChips shader[c].PerFrameSetup();
ForAllChips dataSync[c].PerFrameSetup();
ForAllChips composBuff[c].PerFrameSetup();
ForAllChips compos[c].PerFrameSetup();
ForAllChips composSelX[c].PerFrameSetup();
ForAllChips composSelY[c].PerFrameSetup();
40 ForAllChips composLinX[c].PerFrameSetup();
ForAllChips composLinY[c].PerFrameSetup();
ForAllChips finalCoxelBuff[c].PerFrameSetup();

    DebugPerFrameSetup();
} // PerFrameSetup
45

void Cube4::RunPipeline()
{
    cout << endl << "running pipeline ... " << endl;
50
55

```

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```

int c;

5  #define    ForAllChips    for (c=0; c<numOfChips; ++c)

/*
    // precomputed clk delay
    // now determined on the fly in FinalCoxelBuff::RunForOneClockCycle()
10  int clk_end;
    // volume + 2 Slices delay
    clk_end =
datasetSizeXYZ.X()*datasetSizeXYZ.Y()*(datasetSizeXYZ.Z()+2+blockSize);
    clk_end /= (numOfChips*numOfPipelinesPerChip);

15  // 17 pipeline stages and 4 beam buffer delay
    clk_end += 17+4;

    // final pixel dribbel delay
    clk_end += 4*blockSize;
20  */

    for (clk=0; clk<=clk_end; ++clk) {

        //ForAllChips finalCoxelBuff[c].RunForOneClockCycle();
        ForAllChips compos[c].RunForOneClockCycle();
25  ForAllChips composLinY[c].RunForOneClockCycle();
        ForAllChips composSelY[c].RunForOneClockCycle();
        ForAllChips composLinX[c].CommunicateForOneClockCycle();
        ForAllChips composLinX[c].RunForOneClockCycle();
        ForAllChips composSelX[c].CommunicateForOneClockCycle();
30  ForAllChips composSelX[c].RunForOneClockCycle();
        ForAllChips composBuff[c].RunForOneClockCycle();
        ForAllChips compos[c].WriteResultsToPipelineRegister();
        ForAllChips dataSync[c].RunForOneClockCycle();
        ForAllChips shader[c].RunForOneClockCycle();
35  //ForAllChips gradZLinX[c].RunForOneClockCycle();
        //ForAllChips gradZLinY[c].RunForOneClockCycle();
        //ForAllChips gradZLinZ[c].RunForOneClockCycle();
        //ForAllChips gradZ[c].RunForOneClockCycle();
        //ForAllChips gradX[c].RunForOneClockCycle();
        //ForAllChips gradY[c].RunForOneClockCycle();
40  ForAllChips triLinX[c].CommunicateForOneClockCycle();
        ForAllChips triLinX[c].RunForOneClockCycle();
        ForAllChips triLinY[c].RunForOneClockCycle();
        ForAllChips triLinZ[c].RunForOneClockCycle();
        ForAllChips sliceVoxelFiFo1[c].RunForOneClockCycle();
45  ForAllChips sliceVoxelFiFo0[c].RunForOneClockCycle();
        ForAllChips memCtrl[c].RunForOneClockCycle();
        ForAllChips addrGen[c].RunForOneClockCycle();
        ForAllChips control[c].RunForOneClockCycle();

        //DebugControl(clk);
50  //DebugAddrGen(clk);
        //DebugMemCtrl(clk);

```

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```

//DebugSliceVoxelFiFo0(clk);
5 //DebugTriLinZ(clk);
//DebugTriLinY(clk);
//DebugTriLinX(clk);
//DebugGradY(clk);
//DebugGradX(clk);
10 //DebugGradZ(clk);
//DebugGradZLinZ(clk);
//DebugGradZLinY(clk);
//DebugGradZLinX(clk);
//DebugShader(clk);
//DebugDataSync(clk);
15 //DebugComposSelX(clk);
//DebugComposLinX(clk);
//DebugComposSelY(clk);
//DebugComposLinY(clk);
//DebugCompos(clk);
20 DebugComposBuffer(clk);
//DebugFinalCoxelBuffer(clk);
} // clk loop

// GetFinalImage();
} // RunPipeline
25

// end of Cube4.C
:::::::::::::
cube4/Cube4.h
:::::::::::::
// Cube4.h
30 // (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

35 // Cube4 complete parallel rendering pipeline
// in : dataset, colorTable, illumTable
// out: baseplane image

#ifndef _Cube4_h_ // prevent multiple includes
40 #define _Cube4_h_

#include <fstream.h> // strcmp
#include <iostream.h> // strcmp
#include <string.h> // strcmp
#include <strstream.h> // strstream
45 #include <stdlib.h> // atoi
#include <stdio.h> // sprintf
#include <assert.h>
#include "Object.h"
#include "Misc.h"
50 #include "DynaArray.h"
#include "FixPointNumber.h"

```

55

```

#include "Vector3D.h"
#include "Matrix4x4.h"
5  #include "FiFo.h"
#include "Timer.h"
#include "Voxel.h"
#include "Shadel.h"
#include "Coxel.h"
10 #include "Light.h"
#include "LinearDataset.h"
#include "VoxMem.h"
#include "CoxMem.h"
#include "Control.h"
#include "AddressGenerator.h"
15 #include "MemoryCtrl.h"
#include "SliceVoxelFiFoStage.h"
#include "SliceVoxelFiFoPipeline.h"
#include "TriLinZStage.h"
#include "TriLinZPipeline.h"
20 #include "TriLinYStage.h"
#include "TriLinYPipeline.h"
#include "TriLinXStage.h"
#include "TriLinXPipeline.h"
#include "GradYStage.h"
25 #include "GradYPipeline.h"
#include "GradXStage.h"
#include "GradXPipeline.h"
#include "GradZStage.h"
#include "GradZPipeline.h"
30 #include "GradZLinZStage.h"
#include "GradZLinZPipeline.h"
#include "GradZLinYStage.h"
#include "GradZLinYPipeline.h"
#include "GradZLinXStage.h"
35 #include "GradZLinXPipeline.h"
#include "ShaderStage.h"
#include "ShaderPipeline.h"
#include "DataSyncStage.h"
#include "DataSyncPipeline.h"
40 #include "ComposBufferStage.h"
#include "ComposBufferPipeline.h"
#include "ComposStage.h"
#include "ComposPipeline.h"
#include "ComposSelXStage.h"
45 #include "ComposSelXPipeline.h"
#include "ComposSelYStage.h"
#include "ComposSelYPipeline.h"
#include "ComposLinXStage.h"
#include "ComposLinXPipeline.h"
#include "ComposLinYStage.h"
50 #include "ComposLinYPipeline.h"
#include "FinalCoxelBuffer.h"

```

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```

class Cube4 : virtual public Object (
public:
5   static void      Demo ();

    // constructors & destructors
    Cube4(int argc=0, char *argv[]=0);
    virtual ~Cube4();

10   // show/set data & data properties
    virtual          bool      PrintUsage()          const;
    virtual /*inline*/ bool      SetDatasetFile      (const char * fileName);
    virtual /*inline*/ bool      SetColorTableFile(const char * fileName);
    virtual /*inline*/ bool      SetAlphaTableFile(const char * fileName);
15   virtual /*inline*/ bool      SetReflectanceTableFile(const char *
fileName);
    virtual /*inline*/ bool      SetImageFileRoot (const char * fileName);
    virtual          bool      LoadColorTable();
    virtual          bool      LoadAlphaTable();
    virtual          bool      LoadReflectanceTable();

20   // local computation functions
    virtual bool RenderAnimation();
    virtual void RenderImage();

protected:
25   // internal utility functions
    virtual void PerFrameSetup();
    virtual void RunPipeline();

    // Debugging tools
30   virtual void DebugImage(const PerChipControlFlags & flags);
    virtual void DebugWritePixel( const int c,

                                const Vector3D<int> & voxelPosXYZ,

                                const unsigned char red,
35                                const unsigned char green,
                                const unsigned char blue);

    // Debugging functions for each pipeline stage
    void Cube4::DebugPerFrameSetup();
    bool Cube4::ClkInInterval(const int clk,
40
                                const int pipelineStart,

                                const int startBeam,

                                const int startSlice,
45
                                const int timeWindowSize);
    virtual void DebugControl(const int clk);
    virtual void DebugAddrGen(const int clk);
    virtual void DebugMemCtrl(const int clk);
50

```

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```

virtual void DebugSliceVoxelFiFo0(const int clk);
virtual void DebugSliceVoxelFiFo1(const int clk);
5 virtual void DebugTriLinZ(const int clk);
virtual void DebugTriLinY(const int clk);
virtual void DebugTriLinX(const int clk);
virtual void DebugGradY (const int clk);
virtual void DebugGradX (const int clk);
10 virtual void DebugGradZ (const int clk);
virtual void DebugGradZLinZ(const int clk);
virtual void DebugGradZLinY(const int clk);
virtual void DebugGradZLinX(const int clk);
virtual void DebugShader(const int clk);
virtual void DebugDataSync(const int clk);
15 virtual void DebugCompos (const int clk);
virtual void DebugComposBuffer (const int clk);
virtual void DebugComposSelX (const int clk);
virtual void DebugComposSelY (const int clk);
virtual void DebugComposLinX (const int clk);
virtual void DebugComposLinY (const int clk);
20 virtual void DebugFinalCoxelBuffer (const int clk);

virtual bool ReadCube4PipelineParametersFromFile(const char *
srcFileName);
virtual bool ReadCube4PipelineParametersFromCommandLine(int argc, char
*argv[]);
25 virtual bool SetParameter(const char * id, const char * str );
virtual bool SetDatasetToImageMatrix(const char * str );
virtual bool SetAmbientIntensity(const char * str);
virtual bool SetViewPoint(const char * str);

30 virtual void GetFinalImage();
virtual void MakePSfile(const char * comment);

ProjectionStyles projectionStyle;
CompositingStyles compositingStyle;
35 ShaderModes shaderMode;
CubeModes cubeMode;

LinearDataset *dataset;

char datasetFileName[200],
40 colorTableFileName[200],
alphaTableFileName[200],
reflectanceTableFileName[200],
imageRootFileName[200];

bool datasetLoaded,
45 colorTableLoaded,
alphaTableLoaded,
reflectanceTableLoaded;

int numOfChips, numOfPipelinesPerChip, blockSize; // c p b
50
55

```

```

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    int numOfPartialBlockBeams,      numOfBlockBeams, numOfSlices;    // Nb
NB Ns
5    int numOfClksPerBeam, numOfClksPerSlice, numOfClksPerVolume; // ccB ccS
ccV

    Vector3D<int> datasetSizeXYZ;
    Vector3D<int> datasetSizeUVW;

10    // animation setup
    int numOfFramesInAnimation;

    // view parameters
    Matrix4x4<int> Mpd[3], Mdp[3];
15    Matrix4x4<int> pipelineToDatasetMatrix, datasetToPipelineMatrix;
    Vector3D<FixPointNumber> viewPointUVW;
    Vector3D<FixPointNumber> viewPointXYZ;
    bool viewPointSet;

    // shading parameters
20    DynaArray<Light> lightSourceXYZ;
    DynaArray<Light> lightSourceUVW;
    Vector3D<double> lAmbient;
    double phongExponent;
    double Ka;
25    double Kd;
    double Ks;
    Coxel backgroundCoxel;
    Shadel backgroundShadel;

    // trilin parameters
30    int trilinWeightBits;

    // gradient parameters
    int gradientBits;

    // shader parameters
35    int shadelColorBits;
    int shadelAlphaBits;
    int mapWeightBits;
    bool reflectanceMapIP;
    bool distortionCompensation;
40    bool constantAngularResolution;
    int reflectanceMapBits;
    int atanTableBits;
    int colorTableBits;
    int alphaTableBits;

45    // Alpha Lookup Function
    double threshold;
    double maxWidth;
    double mulAlpha;

50    // compos parameters

55

```

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```

int coxelColorBits;
int coxelAlphaBits;
5 int composWeightBits;

// external DRAM memory
VoxMem          *voxMem;
CoxMem          *coxMem;

10 // Cube4 pipeline stages
Control          *control;
AddressGenerator *addrGen;
MemoryCtrl       *memCtrl;
SliceVoxelFiFoStage *sliceVoxelFiFo0;
SliceVoxelFiFoStage *sliceVoxelFiFo1;
15 TriLinZStage   *triLinZ;
TriLinYStage     *triLinY;
TriLinXStage     *triLinX;
GradYStage       *gradY;
GradXStage       *gradX;
20 GradZStage     *gradZ;
GradZLinZStage   *gradZLinZ;
GradZLinYStage   *gradZLinY;
GradZLinXStage   *gradZLinX;
ShaderStage      *shader;
25 DataSyncStage  *dataSync;
ComposBufferStage *composBuff;
ComposStage      *compos;
ComposSelXStage  *composSelX;
ComposSelYStage  *composSelY;
ComposLinXStage  *composLinX;
30 ComposLinYStage *composLinY;
FinalCoxelBuffer *finalCoxelBuff;

int clk;

// class variables for debugging tools
35 unsigned char *volumeBuffer;
int sliceSize, volumeSize, slabSize, x_step, y_step, z_step;
Vector3D<int> offset;
int partialBeam, beam, blockSlice, blockBeam, blockSlab, startClk, endClk;
bool singleImagePerFrameMode;
40

friend class Control;
friend class SliceVoxelFiFoPipeline;
friend class TriLinZStage;
friend class TriLinZPipeline;
friend class TriLinYStage;
45 friend class TriLinYPipeline;
friend class TriLinXStage;
friend class TriLinXPipeline;
friend class GradZLinZPipeline;
friend class GradZLinYPipeline;
50 friend class GradZLinXPipeline;

```

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```

5         friend class GradYPipeline;
        friend class GradXPipeline;
        friend class ShaderPipeline;
        friend class ShaderStage;
        friend class DataSyncStage;
        friend class DataSyncPipeline;
        friend class ComposStage;
10        friend class ComposPipeline;
        friend class ComposBufferStage;
        friend class ComposBufferPipeline;
        friend class ComposSelXStage;
        friend class ComposSelXPipeline;
        friend class ComposSelYStage;
15        friend class ComposSelYPipeline;
        friend class ComposLinXStage;
        friend class ComposLinXPipeline;
        friend class ComposLinYStage;
        friend class ComposLinYPipeline;
20        friend class FinalCoxelBuffer;
    }; // Cube4

    #endif          // _Cube4_h_
    :::::::::::::::
25    cube4/Cube4Debug.C
    :::::::::::::::
    // Cube4Debug.C
    // (c) Ingmar Bitter '97

30    // Copyright, Mitsubishi Electric Information Technology Center
    // America, Inc., 1997, All rights reserved.

    // to be included from Cube4.C
    // holds all the (unnecessary) :-) debug functions

35    #define RPV results.perPipelineControlFlags->valid

    void Cube4::DebugPerFrameSetup()
    {
40        partialBeam = blockSize/numOfPipelinesPerChip;
        beam = partialBeam * datasetSizeXYZ.X()/blockSize/numOfChips;
        blockSlice = beam * blockSize;
        blockBeam = blockSlice * blockSize;
        blockSlab = blockBeam * datasetSizeXYZ.Y()/blockSize;
45    } // DebugPerFrameSetup

    bool Cube4::ClkInInterval(const int clk,
                                const int pipelineStart,
                                const int startBeam,
50                                const int startSlice,
                                const int timeWindowSize)
    {
55

```

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```

startClk = pipelineStart +
    startBeam /blockSize*blockBeam + startBeam %blockSize*beam +
5   startSlice/blockSize*blockSlab + startSlice%blockSize*blockSlice;
endClk = startClk + timeWindowSize;

return (startClk <= clk && clk <= endClk);
} // ClkInInterval

10 #define ForAll_c_p( bla ) { for (c=0; c<numOfChips; ++c) { for (p=0;
    p<numOfPipelinesPerChip; ++p) { bla ; } } }
#define COUT_c_p(w, bla) for (c=0; c<numOfChips; ++c) { for (p=0;
    p<numOfPipelinesPerChip; ++p) { cout.width(w); bla } cout<<" "; }
#define COUT_p(chip, w, bla) { c=(chip); for (p=0;
15 p<numOfPipelinesPerChip; ++p) { cout.width(w); bla } cout<<" "; }

void Cube4::DebugControl(const int clk)
{
    int c,p;
    /*
20     DebugImage(control[0].results.perChipControlFlags);
    ForAll_c_p( DebugWritePixel
        (c, control[c].results.perPipelineControlFlags[p].voxelPosXYZ,
        0,
            (unsigned char) 128.0 *
25     (1.0 + control[c].results.weightsXYZ[p].X()),
            (unsigned char) 128.0 *
            (1.0 + control[c].results.weightsXYZ[p].Y())));
        */

    if (ClkInInterval(/* current clock */ clk,
30         /* pipeline start */ 0,
        /* beam/slice start */ 0, 0,
        /* time window size */ 2*beam)
        || ClkInInterval(clk, 0, blockSize-1,0,2*beam)
        || ClkInInterval(clk, 0, datasetSizeXYZ.Y()-1,blockSize-1,2*beam)
    ) {
35     cout<<endl; cout.width(4); cout << clk << " Ctrl:";
    cout<<" left="; for (c=0; c<1; ++c) cout<<control[c].leftmostChipIndex<<" ";
    cout<<" vox";
    cout<<" X="; COUT_c_p( 3, cout<<control[c].results.voxelPosXYZ[p].X(); );
    cout<<" Y="; COUT_c_p( 2, cout<<control[c].results.voxelPosXYZ[p].Y(); );
    cout<<" Z="; COUT_c_p( 2, cout<<control[c].results.voxelPosXYZ[p].Z(); );
40     //cout<<" clk=";COUT_c_p( 3,
    cout<<control[c].results.perPipelineControlFlags[p].voxelPosXYZ.Z(); );

    //cout << "\tweights[0] = " << control[0].results.weightsXYZ[0];
    //cout << "\tweights[1] = " << control[0].results.weightsXYZ[1];
45     //cout << "\tendOfRay[0] = " <<
    control[0].results.perPipelineControlFlags[0].endOfRay;
    //cout << "\tendOfRay[1] = " <<
    control[0].results.perPipelineControlFlags[1].endOfRay;
    }
}

```

50

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```

    } // DebugControl

5
void Cube4::DebugAddrGen(const int clk)
{
    int c,p;

    DebugImage(addrGen[0].results.perChipControlFlags);
10    ForAll_c_p( DebugWritePixel
                                (c,
                                addrGen[c].results.perPipelineControlFlags[p].voxelPosXYZ,
                                addrGen[c].results.address[p], 0, 0)
    );

15    if (addrGen[0].inputs.perChipControlFlags->volumeStart)
        cout << endl << "addrGen::volumeStart@inputs@" << clk << " ";
    if (addrGen[0].results.perChipControlFlags.volumeStart)
        cout << endl << "addrGen::volumeStart@results@" << clk << " ";

    int volStart=1;
20    if (ClkInInterval(/* current clock */ clk,
                        /* pipeline start */ volStart,
                        /* beam/slice start */ 0, 0,
                        /* time window size */ 2*beam)
        || ClkInInterval(clk, volStart, blockSize-1,0,2*beam)
        || ClkInInterval(clk, volStart, datasetSizeXYZ.Y()-1,blockSize-1,2*beam)
25    ) {
        cout<<endl; cout.width(4); cout << clk << " AddrGen:";
        cout<<" vox";
        cout<<" X="; COU_T_c_p( 3,
        cout<<addrGen[c].results.perPipelineControlFlags[p].voxelPosXYZ.X(); );
        cout<<" Y="; COU_T_c_p( 2,
30    cout<<addrGen[c].results.perPipelineControlFlags[p].voxelPosXYZ.Y(); );
        cout<<" Z="; COU_T_c_p( 2,
        cout<<addrGen[c].results.perPipelineControlFlags[p].voxelPosXYZ.Z(); );
        cout<<" addr[0:1]="
            <<addrGen[0].results.address[1]
35    <<"\t"<<addrGen[0].results.perPipelineControlFlags[1].voxelPosXYZ;
    }
} // DebugAddrGen

void Cube4::DebugMemCtrl(const int clk)
40 {
    int c,p;

    DebugImage(memCtrl[0].results.perChipControlFlags);
    ForAll_c_p( DebugWritePixel
                                (c,
45    memCtrl[c].results.perPipelineControlFlags[p].voxelPosXYZ,
                                memCtrl[c].results.voxel[p].raw16bit,
                                0, 0) );
}

```

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119
    if (memCtrl[0].inputs.perChipControlFlags-
>volumeStart)
5      cout << endl << "memCtrl::volumeStart@inputs@" << clk << " ";
      if (memCtrl[0].results.perChipControlFlags.volumeStart)
        cout << endl << "memCtrl::volumeStart@results@" << clk << " ";

      int volStart=2;
      if (ClkInInterval(/* current clock */ clk,
10         /* pipeline start */ volStart,
         /* beam/slice start */ 0, 0,
         /* time window size */ 2*beam)
        || ClkInInterval(clk, volStart, blockSize-2,0,3*beam)
        || ClkInInterval(clk, volStart, datasetSizeXYZ.Y()-1,blockSize-1,2*beam)
        ) {
15        cout<<endl; cout.width(4); cout << clk << " MemCtrl:";
        cout<<" ctrl";
        cout<<" X="; COUT_c_p( 3,
        cout<<memCtrl[c].results.perPipelineControlFlags[p].voxelPosXYZ.X(); );
        cout<<" Y="; COUT_c_p( 2,
        cout<<memCtrl[c].results.perPipelineControlFlags[p].voxelPosXYZ.Y(); );
20        cout<<" Z="; COUT_c_p( 2,
        cout<<memCtrl[c].results.perPipelineControlFlags[p].voxelPosXYZ.Z(); );
        cout<<" v[0:1]="
            <<memCtrl[0].results.voxel[1]
            <<memCtrl[0].results.perPipelineControlFlags[1].voxelPosXYZ;

25        /*
        cout<<"\n\t\tvvox";
        cout<<" X="; COUT_c_p( 3, cout<<memCtrl[c].results.voxel[p].raw16bit%32; );
        cout<<" Y="; COUT_c_p( 2, cout<<memCtrl[c].results.voxel[p].raw16bit/32%32;
        );
        cout<<" Z="; COUT_c_p( 2,
30        cout<<memCtrl[c].results.voxel[p].raw16bit/32/32%32; );
        cout<<" v[0:1]="
            <<memCtrl[0].results.voxel[1]
            <<memCtrl[0].results.perPipelineControlFlags[1].voxelPosXYZ;
        */
        //cout<<"\n\t\tvvox";
35        //cout<<" V="; COUT_c_p( 3, cout<<memCtrl[c].results.voxel[p].raw16bit;
        );
        /*
        cout << "in: ";
        cout << "\tout: ";
        cout << "voxel[0] = " << memCtrl[0].results.voxel[0]
40        << memCtrl[0].results.perPipelineControlFlags[0].voxelPosXYZ;
        << memCtrl[0].results.perPipelineControlFlags[1].voxelPosXYZ;
        */
      }
    } // DebugMemCtrl

45
void Cube4::DebugSliceVoxelFiFo0(const int clk)
{
    int c,p;

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55

```

```

    DebugImage(memCtrl[0].results.perChipControlFlags);
    ForAll_c_p( DebugWritePixel
5
        (c,
        sliceVoxelFiFo0[c].results.perPipelineControlFlags[p].voxelPosXYZ,
        (sliceVoxelFiFo0[c].results.voxel[p].raw16bit),0 ,0); );

    if (sliceVoxelFiFo0[0].inputs.perChipControlFlags->volumeStart)
10      cout << endl << "sliceVoxelFiFo0::volumeStart@inputs@" << clk << " ";
    if (sliceVoxelFiFo0[0].results.perChipControlFlags.volumeStart)
      cout << endl << "sliceVoxelFiFo0::volumeStart@results@" << clk << " ";

    int volStart=3;
15    if (ClkInInterval(/* current clock */ clk,
                      /* pipeline start */ volStart,
                      /* beam/slice start */ 0, 0,
                      /* time window size */ 2*beam)
        || ClkInInterval(clk, volStart, blockSize-1,0,2*beam)
        || ClkInInterval(clk, volStart, datasetSizeXYZ.Y()-1,blockSize-1,2*beam)
20    ) {
      cout<<endl; cout.width(4); cout << clk << " SliceFiFo0:";
      cout<<" ctrl";
      cout<<" X="; COU_t_c_p( 3,
      cout<<sliceVoxelFiFo0[c].results.perPipelineControlFlags[p].voxelPosXYZ.X(); );
      cout<<" Y="; COU_t_c_p( 2,
25      cout<<sliceVoxelFiFo0[c].results.perPipelineControlFlags[p].voxelPosXYZ.Y(); );
      cout<<" Z="; COU_t_c_p( 2,
      cout<<sliceVoxelFiFo0[c].results.perPipelineControlFlags[p].voxelPosXYZ.Z(); );
      cout<<" v[0:1]="
          <<sliceVoxelFiFo0[0].results.voxel[1]
30      <<sliceVoxelFiFo0[0].results.perPipelineControlFlags[1].voxelPosXYZ;
    }
  } // DebugSliceVoxelFiFo0

void Cube4::DebugSliceVoxelFiFo1(const int clk)
35
{
    int c,p;

    DebugImage(memCtrl[0].results.perChipControlFlags);
    ForAll_c_p( DebugWritePixel
40
        (c,
        sliceVoxelFiFo1[c].results.perPipelineControlFlags[p].voxelPosXYZ,
        (sliceVoxelFiFo1[c].results.voxel[p].raw16bit),0 ,0); );

    if (sliceVoxelFiFo1[0].inputs.perChipControlFlags->volumeStart)
      cout << endl << "sliceVoxelFiFo1::volumeStart@inputs@" << clk << " ";
45    if (sliceVoxelFiFo1[0].results.perChipControlFlags.volumeStart)
      cout << endl << "sliceVoxelFiFo1::volumeStart@results@" << clk << " ";

    int volStart=4+blockSlice;
50
55

```

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121
    if (ClkInInterval(/* current clock */ clk,
/* pipeline start */ volStart,
/* beam/slice start */ 0, 0,
/* time window size */ 2*beam)
    {
        || ClkInInterval(clk, volStart, blockSize-1,0,2*beam)
        || ClkInInterval(clk, volStart, datasetSizeXYZ.Y()-1,blockSize-1,2*beam)
    } {
        cout<<endl; cout.width(4); cout << clk << " SliceFiFol:";
        cout<<" ctrl";
10         cout<<" X="; COUT_c_p( 3,
        cout<<sliceVoxelFiFol[c].results.perPipelineControlFlags[p].voxelPosXYZ.X(); );
        cout<<" Y="; COUT_c_p( 2,
        cout<<sliceVoxelFiFol[c].results.perPipelineControlFlags[p].voxelPosXYZ.Y(); );
        cout<<" Z="; COUT_c_p( 2,
15         cout<<sliceVoxelFiFol[c].results.perPipelineControlFlags[p].voxelPosXYZ.Z(); );
        cout<<" v[0:1]="
            <<sliceVoxelFiFol[0].results.voxel[1]
            <<sliceVoxelFiFol[0].results.perPipelineControlFlags[1].voxelPosXYZ;
    }
} // DebugSliceVoxelFiFol
20

void Cube4::DebugTriLinZ(const int clk)
{
    int c,p;
25
    DebugImage(triLinZ[0].results.perChipControlFlags);
    ForAll_c_p(DebugWritePixel
                (c,
triLinZ[c].results.perPipelineControlFlags[p].voxelPosXYZ,
30
    (triLinZ[c].triLinZPipeline[p].results.voxel->raw16bit),0 ,0); );

    if (triLinZ[0].inputs.perChipControlFlags->volumeStart)
        cout << endl << "triLinZ::volumeStart@inputs@" << clk << " ";
    if (triLinZ[0].results.perChipControlFlags.volumeStart)
35         cout << endl << "triLinZ::volumeStart@results@" << clk << " ";

    int volStart=5+2*blockSlice;
    if (ClkInInterval(/* current clock */ clk,
/* pipeline start */ volStart;
/* beam/slice start */ 0, 0,
40 /* time window size */ 2*beam+blockSlab+blockSlice)
        || ClkInInterval(clk, volStart, blockSize-2,0,3*beam)
        || ClkInInterval(clk, volStart, datasetSizeXYZ.Y()-1,blockSize-1,2*beam)
    ) {
        cout<<endl; cout.width(4); cout << clk << " TriZ:";
45
        /*
        cout<<" vox";
        cout<<" X="; COUT_c_p( 3,
        cout<<triLinZ[c].results.perPipelineControlFlags[p].voxelPosXYZ.X(); );

```

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122

```

    cout<<" Y="; COUT_c_p( 2,
cout<<triLinZ[c].results.perPipelineControlFlags[p].voxelPosXYZ.Y(); );
    cout<<" Z="; COUT_c_p( 2,
5 cout<<triLinZ[c].results.perPipelineControlFlags[p].voxelPosXYZ.Z(); );
    cout<<" v[0:1]="
        <<Voxel(triLinZ[0].triLinZPipeline[1].a)
        <<Voxel(triLinZ[0].triLinZPipeline[1].b);
    */
10     if (0 == triLinZ[1].results.weightsXYZ[1].Z()) cout<<" out=vox A:";
        else
            cout<<" w=1 vox A:";
            cout<<" X="; COUT_c_p(3, cout<<Voxel(triLinZ[c].triLinZPipeline[p].a).X());
        );
            cout<<" Y="; COUT_c_p(2, cout<<Voxel(triLinZ[c].triLinZPipeline[p].a).Y());
15        );
            cout<<" Z="; COUT_c_p(2, cout<<Voxel(triLinZ[c].triLinZPipeline[p].a).Z());
        );
            cout<<"
Z="<<triLinZ[1].results.perPipelineControlFlags[1].voxelPosXYZ.Z() << "(Ctrl)";
            if (0 == triLinZ[1].results.weightsXYZ[1].Z()) cout<<"\n\t w=0 vox
20 B:"; else
            cout<<"\n\t out=vox B:";
            cout<<" X="; COUT_c_p(3, cout<<Voxel(triLinZ[c].triLinZPipeline[p].b).X());
        );
            cout<<" Y="; COUT_c_p(2, cout<<Voxel(triLinZ[c].triLinZPipeline[p].b).Y());
        );
25        cout<<" Z="; COUT_c_p(2, cout<<Voxel(triLinZ[c].triLinZPipeline[p].b).Z());
        );
    }
} // DebugTriLinZ

30 void Cube4::DebugTriLinY(const int clk)
{
    int c,p;

    DebugImage(triLinY[0].results.perChipControlFlags);
    ForAll_c_p(DebugWritePixel
35                (c,
triLinY[c].results.perPipelineControlFlags[p].voxelPosXYZ,

                (triLinY[c].triLinYPipeline[p].results.voxel->raw16bit),0 ,0));

40    if (triLinY[0].inputs.perChipControlFlags->volumeStart)
        cout << endl << "triLinY::volumeStart@inputs@" << clk << " ";
    if (triLinY[0].results.perChipControlFlags.volumeStart)
        cout << endl << "triLinY::volumeStart@results@" << clk << " ";

    int volStart=6+2*blockSlice+beam;
45    if (ClkInInterval(/* current clock */ clk,
                        /* pipeline start */ volStart,
                        /* beam/slice start */ 1, 1,
                        /* time window size */ blockSize)
50
55

```

```

123
    || ClkInInterval(clk, volStart,      datasetSizeXYZ.Y()-2, blockSize-
1,2*blockSize+3*beam)
    || ClkInInterval(clk, volStart, blockSize,blockSize,blockSize+2*beam)
5    ) {
        cout<<endl; cout.width(4); cout << clk << " TriY:";
        //cout<<" vox";
        //cout<<" X=";      COUT_c_p( 3,
        cout<<triLinY[c].results.perPipelineControlFlags[p].voxelPosXYZ.X(); );
        //cout<<" Y=";      COUT_c_p( 2,
10        cout<<triLinY[c].results.perPipelineControlFlags[p].voxelPosXYZ.Y(); );
        //cout<<" Z=";      COUT_c_p( 2,
        cout<<triLinY[c].results.perPipelineControlFlags[p].voxelPosXYZ.Z(); );
        //cout<<" v[0:1]="
        //    <<Voxel(triLinY[0].triLinYPipeline[1].a)
15        //    <<Voxel(triLinY[0].triLinYPipeline[1].b)
        //
        <<"Wy="<<triLinY[0].triLinYPipeline[1].results.weightsXYZ->Y();
        if (0 == triLinY[1].results.weightsXYZ[1].Z()) cout<<" out=vox A:";
        else
            cout<<" w=1 vox A:";
20        if (!triLinY[1].triLinYPipeline[1].results.perPipelineControlFlags->
        >valid) cout<<"invalid"; else {
            cout<<" X="; COUT_c_p(3,
            cout<<Voxel(triLinY[c].triLinYPipeline[p].a).X(); );
            cout<<" Y="; COUT_c_p(2,
            cout<<Voxel(triLinY[c].triLinYPipeline[p].a).Y(); );
25            cout<<" Z="; COUT_c_p(2,
            cout<<Voxel(triLinY[c].triLinYPipeline[p].a).Z(); );
        }
        if (0 == triLinY[1].results.weightsXYZ[1].Z()) cout<<"\n\t   w=0 vox
        B:"; else
30            cout<<"\n\t   out=vox B:";
            if (!triLinY[1].triLinYPipeline[1].results.perPipelineControlFlags->
            >valid) cout<<"invalid"; else {
                cout<<" X="; COUT_c_p(3,
                cout<<Voxel(triLinY[c].triLinYPipeline[p].b).X(); );
                cout<<" Y="; COUT_c_p(2,
35                cout<<Voxel(triLinY[c].triLinYPipeline[p].b).Y(); );
                cout<<" Z="; COUT_c_p(2,
                cout<<Voxel(triLinY[c].triLinYPipeline[p].b).Z(); );
                cout<<"
                Z="<<triLinY[1].results.perPipelineControlFlags[1].voxelPosXYZ.Z() << "(Ctrl)";
40            }
        } // DebugTriLinY

void Cube4::DebugTriLinX(const int clk)
45 {
    int c,p;
    DebugImage(triLinX[0].results.perChipControlFlags);
    ForAll_c_p(DebugWritePixel
50
55

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124

```

(c,
triLinX[c].results.perPipelineControlFlags[p].voxelPosXYZ,
5      (triLinX[c].triLinXPipeline[p].results.voxel->raw16bit),0,0));

if (triLinX[0].inputs.perChipControlFlags->volumeStart)
    cout << endl << "triLinX::volumeStart@inputs@" << clk << " ";
if (triLinX[0].results.perChipControlFlags.volumeStart)
10    cout << endl << "triLinX::volumeStart@results@" << clk << " ";

int volStart=6 + 2*blockSlice + beam;
if (ClkInInterval(/* current clock */ clk,
                  /* pipeline start */ volStart,
                  /* beam/slice start */ 1, 1,
15                  /* time window size */ blockSize)
    || ClkInInterval(clk, volStart, datasetSizeXYZ.Y()-2,blockSize-
1,2*blockSize+3*beam)
    || ClkInInterval(clk, volStart, blockSize,blockSize,blockSize+2*beam)
    ) {
    cout<<endl; cout.width(4); cout << clk << " TriX:";
20    //cout<<" X="; COUT_c_p(3,
    cout<<triLinX[c].results.perPipelineControlFlags[p].voxelPosXYZ.X(); );
    //cout<<" Y="; COUT_c_p(2,
    cout<<triLinX[c].results.perPipelineControlFlags[p].voxelPosXYZ.Y(); );
    //cout<<" Z="; COUT_c_p(2,
25    cout<<triLinX[c].results.perPipelineControlFlags[p].voxelPosXYZ.Z(); );
    if (0 == triLinX[1].results.weightsXYZ[1].Z()) cout<<" out=vox A:";
    else
        cout<<" w=1 vox A:";
        if (!triLinX[1].triLinXPipeline[1].results.perPipelineControlFlags-
>valid) cout<<"invalid"; else {
30        cout<<" X="; COUT_c_p(3, if
        (!triLinX[c].triLinXPipeline[p].results.perPipelineControlFlags->valid)
        cout<<"I"; else cout<<Voxel(triLinX[c].triLinXPipeline[p].a).X(); );
        cout<<" Y="; COUT_c_p(2, if
        (!triLinX[c].triLinXPipeline[p].results.perPipelineControlFlags->valid)
        cout<<"I"; else cout<<Voxel(triLinX[c].triLinXPipeline[p].a).Y(); );
35        cout<<" Z="; COUT_c_p(2, if
        (!triLinX[c].triLinXPipeline[p].results.perPipelineControlFlags->valid)
        cout<<"I"; else cout<<Voxel(triLinX[c].triLinXPipeline[p].a).Z(); );
        }
        if (0 == triLinX[1].results.weightsXYZ[1].Z()) cout<<"\n\t w=0 vox
40 B:"; else
        cout<<"\n\t out=vox B:";
        if (!triLinX[1].triLinXPipeline[1].results.perPipelineControlFlags-
>valid) cout<<"invalid"; else {
        cout<<" X="; COUT_c_p(3, if
        (!triLinX[c].triLinXPipeline[p].results.perPipelineControlFlags->valid)
        cout<<"I"; else cout<<Voxel(triLinX[c].triLinXPipeline[p].b).X(); );
45        cout<<" Y="; COUT_c_p(2, if
        (!triLinX[c].triLinXPipeline[p].results.perPipelineControlFlags->valid)
        cout<<"I"; else cout<<Voxel(triLinX[c].triLinXPipeline[p].b).Y(); );
50
55

```

```

125
        cout<<" Z=";          COUT_c_p(2, if
(!triLinX[c].triLinXPipeline[p].results.perPipelineControlFlags->valid)
5      cout<<"I"; else cout<<Voxel(triLinX[c].triLinXPipeline[p].b).Z(); );
        cout<<"
Z="<<triLinX[1].results.perPipelineControlFlags[1].voxelPosXYZ.Z() << "(Ctrl)";
    }
/*
    cout<<" I=";
10      COUT_p( 0,2,
cout<<triLinX[c].inputs.perPipelineControlFlags[p].voxelPosXYZ.Z(); );
    cout<<"PBF=";
    for (int partialBeamDelay=blockSize/numOfPipelinesPerChip - 1;
partialBeamDelay>= 0; --partialBeamDelay)
        COUT_p( 0,2,
15      cout<<triLinX[c].triLinXPipeline[p].partialBeamPerPipelineControlFlagsFiFo.Peek(
partialBeamDelay).voxelPosXYZ.Z(); );
    cout<<"CDF=";
    for (int communicationDelay=2 - 1; communicationDelay>= 0; --
communicationDelay)
        COUT_p( 0,2,
20      cout<<triLinX[c].triLinXPipeline[p].communicationDelayPerPipelineControlFlagsFiF
o.Peek(communicationDelay).voxelPosXYZ.Z(); );
    cout<<"CR=";
    COUT_p( 0,2,
cout<<triLinX[c].computation.perPipelineControlFlags[p].voxelPosXYZ.Z(); );
    cout.width(2) ;
25      cout<<triLinX[c].computation.perPipelineControlFlags[p].voxelPosXYZ.Z();
    cout<<" CV=";
    cout.width(2) ;
cout<<triLinX[c].readBufferPerPipelineControlFlags.voxelPosXYZ.Z();
    cout.width(2) ;
30      cout<<triLinX[c].communicationPerPipelineControlFlags.voxelPosXYZ.Z();
    */
    //cout<<" a="; cout<<Voxel(triLinX[0].triLinXPipeline[1].a);
    //cout<<" b="; cout<<Voxel(triLinX[0].triLinXPipeline[1].b);
    }
} // DebugTriLinX
35

void Cube4::DebugGradY(const int clk)
{
    /*
    int blockBeamDelay = blockSize / numOfPipelinesPerChip;
40      int partialBeamsPerBlockSlice = blockSize * blockSize /
numOfPipelinesPerChip;

    DebugImage(5+ 2*blockBeamDelay + 2*partialBeamsPerBlockSlice,
gradY[0].results.perChipControlFlags);

45      for (int c=0; c<numOfChips; ++c) {
        for (int p=0; p<numOfPipelinesPerChip; ++p){
            DebugWritePixel
            (c, p, (unsigned char)
50
55

```



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126
    (0.5 * (255.0 +
        gradY[c].results.gy[p])) , 0 , 0);
    // (c, p, (unsigned char)
5    // gradY[c].gradYPipeline[p].results.voxel->raw16bit);

    }
    }
    */
10    if (21*10<clk && clk<21*10 + 21*14) {
        cout <<endl<<clk<<"\tGradY: ";
        cout << "in: ";
        cout << "voxel[2] " << gradY[0].inputs.voxel[2] << " ";
        cout << "\tcurrent[2] " << gradY[0].gradYPipeline[2].current.raw16bit;
        cout << "\tlastFiFoOut[2] " << gradY[0].gradYPipeline[2].lastFiFoOut.raw16bit;
        cout << "\tout: ";
15        cout << "gy[2] " << gradY[0].results.gy[2];
        cout << "\tvoxel[2] " << gradY[0].results.voxel[2];
        cout << "\tVolStart " << gradY[0].results.perChipControlFlags.volumeStart <<
            " " << gradZLinY[0].results.perChipControlFlags.volumeStart;
    }
20    } // DebugGradY

void Cube4::DebugGradX(const int clk)
{
    /*
25    int blockBeamDelay = blockSize / numOfPipelinesPerChip;
    int partialBeamsPerBlockSlice = blockSize * blockSize /
numOfPipelinesPerChip;

    DebugImage(6 + 2*blockBeamDelay + 2*partialBeamsPerBlockSlice,
gradX[0].results.perChipControlFlags);

30    for (int c=0; c<numOfChips; ++c) {
        for (int p=0; p<numOfPipelinesPerChip; ++p){
            DebugWritePixel
            (c, p, (unsigned char)
            (0.5 * (255.0 + gradX[c].results.gy[p])) , 0 , 0);
35            // (c, p, (unsigned char)
            // gradY[c].gradYPipeline[p].results.voxel->raw16bit);

            }
            }
            */
40    if (10*21<clk && clk<11*21+5) {
        cout <<endl<<clk<<"\tGradX: ";
        cout << "in: ";
        //cout << "left[2] " << gradX[0].inputs.voxel[1].raw16bit << " ";
        //cout << "\tcurrent[2] " << gradX[0].inputs.voxel[2].raw16bit;
        //cout << "\tright[2] " << gradX[0].inputs.voxel[3].raw16bit;
45        cout << "\tWeights[10] " << gradX[0].inputs.weightsXYZ[10];
        cout << "\tout: ";
        cout << "\tWeights[10] " << gradX[0].results.weightsXYZ[10];
        //cout << "gx[2] " << gradX[0].results.gx[2];

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127
    //cout << "\tvoxel[2] " << gradX[0].results.voxel[2];
    }
    if (gradX[0].results.perChipControlFlags.volumeStart)
5      cout << endl << "gradX::volumeStart@" << clk << " ";
    } // DebugGradX

void Cube4::DebugGradZ(const int clk)
10 {
    DebugImage(gradZ[0].results.perChipControlFlags);
    for (int c=0; c<numOfChips; ++c) {
        for (int p=0; p<numOfPipelinesPerChip; ++p) {
            DebugWritePixel
15              (c, gradZ[c].results.perPipelineControlFlags[p].voxelPosXYZ,
                (unsigned char)
                //(gradZ[c].inputs.voxel0[p].raw16bit), 0, 0);
                (255 + gradZ[c].results.gz[p]) / 2, 0, 0);
        }
    }

20    if (gradZ[0].inputs.perChipControlFlags->volumeStart)
        cout << endl << "GradZ::volumeStart@inputs@" << clk << " ";
    if (gradZ[0].results.perChipControlFlags.volumeStart)
        cout << endl << "GradZ::volumeStart@results@" << clk << " ";

25    int volStart=19;
    if (volStart+0*(2*8*8*3)<=clk && clk<volStart+10+1*(2*8*8*3)) {
        cout << endl << clk << "\tGradZ: ";
        cout << "in: ";
        cout << "voxel0[1] " << gradZ[0].gradZPipeline[1].delayVoxel0again << "
30 ";
        cout << "\tvoxel1[1] " << gradZ[0].gradZPipeline[1].inputs.voxel1;
        //cout << "\tweightsXYZ[1] " << gradZ[0].inputs.weightsXYZ[1];
        cout << "\tout: ";
        cout << "gz[1] " << gradZ[0].gradZPipeline[1].results.gz;
        //cout << "\tweightsXYZ[1] " << gradZ[0].results.weightsXYZ[1];
35    }
    } // DebugGradZ

void Cube4::DebugGradZLinZ(const int clk)
40 {
    DebugImage(gradZLinZ[0].results.perChipControlFlags);
    for (int c=0; c<numOfChips; ++c) {
        for (int p=0; p<numOfPipelinesPerChip; ++p) {
            DebugWritePixel
45              (c, gradZLinZ[c].results.perPipelineControlFlags[p].voxelPosXYZ,
                (unsigned char)
                //(gradZLinZ[c].inputs.voxel0[p].raw16bit), 0, 0);
                (255 + gradZLinZ[c].results.gz[p]) / 2, 0, 0);
        }
    }

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    if
    (gradZLinZ[0].inputs.perChipControlFlags->volumeStart)
5      cout << endl << "GradZLinZ::volumeStart@inputs@" << clk << " ";
      if (gradZLinZ[0].results.perChipControlFlags.volumeStart)
        cout << endl << "GradZLinZ::volumeStart@results@" << clk << " ";

      int volStart=19;
      if (volStart+0*(2*8*8*3)<=clk && clk<volStart+10+1*(2*8*8*3)) {
10        cout << endl << clk << "\tGradZLinZ: ";
        cout << "in: ";
        cout << "gz[2] " <<gradZLinZ[0].inputs.gz[2]
          <<gradZLinZ[0].inputs.perPipelineControlFlags[2].voxelPosXYZ<< " ";
        //cout << "\tweightsXYZ[1] " <<gradZLinZ[0].inputs.weightsXYZ[2];
        cout << "\tout: ";
15        cout << "a[2] " <<gradZLinZ[0].gradZLinZPipeline[2].a<< " ";
        cout << "b[2] " <<gradZLinZ[0].gradZLinZPipeline[2].b;
        cout << "\tgzResult[2] " <<gradZLinZ[0].results.gz[2]
          <<gradZLinZ[0].results.perPipelineControlFlags[2].voxelPosXYZ;
        cout << "\tweightsXYZ[2] " <<gradZLinZ[0].results.weightsXYZ[2];
20      }
    } // DebugGradZLinZ

void Cube4::DebugGradZLinY(const int clk)
{
25  DebugImage(gradZLinZ[0].results.perChipControlFlags);
  for (int c=0; c<numOfChips; ++c) {
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
      DebugWritePixel
        (c, gradZLinZ[c].results.perPipelineControlFlags[p].voxelPosXYZ,
30        (unsigned char)
          (255 + gradZLinY[0].results.gz[p]) / 2, 0, 0);
    }
  }

  if (gradZLinY[0].inputs.perChipControlFlags->volumeStart)
35    cout << endl << "GradZLinY::volumeStart@inputs@" << clk << " ";
  if (gradZLinY[0].results.perChipControlFlags.volumeStart)
    cout << endl << "GradZLinY::volumeStart@results@" << clk << " ";

  int volStart=19;
  if (volStart+0*(2*8*8*3)<=clk && clk<volStart+10+1*(2*8*8*3)) {
40    cout << endl << clk << "\tGradZLinY: ";
    cout << "in: ";
    cout << "gz[1] " <<gradZLinY[0].inputs.gz[1]
      <<gradZLinY[0].inputs.perPipelineControlFlags[1].voxelPosXYZ<< " ";
    cout << "\tweightsXYZ[1] " <<gradZLinY[0].inputs.weightsXYZ[1];
45    cout << "\tout: ";
    cout << "gz[1] " <<gradZLinY[0].results.gz[1]
      <<gradZLinY[0].results.perPipelineControlFlags[1].voxelPosXYZ;
    cout << "\tweightsXYZ[1] " <<gradZLinY[0].results.weightsXYZ[1];
50  }
} // DebugGradZLinY

```

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```

5 void Cube4::DebugGradZLinX(const int clk)
{
    /*
        int blockBeamDelay = blockSize / numOfPipelinesPerChip;
        int partialBeamsPerBlockSlice = blockSize * blockSize /
10 numOfPipelinesPerChip;

        DebugImage(5 + blockBeamDelay + 2 * partialBeamsPerBlockSlice,
gradZLinX[0].results.perChipControlFlags);
        for (int c=0; c<numOfChips; ++c) {
            for (int p=0; p<numOfPipelinesPerChip; ++p) {
15 DebugWritePixel
(c, p, (unsigned char)
(255 + gradZLinX[0].results.gz[p]) / 2, 0, 0);
            }
        }
    */
20 if (3*21<clk && clk<4*21+5) {
    cout << endl << clk << "\tGradZLinX: ";
    cout << "in: ";
    cout << "gz[14] " << gradZLinX[0].inputs.gz[14] << " ";
    cout << "\tgz[15] " << gradZLinX[0].inputs.gz[15] << " ";
25 cout << "\tweightsXYZ[14] " << gradZLinX[0].inputs.weightsXYZ[14];
    cout << "\tout: ";
    cout << "gz[14] " << gradZLinX[0].results.gz[14];
    }
} // DebugGradZLinX
30

void Cube4::DebugShader(const int clk)
{
    int c,p;
35 DebugImage(shader[0].results.perChipControlFlags);
    ForAll_c_p(DebugWritePixel
(c,
shader[c].results.perPipelineControlFlags[p].voxelPosXYZ,
shader[c].results.shadel[p].a, 0
,0));
40 //((0.5 * (255.0 + shader[c].inputs.gz[p])));
//((0.5 * (255.0 + shader[c].inputs.gy[p])));
//((0.5 * (255.0 + shader[c].inputs.gx[p])));
//shader[c].inputs.voxel[p].raw16bit);
//((unsigned char) (255 * shader[c].results.shadel[p].r),
45 //((unsigned char) (255 * shader[c].results.shadel[p].g),
//((unsigned char) (255 * shader[c].results.shadel[p].b));

    if (shader[0].inputs.perChipControlFlags->volumeStart)
        cout << endl << "shader::volumeStart@inputs@" << clk << " ";
50 if (shader[0].results.perChipControlFlags.volumeStart)
        cout << endl << "shader::volumeStart@results@" << clk << " ";

```

```

int volStart=10 + 2*blockSlice + beam + partialBeam;
5   if (ClkInInterval(/* current clock */ clk,
                      /* pipeline start */ volStart,
                      /* beam/slice start */ 1, 1,
                      /* time window size */ blockSize)
      || ClkInInterval(clk, volStart, datasetSizeXYZ.Y()-3,blockSize-
1,2*blockSize+3*beam)
10  || ClkInInterval(clk, volStart, blockSize,blockSize,blockSize+2*beam)
    ) {
    cout<<endl; cout.width(4); cout << clk << " Shader:";
    if (!shader[1].shaderPipeline[1].results.perPipelineControlFlags-
>valid) cout<<"invalid"; else {
        cout<<" X="; COUT_c_p(3, if (!shader[c].shaderPipeline[p].RPV)
15  cout<<"I"; else cout<<shader[c].shaderPipeline[p].results.shadel->r; );
        cout<<" Y="; COUT_c_p(2, if (!shader[c].shaderPipeline[p].RPV)
cout<<"I"; else cout<<shader[c].shaderPipeline[p].results.shadel->g; );
        cout<<" Z="; COUT_c_p(2, if (!shader[c].shaderPipeline[p].RPV)
cout<<"I"; else cout<<shader[c].shaderPipeline[p].results.shadel->b; );
20    }

    //cout<<" vox";
    //cout<<" X="; COUT_c_p(3,
cout<<shader[c].results.perPipelineControlFlags[p].voxelPosXYZ.X(); );
    //cout<<" Y="; COUT_c_p(2,
25  cout<<shader[c].results.perPipelineControlFlags[p].voxelPosXYZ.Y(); );
    //cout<<" Z="; COUT_c_p(2,
cout<<shader[c].results.perPipelineControlFlags[p].voxelPosXYZ.Z(); );

    //cout << "in: ";
    //cout << "voxel[5] "<<shader[0].inputs.voxel[5].raw16bit << " ";
30  //cout << "\tWeights[5] "<<shader[0].inputs.weightsXYZ[5];
    //cout << "\tgx[5] "<<shader[0].inputs.gx[5] << " ";
    //cout << "\tgy[5] "<<shader[0].inputs.gy[5] << " ";
    //cout << "\tgz[5] "<<shader[0].inputs.gz[5] << " ";
    //cout << "\tout: ";
35  //cout << "shadel[5]: "<<shader[0].results.shadel[5];
    }
} // DebugShader

void Cube4::DebugDataSync(const int clk)
40 {
    int c,p;
    DebugImage(dataSync[0].results.perChipControlFlags);
    ForAll_c_p(DebugWritePixel
                (c,
45  dataSync[c].results.perPipelineControlFlags[p].voxelPosXYZ,
                dataSync[c].results.shadel[p].a, 0
,0));

    if (dataSync[0].inputs.perChipControlFlags->volumeStart)
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    cout << endl << "dataSync::volumeStart@inputs@" << clk
    << " ";
    if (dataSync[0].results.perChipControlFlags.volumeStart)
5      cout << endl << "dataSync::volumeStart@results@" << clk << " ";

    int volStart=17 + 2*blockSlice + beam + partialBeam;
    if (ClkInInterval(/* current clock */ clk,
                      /* pipeline start */ volStart,
10      /* beam/slice start */ 1, 1,
                      /* time window size */ blockSize)
        || ClkInInterval(clk, volStart, datasetSizeXYZ.Y()-3,blockSize-
1,2*blockSize+3*beam)
        || ClkInInterval(clk, volStart, blockSize,blockSize,blockSize+2*beam)
        ) {
15      cout<<endl; cout.width(4); cout << clk << " DataSync:";
          if
(!dataSync[1].dataSyncPipeline[1].results.perPipelineControlFlags->valid)
cout<<"invalid"; else {
            cout<<" X="; COUT_c_p(3, if
(!dataSync[c].dataSyncPipeline[p].RPV) cout<<"I"; else
20      cout<<dataSync[c].dataSyncPipeline[p].results.shadel->r; );
            cout<<" Y="; COUT_c_p(2, if
(!dataSync[c].dataSyncPipeline[p].RPV) cout<<"I"; else
cout<<dataSync[c].dataSyncPipeline[p].results.shadel->g; );
            cout<<" Z="; COUT_c_p(2, if
25      (!dataSync[c].dataSyncPipeline[p].RPV) cout<<"I"; else
cout<<dataSync[c].dataSyncPipeline[p].results.shadel->b; );
            }
            //cout<<" vox";
            //cout<<" X="; COUT_c_p(3,
cout<<dataSync[c].results.perPipelineControlFlags[p].voxelPosXYZ.X(); );
            //cout<<" Y="; COUT_c_p(2,
30      cout<<dataSync[c].results.perPipelineControlFlags[p].voxelPosXYZ.Y(); );
            //cout<<" Z="; COUT_c_p(2,
cout<<dataSync[c].results.perPipelineControlFlags[p].voxelPosXYZ.Z(); );

            //cout << "in: ";
35      //      cout << "shadel[5]: " <<dataSync[0].inputs.shadel[5];
            //cout << "\tout: ";
            //cout << "shadel[5]: " <<dataSync[0].results.shadel[5];
            //cout << "\tWeights[5] " <<dataSync[0].results.weightsXYZ[5];
        }
    } // DebugDataSync
40

void Cube4::DebugComposBuffer(const int clk)
{
    int c,p;
    DebugImage(composBuff[0].results.perChipControlFlags);
45      ForAll_c_p(DebugWritePixel
                      (c,
                      composBuff[c].results.perPipelineControlFlags[p].voxelPosXYZ,
50
55

```

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0, 0));
/*
5   DebugImage(*composBuff[0].inputs.perChipControlFlags);
   ForAll_c_p(DebugWritePixel
               (c,
composBuff[c].inputs.perPipelineControlFlags[p].voxelPosXYZ,
               composBuff[c].inputs.coxel[p].a,
10  0,0));
   */
   if (composBuff[0].inputs.perChipControlFlags->volumeStart)
       cout << endl << "composBuff::volumeStart@inputs@" << clk << " ";
   if (composBuff[0].results.perChipControlFlags.volumeStart)
       cout << endl << "composBuff::volumeStart@results@" << clk << " ";
15
   int volStart=15 + 3*blockSlice + 3*beam + 3*partialBeam;
   if (ClkInInterval(/* current clock */ clk,
                   /* pipeline start */ volStart,
                   /* beam/slice start */ 0, 0,
                   /* time window size */ 6*beam+blockSlab+3*blockSize)
20   || ClkInInterval(clk, volStart, blockSize-1,0,2*beam)
   || ClkInInterval(clk, volStart, blockSize+blockSize-2,0,5*beam+blockSize)
   || ClkInInterval(clk, volStart, datasetSizeXYZ.Y()-1,blockSize-1,2*beam)
   ) {
       cout<<endl; cout.width(3); cout << clk << " ComposBuff:";
25       //cout<<" X="; COUT_c_p(3, cout<<composBuff[c].results.coxel[p].r; );
       //cout<<" Y="; COUT_c_p(2, cout<<composBuff[c].results.coxel[p].g; );
       //cout<<" Z="; COUT_c_p(2, cout<<composBuff[c].results.coxel[p].b; );
       //cout<<"\n\t Ctrl: ";
       cout<<" X="; COUT_c_p(3,
30       cout<<composBuff[c].results.perPipelineControlFlags[p].voxelPosXYZ.X(); );
       cout<<" Y="; COUT_c_p(2,
       cout<<composBuff[c].results.perPipelineControlFlags[p].voxelPosXYZ.Y(); );
       cout<<" Z="; COUT_c_p(2,
       cout<<composBuff[c].results.perPipelineControlFlags[p].voxelPosXYZ.Z(); );
       }
   } // DebugComposBuffer
35

void Cube4::DebugComposSelX(const int clk)
{
   int c,p;
   DebugImage(composSelX[0].results.perChipControlFlags);
40   ForAll_c_p(DebugWritePixel
               (c,
composSelX[c].results.perPipelineControlFlags[p].voxelPosXYZ,
               composSelX[c].results.coxel[p].a, 0
,0));
45
       //128.0 * (1.0 + composSelX[c].inputs.weightsXYZ[p].X()),
       //128.0 * (1.0 + composSelX[c].inputs.weightsXYZ[p].Y()));

   if (composSelX[0].inputs.perChipControlFlags->volumeStart)
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        cout << endl <<                                "composSelX::volumeStart@inputs@" <<
        clk << " ";
        if (composSelX[0].results.perChipControlFlags.volumeStart)
5         cout << endl << "composSelX::volumeStart@results@" << clk << " ";

        int volStart=13 + 2*blockSlice + beam;
        if (ClkInInterval(/* current clock */ clk,
                           /* pipeline start */ volStart,
10         /* beam/slice start */ 0, 0,
                           /* time window size */ 2*blockSlice+6*beam)
            || ClkInInterval(clk, volStart, blockSize-1,0,2*beam)
            || ClkInInterval(clk, volStart, datasetSizeXYZ.Y()-1,blockSize-1,2*beam)
        ) {
            cout<<endl; cout.width(3); cout << clk << " ComposSelX:";
15         //cout<<" X="; COUT_c_p(3, cout<<composSelX[c].results.coxel[p].r; );
            //cout<<" Y="; COUT_c_p(2, cout<<composSelX[c].results.coxel[p].g; );
            //cout<<" Z="; COUT_c_p(2, cout<<composSelX[c].results.coxel[p].a; );

            //cout<<" I=";
            //COUT_p( 0,2,
20         cout<<composSelX[c].inputs.perPipelineControlFlags[p].voxelPosXYZ.Z(); );
            //cout<<"PBF=";
            //for (int partialBeamDelay=blockSize/numOfPipelinesPerChip - 1;
            partialBeamDelay>= 0; --partialBeamDelay)
            // COUT_p( 0,2,
25         cout<<composSelX[c].composSelXPipeline[p].partialBeamPerPipelineControlFlagsFiFo
            .Peek(partialBeamDelay).voxelPosXYZ.Z(); );
            //cout<<"CDF=";
            //for (int communicationDelay=2 - 1; communicationDelay>= 0; --
            communicationDelay)
            // COUT_p( 0,2,
30         cout<<composSelX[c].composSelXPipeline[p].communicationDelayPerPipelineControlFl
            agsFiFo.Peek(communicationDelay).voxelPosXYZ.Z(); );
            //cout<<"CR=";
            //COUT_p( 0,2,
            cout<<composSelX[c].computation.perPipelineControlFlags[p].voxelPosXYZ.Z(); );
            //cout.width(2) ;
35         cout<<composSelX[c].computation.perPipelineControlFlags[p].voxelPosXYZ.Z();
            //cout<<" CV=";
            //cout.width(2) ;
            cout<<composSelX[c].readBufferPerPipelineControlFlags.voxelPosXYZ.Z();
            //cout.width(2) ;
            cout<<composSelX[c].communicationPerPipelineControlFlags.voxelPosXYZ.Z();
40

            p=numOfPipelinesPerChip-1;

            cout<<"coxelMiddle[1]:
            "<<*composSelX[0].composSelXPipeline[p].inputs.coxelMiddle
            <<"
45         "<<composSelX[0].composSelXPipeline[p].inputs.perPipelineControlFlags-
            >voxelPosXYZ;
            cout<<"\tcoxelRight[1]:
            "<<*composSelX[0].composSelXPipeline[p].inputs.coxelRight;

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//cout << "\tWeights[1]
*<<composSelX[0].composSelXPipeline[p].inputs.weightsXYZ;
cout<< "\tCtrlX[1]
5  *<<TypeStr::XStepDirection[composSelX[0].composSelXPipeline[p].inputs.perChipCon
    trolFlags->xStep];
    cout<<"\tout: ";
    cout<<"coxel[1]: "<<composSelX[0].results.coxel[p]

10     <<composSelX[0].results.perPipelineControlFlags[p].voxelPosXYZ;
    }
} // DebugComposSelX

void Cube4::DebugComposLinX(const int clk)
15 {
    if (composLinX[0].inputs.perChipControlFlags->volumeStart)
        cout << endl << "composLinX::volumeStart@inputs@" << clk << " ";
    if (composLinX[0].results.perChipControlFlags.volumeStart)
        cout << endl << "composLinX::volumeStart@results@" << clk << " ";

20     int p;
    int volStart=18 + 2*blockSlice + beam;
    if (ClkInInterval(/* current clock */ clk,
                      /* pipeline start */ volStart,
                      /* beam/slice start */ 0, 0,
                      /* time window size */ 2*blockSlice+6*beam)
25     ||| ClkInInterval(clk, volStart, blockSize-1,0,2*beam)
     ||| ClkInInterval(clk, volStart, datasetSizeXYZ.Y()-1,blockSize-1,2*beam)
    ) {
        cout<<endl; cout.width(3); cout << clk << " ComposLinX:";
        //cout<<" X="; COUT_c_p(3, cout<<composLinX[c].results.coxel[p].r; );
        //cout<<" Y="; COUT_c_p(2, cout<<composLinX[c].results.coxel[p].g; );
30        //cout<<" Z="; COUT_c_p(2, cout<<composLinX[c].results.coxel[p].a; );

        //cout<<" I=";
        //COUT_p( 0,2,
        cout<<composLinX[c].inputs.perPipelineControlFlags[p].voxelPosXYZ.Z(); );
        //cout<<" PBF=";
35        //for (int partialBeamDelay=blockSize/numOfPipelinesPerChip - 1;
        partialBeamDelay>= 0; --partialBeamDelay)
            // COUT_p( 0,2,
            cout<<composLinX[c].composLinXPipeline[p].partialBeamPerPipelineControlFlagsFiFo
            .Peek(partialBeamDelay).voxelPosXYZ.Z(); );
40        //cout<<"CDF=";
        //for (int communicationDelay=2 - 1; communicationDelay>= 0; --
        communicationDelay)
            // COUT_p( 0,2,
            cout<<composLinX[c].composLinXPipeline[p].communicationDelayPerPipelineControlFl
            agsFiFo.Peek(communicationDelay).voxelPosXYZ.Z(); );
45        //cout<<"CR=";
        //COUT_p( 0,2,
        cout<<composLinX[c].computation.perPipelineControlFlags[p].voxelPosXYZ.Z(); );

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        //cout.width(2) ;
        cout<<composLinX[c].computation.perPipelineControlFlags[p].voxelPosXYZ.Z();
        //cout<<" CV=";
5        //cout.width(2) ;
        cout<<composLinX[c].readBufferPerPipelineControlFlags.voxelPosXYZ.Z();
        //cout.width(2) ;
        cout<<composLinX[c].communicationPerPipelineControlFlags.voxelPosXYZ.Z();

10        p=0;

        cout<<"coxelLeft[1]:
        "<<*composLinX[0].composLinXPipeline[p].inputs.coxelLeft;
        cout<<"\tcoxelMiddle[1]:
        "<<*composLinX[0].composLinXPipeline[p].inputs.coxelMiddle
15        <<"
        "<<composLinX[0].composLinXPipeline[p].inputs.perPipelineControlFlags-
        >voxelPosXYZ;
        //cout << "\tWeights[1]
        "<<*composLinX[0].composLinXPipeline[p].inputs.weightsXYZ;
        cout<< "\tCtrlX[1]
20        "<<TypeStr::XStepDirection[composLinX[0].composLinXPipeline[p].inputs.perChipCon
        trolFlags->xStep];
        cout<<"\tout: ";
        cout<<"coxel[1]: "<<composLinX[0].results.coxel[p]

        <<composLinX[0].results.perPipelineControlFlags[p].voxelPosXYZ;
25    }
    } // DebugComposLinX

void Cube4::DebugComposSely(const int clk)
{
30    if (composSely[0].inputs.perChipControlFlags->volumeStart)
        cout << endl << "composSely::volumeStart@inputs@" << clk << " ";
    if (composSely[0].results.perChipControlFlags.volumeStart)
        cout << endl << "composSely::volumeStart@results@" << clk << " ";

    int c,p;
35    int volStart=13 + 2*blockSlice + beam;
    if (ClkInInterval(/* current clock */ clk,
        /* pipeline start */ volStart,
        /* beam/slice start */ 0, 0,
        /* time window size */ 2*blockSlice+6*beam)
40    || ClkInInterval(clk, volStart, blockSize-1,0,2*beam)
    || ClkInInterval(clk, volStart, datasetSizeXYZ.Y()-1,blockSize-1,2*beam)
    ) {
        cout<<endl; cout.width(3); cout << clk << " ComposSely:";
        //cout<<" X="; COU_t_c_p(3, cout<<composSely[c].results.coxel[p].r; );
        //cout<<" Y="; COU_t_c_p(2, cout<<composSely[c].results.coxel[p].g; );
45        //cout<<" Z="; COU_t_c_p(2, cout<<composSely[c].results.coxel[p].a; );

        c=0; p=0;

50

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    cout<<"coxelFiFo[1]:
    "<<composSely[c].composSelyPipeline[p].fifoCoxel
5    "<<composSely[c].composSelyPipeline[p].results.perPipelineControlFlags-
    >voxelPosXYZ;
    cout<<"\tcoxel[1]: "<<composSely[c].composSelyPipeline[p].inputs.coxel
    "<<composSely[c].composSelyPipeline[p].inputs.perPipelineControlFlags-
10    >voxelPosXYZ;
    //cout << "\tWeights[1]
    "<<composSely[c].composSelyPipeline[p].inputs.weightsXYZ;
    cout<< "\tCtrlX[1]
    "<<TypeStr::YStepDirection[composSely[c].composSelyPipeline[p].inputs.perChipCon
    trolFlags->yStep];
15    cout<<"\tout: ";
    cout<<"coxel[1]: "<<composSely[c].results.coxel[p]

    <<composSely[c].results.perPipelineControlFlags[p].voxelPosXYZ;
    }
    } // DebugComposSely
20

void Cube4::DebugComposLinY(const int clk)
{
    if (composLinY[0].inputs.perChipControlFlags->volumeStart)
        cout << endl << "composLinY::volumeStart@inputs@" << clk << " ";
25    if (composLinY[0].results.perChipControlFlags.volumeStart)
        cout << endl << "composLinY::volumeStart@results@" << clk << " ";

    int c,p;
    int volStart=13 + 2*blockSlice + beam;
    if (ClkInInterval(/* current clock */ clk,
30        /* pipeline start */ volStart,
        /* beam/slice start */ 0, 0,
        /* time window size */ 2*blockSlice+6*beam)
        || ClkInInterval(clk, volStart, blockSize-1,0,2*beam)
        || ClkInInterval(clk, volStart, datasetSizeXYZ.Y()-1,blockSize-1,2*beam)
    ) {
35        cout<<endl; cout.width(3); cout << clk << " ComposLinY:";
        //cout<<" X="; COUT_c_p(3, cout<<composLinY[c].results.coxel[p].r; );
        //cout<<" Y="; COUT_c_p(2, cout<<composLinY[c].results.coxel[p].g; );
        //cout<<" Z="; COUT_c_p(2, cout<<composLinY[c].results.coxel[p].a; );

40        c=0; p=0;

        cout<<"coxelFiFo[1]: "<<composLinY[c].composLinYPipeline[p].fifoCoxel
        "<<composLinY[c].composLinYPipeline[p].results.perPipelineControlFlags-
        >voxelPosXYZ;
45        cout<<"\tcoxel[1]: "<<composLinY[c].composLinYPipeline[p].inputs.coxel
        "<<composLinY[c].composLinYPipeline[p].inputs.perPipelineControlFlags-
        >voxelPosXYZ;
50
55

```

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```

//cout << "\tWeights[1]
"<<composLinY[c].composLinYPipeline[p].inputs.weightsXYZ;
cout<< "\tCtrlX[1]
5  "<<TypeStr::YStepDirection[composLinY[c].composLinYPipeline[p].inputs.perChipCon
trolFlags->yStep];
cout<<"\tout: ";
cout<<"coxel[1]: "<<composLinY[c].results.coxel[p]

10  <<composLinY[c].results.perPipelineControlFlags[p].voxelPosXYZ;
    }
} // DebugComposLinY

void Cube4::DebugCompos(const int clk)
15 {
    int c,p;
    DebugImage(compos[0].results.perChipControlFlags);
    ForAll_c_p(DebugWritePixel
                (c,
20  compos[c].results.perPipelineControlFlags[p].voxelPosXYZ,
    compos[c].results.coxel[p].a, 0 ,0));
    //(255 * compos[c].results.coxel[p].r),
    //(255 * compos[c].results.coxel[p].g),
    //(255 * compos[c].results.coxel[p].b));

25  if (compos[0].inputs.perChipControlFlags->volumeStart)
    cout << endl << "compos::volumeStart@inputs@" << clk << " ";
    if (compos[0].results.perChipControlFlags.volumeStart)
    cout << endl << "compos::volumeStart@results@" << clk << " ";

    if (dataSync[0].results.perChipControlFlags.volumeStart)
    cout << endl << "dataSync::volumeStart@results@" << clk << " ";
30  if (composBuff[0].results.perChipControlFlags.volumeStart)
    cout << endl << "composBuff::volumeStart@results@" << clk << " ";

    //int volStart=14 + 2*blockSlice + 3*beam + 3*partialBeam;
    int volStart=17 + 2*blockSlice + beam + partialBeam;
35  if (ClkInInterval(/* current clock */ clk,
    /* pipeline start */ volStart,
    /* beam/slice start */ 1, 1,
    /* time window size */ blockSize)
    || ClkInInterval(clk, volStart, datasetSizeXYZ.Y()-3,blockSize-
1,2*blockSize+3*beam)
40  || ClkInInterval(clk, volStart, blockSize,blockSize,blockSize+2*beam)
    ) {
    cout<<endl; cout.width(4); cout << clk << " Compos: shadel:";
    if (!compos[1].composPipeline[1].results.perPipelineControlFlags-
>valid) cout<<"invalid"; else {
    cout<<" X="; COUT_c_p(3, if (!compos[c].composPipeline[p].RPV)
45  cout<<"I"; else cout<<compos[c].composPipeline[p].inputs.shadel->r; );
    cout<<" Y="; COUT_c_p(2, if (!compos[c].composPipeline[p].RPV)
    cout<<"I"; else cout<<compos[c].composPipeline[p].inputs.shadel->g; );

```

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138
    cout<<" Z=";          COUT_c_p(2, if
(!compos[c].composPipeline[p].RPV) cout<<"I"; else
5   cout<<compos[c].composPipeline[p].inputs.shadel->b; );
    }
    cout<<"\n\t      coxel:";
    if (!compos[1].composPipeline[1].results.perPipelineControlFlags-
>valid) cout<<"invalid"; else {
        cout<<" X="; COUT_c_p(3, if (!compos[c].composPipeline[p].RPV)
10   cout<<"I"; else cout<<compos[c].composPipeline[p].inputs.coxel->r; );
        cout<<" Y="; COUT_c_p(2, if (!compos[c].composPipeline[p].RPV)
cout<<"I"; else cout<<compos[c].composPipeline[p].inputs.coxel->g; );
        cout<<" Z="; COUT_c_p(2, if (!compos[c].composPipeline[p].RPV)
cout<<"I"; else cout<<compos[c].composPipeline[p].inputs.coxel->b; );
    }
15

    //cout<<" vox";
    //cout<<" X="; COUT_c_p(3,
cout<<compos[c].results.perPipelineControlFlags[p].voxelPosXYZ.X(); );
    //cout<<" Y="; COUT_c_p(2,
20   cout<<compos[c].results.perPipelineControlFlags[p].voxelPosXYZ.Y(); );
    //cout<<" Z="; COUT_c_p(2,
cout<<compos[c].results.perPipelineControlFlags[p].voxelPosXYZ.Z(); );
    //cout<<" X="; COUT_c_p(3, cout<<compos[c].results.coxel[p].r; );
    //cout<<" Y="; COUT_c_p(2, cout<<compos[c].results.coxel[p].g; );
25   //cout<<" Z="; COUT_c_p(2, cout<<compos[c].results.coxel[p].a; );

    //cout << "in: ";
    //      cout << "shadel[5] "<<compos[0].inputs.shadel[5] << " ";
    //      cout << "coxel[5] "<<compos[0].inputs.coxel[5] << " ";
    //cout << "\tWeights[5] "<<compos[0].inputs.weightsXYZ[5];
30   //cout << "\tvoxPos[5] " << voxelPos[5];

    //cout << "\tout: ";
    //      cout << "coxel[5]: "<<compos[0].results.coxel[5];
    }
} // DebugCompos
35

void Cube4::DebugFinalCoxelBuffer(const int clk)
{
    int c,p;
    DebugImage(*finalCoxelBuff[0].inputs.perChipControlFlags);
40   ForAll_c_p(DebugWritePixel
                (c,
finalCoxelBuff[c].inputs.perPipelineControlFlags[p].voxelPosXYZ,
                finalCoxelBuff[c].inputs.coxel[p].a,
0,0));
45   if (finalCoxelBuff[0].inputs.perChipControlFlags->volumeStart)
        cout << endl << "finalCoxelBuff::volumeStart@inputs@" << clk << " ";

    int volStart=21 + 3*blockSlice + beam;
50

55

```

```

139
    if (ClkInInterval(/* current clock      */ clk,
                    /* pipeline start      */ volStart,
5      /* beam/slice start */ 0, 0,
                    /* time window size */ 6*beam)
        || ClkInInterval(clk, volStart, blockSize-1,0,2*beam)
        || ClkInInterval(clk, volStart, datasetSizeXYZ.Y()-1,blockSize-1,2*beam)
    ) {
        cout<<endl; cout.width(3); cout << clk << " ComposBuff:";
10      cout<<" X="; COUT_c_p(3, cout<<finalCoxelBuff[c].inputs.coxel[p].r; );
        cout<<" Y="; COUT_c_p(2, cout<<finalCoxelBuff[c].inputs.coxel[p].g; );
        cout<<" Z="; COUT_c_p(2, cout<<finalCoxelBuff[c].inputs.coxel[p].a; );
    }
} // DebugFinalCoxelBuffer

15
void Cube4::DebugImage(const PerChipControlFlags & flags)
{
    // sliceDelay is number of silice buffers in pipeline up to current stage
    int z;
    static int volumeStartCounter(0);
20    static bool first(true), writeImageVolume(false);
    static char fileNameRoot[100], rgbFileName[110], systemCallStr[200];

    if (first) {
        system("/usr/bin/rm -f img/voxelSlc*.miff \n");
        system("/usr/bin/rm -f img/voxelSlc*.rgb \n");
25    sliceSize = datasetSizeXYZ.X() * datasetSizeXYZ.Y();
        volumeSize = sliceSize * datasetSizeXYZ.Z();
        slabSize = sliceSize * blockSize;
        x_step = 1;
        y_step = datasetSizeXYZ.X();
30    z_step = 3*sliceSize; //rgb
        volumeBuffer = new unsigned char [3*(volumeSize+2*slabSize)]; //rgb
        first = false;
    }

    // write volume image one silce of blocks (slab)
35    // after end of volume control bit
    // at that point all blocks of the main volume are guaranteed to be
    finished

        if (volumeStartCounter==2 && flags.zBlockStart) writeImageVolume = true;
        else writeImageVolume = false;
40    if (flags.volumeStart)
        ++volumeStartCounter;

        if (writeImageVolume) {
            for (z=0; z<datasetSizeXYZ.Z(); ++z) {
45                if (z == datasetSizeXYZ.Z()-1 || !singleImagePerFrameMode) {
                    // save slices as rgb image
                    sprintf(fileNameRoot,"img/voxelSlc%02i",z);

                    sprintf(rgbFileName,"%s.rgb",fileNameRoot);

50
55

```

```

140
{
    ofstream voxelS1cRGBFile(rgbFileName);
5    voxelS1cRGBFile.write(&volumeBuffer[3*z*s1cSize],3*s1cSize);
    }
    sprintf(systemCallStr, "%s %ix%i %s.rgb %s.miff; %s
    %s.rgb & \n",
    "convert -sample 900%x900% -
10    size",
    datasetSizeXYZ.X(),
    datasetSizeXYZ.Y(),
    fileNameRoot, fileNameRoot,
    "/usr/bin/rm -f", fileNameRoot);
15    system(systemCallStr);
}

// show image animation
if (!singleImagePerFrameMode)
    system("animate img/voxelS1c*.miff & \n");
20    // show final image of sequence
    sprintf(systemCallStr,"%s %s.miff %s ; %s \n",
    "convert -sample 200%x200% ",
    fileNameRoot, "img/baseplaneImage.miff",
    ""); //display
25    img/baseplaneImage.miff & ");
    system(systemCallStr);

    // Stop main computation loop
    clk = -10;
30 }
} // DebugImage

void Cube4::DebugWritePixel(const int c,
35    const Vector3D<int> & voxelPosXYZ,
    const unsigned char red,
    const unsigned char green,
    const unsigned char blue)
{
    int r=0,g=0,b=0;
    static const int tile(190);
40
    r = (c==4)*tile + (c==5)*tile + (c==6)*tile;
    g = (c==1)*tile + (c==3)*tile + (c==5)*tile;
    b = (c==2)*tile + (c==3)*tile + (c==6)*tile;
45
    r += red;
    g += green;
    b += blue;

    if (r>255) r=255;
50
55

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```

    if (g>255) g=255;
    if (b>255) b=255;

5   // write Compos results into slab buffer
    int x,y,z;

    x = voxelPosXYZ.X() * x_step;
    y = voxelPosXYZ.Y() * y_step;
10   z = voxelPosXYZ.Z() * z_step;

    volumeBuffer[ x+y+z + 0*sliceSize ] = r;
    volumeBuffer[ x+y+z + 1*sliceSize ] = g;
    volumeBuffer[ x+y+z + 2*sliceSize ] = b;
15 } // DebugWritePixel

    // end of Cube4Debug.C
    ::::::::::::::
    cube4/Cube4Interface.C
    ::::::::::::::
20 // Cube4Interface.C
    // (c) Ingmar Bitter '97 / Urs Kanus '97

    // Copyright, Mitsubishi Electric Information Technology Center
    // America, Inc., 1997, All rights reserved.

25 void Cube4::Demo()
    (
        Cube4 cube4;
        cout << endl <<"Demo of class " << typeid(cube4).name();
        cout << endl <<"size : " << sizeof(Cube4) << " Bytes";
30        cout << endl <<"public member functions:";
        cout << endl <<" cube4.SetDatasetFile() = " <<
        cube4.SetDatasetFile("go");
        cout << endl <<" cube4.SetColorTableFile() = " <<
        cube4.SetColorTableFile("go");
        cout << endl <<" cube4.SetReflectanceTableFile() = " <<
35        cube4.SetReflectanceTableFile("go");
        cout << endl <<" cube4.SetImageFileRoot() = " <<
        cube4.SetImageFileRoot("go");
        cout << endl <<" cube4.LoadColorTable() = " << cube4.LoadColorTable();
        cout << endl <<" cube4.LoadAlphaTable() = " << cube4.LoadAlphaTable();
40        cout << endl <<" cube4.LoadReflectanceTable() = " <<
        cube4.LoadReflectanceTable();
        cout << endl <<" cube4.PrintUsage() = " << cube4.PrintUsage();
        cout << endl <<" cube4.RenderImage() = "; cube4.RenderImage();
        cout << endl <<"End of demo of class " << typeid(cube4).name() << endl;
45    } // Demo

```

```

////////////////////////////////////

```

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142

```

// show/set data & data properties
//
5 // - local show/set functions

bool Cube4::PrintUsage() const
{
    cout << endl << "Usage: cube4 [-ds <dataset file>] [-ct <colorTable
10 file>]" << endl;
    cout << "\t [-at <alpha table file>] [-rt <reflectance table file>]" <<
endl;
    cout << "\t [-ir <image file root>]" << endl;
    cout << "\t [-nc <num of chips>] [-np <num of pipelines>] [-pa][-pe]" <<
endl;
15    cout << "\t [-bs <blocksize>] [-tm \"<image matrix>\"]" << endl;
    cout << "\t [-th <levoy class. threshold>] [-mw <levoy class.
maxwidth>]" << endl;
    cout << "\t [-si] [-bf] [-fb] [-an <num of frames in animation>] [-li
\"<light vector>\"]" << endl;
20    cout << "\t [-px <Phong exponent>] [-ip \"<Pointlight
intensity>\"]" << endl;
    cout << "\t [-ia \"<Ambient intensity>\"] [-ka <Ambient coefficient>]" << endl;
    cout << "\t [-kd <Diffuse coefficient>] [-ks <Specular coefficient>] [-sp]
[-sm] [-sv]" << endl;
    cout << "\t [-sc <Shadel color bits>] [-sa <Shadel alpha bits>]" << endl;
25    cout << "\t [-c4] [-cl] [-cc <Coxel color bits>] [-ca <Coxel alpha
bits>]" << endl;
    cout << "\t [-tw <Trilin weight bits>] [-gc <Gradient component bits>]" <<
endl;
    cout << "\t [-ni] [-ar][<nd>][-rs <Reflectance map address bits>]" << endl;
    cout << "\t [-ts <Atan table address bits>] [-cs <Color xfer table address
30 bits>]" << endl;
    cout << "\t [-as <Alpha xfer table address bits>]" << endl;
    exit(0);

    return true;
} // PrintUsage
35

bool Cube4::SetDatasetFile(const char * fileName)
{
    char str[200];

40    // copy string starting with filename
    strcpy(str, fileName);

    // terminate filename at first space
    str[strcspn(fileName, " ") ] = 0;

45    // compare to previous dataset filename
    if (datasetLoaded) datasetLoaded = (strcmp(str, datasetFileName) == 0);

    // copy new filename into class variable

50

```

55

```

143
        if (!datasetLoaded)          strcpy(datasetFileName, str);

5      return strlen(datasetFileName) > 0;
    } // SetDatasetFile

bool Cube4::SetColorTableFile(const char * fileName)
{
10     char str[200];

        // copy string starting with filename
        strcpy(str, fileName);

        // terminate filename at first space
15     str[strcspn(fileName, " ") ] = 0;

        // compare to previous colortable filename
        if (colorTableLoaded) colorTableLoaded = (strcmp(str, colorTableFileName)
== 0);

20     // copy new filename into class variable
        if (!colorTableLoaded) strcpy(colorTableFileName, str);

        return strlen(colorTableFileName) > 0;
    } // SetColorTableFile

25

bool Cube4::SetAlphaTableFile(const char * fileName)
{
    char str[200];

30     // copy string starting with filename
        strcpy(str, fileName);

        // terminate filename at first space
        str[strcspn(fileName, " ") ] = 0;

35     // compare to previous alphatable filename
        if (alphaTableLoaded) alphaTableLoaded = (strcmp(str, alphaTableFileName)
== 0);

        // copy new filename into class variable
40     if (!alphaTableLoaded) strcpy(alphaTableFileName, str);

        return strlen(alphaTableFileName) > 0;
    } // SetAlphaTableFile

45

bool Cube4::SetReflectanceTableFile(const char * fileName)
{
    char str[200];

        // copy string starting with filename
50

```

55

```

144
    strcpy(str, fileName);

5    // terminate filename at first space
    str[strcspn(fileName, " ") ] = 0;

    // compare to previous illuminance filename
    if (reflectanceTableLoaded) reflectanceTableLoaded = (strcmp(str,
10    reflectanceTableFileName) == 0);

    // copy new filename into class variable
    if (!reflectanceTableLoaded) strcpy(reflectanceTableFileName, str);

    return strlen(reflectanceTableFileName) > 0;
15 } // SetReflectanceTableFile

bool Cube4::SetImageFileRoot(const char * fileName)
{
20    // copy string starting with filename
    strcpy(imageRootFileName, fileName);

    // terminate filename at first space
    imageRootFileName[strcspn(fileName, " ") ] = 0;

25    return strlen(imageRootFileName) > 0;
} // SetImageFileRoot

bool Cube4::LoadColorTable()
{
30    return true;
} // LoadColorTable

bool Cube4::LoadAlphaTable()
{
35    return true;
} // LoadAlphaTable

bool Cube4::LoadReflectanceTable()
{
40    return true;
} // LoadReflectanceTable

45 ///////////////////////////////////////////////////////////////////
// internal utility functions

bool Cube4::ReadCube4PipelineParametersFromFile(const char * srcFileName)
50 {
    ifstream srcFile(srcFileName);

55

```

```

char line[256];
    srcFile.getline(line,255);
5   while (srcFile) {
        SetParameter(&line[0], &line[4]);
        srcFile.getline(line,255);
    }
    srcFile.close();
10  return true;
} // ReadCube4PipelineParametersFromFile

bool Cube4::ReadCube4PipelineParametersFromCommandLine(int argc, char *argv[])
{
15     if (!argc) // no command line parameters (not even cube4 itself)
        // => internally created Cube4 instance
        return false;

    int pos(0);
    while (++pos < argc) {
20         if (strncmp(argv[pos], "-h", 2) == 0) { PrintUsage(); }
        else SetParameter(argv[pos], argv[Min(argc-1, pos+1)]);
    }

    return true;
25 } // ReadCube4PipelineParametersFromCommandLine

bool Cube4::SetParameter(const char * id, const char * str)
{
30     // all parameters are assumed to have exactly 2 specifying characters

    // terminate parameter at first space
    // (parameter file might have description afterwards)
    char param[200];
    strcpy(param, str);
35     param[strcspn(str, " ") = 0;

    // skip some typing :)
#define CMP(sw) (strncmp(id, (sw), 3) == 0)
#define PRN(strA, strB) cout << endl << "switch -" << (strA) << (strB);

40     if CMP("-pf") { PRN("pf: using parameter file: ", param);
ReadCube4PipelineParametersFromFile(param); }
    else if CMP("-ds") { PRN("ds: using dataset: ", param);
SetDatasetFile(param); }
    else if CMP("-ct") { PRN("ct: using colorTable: ", param);
SetColorTableFile(param); }
45     else if CMP("-at") { PRN("at: using alphaTable: ", param);
SetAlphaTableFile(param); }
    else if CMP("-rt") { PRN("rt: using ReflectanceTable: ", param);
SetReflectanceTableFile(param); }

```

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146
    else if CMP("--ir") { PRN("ir:          using image root: ",param);
    SetImageFileRoot(param); }
5   else if CMP("--nc") { PRN("nc: number of cube4 chips:",param); numOfChips =
    atoi(param); }
    else if CMP("--np") { PRN("np: number of pipelines per chip:",param);
    numOfPipelinesPerChip = atoi(param); }
    else if CMP("--bs") { PRN("bs: block size:",param);
    blockSize = atoi(param); }
10  else if CMP("--pa") { PRN("pa: parallel projection","");
    projectionStyle = parallel; }
    else if CMP("--pe") { PRN("pe: perspective projection","");
    projectionStyle = perspective; }
    else if CMP("--vp") { PRN("vp: view point",""); SetViewPoint(str) ; cout <<
    viewPointUVW; }
15  else if CMP("--tm") { PRN("tm: global dataset->image matrix:", "");
    SetDatasetToImageMatrix(str); }
    else if CMP("--th") { PRN("th: classification threshold: ",param); threshold =
    atof(param); }
    else if CMP("--mw") { PRN("mw: classification maxwidth: ",param); maxWidth =
    atof(param); }
20  else if CMP("--ma") { PRN("ma: classification alpha multiplier: ",param);
    mulAlpha = atof(param); }
    else if CMP("--si") { PRN("si: single image per frame","");
    singleImagePerFrameMode = true; }
    else if CMP("--bf") { PRN("bf: BackToFront compositing","");
    compositingStyle = BackToFront; }
25  else if CMP("--fb") { PRN("fb: FrontToBack compositing","");
    compositingStyle = FrontToBack; }
    else if CMP("--an") { PRN("an: animation (render multiple frames)",param);
    numOfFramesInAnimation = atoi(param); }
    else if CMP("--li") { PRN("li: light source","");
    lightSourceUVW.SetSize(lightSourceUVW.Size()+1);
30
    lightSourceUVW[lightSourceUVW.Size()-1](str) ;

    cout << "
    "<<lightSourceUVW[lightSourceUVW.Size()-1];)
    else if CMP("--px") { PRN("px: Phong exponent: ", param); phongExponent =
    atof(param); }
35  else if CMP("--ia") { PRN("ia: Phong ambient intensity: ", param);
    SetAmbientIntensity(str) ; }
    else if CMP("--ka") { PRN("ka: Phong ambient coefficient: ", param); Ka =
    atof(param); ; }
    else if CMP("--ks") { PRN("ks: Phong specular coefficient: ", param); Ks =
    atof(param); }
40  else if CMP("--kd") { PRN("kd: Phong diffuse coefficient: ", param); Kd =
    atof(param); }
    else if CMP("--so") { PRN("so: Shading off (no shading at all): ",param);
    shaderMode = NoShading; }
    else if CMP("--sp") { PRN("sp: Phong shading mode",""); shaderMode = Phong; }
45  else if CMP("--sm") { PRN("sm: Reflectance map shading mode",""); shaderMode =
    RefMap; }
    else if CMP("--sv") { PRN("sv: Reflectance vector shading mode","");
    shaderMode = RefVector; }

```

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    else if CMP("-sc") { PRN("sc: Shadel   color bits: ", param); shadelColorBits
= (char)atoi(param); }
5   else if CMP("-sa") { PRN("sa: Shadel alpha bits: ", param); shadelAlphaBits =
(char)atoi(param); }
    else if CMP("-c4") { PRN("c4: Cube4 classic mode", ""); cubeMode =
Cube4Classic; }
    else if CMP("-cl") { PRN("cl: Cube4 light mode", ""); cubeMode = Cube4Light; }
    else if CMP("-cc") { PRN("cc: Coxel color bits: ", param); coxelColorBits =
10  (char)atoi(param); }
    else if CMP("-ca") { PRN("ca: Coxel alpha bits: ", param); coxelAlphaBits =
(char)atoi(param); }
    else if CMP("-tw") { PRN("tw: Trilin weight bits: ",param); trilinWeightBits =
composWeightBits = (char)atoi(param); }
    else if CMP("-gc") { PRN("gc: Gradient component bits: ",param); gradientBits
15  = atoi(param); }
    else if CMP("-rw") { PRN("rw: Reflectance map weight bits: ",param);
mapWeightBits = atoi(param); }
    else if CMP("-ni") { PRN("ni: Reflectance map with no interpolation","",
reflectanceMapIP = false; }
    else if CMP("-rs") { PRN("rs: Reflectance map Size (address bits): ",param);
20  reflectanceMapBits = atoi(param); }
    else if CMP("-nd") { PRN("nd: Reflectance map no distortion compensation ",
""); distortionCompensation = false; }
    else if CMP("-ar") { PRN("ar: Reflectance map constant angular resolution ",
""); constantAngularResolution = true; }
    else if CMP("-cs") { PRN("cs: Color transferfunction table size (address
25  bits): ",param); colorTableBits = atoi(param); }
    else if CMP("-as") { PRN("as: Alpha transferfunction table size (address
bits): ",param); alphaTableBits = atoi(param); }

    return true;
30  } // SetParameter

```

```

bool Cube4::SetAmbientIntensity(const char * str)
35  {
    char param[200];
    strstream ambientIntensityData;
    double tempX, tempY, tempZ;

40    if (str[0] == '"') {
        // ambientIntensity from command-file

        // copy only part between double quotes
        strcpy(param, &str[1]);
        param[strcspn(param, "\"")] = 0;
45    ambientIntensityData << param;
    }
    else {
        // ambientIntensity from command-line

```

50

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```

5          // copy only part between double quotes

          ambientIntensityData << str;
        }
        ambientIntensityData>>tempX;
        ambientIntensityData>>tempY;
10       ambientIntensityData>>tempZ;

        IAmbient(tempX, tempY, tempZ);

        cout <<" "<<IAmbient<<",";
        return true;
15     } // SetAmbientIntensity

bool Cube4::SetViewPoint(const char * str)
{
20     char param[200];
        stringstream viewPointData;
        double tempX, tempY, tempZ;

        if (str[0] == '"') {
25             // viewPoint from command-file

            // copy only part between double quotes
            strcpy(param, &str[1]);
            param[strlen(param, "\\\"")] = 0;
30             viewPointData << param;
        }
        else {
            // viewPoint from command-line
35             // copy only part between double quotes

            viewPointData << str;
        }
        viewPointData>>tempX;
40       viewPointData>>tempY;
        viewPointData>>tempZ;

        viewPointUVW(tempX, tempY, tempZ);
        viewPointSet = true;
45       return true;
    } // SetViewPoint

bool Cube4::SetDatasetToImageMatrix(const char * str)
50     {
        char param[200];
        stringstream matrixData;
55

```

```

5         if (str[0] == '"') {
            // matrix is given explicitly

            // copy only part between double quotes
            strcpy(param, &str[1]);
            param[strcspn(param, "\"") ] = 0;

10         matrixData << param;
        }
        else {
            // matrix from command-line

15         // copy only part between double quotes

            matrixData << str;
        }

20         double matrix[4][4];
        for (int j=0; j<4; ++j) {
            for (int k=0; k<4; ++k) {
                matrixData >> matrix[j][k];
                cout << " " << matrix[j][k];
25             }
            if (j<3) cout << ",";
        }

        return true;
    } // SetDatasetToImageMatrix
30

void Cube4::GetFinalImage()
{
    // copy final coxel data into rgb memory array
35
    int X = datasetSizeXYZ.X();
    int Y = datasetSizeXYZ.Y();
    int Z = datasetSizeXYZ.Z();
    int sliceSize = X*Y;
40    unsigned char * backImageRGB = new unsigned char [3 * sliceSize];
    unsigned char * toBoImageRGB = new unsigned char [3 * sliceSize];
    unsigned char * sideImageRGB = new unsigned char [3 * sliceSize];

45    // FinalCoxelBuffer::SideAdrr();

    int indexR, indexG, indexB, oneFaceIndex, x, y, address, color;
    indexR = 0*sliceSize;
    indexG = 1*sliceSize;
    indexB = 2*sliceSize;
50    for (y=0; y<Y; ++y) {
        for (x=0; x<X; ++x) {
            address = y*X + x;

55

```



```

150
    backImageRGB[indexR] = (unsigned char) (coxMem[0](address).r
* 255.0);
    backImageRGB[indexG] = (unsigned char) (coxMem[0](address).g *
5 255.0);
    backImageRGB[indexB] = (unsigned char) (coxMem[0](address).b *
255.0);
    ++indexR; ++indexG; ++indexB;
    )
10    }
    indexR = 0*sliceSize;
    indexG = 1*sliceSize;
    indexB = 2*sliceSize;
    for (y=0; y<Y; ++y) {
        for (x=0; x<X; ++x) {
15            address = sliceSize + y*X + x;
            toBoImageRGB[indexR] = (unsigned char) (coxMem[0](address).r *
255.0);
            toBoImageRGB[indexG] = (unsigned char) (coxMem[0](address).g *
255.0);
            toBoImageRGB[indexB] = (unsigned char) (coxMem[0](address).b *
20 255.0);
            ++indexR; ++indexG; ++indexB;
        }
    }
    indexR = 0*sliceSize;
    indexG = 1*sliceSize;
25    indexB = 2*sliceSize;
    for (y=0; y<Y; ++y) {
        for (x=0; x<X; ++x) {
            address = 2*sliceSize + y*X + x;
            sideImageRGB[indexR] = (unsigned char) (coxMem[0](address).r *
30 255.0);
            sideImageRGB[indexG] = (unsigned char) (coxMem[0](address).g *
255.0);
            sideImageRGB[indexB] = (unsigned char) (coxMem[0](address).b *
255.0);
            ++indexR; ++indexG; ++indexB;
35    }
    }

    //////////////////////////////////////
    // recompute sightRay as done in control unit

40    Vector3D<FixPointNumber> sightRay, normalizedSightRay, samplePosIncrement;
    sightRay = datasetSizeXYZ;
    sightRay /= 2.0;
    sightRay -= viewPointXYZ;

    // normalize by z component
45    FixPointNumber norm(sightRay.Z().Abs());

    normalizedSightRay(sightRay.X() / norm,

50

55

```

151

```

norm,                                sightRay.Y() /
5                                     0);

    if (compositingStyle == FrontToBack)
        samplePosIncrement = normalizedSightRay;
    else if (compositingStyle == BackToFront)
        samplePosIncrement = -normalizedSightRay;

10    double dx = double(samplePosIncrement.X());
    double dy = double(samplePosIncrement.Y());
    double dxAbs = ABS(dx);
    double dyAbs = ABS(dy);
    int xOffset = int(dxAbs * (Z-1.0)); // -1 for 0 offset start at first slice
15    int yOffset = int(dyAbs * (Z-1.0));

    // make one big baseplane image
    unsigned char * baseplaneImageRGB = new unsigned char [3 * 9*sliceSize];
    for (x=0; x<3 * 9*sliceSize; ++x) baseplaneImageRGB[x]=0;
20    int baseplaneIndex = 9*sliceSize;

    // back face
    oneFaceIndex = 0;
    for (color=0; color<3; ++color) {
25        for (y=Y; y<2*Y; ++y) {
            for (x=X; x<2*X; ++x) {
                baseplaneImageRGB[baseplaneIndex*color + y*3*X + x]
                    = backImageRGB[oneFaceIndex++];
            }
        }
30    }

    // top/bottom face
    if (yOffset>0) {
        oneFaceIndex = 0;
        for (color=0; color<3; ++color) {
35            for (y=0; y<=yOffset; ++y) {
                for (x=0; x<X; ++x) {
                    baseplaneImageRGB[baseplaneIndex*color
+ (y+Y-
yOffset-1)*3*X
+ X+x-
40    int((yOffset+1-y)*(dxAbs/dyAbs))]
                        = toBoImageRGB[oneFaceIndex++];
                }
            } oneFaceIndex += X*(Y-yOffset-1);
        }
45    }

    // side face
    if (xOffset>0) {
        oneFaceIndex = 0;
50
55

```

```

152
    for (color=0; color<3; ++color) {
        for (x=0; x<xOffset; ++x) {
5           for (y=0; y<Y; ++y) {
                baseplaneImageRGB[baseplaneIndex*color
int((xOffset-1-x)*(dyAbs/dxAbs))*3*X + (Y+y-
xOffset] + x+X-
10           = sideImageRGB[oneFaceIndex++];
                }
            } oneFaceIndex += X*(X-xOffset);
        }
    }

15    // write rgb memory array to disk
    {
        ofstream backImageRGBfile("img/baseplaneImage.rgb");
        backImageRGBfile.write(baseplaneImageRGB, 3 * 9*sliceSize);
    }

20    // convert rgb image to miff image
    char str[200];
    sprintf(str, "convert -size %ix%i %s %s ; %s \n",
            3*datasetSizeXYZ.X(), 3*datasetSizeXYZ.Y(),
            "img/baseplaneImage.rgb",
25    "img/baseplaneImage.miff",
            "/usr/bin/rm -f img/baseplaneImage.rgb");
    system(str);
    sprintf(str, "convert -crop %ix%i+%i+%i %s %s \n",
            X+xOffset,Y+yOffset,X-xOffset,Y-yOffset,
            //2*X,2*Y,0,0,
            "img/baseplaneImage.miff",
30    "img/baseplaneImage.miff");
    system(str);
    sprintf(str, "convert -sample 200%%x200%% %s %s%s%s \n",
            "img/baseplaneImage.miff", "img/",
imageRootFileName, ".miff");
35    system(str);
    // free memory
    delete backImageRGB; backImageRGB = 0;
    delete toBoImageRGB; toBoImageRGB = 0;
    delete sideImageRGB; sideImageRGB = 0;
    delete baseplaneImageRGB; baseplaneImageRGB = 0;
40 } // GetFinalImage

void Cube4::MakePSfile(const char * comment)
{
45    char str[500];
    {
        ofstream imgInfo("img/imgInfo.tex");
        imgInfo << "\\resizebox(8in){!}{\\includegraphics(img/"
            << imageRootFileName << ".eps}})" << endl;
50
55

```

```

153
imgInfo << endl << "\\bf " << imageRootFileName << "}" << endl;
imgInfo << endl << "\\it " << comment << "}" << endl;
5
"; ";

imgInfo << endl << "dataset size:~" << datasetSizeUVW << "; ";
imgInfo << endl << "view point:~" << viewPointUVW << "; ";
imgInfo << endl << "projection style:~"
<< TypeStr::ProjectionStyle[projectionStyle]
10
<< ";\\\\ ";
imgInfo << endl << "trilin weight bits:~" << trilinWeightBits;
imgInfo << endl << "gradient component bits:~" << gradientBits <<
";\\\\ ";
imgInfo << endl << "shading mode:~"
<< TypeStr::ShaderMode[shaderMode] << "; ";
15
imgInfo << endl << "Ka:~"<<Ka<< " Kd:~"<<Kd<< " Ks:~"<<Ks<<"; ";
imgInfo << endl << "phong exponent:~" << phongExponent<< ";\\\\ ";
imgInfo << endl << "lights: " << lightSourceUVW<< ";\\\\ ";
imgInfo << endl << "classification: threshold:~" << threshold;
imgInfo << endl << "maxWidth:~" << maxWidth;
imgInfo << endl << "mulAlpha:~" << mulAlpha;
20
imgInfo << endl << "shadel bits: color" << shadelColorBits
<< " alpha" << shadelAlphaBits << ";\\\\ ";
imgInfo << endl << "compositing style: "
<<
TypeStr::CompositingStyle[compositingStyle] << "; ";
25
imgInfo << endl << "coxel bits: color" << coxelColorBits
<< " alpha" << coxelAlphaBits;
imgInfo << endl;
}
sprintf(str,"convert img/baseplaneImage.miff img/%s.eps \n",
imageRootFileName);
system(str);
30
sprintf(str,"%s ; %s%s \n",
"latex img/image.ltx > /dev/null",
"dvips -o img/",imageRootFileName, ".ps
image.dvi");
system(str);
35
sprintf(str,"ghostview img/%s.ps & \n", imageRootFileName);
system(str);
system("/usr/bin/rm -f im*.aux ; /usr/bin/rm -f image.* ; /usr/bin/rm -f
img/*.aux");
} // MakePSfile

40
// end of Cube4Interface.C
:::::::::::::
cube4/Cube4PipelineParameter.dat
:::::::::::::
// dataset
45
// -nc 2 // number of cube4 chips
// -np 4 // number of pipelines
// -bs 8 // block size
// -ds data/geom/bulb.slc // dataset file

```

```

// -ir Image

5 // pipeline mode
// -pa // projection style
// -c4 // Cube4 light mode

// Levoy classification
// -th 0.6 // threshold
10 // -mw 1.5 // maxwidth
// -ma 10 // mulAlpha

// lights
// -sm
// -ka 0
15 // -kd 1
// -ks 0
// -li " 0.0 0.0 1.0 1 .5 .5 1"
// -li "-0.8 -0.5 1.0 8 8 9 60"
// -li " 0.8 -0.5 1.0 8 8 9 60"
// -li "-0.8 -0.5 1.0 -9 -9 0 99"
20 // -li " 0.8 -0.5 1.0 -9 -9 0 99"
// -li " 0.0 0.4 1.0 3 0 0 50"
// -li "-1.0 1.0 1.0 2 2 2 70"
// -li " 1.0 1.0 1.0 2 2 2 70"
// -li "-0.4 1.0 0.6 2 2 2 70"
// -li " 0.4 1.0 0.6 2 2 2 70"
25 // -li " 0.0 1.0 0.6 2 2 2 99"

:~::~:
cube4/DataSyncPipeline.C
:~::~:
30 // DataSyncPipeline.C
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center .
// America, Inc., 1997, All rights reserved.

35 #include "DataSyncPipeline.h"

void DataSyncPipeline::Demo()
{
    DataSyncPipeline dataSync;
    cout << endl << "Demo of class " << typeid(dataSync).name();
    cout << endl << "size : " << sizeof(DataSyncPipeline) << " Bytes";
40    cout << endl << "public member functions:";
    cout << endl << "DataSyncPipeline dataSync; = " << dataSync;
    cout << endl << "End of demo of class " << typeid(dataSync).name() << endl;
} // Demo

45
////////////////////////////////////
// constructors & destructors

```

50

55

```

155
// static first init
int DataSyncPipeline::numOfChips          = 0;
5 int DataSyncPipeline::numOfPipelinesPerChip = 0;
int DataSyncPipeline::blockSize          = 0;
Cube4 *DataSyncPipeline::cube4          = 0;

DataSyncPipeline::DataSyncPipeline()
10 {
    int blockBeamDelay = blockSize / numOfPipelinesPerChip;
    int syncDelay = 2*blockBeamDelay + 3; // 2 fifo's, 3 extra stages
    blockSyncShade1Fifo.SetSize(syncDelay);
    blockSyncWeightsFifo.SetSize(syncDelay);
    blockSyncPerPipelineControlFlagsFifo.SetSize(syncDelay);
15 blockSyncPerChipControlFlagsFifo.SetSize(syncDelay);
} // constructor

DataSyncPipeline::~DataSyncPipeline()
20 {
} // destructor

////////////////////////////////////
25 // show/set data & data properties

ostream & DataSyncPipeline::Ostream(ostream & os) const
{
    // append DataSyncPipeline info to os
30 os << typeid(*this).name() << "@" << (void *) this;
    os << endl << "  numOfChips          = " << numOfChips;
    os << endl << "  numOfPipelinesPerChip = " << numOfPipelinesPerChip;
    os << endl << "  chipIndex          = " << chipIndex;

35 // return complete os
    return os;
} // Ostream

40 //////////////////////////////////////
// show/set data & data properties
//
// - local show/set functions

45 void DataSyncPipeline::GlobalSetup(const int setNumOfChips,
                                     const int setNumOfPipelinesPerChip,
                                     const int setBlockSize)
50 {
    numOfChips          = setNumOfChips;

```

55

```

156
    numofPipelinesPerChip =      setNumofPipelinesPerChip;
    blockSize              = setBlockSize;
5  } // GlobalSetup

void DataSyncPipeline::LocalSetup(const int setChipIndex,
10      const int setPipelineIndex,
    DataSyncStage & dataSyncStage)
{
    chipIndex = setChipIndex;
    pipelineIndex = setPipelineIndex;
15    inputs.shadel = &(dataSyncStage.inputs.shadel[pipelineIndex]);
    inputs.weightsXYZ = &(dataSyncStage.inputs.weightsXYZ[pipelineIndex]);
    inputs.perChipControlFlags
        = dataSyncStage.inputs.perChipControlFlags;
    inputs.perPipelineControlFlags
        = &(dataSyncStage.inputs.perPipelineControlFlags[pipelineIndex]);
20    results.shadel = &(dataSyncStage.results.shadel[pipelineIndex]);
    results.weightsXYZ = &(dataSyncStage.results.weightsXYZ[pipelineIndex]);
    results.perPipelineControlFlags
        = &(dataSyncStage.results.perPipelineControlFlags[pipelineIndex]);
    results.perChipControlFlags
25        = &(dataSyncStage.results.perChipControlFlags);

    cube4 = dataSyncStage.cube4;
} // LocalSetup

30 void DataSyncPipeline::PerFrameSetup()
{
    // reset pipeline registers already done in DataSyncStage
    blockSyncShadelFiFo.Preset(*(inputs.shadel));
    blockSyncWeightsFiFo.Preset(*(inputs.weightsXYZ));
35    blockSyncPerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineControlFla
gs));
    blockSyncPerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFlags));
} // PerFrameSetup

40 ////////////////////////////////////////////////////
// local computation functions

void DataSyncPipeline::RunForOneClockCycle()
{
    blockSyncShadelFiFo.Exchange
45        (*(inputs.shadel),
        *(results.shadel));
    blockSyncWeightsFiFo.Exchange
        (*(inputs.weightsXYZ),
50
55

```

```

157
    *(results.weightsXYZ));
    blockSyncPerPipelineControlFlagsFiFo.Exchange
5      (*(inputs.perPipelineControlFlags),
        *(results.perPipelineControlFlags));
    if (pipelineIndex == 0)
        blockSyncPerChipControlFlagsFiFo.Exchange
            (*(inputs.perChipControlFlags),
              *(results.perChipControlFlags));
10  } // RunForOneClockCycle

////////////////////////////////////
15  // internal utility functions

// end of DataSyncPipeline.C
:::::::::::::
cube4/DataSyncPipeline.h
20  :::::::::::::::
    // DataSyncPipeline.h
    // (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

25  #ifndef _DataSyncPipeline_h_ // prevent multiple includes
#define _DataSyncPipeline_h_

#include "Misc.h"
30  #include "Object.h"
#include "FiFo.h"
#include "Shadel.h"
#include "Control.h"
#include "FixPointNumber.h"

35  typedef Vector3D<FixPointNumber> FixPointVector3D;

class DataSyncStage;
class Cube4;

40  class DataSyncPipelineInputs {
public: // pointers
    Shadel *shadel;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags *perChipControlFlags;
45  PerPipelineControlFlags *perPipelineControlFlags;
};

class DataSyncPipelineResults {
50  public: // pointers
    Shadel *shadel;
    Vector3D<FixPointNumber> *weightsXYZ;

```



```

                                158
PerChipControlFlags             *perChipControlFlags;
PerPipelineControlFlags *perPipelineControlFlags;
5      };

class DataSyncPipeline : virtual public Object {
public:

10      static void      Demo ();

        // constructors & destructors
        DataSyncPipeline ();
        ~DataSyncPipeline ();

15      // show/set data & data properties
        // - class Object requirements
        virtual ostream & Ostream (ostream & ) const;

        // - local show/set functions
20      static void GlobalSetup (const int setNumOfChips,

        const int setNumOfPipelinesPerChip,

        const int setBlockSize);

25      virtual void LocalSetup(const int setChipIndex,

        const int setPipelineIndex,

        DataSyncStage & dataSyncStage);
        virtual void PerFrameSetup();
30      // local computation functions
        virtual void RunForOneClockCycle();

public:
        DataSyncPipelineInputs inputs;
35      DataSyncPipelineResults results;

protected:
        FiFo<Shadel> blockSyncShadelFiFo;
        FiFo<FixPointVector3D> blockSyncWeightsFiFo;
        FiFo<PerPipelineControlFlags> blockSyncPerPipelineControlFlagsFiFo;
40      FiFo<PerChipControlFlags> blockSyncPerChipControlFlagsFiFo;

        static int numOfChips, numOfPipelinesPerChip, blockSize;
        static Cube4 *cube4;
        int chipIndex, pipelineIndex; // only for debugging purpose

45      };

#include "DataSyncStage.h"
#include "Cube4.h"

#ifdef _DataSyncPipeline_h_
50
55

```

```

5  ::::::::::::::
   cube4/DataSyncStage.C
   ::::::::::::::
   // DataSyncStage.C
   // (c) Ingmar Bitter '97

   // Copyright, Mitsubishi Electric Information Technology Center
   // America, Inc., 1997, All rights reserved.

10  #include "DataSyncStage.h"

   void DataSyncStage::Demo()
   {
       DataSyncStage dataSync;
15       cout << endl <<"Demo of class " << typeid(dataSync).name();
       cout << endl <<"size : " << sizeof(DataSyncStage) << " Bytes";
       cout << endl <<"public member functions:";
       cout << endl <<"DataSyncStage dataSync; = " << dataSync;
       cout << endl << "End of demo of class " << typeid(dataSync).name() << endl;
20   } // Demo

   //////////////////////////////////////
   // constructors & destructors

   // static first init
25   int DataSyncStage::numOfChips          = 0;
   int DataSyncStage::numOfPipelinesPerChip = 0;
   Cube4 *DataSyncStage::cube4 = 0;

   DataSyncStage::DataSyncStage()
30   {
       dataSyncPipeline = new DataSyncPipeline [numOfPipelinesPerChip];
       results.shadel = new Shadel [numOfPipelinesPerChip + 1];
       results.weightsXYZ = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];
       results.perPipelineControlFlags = new PerPipelineControlFlags
35   [numOfPipelinesPerChip];
   } // defaultconstructor

   DataSyncStage::~DataSyncStage()
   {
40       if (dataSyncPipeline) { delete dataSyncPipeline; dataSyncPipeline=0; }
       if (results.shadel) { delete results.shadel; results.shadel=0; }
       if (results.weightsXYZ) { delete results.weightsXYZ; results.weightsXYZ=0; }
       if (results.perPipelineControlFlags) {
45           delete results.perPipelineControlFlags;
           results.perPipelineControlFlags=0;
       }
   } // destructor

```

50

55

```

5 ///////////////////////////////////////////////////////////////////
  // show/set data & data properties

ostream & DataSyncStage::Ostream(ostream & os) const
{
10 // append DataSyncStage info to os
  os << typeid(*this).name() << "@" << (void *) this;
    os << endl << "  numOfChips          = " << numOfChips;
    os << endl << "  numOfPipelinesPerChip = " << numOfPipelinesPerChip;
    os << endl << "  chipIndex            = " << chipIndex;

15 // return complete os
  return os;

} // Ostream

20 ///////////////////////////////////////////////////////////////////
  // show/set data & data properties
  //
  // - local show/set functions

25 void DataSyncStage::GlobalSetup(const int setNumOfChips,

    const int setNumOfPipelinesPerChip,

30    const int setBlockSize,

    Cube4 *setCube4)
{
  numOfChips          = setNumOfChips;
  numOfPipelinesPerChip = setNumOfPipelinesPerChip;
35  DataSyncPipeline::GlobalSetup(numOfChips, numOfPipelinesPerChip,

    setBlockSize);
  cube4 = setCube4;
40 } // GlobalSetup

void DataSyncStage::LocalSetup(const int setChipIndex)
{
  chipIndex = setChipIndex;
45  for (int p=0; p<numOfPipelinesPerChip; ++p) {
    dataSyncPipeline[p].LocalSetup(chipIndex,p,*this);
  }
  } // LocalSetup

50 void DataSyncStage::PerFrameSetup()
{
55

```

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```

int p;
// reset pipeline registers
5   for (p=0; p<numOfPipelinesPerChip; ++p) {
        results.shadel[p] = cube4->backgroundShadel;
        results.weightsXYZ[p](0,0,0);
        results.perPipelineControlFlags[p].Reset();
    }
    results.perChipControlFlags.Reset();
10   for (p=0; p<numOfPipelinesPerChip; ++p) {
        dataSyncPipeline[p].PerFrameSetup();
    }

    // print debug info
15   //static bool first(true); if (first) { cout<<this<<endl; first=false; }
    } // PerFrameSetup

////////////////////////////////////
20   // local computation functions

void DataSyncStage::RunForOneClockCycle()
{
    // communication

25   // computation
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        dataSyncPipeline[p].RunForOneClockCycle();
    }
} // RunForOneClockCycle

30   //////////////////////////////////////
    // internal utility functions

35   // end of DataSyncStage.C
    :::::::::::::::
    cube4/DataSyncStage.h
    :::::::::::::::
    // DataSyncStage.h
    // (c) Ingmar Bitter '97
40   // Copyright, Mitsubishi Electric Information Technology Center
    // America, Inc., 1997, All rights reserved.

    #ifndef _DataSyncStage_h_    // prevent multiple includes
45   #define _DataSyncStage_h_

    #include "Misc.h"
    #include "Object.h"
    #include "Vector3D.h"
    #include "Shadel.h"
50
55

```

```

5      #include "Control.h"
      #include "DataSyncPipeline.h"
      #include "FixPointNumber.h"
      #include "Cube4.h"

      class Cube4;

10     class DataSyncStageInputs {
      public: // pointers
          Shadel *shadel;
          Vector3D<FixPointNumber> *weightsXYZ;
          PerChipControlFlags      *perChipControlFlags;
15         PerPipelineControlFlags *perPipelineControlFlags;
    };

      class DataSyncStageResults {
      public: // arrays
20         Shadel *shadel;
          Vector3D<FixPointNumber> *weightsXYZ;
          PerChipControlFlags      perChipControlFlags;
          PerPipelineControlFlags *perPipelineControlFlags;
    };

25

      class DataSyncStage : virtual public Object {
      public:

30         static void      Demo ();

          // constructors & destructors
          DataSyncStage ();
          ~DataSyncStage ();

35         // show/set data & data properties
          // - class Object requirements
          virtual ostream & Ostream (ostream & )    const;

          // - local show/set functions
40         static void GlobalSetup (const int setNumOfChips,

          const int setNumOfPipelinesPerChip,

          const int setBlockSize,

45         Cube4 *setCube4);
          virtual void LocalSetup (const int setChipIndex);
          virtual void PerFrameSetup ();
          // local computation functions
          virtual void RunForOneClockCycle();

50     public:
          DataSyncPipeline *dataSyncPipeline;

55

```

55

```

int
= 0;
5 int FinalCoxelBuffer::blockSize      = 0;
  Cube4 * FinalCoxelBuffer::cube4      = 0;

FinalCoxelBuffer::FinalCoxelBuffer()
{
10   results.coxelBurstPackage = new Coxel [blockSize];
      coxelSideBuffer= new Coxel [blockSize];
      coxelBuffer      = new Coxel [blockSize*blockSize];
      coxelAddress     = new int   [blockSize];
} // constructor

15 FinalCoxelBuffer::~FinalCoxelBuffer()
{
      if (results.coxelBurstPackage) {
          delete results.coxelBurstPackage;
          results.coxelBurstPackage=0;
20     }
      if (coxelSideBuffer) { delete coxelSideBuffer; coxelSideBuffer=0; }
      if (coxelBuffer)      { delete coxelBuffer;      coxelBuffer=0;      }
      if (coxelAddress)     { delete coxelAddress;     coxelAddress=0;     }
} // destructor

25
///////////////////////////////////////////////////////////////////
// show/set data & data properties
//
// - local show/set functions

30 ostream & FinalCoxelBuffer::Ostream(ostream & os) const
{
    // append Control info to os
    os << typeid(*this).name() << "@" << (void *) this;

35    // return complete os
    return os;
} // Ostream

void FinalCoxelBuffer::GlobalSetup(const int setNumOfChips,
40                                const int setNumOfPipelinesPerChip,
                                const int setBlockSize,
                                Cube4 *setCube4)
45 {
    numOfChips      = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    blockSize       = setBlockSize;

50

55

```

```

165
    cube4 = setCube4;
} // GlobalSetup

5

void FinalCoxelBuffer::LocalSetup(CoxMem * memory)
{
    mem = memory;
    mem->SetSize(3 * blockSize*blockSize);
    currentBufferReadRow(0,blockSize);
10    currentBufferWriteRow(0,blockSize);
    clockCyclesBeforeNextDMA = 0;
} // LocalSetup

15

void FinalCoxelBuffer::PerFrameSetup()
{
    nextBufferOffset = 0;
    datasetSizeXYZ = cube4->datasetSizeXYZ;

20    lineExtend = datasetSizeXYZ.X() / numOfChips;
    sliceExtend = lineExtend * datasetSizeXYZ.Y();

    currentBackPos = 0;
    currentTopBottomPos = sliceExtend;
25    currentSidePos = 2*sliceExtend;

    // reset pipeline registers
    results.address = 0;
    results.packageReady = false;
    for (int k=0; k<blockSize; ++k) {
30        results.coxelBurstPackage[k] = 0;
    }
    // print debug info
    // static bool first(true); if (first) { cout<<this<<endl; first =
false; }
35 } // PerFrameSetup

////////////////////////////////////
// local computation functions

40

void FinalCoxelBuffer::RunForOneClockCycle()
{
    /*

45    p=0 p=1 p=2 ...
    +---+---+---+---+---+---+
    |   |   |   |   |   |   |   | currentBufferRead/WriteRow = 0
    +---+---+---+---+---+---+
    |   |   |   |   |   |   |   | currentBufferRead/WriteRow = 1
    +---+---+---+---+---+---+
50    |   |   |   |   |   |   |   | currentBufferRead/WriteRow = 2
    +---+---+---+---+---+---+

55

```



```

166
+---+---+---+---+---+---+---+---+
|   |   |   |   |   |   |   |   | ...
+---+---+---+---+---+---+---+---+
5  |   |   |   |   |   |   |   |   |
+---+---+---+---+---+---+---+---+
|   |   |   | X |   |   |   |   | X = (p +
+---+---+---+---+---+---+---+---+      ( currentBufferRead/WriteRow
|   |   |   |   |   |   |   |   |      * blockSize
10  )
+---+---+---+---+---+---+---+---+
|   |   |   |   |   |   |   |   |
+---+---+---+---+---+---+---+---+
*/

15  assert(blockSize == numOfPipelinesPerChip);

    // handle back face coxels
    if (inputs.perChipControlFlags[0].endFace & BackFace) {
        for (int p=0; p<numOfPipelinesPerChip; ++p) {
            coxelBuffer[p + int(currentBufferWriteRow)*blockSize]
20             = inputs.coxel[p];
        }
        coxelAddress[currentBufferWriteRow] = currentBackPos;
        ++currentBufferWriteRow;
        currentBackPos += blockSize;
    }
25  else {

        // handle top/bottom face coxels
        if (inputs.perChipControlFlags[0].endFace & TopBottomFace) {
            for (int p=0; p<numOfPipelinesPerChip; ++p) {
                coxelBuffer[p + int(currentBufferWriteRow)*blockSize]
30                 = inputs.coxel[p];
            }
            coxelAddress[currentBufferWriteRow] = currentTopBottomPos;
            ++currentBufferWriteRow;
            currentTopBottomPos += blockSize;
35        }

        // handle side face coxels
        if (inputs.perChipControlFlags[0].endFace & SideFace) {
            // left side
            if (inputs.perPipelineControlFlags[0].endOfRay) {
40                coxelSideBuffer[nextBufferOffset] = inputs.coxel[0];
            }
            // right side
            else {

                assert(inputs.perPipelineControlFlags(numOfPipelinesPerChip-1).endOfRay ==
45                true);
                coxelSideBuffer[nextBufferOffset]
                    = inputs.coxel[numOfPipelinesPerChip-1];
            }
        }
50
55

```

```

5          // both sides
          ++nextBufferOffset;
          if (nextBufferOffset == blockSize) {
              // copy coxelSideBuffer to coxelBuffer
              for (int p=0; p<numOfPipelinesPerChip; ++p) {
                  coxelBuffer[p +
10 int(currentBufferWriteRow)*blockSize]
                      = coxelSideBuffer[p];
                      coxelSideBuffer[p] = Coxel(0,1,0,1);
              }
              coxelAddress[currentBufferWriteRow] = currentSidePos;

15          // update counters
              nextBufferOffset = 0;
              currentSidePos += blockSize;
              ++currentBufferWriteRow;
          }
      }
20 }

//////////////////////////////////////
// assemble coxelBurstPackage

25 // wait for previous DMA transfer to finish
if (clockCyclesBeforeNextDMA > 0) {
    --clockCyclesBeforeNextDMA;
    results.packageReady = false;
}

30 // if previous DMA transfer is finished
else {
    if (currentBufferReadRow == currentBufferWriteRow) {
        // no row complete for DMA
35         results.packageReady = false;
    }
    else {
        // buffer has at least one row ready to go
        for (int p=0; p<numOfPipelinesPerChip; ++p) {
40             results.coxelBurstPackage[p] =
                coxelBuffer[p +
int(currentBufferReadRow)*blockSize];
        }
        results.address = coxelAddress[int(currentBufferReadRow)];
        results.packageReady = true;

45         ++currentBufferReadRow;
        clockCyclesBeforeNextDMA = 1; // blockSize;
    }
}

50

```

55

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```

class FinalCoxelBufferResults {
5 public: // arrays
    Coxel *coxelBurstPackage;
    int address;
    bool packageReady;
};

10

class FinalCoxelBuffer : virtual public Object {
public:

15     static void Demo ();

    // constructors & destructors
    FinalCoxelBuffer();
    ~FinalCoxelBuffer();
    // show/set data & data properties
20     virtual ostream & Ostream (ostream & ) const;

    static void GlobalSetup (const int setNumOfChips,

    const int setNumOfPipelinesPerChip,

25     const int setBlockSize,

    Cube4 *setCube4);
    virtual void LocalSetup(CoxMem * memory);
    virtual void PerFrameSetup();
30

    // local computation functions
    virtual void RunForOneClockCycle();
    //static int BackArrayAdrr();
    //static int BottomArrayAdrr();
35     //static int SideArrayAdrr();

public:
    FinalCoxelBufferInputs inputs;
    FinalCoxelBufferResults results;
40

protected:
    Coxel *coxelSideBuffer; // b buffer
    Coxel *coxelBuffer; // b^2 buffer
    int *coxelAddress; // b buffer
45     int nextBufferOffset;
    ModInt currentBufferReadRow;
    ModInt currentBufferWriteRow;
    static int numOfChips, numOfPipelinesPerChip, blockSize;
    Vector3D<int> datasetSizeXYZ;
    int lineExtend; // this many addresses are needed per line
50     int sliceExtend; // this many addresses are needed per slice
    int currentBackPos;
    int currentTopBottomPos;

```

55

55

```

5 //////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
// show/set data & data properties

ostream & GradXPipeline::Ostream(ostream & os) const
{
    // append GradXPipeline info to os
10   os << typeid(*this).name() << "@" << (void *) this;
        os << endl << "    numOfChips          = " << numOfChips;
        os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
        os << endl << "    chipIndex          = " << chipIndex;

    // return complete os
15   return os;

} // Ostream

20 //////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
// show/set data & data properties
//
// - local show/set functions

25 void GradXPipeline::GlobalSetup(const int setNumOfChips,
                                const int setNumOfPipelinesPerChip)
{
    numOfChips          = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
30 } // GlobalSetup

void GradXPipeline::LocalSetup(const int setChipIndex,
                                const int setPipelineIndex,
35                                GradXStage & gradXStage)
{
    chipIndex = setChipIndex;
    pipelineIndex(setPipelineIndex, numOfPipelinesPerChip+2); // ModInt init
40
    inputs.voxelXa = &(gradXStage.inputs.voxel[pipelineIndex-1]);
    inputs.voxelXb = &(gradXStage.inputs.voxel[pipelineIndex+1]);
    inputs.weightsXYZ = &(gradXStage.inputs.weightsXYZ[int(pipelineIndex)]);
    inputs.perChipControlFlags
    = gradXStage.inputs.perChipControlFlags;
45   inputs.perPipelineControlFlags
    = &(gradXStage.inputs.perPipelineControlFlags[pipelineIndex]);

    results.voxel = &(gradXStage.results.voxel[pipelineIndex]);
    results.gx = &(gradXStage.results.gx[pipelineIndex]);
50

```

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    results.gy =
    &(gradXStage.results.gy[pipelineIndex]);
5    results.weightsXYZ = &(gradXStage.results.weightsXYZ[pipelineIndex]);
    results.perPipelineControlFlags
        = &(gradXStage.results.perPipelineControlFlags[pipelineIndex]);
    results.perChipControlFlags
        = &(gradXStage.results.perChipControlFlags);

10    cube4 = gradXStage.cube4;
    } // LocalSetup

void GradXPipeline::PerFrameSetup()
15 {
    // reset pipeline registers already done in GradXStage
    } // PerFrameSetup

20 ///////////////////////////////////////////////////////////////////
    // local computation functions

void GradXPipeline::RunForOneClockCycle()
{
25    *(results.gx) =
        (ScalarGradient) inputs.voxelXb->raw16bit -
        (ScalarGradient) inputs.voxelXa->raw16bit;

    } // RunForOneClockCycle

30 ///////////////////////////////////////////////////////////////////
    // internal utility functions

35 // end of GradXPipeline.C
    ::::::::::::::
    cube4/GradXPipeline.h
    ::::::::::::::
    // GradXPipeline.h
    // (c) Ingmar Bitter '97

40 // Copyright, Mitsubishi Electric Information Technology Center
    // America, Inc., 1997, All rights reserved.

    #ifndef _GradXPipeline_h_    // prevent multiple includes
45    #define _GradXPipeline_h_

    #include "Misc.h"
    #include "Object.h"
    #include "ModInt.h"
    #include "FiFo.h"
50    #include "Voxel.h"
    #include "Coxel.h"

55

```

```

#include "Control.h"
#include "FixPointNumber.h"

5

class GradXStage;
class Cube4;

10
class GradXPipelineInputs {
public: // pointers
    Voxel *voxelXa;
    Voxel *voxelXb;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags      *perChipControlFlags;
15    PerPipelineControlFlags *perPipelineControlFlags;
};

class GradXPipelineResults {
20 public: // pointers
    Voxel *voxel;
    ScalarGradient *gx, *gy;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags      *perChipControlFlags;
25    PerPipelineControlFlags *perPipelineControlFlags;
};

class GradXPipeline : virtual public Object {
30 public:

    static void      Demo ();

    // constructors & destructors
    GradXPipeline ();
35    ~GradXPipeline ();

    // show/set data & data properties
    // - class Object requirements
    virtual ostream & Ostream (ostream & ) const;

40    // - local show/set functions
    static void GlobalSetup (const int setNumOfChips,

        const int setNumOfPipelinesPerChip);

45    virtual void LocalSetup(const int setChipIndex,

        const int setPipelineIndex,

        GradXStage & gradXStage);
50    virtual void PerFrameSetup();
    // local computation functions
    virtual void RunForOneClockCycle();

55

```



```

public:
    GradXPipelineInputs inputs;
    GradXPipelineResults results;

protected:
    static int    numOfChips, numOfPipelinesPerChip;
    static Cube4 *cube4;
    int          chipIndex;
    ModInt        pipelineIndex;
};

#include "GradXStage.h"
#include "Cube4.h"

#endif          // _GradXPipeline_h_
:::::::::::::
cube4/GradXStage.C
:::::::::::::
// GradXStage.C
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include "GradXStage.h"

void GradXStage::Demo()
{
    GradXStage gradX;
    cout << endl <<"Demo of class " << typeid(gradX).name();
    cout << endl <<"size : " << sizeof(GradXStage) << " Bytes";
    cout << endl <<"public member functions:";
    cout << endl <<"GradXStage gradX; = " << gradX;
    cout << endl << "End of demo of class " << typeid(gradX).name() << endl;
} // Demo

////////////////////////////////////
// constructors & destructors

// static first init
int GradXStage::numOfChips          = 0;
int GradXStage::numOfPipelinesPerChip = 0;
Cube4 *GradXStage::cube4 = 0;

GradXStage::GradXStage()
{
    gradXPipeline = new GradXPipeline [numOfPipelinesPerChip];
    results.voxel = new Voxel [numOfPipelinesPerChip];
    results.gx = new ScalarGradient [numOfPipelinesPerChip];
    results.gy = new ScalarGradient [numOfPipelinesPerChip];
    results.weightsXYZ = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];

```

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```

    results.perPipelineControlFlags = new PerPipelineControlFlags
[numOfPipelinesPerChip];
} // defaultconstructor

5

GradXStage::~GradXStage()
{
    if (gradXPipeline) { delete gradXPipeline; gradXPipeline=0; }
    if (results.voxel) { delete results.voxel; results.voxel=0; }
10    if (results.gx) { delete results.gx; results.gx=0; }
    if (results.gy) { delete results.gy; results.gy=0; }
    if (results.weightsXYZ) { delete results.weightsXYZ; results.weightsXYZ=0; }
}

    if (results.perPipelineControlFlags) {
15        delete results.perPipelineControlFlags;
        results.perPipelineControlFlags=0;
    }
} // destructor

20
////////////////////////////////////
// show/set data & data properties

ostream & GradXStage::Ostream(ostream & os) const
25
{
    // append GradXStage info to os
    os << typeid(*this).name() << "@" << (void *) this;
    os <<endl<< "    numOfChips          = " << numOfChips;
    os <<endl<< "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
    os <<endl<< "    chipIndex            = " << chipIndex;
30
    // return complete os
    return os;
} // Ostream

35
////////////////////////////////////
// show/set data & data properties
//
// - local show/set functions

40

void GradXStage::GlobalSetup(const int setNumOfChips,

    const int setNumOfPipelinesPerChip,

    Cube4 *setCube4)
45
{
    numOfChips          = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    GradXPipeline::GlobalSetup(numOfChips, numOfPipelinesPerChip);
50
}

```

55

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```

        cube4 = setCube4;
    } // GlobalSetup

5
void GradXStage::LocalSetup(const int setChipIndex)
{
    chipIndex = setChipIndex;
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
10        gradXPipeline[p].LocalSetup(chipIndex,p,*this);
    }
} // LocalSetup

void GradXStage::PerFrameSetup()
15
{
    int p;
    // reset pipeline registers
    for (p=0; p<numOfPipelinesPerChip; ++p) {
        results.voxel[p].raw16bit = 0;
20        results.gx[p] = results.gy[p] = 0;
        results.weightsXYZ[p](0,0,0);
        results.perPipelineControlFlags[p].Reset();
    }
    results.perChipControlFlags.Reset();

25    for (p=0; p<numOfPipelinesPerChip; ++p) {
        gradXPipeline[p].PerFrameSetup();
    }

    // print debug info
30    //static bool first(true); if (first) { cout<<this<<endl; first=false; }
} // PerFrameSetup

////////////////////////////////////
// local computation functions

35
void GradXStage::RunForOneClockCycle()
{
    // computation
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
40        gradXPipeline[p].RunForOneClockCycle();
        results.voxel[p] = inputs.voxel[p];
        results.gy[p] = inputs.gy[p];
        results.weightsXYZ[p] = inputs.weightsXYZ[p];
        results.perPipelineControlFlags[p] =
inputs.perPipelineControlFlags[p];
45    }
    results.perChipControlFlags = *(inputs.perChipControlFlags);
} // RunForOneClockCycle

```

50

55

```
// internal utility functions
```

```

5      // end of GradXStage.C
      ::::::::::::::
      cube4/GradXStage.h
      ::::::::::::::
10     // GradXStage.h
      // (c) Ingmar Bitter '97

      // Copyright, Mitsubishi Electric Information Technology Center
      // America, Inc., 1997, All rights reserved.

15     #ifndef _GradXStage_h_ // prevent multiple includes
      #define _GradXStage_h_

      #include "Misc.h"
      #include "Object.h"
20     #include "Voxel.h"
      #include "Control.h"
      #include "GradXPipeline.h"
      #include "FixPointNumber.h"
      #include "Cube4.h"

25     class Cube4;

      class GradXStageInputs {
      public: // pointers
30         Voxel *voxel;
         ScalarGradient *gy;
         Vector3D<FixPointNumber> *weightsXYZ;
         PerChipControlFlags *perChipControlFlags;
         PerPipelineControlFlags *perPipelineControlFlags;
35     };

      class GradXStageResults {
      public: // arrays
40         Voxel *voxel;
         ScalarGradient *gx, *gy;
         Vector3D<FixPointNumber> *weightsXYZ;
         PerChipControlFlags perChipControlFlags;
         PerPipelineControlFlags *perPipelineControlFlags;
45     };

      class GradXStage : virtual public Object {
      public:

50         static void Demo ();

         // constructors & destructors
         GradXStage ();

```

55

```

-GradXStage ();

5 // show/set data & data properties
  // - class Object requirements
  virtual ostream & Ostream (ostream & ) const;

  // - local show/set functions
10 static void GlobalSetup (const int setNumOfChips,
    const int setNumOfPipelinesPerChip,
    Cube4 *setCube4);
  virtual void LocalSetup (const int setChipIndex);
  virtual void PerFrameSetup ();
15 // local computation functions
  virtual void RunForOneClockCycle();

public:
  GradXPipeline *gradXPipeline;
20 GradXStageInputs inputs;
  GradXStageResults results;

protected:
  static int    numOfChips, numOfPipelinesPerChip;
25 static Cube4 *cube4;
  int          chipIndex;

  friend class GradXPipeline;
};

30 #endif // _GradXStage_h_
  ::::::::::::::
  cube4/GradYPipeline.C
  ::::::::::::::
  // GradYPipeline.C
35 // (c) Ingmar Bitter '97

  // Copyright, Mitsubishi Electric Information Technology Center
  // America, Inc., 1997, All rights reserved.

#include "GradYPipeline.h"

40 void GradYPipeline::Demo()
{
  GradYPipeline gradY;
  cout << endl << "Demo of class " << typeid(gradY).name();
  cout << endl << "size : " << sizeof(GradYPipeline) << " Bytes";
45 cout << endl << "public member functions:";
  cout << endl << "GradXStage gradY; = " << gradY;
  cout << endl << "End of demo of class " << typeid(gradY).name() << endl;
} // Demo

```

50

55

```

5 // constructors & destructors

// static first init
int GradYPipeline::numOfChips      = 0;
int GradYPipeline::numOfPipelinesPerChip = 0;
int GradYPipeline::blockSize      = 0;
10 Cube4 *GradYPipeline::cube4     = 0;

GradYPipeline::GradYPipeline()
{
    int partialBeamsPerBlockBeam = blockSize / numOfPipelinesPerChip;

15    blockBeamVoxelFiFo0.SetSize(partialBeamsPerBlockBeam);
    blockBeamVoxelFiFo1.SetSize(partialBeamsPerBlockBeam);
    blockBeamWeightsFiFo.SetSize(partialBeamsPerBlockBeam);
    blockBeamPerChipControlFlagsFiFo.SetSize(partialBeamsPerBlockBeam);
    blockBeamPerPipelineControlFlagsFiFo.SetSize(partialBeamsPerBlockBeam);
20 } // constructor

GradYPipeline::~GradYPipeline()
{
25 } // destructor

////////////////////////////////////
// show/set data & data properties

30 ostream & GradYPipeline::Ostream(ostream & os) const
{
    // append GradYPipeline info to os
    os << typeid(*this).name() << "@" << (void *) this;
    os << endl << "    numOfChips      = " << numOfChips;
35    os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
    os << endl << "    chipIndex      = " << chipIndex;

    // return complete os
    return os;
40 } // Ostream

////////////////////////////////////
// show/set data & data properties
45 //
// - local show/set functions

void GradYPipeline::GlobalSetup(const int setNumOfChips,
50
55

```

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```

const int setNumOfPipelinesPerChip,
5      const int setBlockSize)
{
    numOfChips      = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    blockSize      = setBlockSize;
10 } // GlobalSetup

void GradYPipeline::LocalSetup(const int setChipIndex,
                               const int setPipelineIndex,
15      GradYStage & gradYStage)
{
    chipIndex = setChipIndex;
    pipelineIndex = setPipelineIndex;

    inputs.voxel = &(gradYStage.inputs.voxel[pipelineIndex]);
    inputs.weightsXYZ = &(gradYStage.inputs.weightsXYZ[pipelineIndex]);
    inputs.perChipControlFlags
20     = gradYStage.inputs.perChipControlFlags;
    inputs.perPipelineControlFlags
    = &(gradYStage.inputs.perPipelineControlFlags[pipelineIndex]);
25
    results.voxel = &(gradYStage.results.voxel[pipelineIndex]);
    results.gy = &(gradYStage.results.gy[pipelineIndex]);
    results.weightsXYZ = &(gradYStage.results.weightsXYZ[pipelineIndex]);
    results.perPipelineControlFlags
    = &(gradYStage.results.perPipelineControlFlags[pipelineIndex]);
    results.perChipControlFlags
30     = &(gradYStage.results.perChipControlFlags);

    cube4 = gradYStage.cube4;
} // LocalSetup

35 void GradYPipeline::PerFrameSetup()
{
    // reset pipeline registers already done in GradYStage
    blockBeamVoxelFiFo0.Preset(*(inputs.voxel));
    blockBeamVoxelFiFo1.Preset(*(inputs.voxel));
    blockBeamWeightsFiFo.Preset(*(inputs.weightsXYZ));
    blockBeamPerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineControlFla
40 gs));
    blockBeamPerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFlags));
} // PerFrameSetup

45
////////////////////////////////////
// local computation functions
50
55

```

```

void GradYPipeline::RunForOneClockCycle()
{
    /*
        ----->(x)
        |
        | voxA (seen early during processing => take from FiFo )
        |
10      | voxB (seen late during processing  => take from input)
        |
        | V(y)
    */

15      blockBeamVoxelFiFo0.Exchange( *(inputs.voxel), current );
      blockBeamVoxelFiFo1.Exchange( current, lastFiFoOut);
      blockBeamWeightsFiFo.Exchange(*(inputs.weightsXYZ),

                                   *(results.weightsXYZ));
20      blockBeamPerPipelineControlFlagsFiFo.Exchange
        (*(inputs.perPipelineControlFlags),
         *(results.perPipelineControlFlags));
      if (pipelineIndex == 0)
          blockBeamPerChipControlFlagsFiFo.Exchange
25          (*(inputs.perChipControlFlags),
            *(results.perChipControlFlags));

      *(results.gy) = // voxB - voxA
                     (ScalarGradient) inputs.voxel->raw16bit -
                     (ScalarGradient) lastFiFoOut.raw16bit;
30      *(results.voxel) = current;
} // RunForOneClockCycle

35  ////////////////////////////////////////
    // internal utility functions

    // end of GradYPipeline.C
    :::::::::::::::
40  cube4/GradYPipeline.h
    :::::::::::::::
    // GradYPipeline.h
    // (c) Ingmar Bitter '97

45  // Copyright, Mitsubishi Electric Information Technology Center
    // America, Inc., 1997, All rights reserved.

    #ifndef _GradYPipeline_h_    // prevent multiple includes
    #define _GradYPipeline_h_

50  #include "Misc.h"
    #include "Object.h"

55

```



```

#include "FiFo.h"
#include "Voxel.h"
#include "Coxel.h"
#include "Control.h"
#include "FixPointNumber.h"

class GradYStage;
class Cube4;

typedef Vector3D<FixPointNumber> FixPointVector3D;

class GradYPipelineInputs {
public: // pointers
    Voxel *voxel;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags *perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

class GradYPipelineResults {
public: // pointers
    Voxel *voxel;
    ScalarGradient *gy;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags *perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

class GradYPipeline : virtual public Object {
public:

    static void      Demo ();

    // constructors & destructors
    GradYPipeline ();
    ~GradYPipeline ();

    // show/set data & data properties
    // - class Object requirements
    virtual ostream & Ostream (ostream & ) const;

    // - local show/set functions
    static void GlobalSetup (const int setNumOfChips,
        const int setNumOfPipelinesPerChip,
        const int setBlockSize);

    virtual void LocalSetup(const int setChipIndex,
        const int setPipelineIndex,

```

```

5      GradYStage & gradYStage);
      virtual void PerFrameSetup();
      // local computation functions
      virtual void RunForOneClockCycle();

public:
10     GradYPipelineInputs inputs;
     GradYPipelineResults results;

protected:
     FiFo<Voxel> beamVoxelFiFo0;
     FiFo<Voxel> beamVoxelFiFo1;
15     FiFo<FixPointVector3D> beamWeightsFiFo;
     FiFo<PerPipelineControlFlags> beamPerPipelineControlFlagsFiFo;
     FiFo<PerChipControlFlags> beamPerChipControlFlagsFiFo;

     FiFo<Voxel> blockBeamVoxelFiFo0;
20     FiFo<Voxel> blockBeamVoxelFiFo1;
     FiFo<FixPointVector3D> blockBeamWeightsFiFo;
     FiFo<PerPipelineControlFlags> blockBeamPerPipelineControlFlagsFiFo;
     FiFo<PerChipControlFlags> blockBeamPerChipControlFlagsFiFo;

25     Voxel current, lastFiFoOut;

     static int numOfChips, numOfPipelinesPerChip, blockSize;
     static Cube4 *cube4;
     int chipIndex, pipelineIndex;

30     friend class Cube4;
};

#include "GradYStage.h"
#include "Cube4.h"

35 #endif // _GradYPipeline_h_
:~::~:
cube4/GradYStage.C
:~::~:
40 // GradYStage.C
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

45 #include "GradYStage.h"

void GradYStage::Demo()
{
     GradYStage gradY;
50     cout << endl <<"Demo of class " << typeid(gradY).name();
     cout << endl <<"size : " << sizeof(GradYStage) << " Bytes";
     cout << endl <<"public member functions:";

```

```

184
    cout << endl << "GradYStage gradY;  = " << gradY;
    cout << endl << "End of demo of class " << typeid(gradY).name() << endl;
5   } // Demo

////////////////////////////////////
// constructors & destructors

10  // static first init
    int GradYStage::numOfChips          = 0;
    int GradYStage::numOfPipelinesPerChip = 0;
    Cube4 *GradYStage::cube4 = 0;

    GradYStage::GradYStage()
15  {
        gradYPipeline = new GradYPipeline [numOfPipelinesPerChip];
        results.voxel = new Voxel [numOfPipelinesPerChip+2];
        results.gy = new ScalarGradient [numOfPipelinesPerChip];
        results.weightsXYZ = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];
        results.perPipelineControlFlags = new PerPipelineControlFlags
20  [numOfPipelinesPerChip];
    } // defaultconstructor

    GradYStage::~GradYStage()
25  {
        if (gradYPipeline) { delete gradYPipeline; gradYPipeline=0; }
        if (results.voxel) { delete results.voxel; results.voxel=0; }
        if (results.gy) { delete results.gy; results.gy=0; }
        if (results.weightsXYZ) { delete results.weightsXYZ; results.weightsXYZ=0; }
    }
        if (results.perPipelineControlFlags) {
30  delete results.perPipelineControlFlags;
        results.perPipelineControlFlags=0;
        }
    } // destructor

35  //////////////////////////////////////
    // show/set data & data properties

    ostream & GradYStage::Ostream(ostream & os) const
40  {
        // append GradYStage info to os
        os << typeid(*this).name() << "@" << (void *) this;
        os << endl << "  numOfChips          = " << numOfChips;
        os << endl << "  numOfPipelinesPerChip = " << numOfPipelinesPerChip;
        os << endl << "  chipIndex          = " << chipIndex;
45
        // return complete os
        return os;

50

55

```

185

```

    } // Ostream

5
    ///////////////////////////////////////////////////////////////////
    // show/set data & data properties
    //
    // - local show/set functions

10
    void GradYStage::GlobalSetup(const int setNumOfChips,

        const int setNumOfPipelinesPerChip,

        const int setBlockSize,

15
        Cube4 *setCube4)
    {
        numOfChips          = setNumOfChips;
        numOfPipelinesPerChip = setNumOfPipelinesPerChip;
        GradYPipeline::GlobalSetup(numOfChips,numOfPipelinesPerChip,setBlockSize);
20
        cube4 = setCube4;
    } // GlobalSetup

    void GradYStage::LocalSetup(const int setChipIndex)
25
    {
        chipIndex = setChipIndex;
        for (int p=0; p<numOfPipelinesPerChip; ++p) {
            gradYPipeline[p].LocalSetup(chipIndex,p,*this);
        }
    } // LocalSetup

30

    void GradYStage::PerFrameSetup()
    {
        int p;
        // reset pipeline registers
35
        for (p=0; p<numOfPipelinesPerChip; ++p) {
            results.voxel[p].raw16bit = 0;
            results.gy[p] = 0;
            results.weightsXYZ[p](0,0,0);
            results.perPipelineControlFlags[p].Reset();
40
        }
        results.perChipControlFlags.Reset();

        for (p=0; p<numOfPipelinesPerChip; ++p) {
            gradYPipeline[p].PerFrameSetup();
45
        }

        // print debug info
        //static bool first(true); if (first) { cout<<this<<endl; first=false; }
    } // PerFrameSetup

```

50

55

```

5  // local computation functions

void GradYStage::RunForOneClockCycle()
{
    // computation
10    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        gradYPipeline[p].RunForOneClockCycle();
    }
} // RunForOneClockCycle

15 // internal utility functions

// end of GradYStage.C
20 ::::::::::::::
cube4/GradYStage.h
::::::::::::
// GradYStage.h
// (c) Ingmar Bitter '97

25 // Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#ifdef _GradYStage_h_ // prevent multiple includes
#define _GradYStage_h_

30 #include "Misc.h"
#include "Object.h"
#include "Voxel.h"
#include "Control.h"
#include "GradYPipeline.h"
35 #include "FixPointNumber.h"
#include "Cube4.h"

class Cube4;

40 class GradYStageInputs {
public: // pointers
    Voxel *voxel;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags *perChipControlFlags;
45    PerPipelineControlFlags *perPipelineControlFlags;
};

class GradYStageResults {
50 public: // arrays
    Voxel *voxel;
    ScalarGradient *gy;

55

```

```

// America, Inc., 1997, All rights reserved.
188

5  #include "GradZLinXPipeline.h"

void GradZLinXPipeline::Demo()
{
    GradZLinXPipeline gradZLinX;
    cout << endl << "Demo of class " << typeid(gradZLinX).name();
10    cout << endl << "size : " << sizeof(GradZLinXPipeline) << " Bytes";
    cout << endl << "public member functions:";
    cout << endl << "GradZLinXPipeline gradZLinX; = " << gradZLinX;
    cout << endl << "End of demo of class " << typeid(gradZLinX).name() <<
endl;
15    } // Demo

////////////////////////////////////
// constructors & destructors

20    // static first init
int GradZLinXPipeline::numOfChips          = 0;
int GradZLinXPipeline::numOfPipelinesPerChip = 0;
int GradZLinXPipeline::blockSize          = 0;
Cube4 *GradZLinXPipeline::cube4          = 0;

25    GradZLinXPipeline::GradZLinXPipeline()
{
    int blockBeamDelay = blockSize / numOfPipelinesPerChip;

    blockBeamGradientFiFo.SetSize(blockBeamDelay);
30    } // constructor

GradZLinXPipeline::~GradZLinXPipeline()
{
35    } // destructor

////////////////////////////////////
// show/set data & data properties

40    ostream & GradZLinXPipeline::Ostream(ostream & os) const
{
    // append GradZLinXPipeline info to os
    os << typeid(*this).name() << "@" << (void *) this;
    os << endl << "    numOfChips          = " << numOfChips;
45    os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
    os << endl << "    chipIndex          = " << chipIndex;

    // return complete os
    return os;
50
55

```

```

} // Ostream

5
// //////////////////////////////////////
// show/set data & data properties
//
// - local show/set functions

10
void GradZLinXPipeline::GlobalSetup(const int setNumOfChips,

                                const int setNumOfPipelinesPerChip,

                                const int setBlockSize)
15
{
    numOfChips          = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    blockSize           = setBlockSize;
} // GlobalSetup

20
void GradZLinXPipeline::LocalSetup(const int setChipIndex,

                                const int setPipelineIndex,

                                GradZLinXStage & gradZLinXStage)
25
{
    chipIndex = setChipIndex;
    pipelineIndex = setPipelineIndex;

    inputs.gz = &(gradZLinXStage.inputs.gz[pipelineIndex]);
    rightNeighborGz = &(gradZLinXStage.inputs.gz[pipelineIndex+1]);
30
    inputs.weightsXYZ = &(gradZLinXStage.inputs.weightsXYZ[pipelineIndex]);
    inputs.perChipControlFlags
        = gradZLinXStage.inputs.perChipControlFlags;
    inputs.perPipelineControlFlags
        = &(gradZLinXStage.inputs.perPipelineControlFlags[pipelineIndex]);
35

    tempResults.gz = &(gradZLinXStage.tempResults.gz[pipelineIndex]);
    tempResults.perChipControlFlags
        = &(gradZLinXStage.tempResults.perChipControlFlags);
    results.gz = &(gradZLinXStage.results.gz[pipelineIndex]);
40
    results.perChipControlFlags
        = &(gradZLinXStage.results.perChipControlFlags);

    cube4 = gradZLinXStage.cube4;
} // LocalSetup

45
void GradZLinXPipeline::PerFrameSetup()
{
    // reset pipeline registers already done in GradZLinXStage
    blockBeamGradientFiFo.Preset(*(inputs.gz));
50

55

```

55


```

#include "Voxel.h"
#include "Coxel.h"
5  #include "Control.h"
#include "FixPointNumber.h"

class GradZLinXStage;
class Cube4;

10  class GradZLinXPipelineInputs {
public: // pointers
    ScalarGradient *gz; // partially interpolated
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags *perChipControlFlags;
15  PerPipelineControlFlags *perPipelineControlFlags;
};

class GradZLinXPipelineResults {
20  public: // pointers
    ScalarGradient *gz; // now also x-interpolated
    PerChipControlFlags *perChipControlFlags;
};

25  class GradZLinXPipeline : virtual public Object {
public:

    static void Demo ();

30  // constructors & destructors
    GradZLinXPipeline ();
    ~GradZLinXPipeline ();

35  // show/set data & data properties
    // - class Object requirements
    virtual ostream & Ostream (ostream & ) const;

    // - local show/set functions
40  static void GlobalSetup (const int setNumOfChips,

    const int setNumOfPipelinesPerChip,

    const int setBlockSize);

45  virtual void LocalSetup(const int setChipIndex,

    const int setPipelineIndex,

    GradZLinXStage & gradZLinXStage);
50  virtual void PerFrameSetup();
    // local computation functions
    virtual void RunForOneClockCycle();

55

```

192

```

public:
    GradZLinXPipelineInputs inputs;
    GradZLinXPipelineResults tempResults;
5    GradZLinXPipelineResults results;

protected:
    ScalarGradient *rightNeighborGz;
10    FiFo<ScalarGradient> blockBeamGradientFiFo;

    static int    numOfChips, numOfPipelinesPerChip, blockSize;
    static Cube4 *cube4;
    int          chipIndex, pipelineIndex;
15 };

#include "GradZLinXStage.h"
#include "Cube4.h"

#ifdef          // _GradZLinXPipeline_h_
20 :::::::::::::::
    cube4/GradZLinXStage.C
    :::::::::::::::
    // GradZLinXStage.C
    // (c) Ingmar Bitter '97

25 // Copyright, Mitsubishi Electric Information Technology Center
    // America, Inc., 1997, All rights reserved.

#include "GradZLinXStage.h"

30 void GradZLinXStage::Demo()
{
    GradZLinXStage gradZLinX;
    cout << endl <<"Demo of class " << typeid(gradZLinX).name();
    cout << endl <<"size : " << sizeof(GradZLinXStage) << " Bytes";
35    cout << endl <<"public member functions:";
    cout << endl <<"GradZLinXStage gradZLinX; = " << gradZLinX;
    cout << endl << "End of demo of class "<< typeid(gradZLinX).name() <<
    endl;
} // Demo
40

////////////////////////////////////
// constructors & destructors

// static first init
45 int GradZLinXStage::numOfChips      = 0;
int GradZLinXStage::numOfPipelinesPerChip = 0;
int GradZLinXStage::blockSize        = 0;
Cube4 *GradZLinXStage::cube4 = 0;

50 GradZLinXStage::GradZLinXStage()
{

55

```

```

193
    gradZLinXPipeline = new          GradZLinXPipeline
[numOfPipelinesPerChip];
5    tempResults.gz = new ScalarGradient [numOfPipelinesPerChip];
    results.gz = new ScalarGradient [numOfPipelinesPerChip];

    int blockBeamDelay = blockSize / numOfPipelinesPerChip;
    blockBeamControlFiFo.SetSize(blockBeamDelay);
} // constructor

10

GradZLinXStage::~GradZLinXStage()
{
    if (gradZLinXPipeline) { delete gradZLinXPipeline; gradZLinXPipeline=0;
}
15    if (tempResults.gz)    { delete tempResults.gz;    tempResults.gz=0; }
    if (results.gz)        { delete results.gz;        results.gz=0; }
} // destructor

//////////////////////////////////////
20 // show/set data & data properties

ostream & GradZLinXStage::Ostream(ostream & os) const
{
    // append GradZLinXStage info to os
25    os << typeid(*this).name() << "@" << (void *) this;
    os << endl << "    numOfChips          = " << numOfChips;
    os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
    os << endl << "    chipIndex            = " << chipIndex;

    // return complete os
30    return os;
} // Ostream

35
//////////////////////////////////////
// show/set data & data properties
//
// - local show/set functions

40 void GradZLinXStage::GlobalSetup(const int setNumOfChips,
                                   const int setNumOfPipelinesPerChip,
                                   const int setBlockSize,
45                                   Cube4 *setCube4)
{
    numOfChips          = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
50
55

```

```

194
    blockSize          =          setBlockSize;
    cube4              = setCube4;
5   GradZLinXPipeline::GlobalSetup(numOfChips, numOfPipelinesPerChip,
    blockSize);
} // GlobalSetup

void GradZLinXStage::LocalSetup(const int setChipIndex)
10 {
    chipIndex = setChipIndex;
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        gradZLinXPipeline[p].LocalSetup(chipIndex,p,*this);
    }
15 } // LocalSetup

void GradZLinXStage::PerFrameSetup()
{
    int p;
20    // reset pipeline registers
    for (p=0; p<numOfPipelinesPerChip; ++p) {
        results.gz[p] = 0;
    }
    tempResults.perChipControlFlags.Reset();
    results.perChipControlFlags.Reset();
25    blockBeamControlFiFo.Preset(tempResults.perChipControlFlags);

    for (p=0; p<numOfPipelinesPerChip; ++p) {
        gradZLinXPipeline[p].PerFrameSetup();
    }

30    // print debug info
    //static bool first(true); if (first) { cout<<this<<endl; first=false; }
} // PerFrameSetup

35    //////////////////////////////////////
    // local computation functions

void GradZLinXStage::RunForOneClockCycle()
{
40    // communication
    inputs.gz[numOfPipelinesPerChip] = 0;
    //          = cube4->gradZLinX[chipIndex+1].inputs.voxel[0];

    // computation
    blockBeamControlFiFo.Exchange(tempResults.perChipControlFlags,
45    results.perChipControlFlags);

    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        gradZLinXPipeline[p].RunForOneClockCycle();
    }
50

55

```

```

195
tempResults.perChipControlFlags = *(inputs.perChipControlFlags);
} // RunForOneClockCycle

5

//////////////////////////////////////
// internal utility functions

10
// end of GradZLinXStage.C
::::::::::::::::::
cube4/GradZLinXStage.h
::::::::::::::::::
// GradZLinXStage.h
15
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

20
#ifdef _GradZLinXStage_h_    // prevent multiple includes
#define _GradZLinXStage_h_

#include "Misc.h"
#include "Object.h"
#include "Voxel.h"
25
#include "Control.h"
#include "GradZLinXPipeline.h"
#include "FixPointNumber.h"
#include "Cube4.h"

30
class Cube4;

class GradZLinXStageInputs {
public: // pointers
    ScalarGradient *gz; // partially interpolated
35
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags      *perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

40
class GradZLinXStageResults {
public: // arrays
    ScalarGradient *gz; // now also x-interpolated
    PerChipControlFlags      perChipControlFlags;
};

45

class GradZLinXStage : virtual public Object {
public:

50
    static void      Demo ();

        // constructors & destructors

```

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```

GradZLinXStage ();
~GradZLinXStage ();

5 // show/set data & data properties
  // - class Object requirements
  virtual ostream & Ostream (ostream & )    const;

10 // - local show/set functions
  static void GlobalSetup (const int setNumOfChips,

    const int setNumOfPipelinesPerChip,

    const int setBlockSize,

15    Cube4 *setCube4);
  virtual void LocalSetup (const int setChipIndex);
  virtual void PerFrameSetup ();
  // local computation functions
20  virtual void RunForOneClockCycle();

public:
  GradZLinXPipeline *gradZLinXPipeline;
  GradZLinXStageInputs inputs;
25  GradZLinXStageResults tempResults;
  GradZLinXStageResults results;
  FiFo<PerChipControlFlags> blockBeamControlFiFo;

protected:
  static int    numOfChips, numOfPipelinesPerChip, blockSize;
30  static Cube4 *cube4;
  int          chipIndex;

  friend class GradZLinXPipeline;
};

35 #endif // _GradZLinXStage_h_
.....
cube4/GradZLinYPipeline.C
.....
40 // GradZLinYPipeline.C
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

45 #include "GradZLinYPipeline.h"

void GradZLinYPipeline::Demo()
{
  GradZLinYPipeline gradZLinY;
50  cout << endl <<"Demo of class " << typeid(gradZLinY).name();
  cout << endl <<"size : " << sizeof(GradZLinYPipeline) << " Bytes";
  cout << endl <<"public member functions:";

55

```

```

197
    cout << endl << "GradZLinYPipeline  gradZLinY; = " << gradZLinY;
    cout << endl << "End of demo of class " << typeid(gradZLinY).name() <<
5   endl;
    } // Demo

////////////////////////////////////
10  // constructors & destructors

    // static first init
    int GradZLinYPipeline::numOfChips          = 0;
    int GradZLinYPipeline::numOfPipelinesPerChip = 0;
    int GradZLinYPipeline::blockSize           = 0;
15  int GradZLinYPipeline::maxDatasetSizeX      = 256;
    Cube4 *GradZLinYPipeline::cube4            = 0;

    GradZLinYPipeline::GradZLinYPipeline()
    {
20      // step delay for a y-step within a block
        int beamDelay = (maxDatasetSizeX

                                ) /

        (numOfChips*numOfPipelinesPerChip);

        // step delay for a y-step between blocks
25      int blockBeamDelay = beamDelay * blockSize;

        beamGradientFiFo.SetSize(beamDelay);
        beamWeightsFiFo.SetSize(beamDelay);
        beamPerPipelineControlFlagsFiFo.SetSize(beamDelay);
        beamPerChipControlFlagsFiFo.SetSize(beamDelay);
30      blockBeamGradientFiFo.SetSize(blockBeamDelay);
        blockBeamWeightsFiFo.SetSize(blockBeamDelay);
        blockBeamPerPipelineControlFlagsFiFo.SetSize(blockBeamDelay);
        blockBeamPerChipControlFlagsFiFo.SetSize(blockBeamDelay);
35    } // constructor

    GradZLinYPipeline::~GradZLinYPipeline()
    {
40    } // destructor

////////////////////////////////////
    // show/set data & data properties

45  ostream & GradZLinYPipeline::Ostream(ostream & os) const
    {
        // append GradZLinYPipeline info to os
        os << typeid(*this).name() << "@" << (void *) this;
        os << endl << "    numOfChips          = " << numOfChips;
50      os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;

55

```

```

                                198
                                os <<endl<< "  chipIndex          = " << chipIndex;

5      // return complete os
      return os;

      } // Ostream

10     //////////////////////////////////////
      // show/set data & data properties
      //
      // - local show/set functions

15     void GradZLinYPipeline::GlobalSetup(const int setNumOfChips,
                                           const int setNumOfPipelinesPerChip,,
                                           const int setBlockSize)
    {
20         numOfChips          = setNumOfChips;
         numOfPipelinesPerChip = setNumOfPipelinesPerChip;
         blockSize            = setBlockSize;
    } // GlobalSetup

25     void GradZLinYPipeline::LocalSetup(const int setChipIndex,
                                           const int setPipelineIndex,
                                           GradZLinYStage & gradZLinYStage)
30     {
         chipIndex = setChipIndex;
         pipelineIndex = setPipelineIndex;

         inputs.gz = &(gradZLinYStage.inputs.gz[pipelineIndex]);
         inputs.weightsXYZ = &(gradZLinYStage.inputs.weightsXYZ[pipelineIndex]);
35         inputs.perChipControlFlags
            = gradZLinYStage.inputs.perChipControlFlags;
         inputs.perPipelineControlFlags
            = &(gradZLinYStage.inputs.perPipelineControlFlags[pipelineIndex]);

         results.gz = &(gradZLinYStage.results.gz[pipelineIndex]);
40         results.weightsXYZ = &(gradZLinYStage.results.weightsXYZ[pipelineIndex]);
         results.perPipelineControlFlags
            = &(gradZLinYStage.results.perPipelineControlFlags[pipelineIndex]);
         results.perChipControlFlags
            = &(gradZLinYStage.results.perChipControlFlags);

45         cube4 = gradZLinYStage.cube4;
    } // LocalSetup

50

55

```



```

199
void GradZLinYPipeline::PerFrameSetup()
{
5      // reset pipeline registers already done in GradZLinYStage

      // resize fifo's according to dataset size
      // step delay for a y-step within a block
      int beamDelay = (cube4->datasetSizeXYZ.X()
10      (numOfChips*numOfPipelinesPerChip);

      // step delay for a y-step between blocks
      int blockBeamDelay = beamDelay * blockSize;

      beamGradientFiFo.SetSize(beamDelay);
15      beamWeightsFiFo.SetSize(beamDelay);
      beamPerPipelineControlFlagsFiFo.SetSize(beamDelay);
      beamPerChipControlFlagsFiFo.SetSize(beamDelay);

      blockBeamGradientFiFo.SetSize(blockBeamDelay);
      blockBeamWeightsFiFo.SetSize(blockBeamDelay);
20      blockBeamPerPipelineControlFlagsFiFo.SetSize(blockBeamDelay);
      blockBeamPerChipControlFlagsFiFo.SetSize(blockBeamDelay);

      beamGradientFiFo.Preset(*(inputs.gz));
      beamWeightsFiFo.Preset(*(inputs.weightsXYZ));
      beamPerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineControlFlags));
25      beamPerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFlags));

      blockBeamGradientFiFo.Preset(*(inputs.gz));
      blockBeamWeightsFiFo.Preset(*(inputs.weightsXYZ));
      blockBeamPerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineControlFla
30      gs));
      blockBeamPerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFlags));

      readBigFiFoCounter = readSmallFiFoCounter =
          writeBigFiFoCounter = writeSmallFiFoCounter = -1;
      } // PerFrameSetup
35

      //////////////////////////////////////
      // local computation functions

void GradZLinYPipeline::RunForOneClockCycle()
40      {
      // reset counters
      if (inputs.perChipControlFlags->volumeStart ||
          ((readBigFiFoCounter == 0) &&
            (readSmallFiFoCounter == 0) &&
            (writeBigFiFoCounter == 0) &&
45            (writeSmallFiFoCounter == 0))) {

          readBigFiFoCounter = (cube4->datasetSizeXYZ.X())
50

55

```

200

```

5      ) / (numOfChips*numOfPipelinesPerChip);
        readSmallFiFoCounter = (blockSize-1) * readBigFiFoCounter;

        writeBigFiFoCounter = readBigFiFoCounter;
        writeSmallFiFoCounter = readSmallFiFoCounter;
    }

10     //////////////////////////////////////
    // first read from FiFos into results register

    // at start of block read from big FiFo
    if (readBigFiFoCounter > 0) {
        blockBeamGradientFiFo.Read(outFiFo);
15        blockBeamWeightsFiFo.Read(*(results.weightsXYZ));

        blockBeamPerPipelineControlFlagsFiFo.Read(*(results.perPipelineControlFlags));

        blockBeamPerChipControlFlagsFiFo.Read(*(results.perChipControlFlags));
20        --readBigFiFoCounter;
    }

    // in middle and at end of block read from small FiFo
    else if (readSmallFiFoCounter > 0) {
        beamGradientFiFo.Read(outFiFo);
25        beamWeightsFiFo.Read(*(results.weightsXYZ));

        beamPerPipelineControlFlagsFiFo.Read(*(results.perPipelineControlFlags));
        beamPerChipControlFlagsFiFo.Read(*(results.perChipControlFlags));
        --readSmallFiFoCounter;
30    }

    //////////////////////////////////////
    // now write to FiFos from inputs register

    // at start and in middle of block write to small FiFo
35    if (writeSmallFiFoCounter > 0) {
        beamGradientFiFo.Write(*(inputs.gz));
        beamWeightsFiFo.Write(*(inputs.weightsXYZ));

        beamPerPipelineControlFlagsFiFo.Write(*(inputs.perPipelineControlFlags));
        beamPerChipControlFlagsFiFo.Write(
40        *(inputs.perChipControlFlags));
        --writeSmallFiFoCounter;
    }

    // at end of block write to big FiFo of next chip
    else if (writeBigFiFoCounter > 0) {
45        ModInt c(chipIndex+1, numOfChips);
        int p(pipelineIndex);
        GradZLinYPipeline *next(&cube4->gradZLinY[c].gradZLinYPipeline[p]);
        next->blockBeamGradientFiFo.Write(*(inputs.gz));
50
55

```

55

```

#include "Voxel.h"
#include "Coxel.h"
5  #include "Control.h"
#include "FixPointNumber.h"

class GradZLinYStage;
class Cube4;

10 typedef Vector3D<FixPointNumber> FixPointVector3D;

class GradZLinYPipelineInputs {
public: // pointers
    ScalarGradient *gz; // partially interpolated
15     Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags *perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

20 class GradZLinYPipelineResults {
public: // pointers
    ScalarGradient *gz; // now also y-interpolated
    Vector3D<FixPointNumber> *weightsXYZ;
25     PerChipControlFlags *perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

30 class GradZLinYPipeline : virtual public Object {
public:

    static void      Demo ();

    // constructors & destructors
35     GradZLinYPipeline ();
    ~GradZLinYPipeline ();

    // show/set data & data properties
    // - class Object requirements
40     virtual ostream & Ostream (ostream & ) const;

    // - local show/set functions
    static void GlobalSetup (const int setNumOfChips,

45     const int setNumOfPipelinesPerChip,
    const int setBlockSize);

    virtual void LocalSetup(const int setChipIndex,

50     const int setPipelineIndex,
    GradZLinYStage & gradZLinYStage);

55

```

```

    virtual void PerFrameSetup();
    // local computation functions
5    virtual void RunForOneClockCycle();

public:
    GradZLinYPipelineInputs inputs;
    GradZLinYPipelineResults results;

10 protected:
    FiFo<ScalarGradient>          beamGradientFiFo;
    FiFo<FixPointVector3D>        beamWeightsFiFo;
    FiFo<PerPipelineControlFlags> beamPerPipelineControlFlagsFiFo;
    FiFo<PerChipControlFlags>     beamPerChipControlFlagsFiFo;

15
    FiFo<ScalarGradient>          blockBeamGradientFiFo;
    FiFo<FixPointVector3D>        blockBeamWeightsFiFo;
    FiFo<PerPipelineControlFlags> blockBeamPerPipelineControlFlagsFiFo;
    FiFo<PerChipControlFlags>     blockBeamPerChipControlFlagsFiFo;

20
    ScalarGradient outFiFo;

    int  readSmallFiFoCounter, readBigFiFoCounter;
    int  writeSmallFiFoCounter, writeBigFiFoCounter;

25
    static int  numOfChips, numOfPipelinesPerChip, blockSize;
    static int  maxDatasetSizeX;
    static Cube4 *cube4;
    int         chipIndex, pipelineIndex; ,

30 };

#include "GradZLinYStage.h"
#include "Cube4.h"

#ifdef      // _GradZLinYPipeline_h_
35 :.....:
cube4/GradZLinYStage.C
:.....:
// GradZLinYStage.C
// (c) Ingmar Bitter '97

40
// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include "GradZLinYStage.h"

45 void GradZLinYStage::Demo()
{
    GradZLinYStage gradZLinY;
    cout << endl <<"Demo of class " << typeid(gradZLinY).name();
    cout << endl <<"size : " << sizeof(GradZLinYStage) << " Bytes";
50 cout << endl <<"public member functions:";
    cout << endl <<"GradZLinYStage gradZLinY; = " << gradZLinY;

```

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```

    cout << endl << "End of demo of      class "<< typeid(gradZLinY).name() <<
endl;
} // Demo

5

////////////////////////////////////
// constructors & destructors

10 // static first init
int GradZLinYStage::numOfChips      = 0;
int GradZLinYStage::numOfPipelinesPerChip = 0;
Cube4 *GradZLinYStage::cube4 = 0;

GradZLinYStage::GradZLinYStage()
15 {
    gradZLinYPipeline = new GradZLinYPipeline [numOfPipelinesPerChip];
    results.gz = new ScalarGradient [numOfPipelinesPerChip+1]; // +1 for
communication
    results.weightsXYZ = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];
    results.perPipelineControlFlags = new PerPipelineControlFlags
20 [numOfPipelinesPerChip];
} // defaultconstructor

GradZLinYStage::~GradZLinYStage()
25 {
    if (gradZLinYPipeline) { delete gradZLinYPipeline; gradZLinYPipeline=0;
    }
    if (results.gz) { delete results.gz; results.gz=0; }
    if (results.weightsXYZ) { delete results.weightsXYZ; results.weightsXYZ=0;
    }
30    if (results.perPipelineControlFlags) {
        delete results.perPipelineControlFlags;
        results.perPipelineControlFlags=0;
    }
} // destructor

35

////////////////////////////////////
// show/set data & data properties

ostream & GradZLinYStage::Ostream(ostream & os) const
40 {
    // append GradZLinYStage info to os
    os << typeid(*this).name() << "@" << (void *) this;
    os <<endl<< "    numOfChips      = " << numOfChips;
    os <<endl<< "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
45    os <<endl<< "    chipIndex      = " << chipIndex;

    // return complete os
    return os;
}

```

```

} // Ostream

5
////////////////////////////////////
// show/set data & data properties
//
// - local show/set functions

10
void GradZLinYStage::GlobalSetup(const int setNumOfChips,

                                const int setNumOfPipelinesPerChip,

                                const int setBlockSize,

15
                                Cube4 *setCube4)
{
    numOfChips = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    GradZLinYPipeline::GlobalSetup(numOfChips, numOfPipelinesPerChip,
20
                                setBlockSize);
    cube4 = setCube4;
} // GlobalSetup

25
void GradZLinYStage::LocalSetup(const int setChipIndex)
{
    chipIndex = setChipIndex;
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        gradZLinYPipeline[p].LocalSetup(chipIndex,p,*this);
30
    }
} // LocalSetup

void GradZLinYStage::PerFrameSetup()
{
35
    int p;
    // reset pipeline registers
    for (p=0; p<numOfPipelinesPerChip; ++p) {
        results.gz[p] = 0;
        results.weightsXYZ[p](0,0,0);
40
        results.perPipelineControlFlags[p].Reset();
    }
    results.perChipControlFlags.Reset();

    for (p=0; p<numOfPipelinesPerChip; ++p) {
        gradZLinYPipeline[p].PerFrameSetup();
45
    }

    // print debug info
    //static bool first(true); if (first) { cout<<this<<endl; first=false; }
} // PerFrameSetup

50

55

```

```

5  ///////////////////////////////////////////////////////////////////
   // local computation functions

   void GradZLinYStage::RunForOneClockCycle()
   {
10      // communication

      // computation
      for (int p=0; p<numOfPipelinesPerChip; ++p) {
          gradZLinYPipeline[p].RunForOneClockCycle();
      }
15  } // RunForOneClockCycle

   ///////////////////////////////////////////////////////////////////
   // internal utility functions

20

   // end of GradZLinYStage.C
   :::::::::::::::
   cube4/GradZLinYStage.h
   :::::::::::::::
25  // GradZLinYStage.h
   // (c) Ingmar Bitter '97

   // Copyright, Mitsubishi Electric Information Technology Center
   // America, Inc., 1997, All rights reserved.

30  #ifndef _GradZLinYStage_h_    // prevent multiple includes
   #define _GradZLinYStage_h_

   #include "Misc.h"
   #include "Object.h"
35  #include "Vector3D.h"
   #include "Voxel.h"
   #include "Control.h"
   #include "GradZLinYPipeline.h"
   #include "FixPointNumber.h"
40  #include "Cube4.h"

   class Cube4;

   class GradZLinYStageInputs {
45  public: // pointers
      ScalarGradient *gz; // partially interpolated
      Vector3D<FixPointNumber> *weightsXYZ;
      PerChipControlFlags      *perChipControlFlags;
      PerPipelineControlFlags  *perPipelineControlFlags;
50  };

```

55


```

class GradZLinYStageResults {
public: // arrays
5     ScalarGradient *gz; // now also y-interpolated
     Vector3D<FixPointNumber> *weightsXYZ;
     PerChipControlFlags      perChipControlFlags;
     PerPipelineControlFlags *perPipelineControlFlags;
};

10

class GradZLinYStage : virtual public Object {
public:

15     static void      Demo ();

     // constructors & destructors
     GradZLinYStage ();
     ~GradZLinYStage ();

20     // show/set data & data properties
     // - class Object requirements
     virtual ostream & Ostream (ostream & )    const;

     // - local show/set functions
25     static void GlobalSetup (const int setNumOfChips,

     const int setNumOfPipelinesPerChip,

     const int setBlockSize,

30     Cube4 *setCube4);
     virtual void LocalSetup (const int setChipIndex);
     virtual void PerFrameSetup ();
     // local computation functions
     virtual void RunForOneClockCycle();

35
public:
     GradZLinYPipeline *gradZLinYPipeline;
     GradZLinYStageInputs inputs;
     GradZLinYStageResults results;

40
protected:
     static int      numOfChips, numOfPipelinesPerChip;
     static Cube4 *cube4;
     int             chipIndex;

45     friend class GradZLinYPipeline;
};

#endif // _GradZLinYStage_h_
:::
50 cube4/GradZLinZPipeline.C
:::
// GradZLinZPipeline.C

```

```

// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include "GradZLinZPipeline.h"

void GradZLinZPipeline::Demo()
{
    GradZLinZPipeline gradZLinZ;
    cout << endl << "Demo of class " << typeid(gradZLinZ).name();
    cout << endl << "size : " << sizeof(GradZLinZPipeline) << " Bytes";
    cout << endl << "public member functions:";
    cout << endl << "GradZLinZPipeline gradZLinZ; = " << gradZLinZ;
    cout << endl << "End of demo of class " << typeid(gradZLinZ).name() <<
endl;
} // Demo

////////////////////////////////////
// constructors & destructors

// static first init
int GradZLinZPipeline::numOfChips          = 0;
int GradZLinZPipeline::numOfPipelinesPerChip = 0;
int GradZLinZPipeline::blockSize          = 0;
int GradZLinZPipeline::maxDatasetSizeX    = 256;
int GradZLinZPipeline::maxDatasetSizeY    = 256;
Cube4 *GradZLinZPipeline::cube4          = 0;

GradZLinZPipeline::GradZLinZPipeline()
{
    // step delay for a z-step within a block
    int blockSliceDelay = (maxDatasetSizeX*blockSize
                                                                    ) /
(numOfChips*numOfPipelinesPerChip);

    // step delay for a z-step between blocks
    int volumeSliceDelay = (maxDatasetSizeX*maxDatasetSizeY
                                                                    )
/ (numOfChips*numOfPipelinesPerChip);

    blockSliceGradientFiFo.SetSize(blockSliceDelay);
    blockSliceWeightsFiFo.SetSize(blockSliceDelay);
    blockSlicePerPipelineControlFlagsFiFo.SetSize(blockSliceDelay);
    blockSlicePerChipControlFlagsFiFo.SetSize(blockSliceDelay);

    volumeSliceGradientFiFo.SetSize(volumeSliceDelay);
    volumeSliceWeightsFiFo.SetSize(volumeSliceDelay);
    volumeSlicePerPipelineControlFlagsFiFo.SetSize(volumeSliceDelay);
    volumeSlicePerChipControlFlagsFiFo.SetSize(volumeSliceDelay);
} // constructor

```

```

GradZLinZPipeline::~GradZLinZPipeline()
5 {
  } // destructor

////////////////////////////////////
10 // show/set data & data properties

ostream & GradZLinZPipeline::Ostream(ostream & os) const
{
  // append GradZLinZPipeline info to os
  os << typeid(*this).name() << "@" << (void *) this;
15   os << endl << "   numOfChips           = " << numOfChips;
   os << endl << "   numOfPipelinesPerChip = " << numOfPipelinesPerChip;
   os << endl << "   chipIndex           = " << chipIndex;

  // return complete os
20   return os;
} // Ostream

////////////////////////////////////
25 // show/set data & data properties
//
// - local show/set functions

30 void GradZLinZPipeline::GlobalSetup(const int setNumOfChips,
                                     const int setNumOfPipelinesPerChip,
                                     const int setBlockSize)
{
35   numOfChips           = setNumOfChips;
   numOfPipelinesPerChip = setNumOfPipelinesPerChip;
   blockSize            = setBlockSize;
} // GlobalSetup

40 void GradZLinZPipeline::LocalSetup(const int setChipIndex,
                                     const int setPipelineIndex,
                                     GradZLinZStage & gradZLinZStage)
45 {
   chipIndex = setChipIndex;
   pipelineIndex = setPipelineIndex;

   inputs.gz = &(gradZLinZStage.inputs.gz[pipelineIndex]);
   inputs.weightsXYZ = &(gradZLinZStage.inputs.weightsXYZ[pipelineIndex]);
50

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```

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```

    inputs.perChipControlFlags
        = gradZLinZStage.inputs.perChipControlFlags;
5    inputs.perPipelineControlFlags
        = &(gradZLinZStage.inputs.perPipelineControlFlags[pipelineIndex]);

    results.gz = &(gradZLinZStage.results.gz[pipelineIndex]);
    results.weightsXYZ = &(gradZLinZStage.results.weightsXYZ[pipelineIndex]);
    results.perPipelineControlFlags
10    = &(gradZLinZStage.results.perPipelineControlFlags[pipelineIndex]);
    results.perChipControlFlags
        = &(gradZLinZStage.results.perChipControlFlags);

    cube4 = gradZLinZStage.cube4;
} // LocalSetup
15

void GradZLinZPipeline::PerFrameSetup()
{
    // reset pipeline registers already done in GradZLinZStage

20    // resize fifo's according to dataset size
    // step delay for a z-step within a block
    int blockSliceDelay = (cube4->datasetSizeXYZ.X()*blockSize
                                                                    ) /
        (numOfChips*numOfPipelinesPerChip);

25    // step delay for a z-step between blocks
    int volumeSliceDelay = (cube4->datasetSizeXYZ.X()*cube4-
        >datasetSizeXYZ.Y()
                                                                    )
        / (numOfChips*numOfPipelinesPerChip);

30    blockSliceGradientFiFo.SetSize(blockSliceDelay);
    blockSliceWeightsFiFo.SetSize(blockSliceDelay);
    blockSlicePerPipelineControlFlagsFiFo.SetSize(blockSliceDelay);
    blockSlicePerChipControlFlagsFiFo.SetSize(blockSliceDelay);

35    volumeSliceGradientFiFo.SetSize(volumeSliceDelay);
    volumeSliceWeightsFiFo.SetSize(volumeSliceDelay);
    volumeSlicePerPipelineControlFlagsFiFo.SetSize(volumeSliceDelay);
    volumeSlicePerChipControlFlagsFiFo.SetSize(volumeSliceDelay);

    blockSliceGradientFiFo.Preset(*(inputs.gz));
    blockSliceWeightsFiFo.Preset(*(inputs.weightsXYZ));
40    blockSlicePerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineControlFl
ags));
    blockSlicePerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFlags));

    volumeSliceGradientFiFo.Preset(*(inputs.gz));
    volumeSliceWeightsFiFo.Preset(*(inputs.weightsXYZ));
45    volumeSlicePerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineControlF
lags));
    volumeSlicePerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFlags));

```

50

55

```

    readBigFiFoCounter = readSmallFiFoCounter =
    writeBigFiFoCounter = writeSmallFiFoCounter = -1;
5  } // PerFrameSetup

////////////////////////////////////
// local computation functions
10 void GradZLinZPipeline::RunForOneClockCycle()
{
    // reset counters
    if (inputs.perChipControlFlags->volumeStart ||
        ((readBigFiFoCounter == 0) &&
15         (readSmallFiFoCounter == 0) &&
         (writeBigFiFoCounter == 0) &&
         (writeSmallFiFoCounter == 0))) {

        readBigFiFoCounter = (cube4->datasetSizeXYZ.X()*blockSize
20         / (numOfChips*numOfPipelinesPerChip);
        readSmallFiFoCounter = (blockSize-1) * readBigFiFoCounter;

        writeBigFiFoCounter = readBigFiFoCounter;
        writeSmallFiFoCounter = readSmallFiFoCounter;
25     }

    //////////////////////////////////
    // first read from FiFos into results register

    // at start of block read from big FiFo
30     if (readBigFiFoCounter > 0) {
        volumeSliceGradientFiFo.Read(outFiFo);
        volumeSliceWeightsFiFo.Read(*(results.weightsXYZ));

        volumeSlicePerPipelineControlFlagsFiFo.Read(*(results.perPipelineControlFl
35         ags));

        volumeSlicePerChipControlFlagsFiFo.Read(*(results.perChipControlFlags));
        --readBigFiFoCounter;
        // if (chipIndex == 0 && pipelineIndex == 0)
        cout<<"R"<<*(results.voxel)<<volumeSliceGradientFiFo<<endl;
40     }

    // in middle and at end of block read from small FiFo
    else if (readSmallFiFoCounter > 0) {
        blockSliceGradientFiFo.Read(outFiFo);
        blockSliceWeightsFiFo.Read(*(results.weightsXYZ));
45     }

    blockSlicePerPipelineControlFlagsFiFo.Read(*(results.perPipelineControlFla
        gs));

    blockSlicePerChipControlFlagsFiFo.Read(*(results.perChipControlFlags));
50

55

```

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```

--readSmallFiFoCounter;
// if (chipIndex == 0 && pipelineIndex == 0)    cout<<"r";
5      }

////////////////////////////////////
// now write to FiFos from inputs register

10     // at start and in middle of block write to small FiFo
    if (writeSmallFiFoCounter > 0) {
        blockSliceGradientFiFo.Write(*(inputs.gz));
        blockSliceWeightsFiFo.Write(*(inputs.weightsXYZ) );

        blockSlicePerPipelineControlFlagsFiFo.Write(*(inputs.perPipelineControlFlags));
15    }
    blockSlicePerChipControlFlagsFiFo.Write(
        *(inputs.perChipControlFlags));
        --writeSmallFiFoCounter;
        // if (chipIndex == 0 && pipelineIndex == 0) cout<<"w";
20    }

    // at end of block write to big FiFo of next chip
    else if (writeBigFiFoCounter > 0) {
        ModInt c(chipIndex+1, numOfChips);
        int p(pipelineIndex);
        GradZLinZPipeline *next(&cube4->gradZLinZ[c].gradZLinZPipeline[p]);
25    next->volumeSliceGradientFiFo.Write(*(inputs.gz));
        next->volumeSliceWeightsFiFo.Write(*(inputs.weightsXYZ) );
        next->volumeSlicePerPipelineControlFlagsFiFo.Write(*(inputs.perPipelineControlFlags));
        ;
30    next->volumeSlicePerChipControlFlagsFiFo.Write(*(inputs.perChipControlFlags));
        --writeBigFiFoCounter;
        //if (chipIndex == 0 && pipelineIndex == 0) cout<<"W";
    }

35    // Linear interpolation
        // c = w(b-a)+a
        //
        // w=0 -> c=a
        // w=1 -> c=b

40    if (cube4->cubeMode == Cube4Light) {
        // just pick current voxel (as if w=0)
        *(results.gz) = *(inputs.gz); // w=0;
        // use weights later on in composing
    }

45    else if (cube4->cubeMode == Cube4Classic) {
        // do real interpolation
        a(*(inputs.gz));
        b(outFiFo);
50
55

```

```

5      + a);
      }
      } // RunForOneClockCycle

////////////////////////////////////
10  // internal utility functions

// end of GradZLinZPipeline.C
:::::::::::::
cube4/GradZLinZPipeline.h
:::::::::::::
15  // GradZLinZPipeline.h
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

20  #ifndef _GradZLinZPipeline_h_ // prevent multiple includes
#define _GradZLinZPipeline_h_

#include "Misc.h"
#include "Object.h"
25  #include "FiFo.h"
#include "Voxel.h"
#include "Coxel.h"
#include "Control.h"
#include "FixPointNumber.h"

30  typedef Vector3D<FixPointNumber> FixPointVector3D;

class GradZLinZStage;
class Cube4;

class GradZLinZPipelineInputs {
35  public: // pointers
        ScalarGradient *gz; // on voxel grid
        Vector3D<FixPointNumber> *weightsXYZ;
        PerChipControlFlags *perChipControlFlags;
        PerPipelineControlFlags *perPipelineControlFlags;
40  };

class GradZLinZPipelineResults {
public: // pointers
        ScalarGradient *gz; // now z-interpolated
        Vector3D<FixPointNumber> *weightsXYZ;
45  PerChipControlFlags *perChipControlFlags;
        PerPipelineControlFlags *perPipelineControlFlags;
};

```

50

55

```

5  class GradZLinZPipeline : virtual public Object {
    public:

        static void      Demo ();

        // constructors & destructors
10     GradZLinZPipeline ();
        ~GradZLinZPipeline ();

        // show/set data & data properties
        // - class Object requirements
15     virtual ostream & Ostream (ostream & ) const;

        // - local show/set functions
        static void GlobalSetup (const int setNumOfChips,

20     const int setNumOfPipelinesPerChip,

        const int setBlockSize);

        virtual void LocalSetup(const int setChipIndex,

25     const int setPipelineIndex,

        GradZLinZStage & gradZLinZStage);
        virtual void PerFrameSetup();
        // local computation functions
30     virtual void RunForOneClockCycle();

    public:
        GradZLinZPipelineInputs inputs;
        GradZLinZPipelineResults results;

35     protected:
        FiFo<ScalarGradient>      blockSliceGradientFiFo;
        FiFo<FixPointVector3D>    blockSliceWeightsFiFo;
        FiFo<PerPipelineControlFlags> blockSlicePerPipelineControlFlagsFiFo;
        FiFo<PerChipControlFlags>  blockSlicePerChipControlFlagsFiFo;

40     FiFo<ScalarGradient>      volumeSliceGradientFiFo;
        FiFo<FixPointVector3D>    volumeSliceWeightsFiFo;
        FiFo<PerPipelineControlFlags> volumeSlicePerPipelineControlFlagsFiFo;
        FiFo<PerChipControlFlags>  volumeSlicePerChipControlFlagsFiFo;

45     int  readSmallFiFoCounter,  readBigFiFoCounter;
        int  writeSmallFiFoCounter, writeBigFiFoCounter;

        ScalarGradient outFiFo;
        FixPointNumber a,b;

50     static int  numOfChips, numOfPipelinesPerChip, blockSize;

```

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```

215
static int          maxDatasetSizeX,maxDatasetSizeY;
static Cube4 *cube4;
5   int             chipIndex, pipelineIndex;

    friend class Cube4;

}; // class GradZLinZPipeline

10  #include "GradZLinZStage.h"
    #include "Cube4.h"

    #endif          // _GradZLinZPipeline_h_
    :::::::::::::::
    cube4/GradZLinZStage.C
    :::::::::::::::
15  // GradZLinZStage.C
    // (c) Ingmar Bitter '97

    // Copyright, Mitsubishi Electric Information Technology Center .
    // America, Inc., 1997, All rights reserved.

20  #include "GradZLinZStage.h"

void GradZLinZStage::Demo()
{
25  GradZLinZStage gradZLinZ;
    cout << endl <<"Demo of class " << typeid(gradZLinZ).name();
    cout << endl <<"size : " << sizeof(GradZLinZStage) << " Bytes";
    cout << endl <<"public member functions:";
    cout << endl <<"GradZLinZStage gradZLinZ; = " << gradZLinZ;
    cout << endl << "End of demo of class "<< typeid(gradZLinZ).name() <<
30  endl;
} // Demo

////////////////////////////////////
// constructors & destructors

35  // static first init
int GradZLinZStage::numOfChips          = 0;
int GradZLinZStage::numOfPipelinesPerChip = 0;
Cube4 *GradZLinZStage::cube4 = 0;

40  GradZLinZStage::GradZLinZStage()
{
    gradZLinZPipeline = new GradZLinZPipeline [numOfPipelinesPerChip];
    results.gz = new ScalarGradient [numOfPipelinesPerChip];
    results.weightsXYZ = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];
    results.perPipelineControlFlags = new PerPipelineControlFlags
45  [numOfPipelinesPerChip];
} // defaultconstructor

```

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```

GradZLinZStage::~GradZLinZStage()
{
    if (gradZLinZPipeline) { delete gradZLinZPipeline; gradZLinZPipeline=0;
5      }
    if (results.gz) { delete results.gz; results.gz=0; }
    if (results.weightsXYZ) { delete results.weightsXYZ; results.weightsXYZ=0;
    }
    if (results.perPipelineControlFlags) {
10      delete results.perPipelineControlFlags;
      results.perPipelineControlFlags=0;
    }
} // destructor

15  //////////////////////////////////////
    // show/set data & data properties

ostream & GradZLinZStage::Ostream(ostream & os) const
{
20  // append GradZLinZStage info to os
    os << typeid(*this).name() << "@" << (void *) this;
    os <<endl<< "    numOfChips          = " << numOfChips;
    os <<endl<< "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
    os <<endl<< "    chipIndex            = " << chipIndex;

25  // return complete os
    return os;
} // Ostream

30  //////////////////////////////////////
    // show/set data & data properties
    //
    // - local show/set functions

35  void GradZLinZStage::GlobalSetup(const int setNumOfChips,
                                   const int setNumOfPipelinesPerChip,
                                   const int setBlockSize,
40  Cube4 *setCube4)
{
    numOfChips          = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    GradZLinZPipeline::GlobalSetup(numOfChips, numOfPipelinesPerChip,
45  setBlockSize);
    cube4 = setCube4;
} // GlobalSetup

```

50

55

55

```

// GradZLinZStage.h
// (c) Ingmar Bitter '97

5 // Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

// prevent multiple includes
10 #define _GradZLinZStage_h_

#include "Misc.h"
#include "Object.h"
#include "Vector3D.h"
#include "Voxel.h"
15 #include "Control.h"
#include "GradZLinZPipeline.h"
#include "FixPointNumber.h"
#include "Cube4.h"

20 class Cube4;

class GradZLinZStageInputs {
public: // pointers
    ScalarGradient *gz; // on voxel grid
    Vector3D<FixPointNumber> *weightsXYZ;
25     PerChipControlFlags *perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

30 class GradZLinZStageResults {
public: // arrays
    ScalarGradient *gz; // now z-interpolated
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags perChipControlFlags;
35     PerPipelineControlFlags *perPipelineControlFlags;
};

class GradZLinZStage : virtual public Object {
public:
40     static void Demo ();

    // constructors & destructors
    GradZLinZStage ();
45     ~GradZLinZStage ();

    // show/set data & data properties
    // - class Object requirements
    virtual ostream & Ostream (ostream & ) const;

50     // - local show/set functions
    static void GlobalSetup (const int setNumOfChips,

55

```

```

5         const int setNumOfPipelinesPerChip,

        const int setBlockSize,

        Cube4 *setCube4);
        virtual void LocalSetup (const int setChipIndex);
        virtual void PerFrameSetup ();
10     // local computation functions
        virtual void RunForOneClockCycle();

public:
        GradZLinZPipeline *gradZLinZPipeline;
        GradZLinZStageInputs inputs;
15     GradZLinZStageResults results;

protected:
        static int    numOfChips, numOfPipelinesPerChip;
        static Cube4 *cube4;
20     int            chipIndex;

        friend class GradZLinZPipeline;
};

#endif // _GradZLinZStage_h_
25  :::::::::::::::
cube4/GradZPipeline.C
:::::::::::::
// GradZPipeline.C
// (c) Ingmar Bitter '97

30  // Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include "GradZPipeline.h"

35  void GradZPipeline::Demo()
{
        GradZPipeline gradZ;
        cout << endl << "Demo of class " << typeid(gradZ).name();
        cout << endl << "size : " << sizeof(GradZPipeline) << " Bytes";
        cout << endl << "public member functions:";
40     cout << endl << "GradZPipeline gradZ; = " << gradZ;
        cout << endl << "End of demo of class " << typeid(gradZ).name() << endl;
} // Demo

45  //////////////////////////////////////
// constructors & destructors

// static first init
int GradZPipeline::numOfChips          = 0;
int GradZPipeline::numOfPipelinesPerChip = 0;
50

```

55

```

5      GradZPipeline::GradZPipeline()
      {
      } // constructor

      GradZPipeline::~GradZPipeline()
10     {
      } // destructor

      //////////////////////////////////////
      // show/set data & data properties
15

      ostream & GradZPipeline::Ostream(ostream & os) const
      {
      // append GradZPipeline info to os
20     os << typeid(*this).name() << "@" << (void *) this;
        os << endl << "   numOfChips          = " << numOfChips;
        os << endl << "   numOfPipelinesPerChip = " << numOfPipelinesPerChip;
        os << endl << "   chipIndex          = " << chipIndex;

      // return complete os
25     return os;

      } // Ostream

30     //////////////////////////////////////
      // show/set data & data properties
      //
      // - local show/set functions

35     void GradZPipeline::GlobalSetup(const int setNumOfChips,

        const int setNumOfPipelinesPerChip)
      {
        numOfChips          = setNumOfChips;
40        numOfPipelinesPerChip = setNumOfPipelinesPerChip;
      } // GlobalSetup

      void GradZPipeline::LocalSetup(const int setChipIndex,

45        const int setPipelineIndex,

        GradZStage & gradZStage)
      {
        chipIndex = setChipIndex;
50        pipelineIndex = setPipelineIndex;

55

```

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```

        inputs.voxel0 =
&(gradZStage.inputs.voxel0[pipelineIndex]);
5      inputs.voxel1 = &(gradZStage.inputs.voxel1[pipelineIndex]);
      inputs.weightsXYZ = &(gradZStage.inputs.weightsXYZ[pipelineIndex]);
      inputs.perChipControlFlags
        = gradZStage.inputs.perChipControlFlags;
      inputs.perPipelineControlFlags
10      = &(gradZStage.inputs.perPipelineControlFlags[pipelineIndex]);

      results.weightsXYZ = &(gradZStage.results.weightsXYZ[pipelineIndex]);
      results.gz = &(gradZStage.results.gz[pipelineIndex]);
      results.perPipelineControlFlags
        = &(gradZStage.results.perPipelineControlFlags[pipelineIndex]);
15      results.perChipControlFlags
        = &(gradZStage.results.perChipControlFlags);
    } // LocalSetup

void GradZPipeline::PerFrameSetup()
20 {
    // reset pipeline registers already done in GradZStage
    delayVoxel0 = delayVoxel0again = 0;
    delayWeightsXYZ(0,0,0);
    delayPerPipelineControlFlags.Reset();
25    delayPerChipControlFlags.Reset();
} // PerFrameSetup

////////////////////////////////////
30 // local computation functions

void GradZPipeline::RunForOneClockCycle()
{
    /*
        /(z)
35    /
    /voxB (seen late (recently) during processing => take from memCtrl )
    /
    /voxA (seen early (long ago) during processing => take from FiFol )
    /
40    +----->(x)
        |
        |
        |
        V(y)

45    */
    ScalarGradient voxB = delayVoxel0again.raw16bit;
    ScalarGradient voxA = inputs.voxel1->raw16bit;

    *(results.gz) = voxB - voxA;
50
55

```

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```

// complete the time-lineup

5      *(results.weightsXYZ) = delayWeightsXYZ;
      *(results.perPipelineControlFlags) = delayPerPipelineControlFlags;
      if (pipelineIndex == 0)
          *(results.perChipControlFlags) = delayPerChipControlFlags;

10     delayVoxel0again = delayVoxel0;
        delayVoxel0 = *(inputs.voxel0);

        delayWeightsXYZ = *(inputs.weightsXYZ);
        delayPerPipelineControlFlags = *(inputs.perPipelineControlFlags);
        delayPerChipControlFlags = *(inputs.perChipControlFlags);

15     } // RunForOneClockCycle

////////////////////////////////////
20    // internal utility functions

// end of GradZPipeline.C
:::::::::::::
cube4/GradZPipeline.h
25    :::::::::::::::
// GradZPipeline.h
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
30 // America, Inc., 1997, All rights reserved.

#ifndef _GradZPipeline_h_ // prevent multiple includes
#define _GradZPipeline_h_

35 #include "Misc.h"
#include "Object.h"
#include "Voxel.h"
#include "Coxel.h"
#include "Control.h"
#include "FixPointNumber.h"

40 class GradZStage;
class Cube4;

class GradZPipelineInputs {
45 public: // pointers
        Voxel *voxel0;
        Voxel *voxel1;
        Vector3D<FixPointNumber> *weightsXYZ;
        PerChipControlFlags *perChipControlFlags;
        PerPipelineControlFlags *perPipelineControlFlags;
50 };

```

55


```

class GradZPipelineResults {
5 public: // pointers
    ScalarGradient *gz; // on voxel grid
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags *perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
10 };

class GradZPipeline : virtual public Object {
public:

15     static void      Demo ();

        // constructors & destructors
        GradZPipeline ();
        ~GradZPipeline ();

20     // show/set data & data properties
        // - class Object requirements
        virtual ostream & Ostream (ostream & ) const;

        // - local show/set functions
25     static void GlobalSetup (const int setNumOfChips,

        const int setNumOfPipelinesPerChip);

        virtual void LocalSetup(const int setChipIndex,
30     const int setPipelineIndex,

        GradZStage & gradZStage);
        virtual void PerFrameSetup();
35     // local computation functions
        virtual void RunForOneClockCycle();

public:
        GradZPipelineInputs inputs;
        GradZPipelineResults results;
40

protected:
        Voxel delayVoxel0;
        Voxel delayVoxel0again;
        Vector3D<FixPointNumber> delayWeightsXYZ;
45     PerChipControlFlags      delayPerChipControlFlags;
        PerPipelineControlFlags delayPerPipelineControlFlags;
        static int      numOfChips, numOfPipelinesPerChip;
        static Cube4 *cube4;
        int      chipIndex, pipelineIndex;

50     friend class Cube4;

};

55

```

```

#include "GradZStage.h"
#include "Cube4.h"

#ifdef _GradZPipeline_h_
:~::~:
cube4/GradZStage.C
:~::~:
// GradZStage.C
10 // (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

15 #include "GradZStage.h"

void GradZStage::Demo()
{
    GradZStage gradZ;
    cout << endl <<"Demo of class " << typeid(gradZ).name();
    cout << endl <<"size : " << sizeof(GradZStage) << " Bytes";
20    cout << endl <<"public member functions:";
    cout << endl <<"GradZStage gradZ; = " << gradZ;
    cout << endl << "End of demo of class " << typeid(gradZ).name() << endl;
} // Demo

25
////////////////////////////////////
// constructors & destructors

// static first init
int GradZStage::numOfChips = 0;
30 int GradZStage::numOfPipelinesPerChip = 0;
Cube4 *GradZStage::cube4 = 0;

GradZStage::GradZStage()
{
35    gradZPipeline = new GradZPipeline [numOfPipelinesPerChip];
    results.gz = new ScalarGradient [numOfPipelinesPerChip];
    results.weightsXYZ = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];
    results.perPipelineControlFlags = new PerPipelineControlFlags
[numOfPipelinesPerChip];
} // defaultconstructor

40

GradZStage::~GradZStage()
{
    if (gradZPipeline) { delete gradZPipeline; gradZPipeline=0; }
    if (results.gz) { delete results.gz; results.gz=0; }
45    if (results.weightsXYZ) { delete results.weightsXYZ; results.weightsXYZ=0; }
}

    if (results.perPipelineControlFlags) {
        delete results.perPipelineControlFlags;
50
55

```

```

        results.perPipelineControlFlags=0;
    }
5   } // destructor

////////////////////////////////////
10  // show/set data & data properties

ostream & GradZStage::Ostream(ostream & os) const
{
    // append GradZStage info to os
15   os << typeid(*this).name() << "@" << (void *) this;
        os << endl << "    numOfChips          = " << numOfChips;
        os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
        os << endl << "    chipIndex          = " << chipIndex;

20   // return complete os
    return os;

} // Ostream

25  //////////////////////////////////////
    // show/set data & data properties
    //
    // - local show/set functions

30  void GradZStage::GlobalSetup(const int setNumOfChips,
        const int setNumOfPipelinesPerChip,
        Cube4 *setCube4)
35  {
        numOfChips          = setNumOfChips;
        numOfPipelinesPerChip = setNumOfPipelinesPerChip;
        GradZPipeline::GlobalSetup(numOfChips, numOfPipelinesPerChip);
        cube4 = setCube4;
40  } // GlobalSetup

void GradZStage::LocalSetup(const int setChipIndex)
{
    chipIndex = setChipIndex;
45   for (int p=0; p<numOfPipelinesPerChip; ++p) {
        gradZPipeline[p].LocalSetup(chipIndex,p,*this);
    }
} // LocalSetup

50  void GradZStage::PerFrameSetup()

55

```

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```

{
    int p;
    // reset pipeline registers
5   for (p=0; p<numOfPipelinesPerChip; ++p) {
        results.gz[p] = 0;
        results.weightsXYZ[p](0,0,0);
        results.perPipelineControlFlags[p].Reset();
    }
10  results.perChipControlFlags.Reset();

    for (p=0; p<numOfPipelinesPerChip; ++p) {
        gradZPipeline[p].PerFrameSetup();
    }

15  // print debug info
    //static bool first(true); if (first) { cout<<this<<endl; first=false; }
} // PerFrameSetup

20  //////////////////////////////////////
    // local computation functions

void GradZStage::RunForOneClockCycle()
{
    // computation
25  for (int p=0; p<numOfPipelinesPerChip; ++p) {
        gradZPipeline[p].RunForOneClockCycle();
    }
} // RunForOneClockCycle

30  //////////////////////////////////////
    // internal utility functions

// end of GradZStage.C
35  :::::::::::::::
cube4/GradZStage.h
:::::::::::::
// GradZStage.h
// (c) Ingmar Bitter '97

40  // Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#ifdef _GradZStage_h_ // prevent multiple includes
#define _GradZStage_h_

45  #include "Misc.h"
#include "Object.h"
#include "Voxel.h"
#include "Control.h"
#include "GradZPipeline.h"
50

```

55

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```

#include "FixPointNumber.h"
#include "Cube4.h"

class Cube4;

class GradZStageInputs {
public: // pointers
    Voxel *voxel0; // from memCtrl
    Voxel *voxel1; // from SliceVoxelFiFo1
    Vector3D<FixPointNumber> *weightsXYZ; // from SliceVoxelFiFo0
    PerChipControlFlags *perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

class GradZStageResults {
public: // arrays
    ScalarGradient *gz; // on voxel grid
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

class GradZStage : virtual public Object {
public:

    static void Demo ();

    // constructors & destructors
    GradZStage ();
    ~GradZStage ();

    // show/set data & data properties
    // - class Object requirements
    virtual ostream & Ostream (ostream & ) const;

    // - local show/set functions
    static void GlobalSetup (const int setNumOfChips,
        const int setNumOfPipelinesPerChip,
        Cube4 *setCube4);
    virtual void LocalSetup (const int setChipIndex);
    virtual void PerFrameSetup ();
    // local computation functions
    virtual void RunForOneClockCycle();

public:
    GradZPipeline *gradZPipeline;
    GradZStageInputs inputs;
    GradZStageResults results;

```

55

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```

    : direction(setDirection),
    sharpness(setSharpness)
5   {
    } // constructor

Light::Light(const Light & src)
    : direction(src.direction), intensity(src.intensity), sharpness(src.sharpness)
10  {
    } // constructor

////////////////////////////////////
// show/set data & data properties
15  //

ostream & Light::Ostream(ostream & os) const
{
    // append Light info to os
20    os << "dir" << direction << " Irgb" << intensity << " s: " << sharpness;

    // return complete os
    return os;

} // Ostream
25

Light & Light::operator () (const double Px, const double Py, const double Pz)
{
    direction(Px,Py,Pz);
    intensity(1,1,1);
30    sharpness = 1;
    return *this;
} // operator ()

Light & Light::operator () (const double Px, const double Py, const double Pz,
35    const double Ir, const double Ig, const double Ib,
    const int setSharpness)
{
40    direction(Px,Py,Pz);
    intensity(Ir,Ig,Ib);
    sharpness = setSharpness;
    return *this;
} // operator ()

45
Light & Light::operator = (const int k)
{
    direction(k,k,k);
    intensity(0,0,0);
50
55

```

```

        sharpness = 1;
        return *this;
5    } // operator ()

Light & Light::operator () (const char * str)
{
    strstream lightVectorData;
10    char buff[200];

    if (str[0] == '"') {
        // lightVector in double quotes
        // copy only part between double quotes
15        strcpy(buff, &str[1]);
        buff[strcspn(buff, "\"")] = 0;
        lightVectorData << buff;
    }
    else {
20        // plain lightVector
        // copy completely
        lightVectorData << str;
    }
    lightVectorData >> (*this);
    return *this;
25 } // operator ()

istream & operator >> (istream & is, Light & light)
{
30    double Px; double Py; double Pz;
    double Ir=1; double Ig=1; double Ib=1;
    int setSharpness=1;

    is >> Px >> Py >> Pz;
35    if (is) is >> Ir >> Ig >> Ib;
    if (is) is >> setSharpness;

    light(Px,Py,Pz, Ir,Ig,Ib, setSharpness);

40    return is;
} // operator >>

Vector3D<double> Light::Direction()
{
45    return direction;
} // Direction

Vector3D<double> Light::Intensity()
{
50    return intensity;
} // Intensity

55

```



```

int Light::Sharpness()
{
5   return sharpness;
} // Sharpness

Light & Light::TransformDirection(const Matrix4x4<int> & M)
{
10  direction = M * direction;
    return *this;
} // TransformDirection

15  // end of Light.C
    .....
cube4/Light.h
    .....
// Light.h
// (c) Ingmar Bitter '97

20  // Copyright, Mitsubishi Electric Information Technology Center
    // America, Inc., 1997, All rights reserved.

#ifndef _Light_h_ // prevent multiple includes
#define _Light_h_

25  #include "Object.h"
    #include "Vector3D.h"
    #include "Matrix4x4.h"

class Light : virtual public Object {
30  public:
    static void    Demo ();

    // constructors & destructors

    /*inline*/    Light();

35  /*inline*/    Light(double Px, double Py, double Pz,
        double Ir=1, double
        Ig=1, double Ib=1,
        int setSharpness=1);

40  /*inline*/    Light(const Vector3D<double> & setPos,
        const
        Vector3D<double> & setIntensity,
        const int
        setSharpness);
    /*inline*/    Light(const Light & src);

45  // show/set data & data properties

    virtual /*inline*/ Light & operator () (const double Px,

```

50

55

```

5                                     const double Py,
                                     const double Pz,
                                     const double Ir,
10                                     const double Ig,
                                     const double Ib,
                                     const int setSharpness); // set
function
15     virtual /*inline*/ Light & operator () (const double Px,
                                     const double Py,
                                     const double Pz);
    virtual /*inline*/ Light & operator () (const char * str);
20     virtual /*inline*/ Light & operator = (const int k);
    virtual /*inline*/ ostream & Ostream (ostream &) const;
    friend istream & operator >> (istream & is, Light & light);
25     virtual /*inline*/ Vector3D<double> Direction();
    virtual /*inline*/ Vector3D<double> Intensity();
    virtual /*inline*/ int Sharpness();
    virtual /*inline*/ Light & TransformDirection(const Matrix4x4<int> & M);
30 protected:
    Vector3D<double> direction;
    Vector3D<double> intensity;
    int sharpness;
};
35 #endif // _Light_h_
    ::::::::::::::
    cube4/LinearDataset.C
    ::::::::::::::
    // LinearDataset.cpp
    // (c) Ingmar Bitter '97
40 // Copyright, Mitsubishi Electric Information Technology Center
    // America, Inc., 1997, All rights reserved.
    // #define SHOW_ICON
    // #define DEBUG_SLC_READ
45 #include "LinearDataset.h"
    void LinearDataset::Demo()
    {
50
55

```

```

233
    LinearDataset      dataset("bulb.slc");
    cout << endl <<"Demo of class " << typeid(dataset).name();
5    cout << endl <<"size : " << sizeof(LinearDataset) << " Bytes";
    cout << endl <<"public member functions:";
    cout << endl <<"dataset.datasetFileName" << dataset.datasetFileName;
    cout << endl << "End of demo of class " << typeid(dataset).name() << endl;
} // Demo

10

////////////////////////////////////
// constructors & destructors

LinearDataset::LinearDataset(const char * fileName)
15 {
    SetDatasetFile(fileName);
    ReadVolvisSLC();
} // constructor

20
LinearDataset::~LinearDataset()
{
    if (voxelData) delete voxelData;
} // destructor

25

////////////////////////////////////
// show/set data & data properties
//
// - local show/set functions

30
bool LinearDataset::SetDatasetFile(const char * fileName)
{
    // copy string starting with filename
    strcpy(datasetFileName, fileName);
35
    // terminate filename at first space
    datasetFileName[strcspn(fileName, " ") ] = 0;

    return strlen(datasetFileName) > 0;
} // SetDatasetFile

40

bool LinearDataset::ReadVolvisSLC()
{
    // load dataset temporarily into regular linear 3D grid array

45
    cout << endl << "loading dataset \"" << datasetFileName << "\".";
    int magicDataTypeNumber;
    int u,v,w;
    int bitsPerVoxel;
    float unitLengthU, unitLengthV, unitLengthW;
50
    int unitType, dataOrigin, dataModification, compressionType;
    unsigned char X;

55

```

```

ifstream srcFile(datasetFileName);

5   srcFile >> magicDataTypeNumber;
    srcFile >> u >> v >> w; sizeUVW(u,v,w);
    srcFile >> bitsPerVoxel;
    srcFile >> unitLengthU >> unitLengthV >> unitLengthW;
    srcFile >> unitType >> dataOrigin >> dataModification >> compressionType;

10   cout << endl << "magicDataTypeNumber:" << magicDataTypeNumber;
    cout << "    sizeUVW: " << sizeUVW;
    cout << "    bitsPerVoxel:" << bitsPerVoxel;
    cout << endl << "unitLength: u=" << unitLengthU;
    cout << "    v=" << unitLengthV;
15   cout << "    w=" << unitLengthW;
    cout << endl << "unitType:" << TypeStr::Unit[unitType];
    cout << "    dataOrigin:" << TypeStr::DataOrigin[dataOrigin];
    cout << endl << "dataModification:" <<
TypeStr::DataModification[dataModification];
20   cout << "    compressionType:" <<
TypeStr::DataCompression[compressionType];

    ReadVolvisIcon(srcFile);

    // read dataset

25   int datasetSize = sizeUVW.U() * sizeUVW.V() * sizeUVW.W();
    int dataSliceSize = sizeUVW.U() * sizeUVW.V();
    int compressedSize;

    voxelData = new unsigned char[datasetSize];
30   assert(voxelData);
    unsigned char *compressedSlice = new unsigned char[2*dataSliceSize];
    assert(compressedSlice);
    unsigned char *slice = voxelData;

35   #ifdef DEBUG_SLC_READ
    char str[500];
    sprintf(str, " /bin/rm -f img/slc*.miff & \n");
    cout << str;
    system(str);
    #endif

40   cout << endl << "reading voxel data "; cout.flush();
    for (int z=0; z<sizeUVW.W(); ++z, slice += dataSliceSize) {
        switch (compressionType) {
            case NO_COMPRESSION:      srcFile.read(slice,dataSliceSize);
45   break;
            case RUN_LENGTH_ENCODE:
                // read compressed slice size
                srcFile >> compressedSize;

                // advance to real data

50
55

```

```

235
for ( X = '\0'; X != 'X'; srcFile.get(X) ) ;

5      // read in slice
      srcFile.read(compressedSlice, compressedSize);
      assert( compressedSize == (int) srcFile.gcount() );

      // decompress slice
      // see also:
10      /home/fs2/mmshare/pkg/VolVis.2.1/lib/file_io/src/C_compression.c
      register unsigned char *compressData = compressedSlice;
      register unsigned char *voxel = slice;
      register unsigned char currentValue = *compressData;
      register unsigned char remaining;

15      for (currentValue = *(compressData++); (remaining =
      (currentValue & 0x7f));
          currentValue = *(compressData++) ) {
          if ( currentValue & 0x80 ) {
          while ( remaining-- )
20              *(voxel++) = *(compressData++);
          }
          else {
          currentValue = *(compressData++);
          while ( remaining-- )
25              *(voxel++) = currentValue;
          }
          }
          break;
      } // switch
      if (z%10) cout << "."; else cout << ":"; cerr.flush();

30      #ifdef DEBUG_SLC_READ
          // save slices as gray image
          char fileName[50];
          sprintf(fileName, "img/slc%03i.gray", z);
          {
          ofstream slcGrayFile(fileName);
35          slcGrayFile.write(slice, dataSliceSize); }
          sprintf(str, "convert -geometry 64x64 -size %ix%i img/slc%03i.gray
img/slc%03i.miff; /usr/bin/rm -f img/slc%03i.gray & \n",
          sizeUVW.U(), sizeUVW.V(), z, z, z);
          //cout << str;
          cout.flush();
40          system(str);
      #endif
      } // for z
      delete compressedSlice; // free memory

45      #ifdef DEBUG_SLC_READ
          sprintf(str, "animate img/slc*.miff & \n");
          //cout << str;
          system(str);
      #endif

50

55

```

```

    return true;
} // ReadVolvisSLC

5

void LinearDataset::ReadVolvisIcon(istream & srcFile)
{
    unsigned char *iconRed, *iconGreen, *iconBlue, X;
    int iconX, iconY;
10
    srcFile >> iconX >> iconY;

    cout << endl << "icon:" << iconX << "x" << iconY;

15
    for ( X = '\0'; X != 'X'; srcFile.get(X) );

    // load icon
    iconRed = new unsigned char[iconX * iconY]; assert(iconRed);
    iconGreen = new unsigned char[iconX * iconY]; assert(iconGreen);
20
    iconBlue = new unsigned char[iconX * iconY]; assert(iconBlue);

    srcFile.read(iconRed, iconX*iconY);
    srcFile.read(iconGreen, iconX*iconY);
    srcFile.read(iconBlue, iconX*iconY);

25
#ifdef SHOW_ICON
    // save icon as separate rgb file
    {
        ofstream iconFile("icon.rgb");
        iconFile.write(iconRed, iconX*iconY);
        iconFile.write(iconGreen, iconX*iconY);
30
        iconFile.write(iconBlue, iconX*iconY);
    }
#endif

    delete iconRed;
35
    delete iconGreen;
    delete iconBlue;

#ifdef SHOW_ICON
    // show icon
    char str[500];
40
    sprintf(str, "convert -size %ix%i icon.rgb icon.miff ;", iconX, iconY);
    strcat(str, " /bin/rm -f icon.rgb ; display -delay 10 icon.miff & \n");
    //cout << str;
    system(str);
#endif
45
} // ReadVolvisIcon

// end of LinearDataset.C
:~::~:~::~:~::~:~::~:~::~:
cube4/LinearDataset.h
:~::~:~::~:~::~:~::~:~::~:
50
// LinearDataset.h

55

```



```
# Copyright, Mitsubishi Electric Information Technology Center
# America, Inc., 1997, All rights reserved.
```

```
EXECUTABLE = go
```

```
SRC = main.C Test.C Object.C ModInt.C FixPointNumber.C Vector3D.C Matrix4x4.C
\
```

```
10 DynaArray.C Timer.C Misc.C FiFo.C Voxel.C Coxel.C Shadel.C
Light.C\
```

```
LinearDataset.C Control.C AddressGenerator.C \
VoxMem.C CoxMem.C MemoryCtrl.C \
SliceVoxelFiFoStage.C SliceVoxelFiFoPipeline.C \
TriLinZStage.C TriLinZPipeline.C \
15 TriLinYStage.C TriLinYPipeline.C \
TriLinXStage.C TriLinXPipeline.C \
GradYStage.C GradYPipeline.C \
GradXStage.C GradXPipeline.C \
GradZStage.C GradZPipeline.C \
GradZLinZStage.C GradZLinZPipeline.C \
20 GradZLinYStage.C GradZLinYPipeline.C \
GradZLinXStage.C GradZLinXPipeline.C \
ColorLUT.C \
ShaderStage.C ShaderPipeline.C ReflectanceMap.C \
DataSyncStage.C DataSyncPipeline.C \
ComposStage.C ComposPipeline.C \
25 ComposBufferStage.C ComposBufferPipeline.C \
ComposSelXStage.C ComposSelXPipeline.C \
ComposSelYStage.C ComposSelYPipeline.C \
ComposLinXStage.C ComposLinXPipeline.C \
ComposLinYStage.C ComposLinYPipeline.C \
30 FinalCoxelBuffer.C \
Cube4.C
```

```
RM = /bin/rm -fs
```

```
35 #OPTIMIZE = -O3
OPTIMIZE = -g
WARN = -fullwarn -woff 1314
CDEBUGFLAGS = $(OPTIMIZE) $(WARN)
CCOPTIONS = -n32 -mips4 -r10000
```

```
40 CC = CC
```

```
INCLUDES =
#LIBS = -lfastm -lm
LIBS = -lm
CFLAGS = $(CCOPTIONS) $(CDEBUGFLAGS) $(INCLUDES)
```

```
45 OFILES = $(SRC:.C=.o)
```

```
$(EXECUTABLE): $(OFILES)
```



```

$(CC) $(OFILES) $(CFLAGS) $(LIBS) -o $(EXECUTABLE)

#
# target: dependency \n tab rule
#
.C.o:
    $(CC) $(CFLAGS) -c $<

#
# switch:: ; \n tab rule
#
clean:
    ;
    find . -name "*.o" -print -exec mv {} ~/dumpster \; ;
    find . -name "*~" -print -exec mv {} ~/dumpster \; ;
    find . -name "go" -print -exec mv {} ~/dumpster \; ;
    find . -name "core" -print -exec mv {} ~/dumpster \; ;

all:
    ;
    pmake -u

depend:
    makedepend -- $(CFLAGS) -- $(SRC)

# DO NOT DELETE

main.o: Test.h Cube4.h /usr/include/string.h /usr/include/standards.h
main.o: /usr/include/stdlib.h /usr/include/sgidefs.h /usr/include/stdio.h
main.o: /usr/include/assert.h Object.h Global.h Misc.h DynaArray.h
main.o: FixPointNumber.h Vector3D.h /usr/include/math.h ModInt.h
main.o: /usr/include/limits.h Matrix4x4.h FiFo.h Timer.h
main.o: /usr/include/sys/time.h /usr/include/sys/times.h
main.o: /usr/include/sys/types.h /usr/include/unistd.h Voxel.h Shadel.h
main.o: Coxel.h Light.h LinearDataset.h VoxMem.h CoxMem.h Control.h
main.o: AddressGenerator.h MemoryCtrl.h SliceVoxelFiFoStage.h
main.o: SliceVoxelFiFoPipeline.h TriLinZStage.h TriLinZPipeline.h
main.o: TriLinYStage.h TriLinYPipeline.h TriLinXStage.h TriLinXPipeline.h
main.o: GradYStage.h GradYPipeline.h GradXStage.h GradXPipeline.h
main.o: GradZStage.h GradZPipeline.h GradZLinZStage.h GradZLinZPipeline.h
main.o: GradZLinYStage.h GradZLinYPipeline.h GradZLinXStage.h
main.o: GradZLinXPipeline.h ShaderStage.h ShaderPipeline.h ReflectanceMap.h
main.o: ColorLUT.h DataSyncStage.h DataSyncPipeline.h ComposBufferStage.h
main.o: ComposBufferPipeline.h ComposStage.h ComposPipeline.h
main.o: ComposSelXStage.h ComposSelXPipeline.h ComposSelYStage.h
main.o: ComposSelYPipeline.h ComposLinXStage.h ComposLinXPipeline.h
main.o: ComposLinYStage.h ComposLinYPipeline.h FinalCoxelBuffer.h
Test.o: Test.h Cube4.h /usr/include/string.h /usr/include/standards.h
Test.o: /usr/include/stdlib.h /usr/include/sgidefs.h /usr/include/stdio.h
Test.o: /usr/include/assert.h Object.h Global.h Misc.h DynaArray.h
Test.o: FixPointNumber.h Vector3D.h /usr/include/math.h ModInt.h
Test.o: /usr/include/limits.h Matrix4x4.h FiFo.h Timer.h
Test.o: /usr/include/sys/time.h /usr/include/sys/times.h
Test.o: /usr/include/sys/types.h /usr/include/unistd.h Voxel.h Shadel.h
Test.o: Coxel.h Light.h LinearDataset.h VoxMem.h CoxMem.h Control.h

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Test.o: AddressGenerator.h MemoryCtrl.h SliceVoxelFiFoStage.h
 Test.o: SliceVoxelFiFoPipeline.h TriLinZStage.h TriLinZPipeline.h
 5 Test.o: TriLinYStage.h TriLinYPipeline.h TriLinXStage.h TriLinXPipeline.h
 Test.o: GradYStage.h GradYPipeline.h GradXStage.h GradXPipeline.h
 Test.o: GradZStage.h GradZPipeline.h GradZLinZStage.h GradZLinZPipeline.h
 Test.o: GradZLinYStage.h GradZLinYPipeline.h GradZLinXStage.h
 Test.o: GradZLinXPipeline.h ShaderStage.h ShaderPipeline.h ReflectanceMap.h
 Test.o: ColorLUT.h DataSyncStage.h DataSyncPipeline.h ComposBufferStage.h
 10 Test.o: ComposBufferPipeline.h ComposStage.h ComposPipeline.h
 Test.o: ComposSelXStage.h ComposSelXPipeline.h ComposSelYStage.h
 Test.o: ComposSelYPipeline.h ComposLinXStage.h ComposLinXPipeline.h
 Test.o: ComposLinYStage.h ComposLinYPipeline.h FinalCoxelBuffer.h
 Object.o: Object.h /usr/include/string.h /usr/include/standards.h Global.h
 15 Object.o: /usr/include/assert.h /usr/include/stdlib.h /usr/include/sgidefs.h
 ModInt.o: ModInt.h Object.h /usr/include/string.h /usr/include/standards.h
 ModInt.o: Global.h /usr/include/assert.h /usr/include/stdlib.h
 ModInt.o: /usr/include/sgidefs.h /usr/include/limits.h
 FixPointNumber.o: FixPointNumber.h Object.h /usr/include/string.h
 FixPointNumber.o: /usr/include/standards.h Global.h /usr/include/assert.h
 20 FixPointNumber.o: /usr/include/stdlib.h /usr/include/sgidefs.h
 Vector3D.o: Vector3D.h /usr/include/math.h /usr/include/sgidefs.h
 Vector3D.o: /usr/include/standards.h Object.h /usr/include/string.h Global.h
 Vector3D.o: /usr/include/assert.h /usr/include/stdlib.h ModInt.h
 Vector3D.o: /usr/include/limits.h
 Matrix4x4.o: Matrix4x4.h /usr/include/math.h /usr/include/sgidefs.h
 25 Matrix4x4.o: /usr/include/standards.h Object.h /usr/include/string.h Global.h
 Matrix4x4.o: /usr/include/assert.h /usr/include/stdlib.h Vector3D.h ModInt.h
 Matrix4x4.o: /usr/include/limits.h FixPointNumber.h
 DynaArray.o: DynaArray.h /usr/include/assert.h Object.h /usr/include/string.h
 DynaArray.o: /usr/include/standards.h Global.h /usr/include/stdlib.h
 30 DynaArray.o: /usr/include/sgidefs.h
 Timer.o: Timer.h /usr/include/sys/time.h /usr/include/standards.h
 Timer.o: /usr/include/sgidefs.h /usr/include/sys/times.h
 Timer.o: /usr/include/sys/types.h /usr/include/unistd.h Object.h
 Timer.o: /usr/include/string.h Global.h /usr/include/assert.h
 Timer.o: /usr/include/stdlib.h
 35 Misc.o: Misc.h
 FiFo.o: FiFo.h Object.h /usr/include/string.h /usr/include/standards.h
 FiFo.o: Global.h /usr/include/assert.h /usr/include/stdlib.h
 FiFo.o: /usr/include/sgidefs.h
 Voxel.o: Voxel.h Global.h /usr/include/assert.h /usr/include/stdlib.h
 Voxel.o: /usr/include/standards.h /usr/include/sgidefs.h
 40 Coxel.o: Coxel.h FixPointNumber.h Object.h /usr/include/string.h
 Coxel.o: /usr/include/standards.h Global.h /usr/include/assert.h
 Coxel.o: /usr/include/stdlib.h /usr/include/sgidefs.h
 Shadel.o: Shadel.h FixPointNumber.h Object.h /usr/include/string.h
 Shadel.o: /usr/include/standards.h Global.h /usr/include/assert.h
 45 Shadel.o: /usr/include/stdlib.h /usr/include/sgidefs.h
 Light.o: Light.h Object.h /usr/include/string.h /usr/include/standards.h
 Light.o: Global.h /usr/include/assert.h /usr/include/stdlib.h
 Light.o: /usr/include/sgidefs.h Vector3D.h /usr/include/math.h ModInt.h
 Light.o: /usr/include/limits.h Matrix4x4.h FixPointNumber.h
 50 LinearDataset.o: LinearDataset.h /usr/include/string.h

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```

LinearDataset.o:                               /usr/include/standards.h
/usr/include/stdio.h
5 LinearDataset.o: /usr/include/sgidefs.h Object.h Global.h
LinearDataset.o: /usr/include/assert.h /usr/include/stdlib.h Misc.h
LinearDataset.o: Vector3D.h /usr/include/math.h ModInt.h
LinearDataset.o: /usr/include/limits.h
Control.o: Control.h Misc.h Object.h /usr/include/string.h
Control.o: /usr/include/standards.h Global.h /usr/include/assert.h
10 Control.o: /usr/include/stdlib.h /usr/include/sgidefs.h ModInt.h
Control.o: /usr/include/limits.h FixPointNumber.h Vector3D.h
Control.o: /usr/include/math.h Matrix4x4.h
AddressGenerator.o: AddressGenerator.h Object.h /usr/include/string.h
AddressGenerator.o: /usr/include/standards.h Global.h /usr/include/assert.h
AddressGenerator.o: /usr/include/stdlib.h /usr/include/sgidefs.h Vector3D.h
15 AddressGenerator.o: /usr/include/math.h ModInt.h /usr/include/limits.h
AddressGenerator.o: Matrix4x4.h FixPointNumber.h Control.h Misc.h
VoxMem.o: VoxMem.h Object.h /usr/include/string.h /usr/include/standards.h
VoxMem.o: Global.h /usr/include/assert.h /usr/include/stdlib.h
VoxMem.o: /usr/include/sgidefs.h Misc.h Voxel.h
20 CoxMem.o: CoxMem.h Object.h /usr/include/string.h /usr/include/standards.h
CoxMem.o: Global.h /usr/include/assert.h /usr/include/stdlib.h
CoxMem.o: /usr/include/sgidefs.h Misc.h Coxel.h FixPointNumber.h
MemoryCtrl.o: MemoryCtrl.h Misc.h Object.h /usr/include/string.h
MemoryCtrl.o: /usr/include/standards.h Global.h /usr/include/assert.h
MemoryCtrl.o: /usr/include/stdlib.h /usr/include/sgidefs.h FixPointNumber.h
25 MemoryCtrl.o: Vector3D.h /usr/include/math.h ModInt.h /usr/include/limits.h
MemoryCtrl.o: Voxel.h VoxMem.h Control.h Matrix4x4.h
SliceVoxelFiFoStage.o: SliceVoxelFiFoStage.h Misc.h Object.h
SliceVoxelFiFoStage.o: /usr/include/string.h /usr/include/standards.h
SliceVoxelFiFoStage.o: Global.h /usr/include/assert.h /usr/include/stdlib.h
30 SliceVoxelFiFoStage.o: /usr/include/sgidefs.h Voxel.h Control.h ModInt.h
SliceVoxelFiFoStage.o: /usr/include/limits.h FixPointNumber.h Vector3D.h
SliceVoxelFiFoStage.o: /usr/include/math.h Matrix4x4.h
SliceVoxelFiFoStage.o: SliceVoxelFiFoPipeline.h FiFo.h Coxel.h Cube4.h
SliceVoxelFiFoStage.o: /usr/include/stdio.h DynaArray.h Timer.h
SliceVoxelFiFoStage.o: /usr/include/sys/time.h /usr/include/sys/times.h
35 SliceVoxelFiFoStage.o: /usr/include/sys/types.h /usr/include/unistd.h
SliceVoxelFiFoStage.o: Shadel.h Light.h LinearDataset.h VoxMem.h CoxMem.h
SliceVoxelFiFoStage.o: AddressGenerator.h MemoryCtrl.h TriLinZStage.h
SliceVoxelFiFoStage.o: TriLinZPipeline.h TriLinYStage.h TriLinYPipeline.h
SliceVoxelFiFoStage.o: TriLinXStage.h TriLinXPipeline.h GradYStage.h
40 SliceVoxelFiFoStage.o: GradYPipeline.h GradXStage.h GradXPipeline.h
SliceVoxelFiFoStage.o: GradZStage.h GradZPipeline.h GradZLinZStage.h
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SliceVoxelFiFoStage.o: GradZLinXPipeline.h ShaderStage.h ShaderPipeline.h
SliceVoxelFiFoStage.o: ReflectanceMap.h ColorLUT.h DataSyncStage.h
45 SliceVoxelFiFoStage.o: DataSyncPipeline.h ComposBufferStage.h
SliceVoxelFiFoStage.o: ComposBufferPipeline.h ComposStage.h ComposPipeline.h
SliceVoxelFiFoStage.o: ComposSelXStage.h ComposSelXPipeline.h
SliceVoxelFiFoStage.o: ComposSelYStage.h ComposSelYPipeline.h
SliceVoxelFiFoStage.o: ComposLinXStage.h ComposLinXPipeline.h
50 SliceVoxelFiFoStage.o: ComposLinYStage.h ComposLinYPipeline.h

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SliceVoxelFiFoStage.o:                               FinalCoxelBuffer.h
SliceVoxelFiFoPipeline.o: SliceVoxelFiFoPipeline.h Misc.h Object.h
5 SliceVoxelFiFoPipeline.o: /usr/include/string.h /usr/include/standards.h
SliceVoxelFiFoPipeline.o: Global.h /usr/include/assert.h
SliceVoxelFiFoPipeline.o: /usr/include/stdlib.h /usr/include/sgidefs.h FiFo.h
SliceVoxelFiFoPipeline.o: Voxel.h Coxel.h FixPointNumber.h Control.h ModInt.h
SliceVoxelFiFoPipeline.o: /usr/include/limits.h Vector3D.h
SliceVoxelFiFoPipeline.o: /usr/include/math.h Matrix4x4.h
10 SliceVoxelFiFoPipeline.o: SliceVoxelFiFoStage.h Cube4.h /usr/include/stdio.h
SliceVoxelFiFoPipeline.o: DynaArray.h Timer.h /usr/include/sys/time.h
SliceVoxelFiFoPipeline.o: /usr/include/sys/times.h /usr/include/sys/types.h
SliceVoxelFiFoPipeline.o: /usr/include/unistd.h Shadel.h Light.h
SliceVoxelFiFoPipeline.o: LinearDataset.h VoxMem.h CoxMem.h
15 SliceVoxelFiFoPipeline.o: AddressGenerator.h MemoryCtrl.h TriLinZStage.h
SliceVoxelFiFoPipeline.o: TriLinZPipeline.h TriLinYStage.h TriLinYPipeline.h
SliceVoxelFiFoPipeline.o: TriLinXStage.h TriLinXPipeline.h GradYStage.h
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20 SliceVoxelFiFoPipeline.o: GradZLinYPipeline.h GradZLinXStage.h
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25 SliceVoxelFiFoPipeline.o: ComposSelXPipeline.h ComposSelYStage.h
SliceVoxelFiFoPipeline.o: ComposSelYPipeline.h ComposLinXStage.h
SliceVoxelFiFoPipeline.o: ComposLinXPipeline.h ComposLinYStage.h
SliceVoxelFiFoPipeline.o: ComposLinYPipeline.h FinalCoxelBuffer.h
TriLinZStage.o: TriLinZStage.h Misc.h Object.h /usr/include/string.h
30 TriLinZStage.o: /usr/include/standards.h Global.h /usr/include/assert.h
TriLinZStage.o: /usr/include/stdlib.h /usr/include/sgidefs.h Voxel.h
TriLinZStage.o: Control.h ModInt.h /usr/include/limits.h FixPointNumber.h
TriLinZStage.o: Vector3D.h /usr/include/math.h Matrix4x4.h TriLinZPipeline.h
TriLinZStage.o: Coxel.h Cube4.h /usr/include/stdio.h DynaArray.h FiFo.h
TriLinZStage.o: Timer.h /usr/include/sys/time.h /usr/include/sys/times.h
35 TriLinZStage.o: /usr/include/sys/types.h /usr/include/unistd.h Shadel.h
TriLinZStage.o: Light.h LinearDataset.h VoxMem.h CoxMem.h AddressGenerator.h
TriLinZStage.o: MemoryCtrl.h SliceVoxelFiFoStage.h SliceVoxelFiFoPipeline.h
TriLinZStage.o: TriLinYStage.h TriLinYPipeline.h TriLinXStage.h
TriLinZStage.o: TriLinXPipeline.h GradYStage.h GradYPipeline.h GradXStage.h
TriLinZStage.o: GradXPipeline.h GradZStage.h GradZPipeline.h GradZLinZStage.h
40 TriLinZStage.o: GradZLinZPipeline.h GradZLinYStage.h GradZLinYPipeline.h
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TriLinZStage.o: ComposStage.h ComposPipeline.h ComposSelXStage.h
TriLinZStage.o: ComposSelXPipeline.h ComposSelYStage.h ComposSelYPipeline.h
45 TriLinZStage.o: ComposLinXStage.h ComposLinXPipeline.h ComposLinYStage.h
TriLinZStage.o: ComposLinYPipeline.h FinalCoxelBuffer.h
TriLinZPipeline.o: TriLinZPipeline.h Misc.h Object.h /usr/include/string.h
TriLinZPipeline.o: /usr/include/standards.h Global.h /usr/include/assert.h
TriLinZPipeline.o: /usr/include/stdlib.h /usr/include/sgidefs.h Voxel.h

```

TriLinZPipeline.o: Coxel.h
 TriLinZPipeline.o: /usr/include/limits.h Vector3D.h /usr/include/math.h
 5 TriLinZPipeline.o: Matrix4x4.h TriLinZStage.h Cube4.h /usr/include/stdio.h
 TriLinZPipeline.o: DynaArray.h FiFo.h Timer.h /usr/include/sys/time.h
 TriLinZPipeline.o: /usr/include/sys/times.h /usr/include/sys/types.h
 TriLinZPipeline.o: /usr/include/unistd.h Shadel.h Light.h LinearDataset.h
 TriLinZPipeline.o: VoxMem.h CoxMem.h AddressGenerator.h MemoryCtrl.h
 TriLinZPipeline.o: SliceVoxelFiFoStage.h SliceVoxelFiFoPipeline.h
 10 TriLinZPipeline.o: TriLinYStage.h TriLinYPipeline.h TriLinXStage.h
 TriLinZPipeline.o: TriLinXPipeline.h GradYStage.h GradYPipeline.h
 TriLinZPipeline.o: GradXStage.h GradXPipeline.h GradZStage.h GradZPipeline.h
 TriLinZPipeline.o: GradZLinZStage.h GradZLinZPipeline.h GradZLinYStage.h
 TriLinZPipeline.o: GradZLinYPipeline.h GradZLinXStage.h GradZLinXPipeline.h
 15 TriLinZPipeline.o: ShaderStage.h ShaderPipeline.h ReflectanceMap.h ColorLUT.h
 TriLinZPipeline.o: DataSyncStage.h DataSyncPipeline.h ComposBufferStage.h
 TriLinZPipeline.o: ComposBufferPipeline.h ComposStage.h ComposPipeline.h
 TriLinZPipeline.o: ComposSelXStage.h ComposSelXPipeline.h ComposSelYStage.h
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 TriLinZPipeline.o: ComposLinXPipeline.h ComposLinYStage.h
 20 TriLinZPipeline.o: ComposLinYPipeline.h FinalCoxelBuffer.h
 TriLinYStage.o: TriLinYStage.h Misc.h Object.h /usr/include/string.h
 TriLinYStage.o: /usr/include/standards.h Global.h /usr/include/assert.h
 TriLinYStage.o: /usr/include/stdlib.h /usr/include/sgidefs.h Vector3D.h
 TriLinYStage.o: /usr/include/math.h ModInt.h /usr/include/limits.h Voxel.h
 25 TriLinYStage.o: Control.h FixPointNumber.h Matrix4x4.h TriLinYPipeline.h
 TriLinYStage.o: FiFo.h Coxel.h Cube4.h /usr/include/stdio.h DynaArray.h
 TriLinYStage.o: Timer.h /usr/include/sys/time.h /usr/include/sys/times.h
 TriLinYStage.o: /usr/include/sys/types.h /usr/include/unistd.h Shadel.h
 TriLinYStage.o: Light.h LinearDataset.h VoxMem.h CoxMem.h AddressGenerator.h
 TriLinYStage.o: MemoryCtrl.h SliceVoxelFiFoStage.h SliceVoxelFiFoPipeline.h
 30 TriLinYStage.o: TriLinZStage.h TriLinZPipeline.h TriLinXStage.h
 TriLinYStage.o: TriLinXPipeline.h GradYStage.h GradYPipeline.h GradXStage.h
 TriLinYStage.o: GradXPipeline.h GradZStage.h GradZPipeline.h GradZLinZStage.h
 TriLinYStage.o: GradZLinZPipeline.h GradZLinYStage.h GradZLinYPipeline.h
 TriLinYStage.o: GradZLinXStage.h GradZLinXPipeline.h ShaderStage.h
 TriLinYStage.o: ShaderPipeline.h ReflectanceMap.h ColorLUT.h DataSyncStage.h
 35 TriLinYStage.o: DataSyncPipeline.h ComposBufferStage.h ComposBufferPipeline.h
 TriLinYStage.o: ComposStage.h ComposPipeline.h ComposSelXStage.h
 TriLinYStage.o: ComposSelXPipeline.h ComposSelyStage.h ComposSelyYPipeline.h
 TriLinYStage.o: ComposLinXStage.h ComposLinXPipeline.h ComposLinYStage.h
 TriLinYStage.o: ComposLinYPipeline.h FinalCoxelBuffer.h
 40 TriLinYPipeline.o: TriLinYPipeline.h Misc.h Object.h /usr/include/string.h
 TriLinYPipeline.o: /usr/include/standards.h Global.h /usr/include/assert.h
 TriLinYPipeline.o: /usr/include/stdlib.h /usr/include/sgidefs.h FiFo.h
 TriLinYPipeline.o: Voxel.h Coxel.h FixPointNumber.h Control.h ModInt.h
 TriLinYPipeline.o: /usr/include/limits.h Vector3D.h /usr/include/math.h
 45 TriLinYPipeline.o: Matrix4x4.h TriLinYStage.h Cube4.h /usr/include/stdio.h
 TriLinYPipeline.o: DynaArray.h Timer.h /usr/include/sys/time.h
 TriLinYPipeline.o: /usr/include/sys/times.h /usr/include/sys/types.h
 TriLinYPipeline.o: /usr/include/unistd.h Shadel.h Light.h LinearDataset.h
 TriLinYPipeline.o: VoxMem.h CoxMem.h AddressGenerator.h MemoryCtrl.h
 TriLinYPipeline.o: SliceVoxelFiFoStage.h SliceVoxelFiFoPipeline.h
 50 TriLinYPipeline.o: TriLinZStage.h TriLinZPipeline.h TriLinXStage.h

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TriLinYPipeline.o: TriLinXPipeline.h      GradYStage.h GradYPipeline.h
TriLinYPipeline.o: GradXStage.h GradXPipeline.h GradZStage.h GradZPipeline.h
5 TriLinYPipeline.o: GradZLinZStage.h GradZLinZPipeline.h GradZLinYStage.h
TriLinYPipeline.o: GradZLinYPipeline.h GradZLinXStage.h GradZLinXPipeline.h
TriLinYPipeline.o: ShaderStage.h ShaderPipeline.h ReflectanceMap.h ColorLUT.h
TriLinYPipeline.o: DataSyncStage.h DataSyncPipeline.h ComposBufferStage.h
TriLinYPipeline.o: ComposBufferPipeline.h ComposStage.h ComposPipeline.h
TriLinYPipeline.o: ComposSelXStage.h ComposSelXPipeline.h ComposSelYStage.h
10 TriLinYPipeline.o: ComposSelYPipeline.h ComposLinXStage.h
TriLinYPipeline.o: ComposLinXPipeline.h ComposLinYStage.h
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TriLinXStage.o: /usr/include/stdlib.h /usr/include/sgidefs.h Voxel.h
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TriLinXPipeline.o: ComposSelXStage.h ComposSelXPipeline.h ComposSelYStage.h
TriLinXPipeline.o: ComposSelYPipeline.h ComposLinXStage.h

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TriLinXPipeline.o: ComposLinXPipeline.h ComposLinYStage.h
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15 GradYStage.o: TriLinYPipeline.h TriLinXStage.h TriLinXPipeline.h GradXStage.h
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GradXStage.o: Cube4.h /usr/include/stdio.h DynaArray.h Timer.h
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GradZStage.o: ComposSelXPipeline.h ComposSelYStage.h ComposSelYPipeline.h
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 GradZLinZPipeline.o: Matrix4x4.h GradZLinZStage.h Cube4.h

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GradZLinZPipeline.o: /usr/include/stdio.h DynaArray.h
Timer.h
5 GradZLinZPipeline.o: /usr/include/sys/time.h /usr/include/sys/times.h
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GradZLinYPipeline.o: Light.h LinearDataset.h VoxMem.h CoxMem.h
50 GradZLinYPipeline.o: AddressGenerator.h MemoryCtrl.h SliceVoxelFiFoStage.h

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GradZLinYPipeline.o:                               SliceVoxelFiFoPipeline.h TriLinZStage.h
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GradZLinXStage.o: TriLinYStage.h TriLinYPipeline.h TriLinXStage.h
25 GradZLinXStage.o: TriLinXPipeline.h GradYStage.h GradYPipeline.h GradXStage.h
GradZLinXStage.o: GradXPipeline.h GradZStage.h GradZPipeline.h
GradZLinXStage.o: GradZLinZStage.h GradZLinZPipeline.h GradZLinYStage.h
GradZLinXStage.o: GradZLinYPipeline.h ShaderStage.h ShaderPipeline.h
GradZLinXStage.o: ReflectanceMap.h ColorLUT.h DataSyncStage.h
GradZLinXStage.o: DataSyncPipeline.h ComposBufferStage.h
30 GradZLinXStage.o: ComposBufferPipeline.h ComposStage.h ComposPipeline.h
GradZLinXStage.o: ComposSelXStage.h ComposSelXPipeline.h ComposSelYStage.h
GradZLinXStage.o: ComposSelYPipeline.h ComposLinXStage.h ComposLinXPipeline.h
GradZLinXStage.o: ComposLinYStage.h ComposLinYPipeline.h FinalCoxelBuffer.h
GradZLinXPipeline.o: GradZLinXPipeline.h Misc.h Object.h
GradZLinXPipeline.o: /usr/include/string.h /usr/include/standards.h Global.h
35 GradZLinXPipeline.o: /usr/include/assert.h /usr/include/stdlib.h
GradZLinXPipeline.o: /usr/include/sgidefs.h FiFo.h Voxel.h Coxel.h
GradZLinXPipeline.o: FixPointNumber.h Control.h ModInt.h
GradZLinXPipeline.o: /usr/include/limits.h Vector3D.h /usr/include/math.h
GradZLinXPipeline.o: Matrix4x4.h GradZLinXStage.h Cube4.h
GradZLinXPipeline.o: /usr/include/stdio.h DynaArray.h Timer.h
40 GradZLinXPipeline.o: /usr/include/sys/time.h /usr/include/sys/times.h
GradZLinXPipeline.o: /usr/include/sys/types.h /usr/include/unistd.h Shadel.h
GradZLinXPipeline.o: Light.h LinearDataset.h VoxMem.h CoxMem.h
GradZLinXPipeline.o: AddressGenerator.h MemoryCtrl.h SliceVoxelFiFoStage.h
GradZLinXPipeline.o: SliceVoxelFiFoPipeline.h TriLinZStage.h
GradZLinXPipeline.o: TriLinZPipeline.h TriLinYStage.h TriLinYPipeline.h
45 GradZLinXPipeline.o: TriLinXStage.h TriLinXPipeline.h GradYStage.h
GradZLinXPipeline.o: GradYPipeline.h GradXStage.h GradXPipeline.h
GradZLinXPipeline.o: GradZStage.h GradZPipeline.h GradZLinZStage.h

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GradZLinXPipeline.o:                               GradZLinZPipeline.h GradZLinYStage.h
GradZLinYPipeline.h
5 GradZLinXPipeline.o: ShaderStage.h ShaderPipeline.h ReflectanceMap.h
GradZLinXPipeline.o: ColorLUT.h DataSyncStage.h DataSyncPipeline.h
GradZLinXPipeline.o: ComposBufferStage.h ComposBufferPipeline.h ComposStage.h
GradZLinXPipeline.o: ComposPipeline.h ComposSelXStage.h ComposSelXPipeline.h
GradZLinXPipeline.o: ComposSelYStage.h ComposSelYPipeline.h ComposLinXStage.h
GradZLinXPipeline.o: ComposLinXPipeline.h ComposLinYStage.h
10 GradZLinXPipeline.o: ComposLinYPipeline.h FinalCoxelBuffer.h
ColorLUT.o: Cube4.h /usr/include/string.h /usr/include/standards.h
ColorLUT.o: /usr/include/stdlib.h /usr/include/sgidefs.h /usr/include/stdio.h
ColorLUT.o: /usr/include/assert.h Object.h Global.h Misc.h DynaArray.h
ColorLUT.o: FixPointNumber.h Vector3D.h /usr/include/math.h ModInt.h
15 ColorLUT.o: /usr/include/limits.h Matrix4x4.h FiFo.h Timer.h
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ColorLUT.o: /usr/include/sys/types.h /usr/include/unistd.h Voxel.h Shadel.h
ColorLUT.o: Coxel.h Light.h LinearDataset.h VoxMem.h CoxMem.h Control.h
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20 ColorLUT.o: TriLinYStage.h TriLinYPipeline.h TriLinXStage.h TriLinXPipeline.h
ColorLUT.o: GradYStage.h GradYPipeline.h GradXStage.h GradXPipeline.h
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45 ShaderStage.o: ComposStage.h ComposPipeline.h ComposSelXStage.h
ShaderStage.o: ComposSelXPipeline.h ComposSelYStage.h ComposSelYPipeline.h
ShaderStage.o: ComposLinXStage.h ComposLinXPipeline.h ComposLinYStage.h
ShaderStage.o: ComposLinYPipeline.h FinalCoxelBuffer.h
ShaderPipeline.o: ShaderPipeline.h Misc.h Object.h /usr/include/string.h
50 ShaderPipeline.o: /usr/include/standards.h Global.h /usr/include/assert.h

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ShaderPipeline.o: /usr/include/stdlib.h /usr/include/sgidefs.h Voxel.h
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ShaderPipeline.o: Matrix4x4.h ReflectanceMap.h DynaArray.h Light.h ColorLUT.h
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20 ShaderPipeline.o: ComposLinYStage.h ComposLinYPipeline.h FinalCoxelBuffer.h
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25 ReflectanceMap.o: /usr/include/limits.h DynaArray.h Light.h Matrix4x4.h
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30 DataSyncStage.o: FixPointNumber.h Control.h Matrix4x4.h DataSyncPipeline.h
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35 DataSyncStage.o: AddressGenerator.h MemoryCtrl.h SliceVoxelFiFoStage.h
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45 DataSyncStage.o: ComposLinXPipeline.h ComposLinYStage.h ComposLinYPipeline.h
DataSyncStage.o: FinalCoxelBuffer.h
DataSyncPipeline.o: DataSyncPipeline.h Misc.h Object.h /usr/include/string.h
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DataSyncPipeline.o: Shadel.h FixPointNumber.h Control.h ModInt.h
50 DataSyncPipeline.o: /usr/include/limits.h Vector3D.h /usr/include/math.h

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/usr/include/stdio.h
DataSyncPipeline.o: DynaArray.h Timer.h /usr/include/sys/time.h
5 DataSyncPipeline.o: /usr/include/sys/times.h /usr/include/sys/types.h
DataSyncPipeline.o: /usr/include/unistd.h Voxel.h Coxel.h Light.h
DataSyncPipeline.o: LinearDataset.h VoxMem.h CoxMem.h AddressGenerator.h
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10 DataSyncPipeline.o: TriLinYStage.h TriLinYPipeline.h TriLinXStage.h
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DataSyncPipeline.o: ShaderStage.h ShaderPipeline.h ReflectanceMap.h
15 DataSyncPipeline.o: ColorLUT.h ComposBufferStage.h ComposBufferPipeline.h
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DataSyncPipeline.o: ComposSelXPipeline.h ComposSelYStage.h
DataSyncPipeline.o: ComposSelYPipeline.h ComposLinXStage.h
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20 ComposStage.o: ComposStage.h Misc.h Object.h /usr/include/string.h
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25 ComposStage.o: Shadel.h Cube4.h /usr/include/stdio.h DynaArray.h FiFo.h
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30 ComposStage.o: TriLinYPipeline.h TriLinXStage.h TriLinXPipeline.h
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35 ComposStage.o: ShaderPipeline.h ReflectanceMap.h ColorLUT.h DataSyncStage.h
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40 ComposPipeline.o: /usr/include/standards.h Global.h /usr/include/assert.h
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45 ComposPipeline.o: /usr/include/sys/time.h /usr/include/sys/times.h
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ComposPipeline.o: LinearDataset.h VoxMem.h CoxMem.h AddressGenerator.h
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ComposPipeline.o: TriLinZStage.h TriLinZPipeline.h TriLinYStage.h
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ComposPipeline.o: TriLinYPipeline.h TriLinXStage.h TriLinXPipeline.h
 ComposPipeline.o: GradYStage.h GradYPipeline.h GradXStage.h GradXPipeline.h
 5 ComposPipeline.o: GradZStage.h GradZPipeline.h GradZLinZStage.h
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 10 ComposPipeline.o: ComposSelXPipeline.h ComposSelYStage.h ComposSelYPipeline.h
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 20 ComposBufferStage.o: /usr/include/sys/times.h /usr/include/sys/types.h
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ComposBufferPipeline.o: GradZLinZPipeline.h GradZLinYStage.h
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5 ComposBufferPipeline.o: GradZLinXPipeline.h ShaderStage.h ShaderPipeline.h
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50 ComposSelXPipeline.o: ReflectanceMap.h ColorLUT.h DataSyncStage.h

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ComposSelXPipeline.o: DataSyncPipeline.h ComposBufferStage.h
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5 ComposSelXPipeline.o: ComposSelYStage.h ComposSelYPipeline.h
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10 ComposSelYStage.o: /usr/include/stdlib.h /usr/include/sgidefs.h Vector3D.h
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15 ComposSelYStage.o: /usr/include/unistd.h Voxel.h Shadel.h Light.h
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ComposSelyPipeline.o: ComposLinYStage.h ComposLinYPipeline.h
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10 ComposLinXStage.o: DynaArray.h FiFo.h Timer.h /usr/include/sys/time.h
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30 ComposLinXPipeline.o: /usr/include/math.h Matrix4x4.h ComposLinXStage.h
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50 ComposLinYStage.o: /usr/include/standards.h Global.h /usr/include/assert.h

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5 ComposLinYStage.o: /usr/include/math.h ModInt.h /usr/include/limits.h Coxel.h
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10 ComposLinYStage.o: LinearDataset.h VoxMem.h CoxMem.h AddressGenerator.h
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30 ComposLinYPipeline.o: /usr/include/sys/types.h /usr/include/unistd.h Voxel.h
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45 ComposLinYPipeline.o: FinalCoxelBuffer.h
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FinalCoxelBuffer.o: Misc.h ModInt.h /usr/include/limits.h FixPointNumber.h
50 FinalCoxelBuffer.o: Vector3D.h /usr/include/math.h Matrix4x4.h Coxel.h

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FinalCoxelBuffer.o: CoxMem.h Cube4.h /usr/include/stdio.h DynaArray.h FiFo.h
FinalCoxelBuffer.o: Timer.h /usr/include/sys/time.h /usr/include/sys/types.h
5 FinalCoxelBuffer.o: /usr/include/sys/types.h /usr/include/unistd.h Voxel.h
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10 FinalCoxelBuffer.o: GradXStage.h GradXPipeline.h GradZStage.h GradZPipeline.h
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15 FinalCoxelBuffer.o: ComposPipeline.h ComposSelXStage.h ComposSelXPipeline.h
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20 Cube4.o: /usr/include/assert.h Object.h Global.h Misc.h DynaArray.h
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25 Cube4.o: AddressGenerator.h MemoryCtrl.h SliceVoxelFiFoStage.h
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35 Cube4.o: Cube4Interface.C Cube4Debug.C
:::
cube4/MemoryCtrl.C
:::
// MemoryCtrl.C
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include "MemoryCtrl.h"

45 void MemoryCtrl::Demo()
{
    MemoryCtrl control;

```

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    cout << endl << "Demo of class " << typeid(control).name();
    cout << endl << "size : " << sizeof(MemoryCtrl) << " Bytes";
5    cout << endl << "public member functions:";
    cout << endl << "MemoryCtrl control; = " << control;
    cout << endl << "End of demo of class " << typeid(control).name() << endl;
} // Demo

10  //////////////////////////////////////
    // constructors & destructors

    // static first init
    int MemoryCtrl::numOfChips = 0;
    int MemoryCtrl::numOfPipelinesPerChip = 0;
15
    MemoryCtrl::MemoryCtrl()
    {
        results.voxel = new Voxel {numOfPipelinesPerChip};
        results.weightsXYZ = new Vector3D<FixPointNumber> {numOfPipelinesPerChip};
        results.perPipelineControlFlags = new PerPipelineControlFlags
20  {numOfPipelinesPerChip};
    } // constructor

    MemoryCtrl::~MemoryCtrl()
25  {
        if (results.voxel) { delete results.voxel; results.voxel=0; }
        if (results.weightsXYZ) { delete results.weightsXYZ; results.weightsXYZ=0; }
    }
        if (results.perPipelineControlFlags) {
            delete results.perPipelineControlFlags;
30         results.perPipelineControlFlags=0;
        }
    } // destructor

35  //////////////////////////////////////
    // show/set data & data properties

    ostream & MemoryCtrl::Ostream(ostream & os) const
    {
        // append MemoryCtrl info to os
40     os << typeid(*this).name() << "@" << (void *) this;
        os << endl << "    numOfChips          = " << numOfChips;
        os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
        os << endl << "    chipIndex            = " << chipIndex;
        os << endl << "    memory                = " << mem;
45
        // return complete os
        return os;
    } // Ostream

50
55

```

```

5  ///////////////////////////////////////////////////////////////////
   // show/set data & data properties
   //
   // - local show/set functions

10 void MemoryCtrl::GlobalSetup(const int setNumOfChips,
    const int setNumOfPipelinesPerChip)
   {
       numOfChips      = setNumOfChips;
       numOfPipelinesPerChip = setNumOfPipelinesPerChip;
15   } // GlobalSetup

void MemoryCtrl::LocalSetup(const int setChipIndex, VoxMem * memory)
   {
20     chipIndex      = setChipIndex;
       mem = memory;
   } // LocalSetup

void MemoryCtrl::PerFrameSetup()
25   {
       // reset pipeline registers
       for (int p=0; p<numOfPipelinesPerChip; ++p) {
           results.voxel[p] = 0;
           results.perPipelineControlFlags[p].Reset();
30       }
       results.perChipControlFlags.Reset();

       // print debug info
       //static bool first(true); if (first) { cout<<this<<endl; first=false; }
   } // Init
35

   ///////////////////////////////////////////////////////////////////
   // local computation functions

void MemoryCtrl::RunForOneClockCycle()
40   {
       // add0 = cube4->addGen[0].MemoryAddress(x ,y,z);
       // add1 = cube4->addGen[0].MemoryAddress(x+1,y,z);

       // for startOfVolume timing in SliceVoxelPiFol
45       results.delayedPerChipControlFlags = results.perChipControlFlags;

       // normal stuff do do at each clock cycle
       for (int p=0; p<numOfPipelinesPerChip; ++p) {
           results.voxel[p] = (*mem)(inputs.address[p]);
           results.weightsXYZ[p] = inputs.weightsXYZ[p];
50       }

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    results.perPipelineControlFlags[p] = inputs.perPipelineControlFlags[p];
5      }
    results.perChipControlFlags = *(inputs.perChipControlFlags);
  } // RunForOneClockCycle

10  ////////////////////////////////////////
  // internal utility functions

  // end of MemoryCtrl.C
  ::::::::::::::
15  cube4/MemoryCtrl.h
  ::::::::::::::
  // MemoryCtrl.h
  // (c) Ingmar Bitter '97

  // Copyright, Mitsubishi Electric Information Technology Center
20  // America, Inc., 1997, All rights reserved.

  #ifndef _MemoryCtrl_h_ // prevent multiple includes
  #define _MemoryCtrl_h_

25  #include "Misc.h"
  #include "Object.h"
  #include "FixPointNumber.h"
  #include "Vector3D.h"
  #include "Voxel.h"
  #include "VoxMem.h"
30  #include "Control.h"

  class MemoryCtrlInputs {
  public: // pointers
    int *address;
35    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags *perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
  };

40  class MemoryCtrlResults {
  public: // arrays
    Voxel *voxel;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags perChipControlFlags;
45    PerChipControlFlags delayedPerChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
  };

50  class MemoryCtrl : virtual public Object {
  public:

```

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5      static void      Demo ();

        // constructors & destructors
        MemoryCtrl ();
        ~MemoryCtrl ();

10     // show/set data & data properties
        // - class Object requirements
        virtual ostream & Ostream (ostream & )    const;

        // - local show/set functions
15     static void GlobalSetup (const int setNumOfChips,

        const int setNumOfPipelinesPerChip);

        virtual void LocalSetup(const int setChipIndex, VoxMem * memory);
        virtual void PerFrameSetup();
20     // local computation functions
        virtual void RunForOneClockCycle();

public:
        MemoryCtrlInputs inputs;
25     MemoryCtrlResults results;

protected:
        VoxMem *mem;
        static int numOfChips, numOfPipelinesPerChip;
        int      chipIndex;
30     // static Cube4 *cube4;
};

#ifdef      // _MemoryCtrl_h_
:::
35 cube4/Misc.C
:::
// Misc.C
// (c) Ingmar Bitter '97 / Urs Kanus '97

40 // Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include "Misc.h"

45 // Cube4 stuff
const char * TypeStr::ProjectionStyle[] = PROJECTION_STYLES_STR;
const char * TypeStr::CompositingStyle[] = COMPOSITING_STYLES_STR;
const char * TypeStr::ShaderMode[]      = SHADER_MODES_STR;
const char * TypeStr::CubeMode[]        = CUBE_MODES_STR;
50 const char * TypeStr::MajorViewDirection[] = MAJOR_VIEW_DIRECTION_STR;
const char * TypeStr::XStepDirection[]    = X_STEP_DIRECTION_STR;
const char * TypeStr::YStepDirection[]    = Y_STEP_DIRECTION_STR;
const char * TypeStr::RayEndFace[]        = RAY_END_FACES_STR;

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// VolVis SLC stuff
5  const char * TypeStr::Unit[]           = UNIT_TYPE_STR;
    const char * TypeStr::DataOrigin[]    = DATA_ORIGIN_TYPE_STR;
    const char * TypeStr::DataModification[] = DATA_MODIFICATION_TYPE_STR;
    const char * TypeStr::DataCompression[] = DATA_COMPRESSION_TYPE_STR;

// end of Misc.C
10  :::::::::::::::
    cube4/Misc.h
    :::::::::::::::
    // Misc.h
    // (c) Ingmar Bitter '97

15  // Copyright, Mitsubishi Electric Information Technology Center
    // America, Inc., 1997, All rights reserved.

    #ifndef _Misc_h_ // prevent multiple includes
    #define _Misc_h_

20  typedef int ScalarGradient;

    typedef enum { parallel, perspective } ProjectionStyles;
    #define PROJECTION_STYLES_STR {"parallel","perspective"}

25  typedef enum { BackToFront, FrontToBack } CompositingStyles;
    #define COMPOSITING_STYLES_STR {"BackToFront","FrontToBack"}

    typedef enum { NoShading, Phong, RefMap, RefVector } ShaderModes;
    #define SHADER_MODES_STR
30  {"NoShading","Phong","ReflectanceMap","ReflectanceVector"}

    typedef enum { Cube4Classic, Cube4Light } CubeModes;
    #define CUBE_MODES_STR {"Cube4Classic","Cube4Light"}

35  typedef enum { ViewFront, ViewLeft, ViewTop } MajorViewDirections;
    #define MAJOR_VIEW_DIRECTION_STR {"ViewFront", "ViewLeft", "ViewTop"}

    typedef enum { Left=0, Middle=1, Right=2 } XStepDirections;
    #define X_STEP_DIRECTION_STR {"Left", "Middle", "Right"}
    typedef enum { Up=0, /*Middle=1,*/ Down=2 } YStepDirections;
40  #define Y_STEP_DIRECTION_STR {"Up", "Middle", "Down"}

    // Weight in Compos unit
    static const int StepDirection[3] = {-1, 0, 1};

45  typedef enum { None=0, BackFace=1, TopBottomFace=2, SideFace=4 } RayEndFaces;
    #define RAY_END_FACES_STR {"None", "BackFace", "TopBottomFace", "SideFace",
        "SideFace"}

// VolVis SLC stuff
50
55

```

```

264
typedef enum { METER, MILLIMETER, MICRON, FOOT, INCH } UnitType;
#define UNIT_TYPE_STR {"meter","millimeter","micron","foot","inch"}

5
typedef enum { BIORAD_CONFOCAL_DATA, MAGNETIC_RESONANCE_DATA,
COMPUTED_TOMOGRAPHY_DATA,
SIMULATION_DATA,
BINARY_VOXELIZED_DATA, FUZZY_VOXELIZED_DATA,
FUN_VOXELIZED_DATA, OTHER_DATA_ORIGIN
10
} DataOriginType;
#define DATA_ORIGIN_TYPE_STR {"Biorad confocal","MRI","CT","simulated", \
"binary voxelized","fuzzy voxelized","fun
voxelized","other origin"}

typedef enum { ORIGINAL_DATA, RESAMPLED_DATA, RESAMPLED_FILTERED_DATA,
15
FILTERED_DATA,
OTHER_DATA_MODIFICATION } DataModificationType;
#define DATA_MODIFICATION_TYPE_STR {"original","resampled", \
"resampled & filtered","filtered","other modified"}

typedef enum { NO_COMPRESSION, RUN_LENGTH_ENCODE } DataCompressionType;
20
#define DATA_COMPRESSION_TYPE_STR {"no compression","run length encoding"}

class TypeStr {
public:
// Cube4 stuff
25
static const char * ProjectionStyle[];
static const char * CompositingStyle[];
static const char * ShaderMode[];
static const char * CubeMode[];
static const char * MajorViewDirection[];
static const char * XStepDirection[];
30
static const char * YStepDirection[];
static const char * RayEndFace[];

// VolVis SLC stuff
static const char * Unit[];
static const char * DataOrigin[];
35
static const char * DataModification[];
static const char * DataCompression[];
}; // class TypeStr

#endif // _Misc_h_
40
:::::::::::::
cube4/ReflectanceMap.C
:::::::::::::
// ReflectanceMap.C
// (c) Ingmar Bitter '97 / Urs Kanus '97

45
// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#ifdef WIN32
50
55

```

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```

#include "RMap.h"
#include <strstream.h>
5  #else
#include "ReflectanceMap.h"
#include <strstream.h>
#endif

#include <fstream.h>
10 #include <ctype.h>
#include <stdio.h>    // sprintf

const double epsilon = .001;

void ReflectanceMap::Demo()
15 {
    Vector3D<double> view (1,0,0);
    Light source(1,0,0,1,1,1);
    DynaArray<Light> lightarray;
    lightarray.SetSize(1);
20    lightarray[0] = source;

    ReflectanceMap rmap;
    cout << endl <<"Demo of class " << typeid(rmap).name();
    cout << endl <<"size : " << sizeof(ReflectanceMap) << " Bytes";
    cout << endl <<"public member functions:";
25    cout << endl <<"ReflectanceMap rmap;" ;
    cout << endl <<"\t-----\n" << endl << rmap << "\t-----\n";
    cout << endl <<"PerFrameSetup(";
    cout << endl <<"\t\tconst int          newComponentAddressBits,";
    cout << endl <<"\t\tconst bool          constAngResolution,";
    cout << endl <<"\t\tVector3D<double>      &view,";
30    cout << endl <<"\t\tDynaArray<Light>    &lightarray,";
    cout << endl <<"\t\tconst double          specExp )";
    cout << endl <<"PerFrameSetup(3,3,true,false,view,lightarr,2)";
    rmap.PerFrameSetup(3,3,true,false,view,lightarray,2);
    cout << endl <<"\t-----\n" << endl << rmap << "\t-----\n";
35    cout << endl <<"virtual void LookUp(";
    cout << endl <<"\t\tconst Vector3D<FixPointNumber> gradientXYZ,";
    cout << endl <<"\t\tconst bool interpolateReflMap,";
    cout << endl <<"\t\tconst bool distortionCompensation,";
    cout << endl <<"\t\tVector3D<FixPointNumber> &diffuseIntensity,";
    cout << endl <<"\t\tVector3D<FixPointNumber> &specularIntensity )";
40    cout << endl <<"virtual void WriteTable(const char * fileName);";
    cout << endl <<"virtual void ReadTable (const char * fileName);";
    cout << endl <<"virtual Vector3D<double> DiffuseIntensity( const
Vector3D<double> & norm)";
    cout << endl <<"virtual Vector3D<double> SpecularIntensity(const
Vector3D<double> & norm)";
45    cout << endl <<"void ShowValues( const char * fileName=\"\" )";
    cout << endl;

    // ...

```

50

55

266

```

    cout << endl << "End of demo of class " << typeid(rmap).name() << endl;
} // Demo

```

```

5 void ReflectanceMap::ShowMapImage(const bool refVectorLookup,
                                   const bool refMapInterpolation)
{
10     cout << refVectorLookup << refMapInterpolation;

    int range = 0x1 << componentAddressBits;

    double du = 1.0/double(range - 1);
    double dv = 1.0/double(range - 1);
15     double u, v;
    int colorPlaneOffset = 48 * range * range;
    int lineOffset = 8 * range;
    //int faceUSkip = 2 * range;
    int faceVSkip = 2 * range * lineOffset;
20     Vector3D<FixPointNumber> diffuseIntensity; //, specularIntensity;
    char * mapImage = new char[48 * range * range * 3 - 1];
    int i, j;
    int faceUOffset = 0;
    int faceVOffset = 0;

25     for ( i = -range+1, u = -1; i <= range; i++, u += du)
    { //cout << u << " ";
        for (j = -range+1, v = -1; j <= range; j++, v += dv)
        { //cout << v << " ";

30             Vector3D<FixPointNumber> NegNX( -1, u, v);
            DiffuseLookUp(NegNX, false, false, diffuseIntensity);
            mapImage[faceVSkip + faceVOffset*lineOffset +
                    faceUOffset - 1] =
char(255*diffuseIntensity.R());
            mapImage[faceVSkip + faceVOffset*lineOffset + faceUOffset +
35                    colorPlaneOffset - 1] =
char(255*diffuseIntensity.G());
            mapImage[faceVSkip + faceVOffset*lineOffset + faceUOffset +
                    2*colorPlaneOffset - 1] =
char(255*diffuseIntensity.B());

40             /*
            Vector3D<FixPointNumber> NegNY( u, -1, -v);
            DiffuseLookUp(NegNY, false, false, diffuseIntensity);
            mapImage[faceVSkip + faceVOffset*lineOffset +
                    faceUSkip + faceUOffset] =
45 char(255*diffuseIntensity.R());
            mapImage[faceVSkip + faceVOffset*lineOffset +
                    faceUSkip + faceUOffset +
                    colorPlaneOffset] =
char(255*diffuseIntensity.G());
50             mapImage[faceVSkip + faceVOffset*lineOffset +

```

```

267
        faceUSkip + faceUOffset +
        2*colorPlaneOffset ] =
5 char(255*diffuseIntensity.B());

        Vector3D<FixPointNumber> PosNZ( u, -v, 1);
        DiffuseLookUp(PosNZ, false, false, diffuseIntensity);
        mapImage[2*faceVSkip + faceVOffset*lineOffset +
        faceUSkip + faceUOffset] =
10 char(255*diffuseIntensity.R());
        mapImage[2*faceVSkip + faceVOffset*lineOffset +
        faceUSkip + faceUOffset +
        colorPlaneOffset] =
        char(255*diffuseIntensity.G());
        mapImage[2*faceVSkip + faceVOffset*lineOffset +
15 faceUSkip + faceUOffset +
        2*colorPlaneOffset] =
        char(255*diffuseIntensity.B());

        Vector3D<FixPointNumber> NegNZ( u, v, -1);
        DiffuseLookUp(NegNZ, false, false, diffuseIntensity);
        mapImage[faceVOffset*lineOffset +
        faceUSkip + faceUOffset] =
        char(255*diffuseIntensity.R());
        mapImage[faceVOffset*lineOffset + faceUSkip +
25 faceUOffset + colorPlaneOffset] =
        char(255*diffuseIntensity.G());
        mapImage[faceVOffset*lineOffset + faceUSkip +
        faceUOffset + 2*colorPlaneOffset] =
        char(255*diffuseIntensity.B());

        Vector3D<FixPointNumber> PosNX(1, -u, v);
        DiffuseLookUp(PosNX, false, false, diffuseIntensity);
        mapImage[faceVSkip + faceVOffset*lineOffset +
        2*faceUSkip + faceUOffset] =
30 char(255*diffuseIntensity.R());
        mapImage[faceVSkip + faceVOffset*lineOffset + 2*faceUSkip +
        faceUOffset + colorPlaneOffset] =
        char(255*diffuseIntensity.G());
        mapImage[faceVSkip + faceVOffset*lineOffset + 2*faceUSkip +
        faceUOffset + 2*colorPlaneOffset] =
35 char(255*diffuseIntensity.B());

        Vector3D<FixPointNumber> PosNY( u, 1, v);
        DiffuseLookUp(PosNY, false, false, diffuseIntensity);
        mapImage[faceVSkip + faceVOffset*lineOffset +
        3*faceUSkip + faceUOffset] =
45 char(255*diffuseIntensity.R());
        mapImage[faceVSkip + faceVOffset*lineOffset + 3*faceUSkip +
        faceUOffset + colorPlaneOffset] =
        char(255*diffuseIntensity.G());
        mapImage[faceVSkip + faceVOffset*lineOffset + 3*faceUSkip +
50 char(255*diffuseIntensity.B());

        Vector3D<FixPointNumber> PosNY( u, 1, v);
        DiffuseLookUp(PosNY, false, false, diffuseIntensity);
        mapImage[faceVSkip + faceVOffset*lineOffset +
        3*faceUSkip + faceUOffset] =
55 char(255*diffuseIntensity.R());
        mapImage[faceVSkip + faceVOffset*lineOffset + 3*faceUSkip +
        faceUOffset + colorPlaneOffset] =
        char(255*diffuseIntensity.G());
        mapImage[faceVSkip + faceVOffset*lineOffset + 3*faceUSkip +
        faceUOffset + 2*colorPlaneOffset] =
        char(255*diffuseIntensity.B());

```

```

268
                                faceUOffset + 2*colorPlaneOffset]
= char(255*diffuseIntensity.B());
5
                                */
                                faceVOffset++;
                                }
                                faceVOffset = 0;
                                faceUOffset++;
                                }
10
    // now write the image to a file

    char mapFileName[50];
    sprintf(mapFileName,"img/refMapImage.rgb");
    ofstream mapImageFile(mapFileName);
15
    mapImageFile.write(mapImage, 3 * colorPlaneOffset);

    char str[200];
    sprintf(str,"convert -size %ix%i %s %s \n",
20
                                8*range, 6*range,
                                "img/refMapImage.rgb",
                                "img/refMapImage.miff");
    system(str);
}

25

void ReflectanceMap::ShowValues(const char * fileName, int color)
{
    ofstream output(fileName);
    int range = 0x1 << componentAddressBits;
30

    double du = 1.0/double(range - 1);
    double dv = 1.0/double(range - 1);
    double u, v;
    Vector3D<FixPointNumber> diffuseIntensity; //, specularIntensity;
35

    strstream posXfaceR; //, posXfaceG, posXfaceB,
    strstream posYfaceR; //, posYfaceG, posYfaceB,
    strstream posZfaceR; //, posZfaceG, posZfaceB,
    strstream negXfaceR; //, negXfaceG, negXfaceB,
    strstream negYfaceR; //, negYfaceG, negYfaceB,
40
    strstream negZfaceR; //, negZfaceG, negZfaceB;
    int i,j;
    int prec = 4;
    int wid = prec + 2;
    Vector3D<FixPointNumber> filter;
    switch (color) {
45
    case 0:
        filter(1,0,0); break;
    case 1:
        filter(0,1,0); break;

50

55

```

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```

case 2:
    filter(0,0,1); break;
5  default:
    return;
}

10 char *filler = new char[(2*range)*(wid+1) +1];
    for ( i=0; i<(2*range)*(wid+1) +1; i++) filler[i] = ' ';
    filler[2*range*(wid+1)] = '\0';

    for ( i =-range+1,u=-1; i <= range; i++, u += du)
    { //cout << u << " ";
15         for (j=-range+1, v = -1; j <= range; j++, v+=dv)
            { //cout << v << " ";

                Vector3D<FixPointNumber> NegNX( -1, u, v);
                DiffuseLookUp(NegNX, false, false, diffuseIntensity);
20
                posYfaceR.precision(prec); posYfaceR.width(wid);
                posYfaceR << (double)(diffuseIntensity*filter) << " ";

25

                Vector3D<FixPointNumber> NegNY( u,-1, -v);
                DiffuseLookUp(NegNY, false, false, diffuseIntensity);
                negYfaceR.precision(prec); negYfaceR.width(wid);
30                negYfaceR << (double)(diffuseIntensity*filter) << " ";

                Vector3D<FixPointNumber> PosNZ( u, -v, 1);
                DiffuseLookUp(PosNZ, false, false, diffuseIntensity);
                posZfaceR.precision(prec); posZfaceR.width(wid);
35                posZfaceR << (double)(diffuseIntensity*filter) << " ";

                Vector3D<FixPointNumber> NegNZ( u, v, -1);
                DiffuseLookUp(NegNZ, false, false, diffuseIntensity);
40                negZfaceR.precision(prec); negZfaceR.width(wid);
                negZfaceR << (double)(diffuseIntensity*filter) << " ";

            }
        }
        for (j=-range+1, v = -1; j <= range; j++, v+=dv)
45        {
            Vector3D<FixPointNumber> PosNY( u, 1, v);
            DiffuseLookUp(PosNY, false, false, diffuseIntensity);
            posYfaceR.precision(prec); posYfaceR.width(wid);
            posYfaceR << (double)(diffuseIntensity*filter) << " ";
50        }

        for (j=-range+1, v = -1; j <= range; j++, v+=dv)
        {
55

```

```

5      Vector3D<FixPointNumber> PosNX(1, -u, v);
      DiffuseLookUp(PosNX, false, false, diffuseIntensity);
      posYfaceR.precision(prec); posYfaceR.width(wid);
      posYfaceR << (double)(diffuseIntensity*filter) << " ";

10      }
      posXfaceR << "\n";
      posYfaceR << "\n";
      posZfaceR << "\n";
      negXfaceR << "\n";
      negYfaceR << "\n";
15      negZfaceR << "\n";
    }
    posXfaceR << ends;
    posYfaceR << ends;
    posZfaceR << ends;
20    negXfaceR << ends;
    negYfaceR << ends;
    negZfaceR << ends;

    /*      cout << negZfaceR.str();
25      cout << filler << "-----\n";
      cout << posYfaceR.str();
      cout << filler << "-----\n";
      cout << posZfaceR.str();
      cout << filler << "-----\n";
30      */
      output << negZfaceR.str();
      output << filler << "-----\n";
      output << posYfaceR.str();
      output << filler << "-----\n";
35      output << posZfaceR.str();
      output << filler << "-----\n";
      output << negYfaceR.str();

      output.close();
40      delete [] filler;
    }

    //////////////////////////////////////
45    // Construction/Destruction
    //////////////////////////////////////

    ReflectanceMap::ReflectanceMap()
    {
        componentAddressBits = 0;
50        pDiffuseIntensities = 0;
        pSpecularIntensities = 0;
        //Light source(1.0,0.0,0.0);
55

```


271

```

    lightSource.SetSize(0);
    //lightSource[0] = source;
5      }

    ReflectanceMap::~ReflectanceMap()
    {
10      }

    void ReflectanceMap::PerFrameSetup(const int newComponentAddressBits,

        const int newMapWeightBits,

15        const bool constantAngularResolution,

        const bool refVectorLookup,

20        const Vector3D<double> & newViewVector,

        const DynaArray<Light> & newLightSource,

        const double newSpecularExponent)
25    {
        enum (NO_CHANGE, DIFFUSE, SPECULAR);

        int state1 = NO_CHANGE;
        int state2 = NO_CHANGE;
30        static int range;

        mapWeightBits = newMapWeightBits;

35        if (componentAddressBits != newComponentAddressBits) {
            state1 = DIFFUSE;
            state2 = SPECULAR;
            componentAddressBits = newComponentAddressBits;

40            range = 0x1 << componentAddressBits;

            delete [] pDiffuseIntensities;
            delete [] pSpecularIntensities;

45            // map has one section for each maximum component x,y, or z
            // each section has 8 subsections (4 quadrants, 2 faces)
            // each subsection contains range * range values
            pDiffuseIntensities = new rgb[range * range * 8 * 3];
            pSpecularIntensities = new rgb[range * range * 8 * 3];
50        }

        // Handle changing light sources here

55

```

```

272
    if(lightSource.Size() != newLightSource.Size())
    {
5         statel = DIFFUSE;
        state2 = SPECULAR;
    }
    else
    {
10         for (int i =0; i < lightSource.Size(); i++)
        {
            if(lightSource[i].Direction() !=
newLightSource[i].Direction() ||
15 newLightSource[i].Intensity() !=
            lightSource[i].Intensity() !=
            {
                statel = DIFFUSE;
                state2 = SPECULAR;
                break;
            }
20         }
    }
    if( statel == NO_CHANGE) {
        Vector3D<double> temp = viewVector - newViewVector;

25        // if we use reflection vector lookup, view vector change
        // doesn't matter
        if (!refVectorLookup){
            state2 = (temp.Norm() > epsilon ) ? SPECULAR : state2;
        }
30        state2 = (specularExponent - newSpecularExponent > epsilon)
            ? SPECULAR : state2;
    }

    if(statel == NO_CHANGE && state2 == NO_CHANGE) return;

35    viewVector = newViewVector;
    specularExponent = newSpecularExponent;
    lightSource = newLightSource;
    int mapOffset = range*range*8;
    short sign1, sign2;
40    int signAddress;

    // alpha between 0 to 45 degrees
    double alphaIncrement = (PI / 4.0) / double(range - 1);
45    double alphaU = 0.0;
    double alphaV = 0.0;

    // or range-1 steps between 0 and 1
    double dU = 1.0/double(range - 1);
50    double dV = 1.0/double(range - 1);

    double u = 0.0;
    double v = 0.0;

```

55

273

```

5   for ( int quadrant = 0; quadrant < 4; quadrant++){
      for ( int axis1 = 0; axis1 < range; axis1++){
          for ( int axis2 = 0; axis2 < range; axis2++){

              // we can either have constant stepping along the cube
              // or constant angular stepping of the normals
10          if (constantAngularResolution){
              u = tan(alphaU);
              v = tan(alphaV);
          }

15          // we go ^+
          //      |
          //      1 | 0
          //      ----+-----> +
          //      2 | 3
          //      |
          switch (quadrant){
              case 0: sign1 = 1; sign2 = 1; break;
              case 1: sign1 = -1; sign2 = 1; break;
              case 2: sign1 = -1; sign2 = -1; break;
              case 3: sign1 = 1; sign2 = -1; break;
          }

25          Vector3D<double> PosNX(      1, sign1*u, sign2*v);
          Vector3D<double> NegNX(     -1, sign1*u, sign2*v);
          Vector3D<double> PosNY( sign1*u,      1, sign2*v);
          Vector3D<double> NegNY( sign1*u,     -1, sign2*v);
          Vector3D<double> PosNZ( sign1*u, sign2*v,      1);
          Vector3D<double> NegNZ( sign1*u, sign2*v,     -1);

          Vector3D<double> temp;
          char signs;

35          if(state1 == DIFFUSE){

              temp = DiffuseIntensity(PosNX);
              signs =
40                  2 * (sign1<0) +
                  4 * (sign2<0);
              signAddress = signs<<(2*componentAddressBits);

          pDiffuseIntensities[signAddress+axis2*range+axis1] (temp.R(),

45          temp.G(),

          temp.B());

50

55

```

```

                274
temp = DiffuseIntensity(PosNY);
signs =
5      1 * (sign1<0) +
        4 * (sign2<0);
signAddress = signs<<(2*componentAddressBits);

pDiffuseIntensities[mapOffset+signAddress+axis2*range+axis1](temp.R(),
10
                                temp.G(),

                                temp.B());

15
temp = DiffuseIntensity(PosNZ);
signs =
        1 * (sign1<0) +
20      2 * (sign2<0);
signAddress = signs<<(2*componentAddressBits);

pDiffuseIntensities[2*mapOffset+signAddress+axis2*range+axis1](temp.R(),
25
                                temp.G(),

                                temp.B());

30
temp = DiffuseIntensity(NegNX);
signs = 1 +
        2 * (sign1<0) +
        4 * (sign2<0);
35 signAddress = signs<<(2*componentAddressBits);

pDiffuseIntensities[signAddress+axis2*range+axis1](temp.R(),

temp.G(),
40
temp.B());

temp = DiffuseIntensity(NegNY);
45 signs = 2 +
        1 * (sign1<0) +
        4 * (sign2<0);
signAddress = signs<<(2*componentAddressBits);

50 pDiffuseIntensities[mapOffset+signAddress+axis2*range+axis1](temp.R(),

temp.G(),

55

```

```

5                                     temp.B());

    temp = DiffuseIntensity(NegNZ);
    signs = 4 +
        1 * (sign1<0) +
10        2 * (sign2<0);
    signAddress = signs<<(2*componentAddressBits);

    pDiffuseIntensities[2*mapOffset+signAddress+axis2*range+axis1](temp.R(),

15                                     temp.G(),

                                     temp.B());

20
    }

    if( state2 == SPECULAR ) {

25        temp = SpecularIntensity(PosNX, refVectorLookup);
        signs =
            2 * (sign1<0) +
            4 * (sign2<0);
        signAddress = signs<<(2*componentAddressBits);

30    pSpecularIntensities[signAddress+axis2*range+axis1](temp.R(),

        temp.G(),

35        temp.B());

        temp = SpecularIntensity(PosNY, refVectorLookup);
        signs =
40        1 * (sign1<0) +
        4 * (sign2<0);
        signAddress = signs<<(2*componentAddressBits);

        pSpecularIntensities[mapOffset+signAddress+axis2*range+axis1](temp.R(),

45        temp.G(),

        temp.B());

        temp = SpecularIntensity(PosNZ, refVectorLookup);
        signs =

55

```

```

276
1 * (sign1<0) +
2 * (sign2<0);
5      signAddress = signs<<(2*componentAddressBits);

pSpecularIntensities[2*mapOffset+signAddress+axis2*range+axis1](temp.R(),

10      temp.G(),

      temp.B());

15      temp = SpecularIntensity(NegNX, refVectorLookup);
      signs = 1 +
            2 * (sign1<0) +
            4 * (sign2<0);
      signAddress = signs<<(2*componentAddressBits);

20      pSpecularIntensities[signAddress+axis2*range+axis1](temp.R(),

      temp.G(),

25      temp.B());
      temp = SpecularIntensity(NegNY, refVectorLookup);
      signs = 2 +
            1 * (sign1<0) +
30      4 * (sign2<0);
      signAddress = signs<<(2*componentAddressBits);

      pSpecularIntensities[mapOffset+signAddress+axis2*range+axis1](temp.R(),

35      temp.G(),

      temp.B());

40      temp = SpecularIntensity(NegNZ, refVectorLookup);
      signs = 4 +
            1 * (sign1<0) +
            2 * (sign2<0);
      signAddress = signs<<(2*componentAddressBits);

45      pSpecularIntensities[2*mapOffset+signAddress+axis2*range+axis1](temp.R(),

      temp.G(),

50      temp.B());

55

```

```

277
    }
    if (axis2 == range-1){
5         v = 0.0;
        alphaV = 0.0;
    }
    else{
        v += dV;
10        alphaV += alphaIncrement;
    }
}
if (axis1 == range-1){
    u = 0.0;
    alphaU = 0.0;
15 }
else{
    u += dU;
    alphaU += alphaIncrement;
20 }
}
}

25 void ReflectanceMap::WriteTable(const char * fileName)
{
    ofstream output(fileName);
    output << "Reflectance Map File\n";
    output << *this;
30 output << "\n\n";
    int range = 0x1 << componentAddressBits;

    int arraySize = range * range * 8 * 3; // See explanation in
    PerFrameSetup
35
    output << "\ndiffuse intensities\n\n";

    for( int i=0; i < arraySize; i++)
    {
40
        output << pDiffuseIntensities[i].R() << " " ;
        output << pDiffuseIntensities[i].G() << " " ;
        output << pDiffuseIntensities[i].B() << " ";
    }
45
    output << "\nspecular intensities\n\n";

    for( i=0; i < arraySize; i++)
        output << pSpecularIntensities[i].R() << " " <<
50         pSpecularIntensities[i].G() << " " <<
        pSpecularIntensities[i].B() << " ";

    output.close();
55

```

```

    }
5
void skipAlpha( ifstream input)
{
    cout << input;
    /*    int c;
10    while ((c = input.get()) != EOF)
    {
        if (!isdigit(c) && c != '-')
            continue;

        input.putback(c);
15        break;
    }
    */
}

20
void ReflectanceMap::ReadTable (const char * fileName)
{
    cout << fileName;
    /*    ifstream input(fileName);
25
    skipAlpha(input);
    input >> componentAddressBits;
    skipAlpha(input);

30
    double x,y,z,r,g,b;
    input>> x; input.get();
    input>> y; input.get();
    input>> z;
    viewVector(x,y,z);
35
    skipAlpha(input);
    int numLights;
    input >> numLights;
    skipAlpha(input);
40
    lightSource.SetSize(numLights);
    Light source;
    for (int i=0; i< numLights; i++)
    {
45
        input >> x; input.get();
        input >> y; input.get();
        input >> z; skipAlpha(input);
        input >> r; input.get();
        input >> g; input.get();
50
        input >> b; skipAlpha(input);
        source(x,y,z,r,g,b,1);
        lightSource[i] = source;
    }
55

```



```

5         input >> specularExponent;

        skipAlpha(input);

        delete [] pDiffuseIntensities;
10        delete [] pSpecularIntensities;

        int range = 0x1 << componentAddressBits;
        int arraySize = range * range * 8 * 3; // See explanation in
PerFrameSetup
15        pDiffuseIntensities = new rgb[range * range * 8 * 3];
        pSpecularIntensities = new rgb[range * range * 8 * 3];

        for (i=0; i<arraySize; i++)
        {
20                input >> r;
                input >> g;
                input >> b;
                pDiffuseIntensities[i](r,g,b);

25        }
        skipAlpha(input);

        for (i=0; i<arraySize; i++)
        {
30                input >> r;
                input >> g;
                input >> b;
                pSpecularIntensities[i](r,g,b);
        }
35

        input.close();
        */

40    }

    //////////////////////////////////////
    // show/set data & data properties
    //

45    ostream & ReflectanceMap::Ostream(ostream & os) const
    {
        // append Light info to os
        os << "Bits in Gradient\t\t" << componentAddressBits << "\n";
        os << "View Vector\t\t\t" << viewVector << "\n";
50        os << "Number of Light Sources\t\t" << lightSource.Size() << "\n";
        for (int i=0; i < lightSource.Size(); i++)
            os << "Light source " << "\t\t\t" << lightSource[i] << "\n";

55

```

```

280
os << "Specular Exponent\t\t" << specularExponent << "\n";

5
// return complete os
return os;

} // Ostream

10

Vector3D<double> ReflectanceMap::DiffuseIntensity(const Vector3D<double> & norm)
{
    Vector3D<double> intensitySum(0,0,0), lightVector, surfaceNormal;
15
    double n;

    n = norm.Norm();
    if (n>0) {
        surfaceNormal = norm/n;
    }

20
    for (int i=0; i < lightSource.Size(); i++) {

        lightVector=lightSource[i].Direction();
        lightVector /= lightVector.Norm();

25
        double NL = surfaceNormal * lightVector;
        if (NL < 0)
            NL = 0;
        else
            NL = pow(NL, lightSource[i].Sharpness());

30
        intensitySum += (lightSource[i].Intensity()) * NL;
    }
    return intensitySum;

} // DiffuseIntensity

35

Vector3D<double> ReflectanceMap::SpecularIntensity(const Vector3D<double> &
vector,

const
40
bool refVectorLookup)
{
    Vector3D<double> intensitySum(0,0,0), lightVector;
    Vector3D<double> surfaceNormal, lightReflection;
    Vector3D<double> eyeReflection;
    double n, RL, RV, NL, phongComponent;

45
    if (refVectorLookup){ // vector is reflectionVector
        n = vector.Norm();
        if (n>0){

50

55

```

```

281
    eyeReflection = vector / n;
5      }

    for (int light=0; light<lightSource.Size(); ++light) {

        lightVector = lightSource[light].Direction();
        lightVector /= lightVector.Norm();
10      RL = eyeReflection * lightVector;

        if (RL < 0)
            phongComponent = 0;
15      else
            phongComponent = pow(RL, specularExponent);

        intensitySum +=
            lightSource[light].Intensity() * phongComponent;
20      }
    }
    else{ // vector is surface normal

        n = vector.Norm();
        if (n>0) {
25          surfaceNormal = vector/n;
        }

        for (int light=0; light<lightSource.Size(); ++light) {

30          lightVector = lightSource[light].Direction();
            lightVector /= lightVector.Norm();

            NL = surfaceNormal * lightVector;

35          lightReflection = surfaceNormal;
            lightReflection *= (2*NL);
            lightReflection = lightReflection - lightVector;

            RV = lightReflection * viewVector;
40          if (RV < 0)
                phongComponent = 0;
            else
                phongComponent = pow(RV, specularExponent);

45          intensitySum += lightSource[light].Intensity() *
phongComponent;
        }
    }

50    return intensitySum;
} // SpecularIntensity

55

```

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```

void
ReflectanceMap::ComputeLookupVector(const Vector3D<FixPointNumber> vectorXYZ,
5
                                   FixPointNumber & index1,
                                   FixPointNumber & index2,
                                   int & mapAddress)
10 {
    FixPointNumber maxComponent, vector1, vector2;
    Vector3D<FixPointNumber> vector;

    int range = 1<<componentAddressBits;
15 int faceQuadrant = range * range;
    int frontAndBackFace = faceQuadrant * 8;
    int mapOffset;

    short gradientInputPrecision = vectorXYZ.X().FractionBits();

20 // extract sign bits
    int signs =
        1 * (vectorXYZ.X()<0) +
        2 * (vectorXYZ.Y()<0) +
        4 * (vectorXYZ.Z()<0);

25 vector((FixPointNumber) (vectorXYZ.X().Abs()),
        (FixPointNumber) (vectorXYZ.Y().Abs()),
        (FixPointNumber) (vectorXYZ.Z().Abs()));

    // Sort
30 bool yGreaterX, zGreaterX, zGreaterY;
    bool equal;

    yGreaterX = (vector.X() < vector.Y());
    zGreaterX = (vector.X() < vector.Z());
35 zGreaterY = (vector.Y() < vector.Z());

    equal = (!yGreaterX && !zGreaterX && !zGreaterY);

    if (zGreaterX && zGreaterY) {
40         maxComponent = vector.Z();
        vector1 = vector.X();
        vector2 = vector.Y();
        mapOffset = 2 * frontAndBackFace; // address upper third of table
    }
    else if (zGreaterX && !zGreaterY) {
45         if (yGreaterX) {
            maxComponent = vector.Y();
            vector1 = vector.X();
            vector2 = vector.Z();
            mapOffset = frontAndBackFace; // address middle third of table
50
55

```

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```

    }
    else(
5         maxComponent = vector.Z();
          vector1 = vector.X();
          vector2 = vector.Y();
          mapOffset = 2 * frontAndBackFace; // address upper third of
table      table
    )
10     }
    else if (!zGreaterX && zGreaterY) {
        if (yGreaterX) {
            maxComponent = vector.Z();
            vector1 = vector.X();
            vector2 = vector.Y();
15         mapOffset = 2 * frontAndBackFace; // address upper third of
table      table
        }
        else {
            maxComponent = vector.X();
            vector1 = vector.Y();
20         vector2 = vector.Z();
            mapOffset = 0; // lower third of table
        }
    }
    else if (!zGreaterX && !zGreaterY) {
25         if (yGreaterX) {
            maxComponent = vector.Y();
            vector1 = vector.X();
            vector2 = vector.Z();
            mapOffset = frontAndBackFace; // address middle third of table
        }
        else {
30         maxComponent = vector.X();
            vector1 = vector.Y();
            vector2 = vector.Z();
            mapOffset = 0; // lower third of table
        }
    }
35     }
    else if (equal) {
        maxComponent = vector.X();
        vector1 = vector.Y();
        vector2 = vector.Z();
        mapOffset = 0; // lower third of table
40     cout << endl << "equal : "<<maxComponent<<" "<<vector1<<" "<<vector2;
    }

    // Shift
    if (maxComponent>0){
45         int compare = 1<<(gradientInputPrecision - 1);
        int bitNumber = gradientInputPrecision - 1;
        bool done = false;

        // all significant bits after decimal point
50
55

```

```

284
maxComponent = maxComponent>>gradientInputPrecision;
vector1 = vector1>>gradientInputPrecision;
5 vector2 = vector2>>gradientInputPrecision;

while (bitNumber>0 && !done){
    if (!(maxComponent & compare) &&
        !(vector1 & compare) &&
        !(vector2 & compare)){
10 maxComponent = maxComponent<<1;
        vector1 = vector1<<1;
        vector2 = vector2<<1;
    }
    else
15 done = true;
        bitNumber--;
    }
}

// Normalization
20 if (maxComponent>0){
    vector1 /= maxComponent;
    vector2 /= maxComponent;
}

25 index1 = vector1;
index2 = vector2;

signs = signs * faceQuadrant;
30 mapAddress = mapOffset + signs;
}

void ReflectanceMap::DiffuseLookUp(const Vector3D<FixPointNumber> gradientXYZ,
35 const bool interpolateReflMap,
    const bool distortionCompensation,
    Vector3D<FixPointNumber> & diffuseIntensity)
40 {
    FixPointNumber index1;
    FixPointNumber index2;
    int mapAddress;
    int range = 1<<componentAddressBits;
    double alphaIncrementReciprocal = double(range - 1)/(PI/4.0);
45 ComputeLookupVector(gradientXYZ, index1, index2, mapAddress);

    if (!distortionCompensation){
        // We don't want 1.0 if we don't use distortion compensation
50 index1 *= (double(range-1)/double(range));
    }
}

```

55

```

                                285
                                index2 *= (double(range- 1)/double(range));
}

5
// Distortion compensation computed on the fly
if (distortionCompensation){
    index1 = atan(index1) * alphaIncrementReciprocal;
    index2 = atan(index2) * alphaIncrementReciprocal;
10
}
else{
    index1 = index1<<componentAddressBits;
    index2 = index2<<componentAddressBits;
}

15
// Reflectance map address and interpolation weights
char addr1 = int(index1);
char addr2 = int(index2);

FixPointNumber weight1 = index1 - FixPointNumber(addr1);
20
weight1 = weight1.Round(mapWeightBits);

FixPointNumber weight2 = index2 - FixPointNumber(addr2);
weight2 = weight2.Round(mapWeightBits);

25
// Map Access & Interpolation (diffuse component)
if (interpolateReflMap) {
    Vector3D<FixPointNumber> intensityBase, intensityRight;
    Vector3D<FixPointNumber> intensityTopLeft, intensityTopRight;
    Vector3D<FixPointNumber> top, bottom;

30
    //interpolate diffuse part
    intensityBase = pDiffuseIntensities[mapAddress+addr2*range+addr1];
    intensityRight =
pDiffuseIntensities[mapAddress+addr2*range+addr1+1];
    intensityTopLeft =
35
pDiffuseIntensities[mapAddress+(addr2+1)*range+addr1];
    intensityTopRight =
pDiffuseIntensities[mapAddress+(addr2+1)*range+addr1+1];

    bottom = intensityRight - intensityBase;
40
    bottom *= weight1;
    bottom += intensityBase;

    top = intensityTopRight - intensityTopLeft;
    top *= weight1;
45
    top += intensityTopLeft;

    diffuseIntensity = top - bottom;
    diffuseIntensity *= weight2;
    diffuseIntensity += bottom;

50
}
else{

55

```

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```

    diffuseIntensity =
pDiffuseIntensities[mapAddress+addr2*range+addr1];
5      }
    }

void ReflectanceMap::SpecularLookUp(const Vector3D<FixPointNumber> vectorXYZ,
10      const bool interpolateReflMap,
      const bool distortionCompensation,
      Vector3D<FixPointNumber> & specularIntensity)
15  {
    FixPointNumber index1;
    FixPointNumber index2;
    int mapAddress;
    int range = 1<<componentAddressBits;
20    double alphaIncrementReciprocal = double(range - 1)/(PI/4.0);

    ComputeLookUpVector(vectorXYZ, index1, index2, mapAddress);

    if (!distortionCompensation){
25      // We don't want 1.0 if we don't use distortion compensation
      index1 *= (double(range-1)/double(range));
      index2 *= (double(range-1)/double(range));
    }

    // Distortion compensation computed on the fly
    if (distortionCompensation){
30      index1 = atan(index1) * alphaIncrementReciprocal;
      index2 = atan(index2) * alphaIncrementReciprocal;
    }
    else{
35      index1 = index1<<componentAddressBits;
      index2 = index2<<componentAddressBits;
    }

    // Reflectance map address and interpolation weights
40    char addr1 = int(index1);
    char addr2 = int(index2);

    FixPointNumber weight1 = index1 - FixPointNumber(addr1);
    weight1 = weight1.Round(mapWeightBits);

45    FixPointNumber weight2 = index2 - FixPointNumber(addr2);
    weight2 = weight2.Round(mapWeightBits);

    // Map Access & Interpolation (specular component)
50    if (interpolateReflMap) {

```

55


```

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Vector3D<FixPointNumber>    intensityBase, intensityRight;
Vector3D<FixPointNumber> intensityTopLeft, intensityTopRight;
5   Vector3D<FixPointNumber> top, bottom;

    // only for debugging: report address overflow
    if ((addr1 > (range - 2)) || (addr2 > (range - 2))){
        cout <<endl<<"Address-Overflow !!!(addr1 = "<<addr1<<" , addr2
= ";
10         cout <<addr2;
    }

    //interpolate specular part
    intensityBase = pSpecularIntensities[mapAddress+addr2*range+addr1];
    intensityRight =
15   pSpecularIntensities[mapAddress+addr2*range+addr1+1];
    intensityTopLeft =
    pSpecularIntensities[mapAddress+(addr2+1)*range+addr1];
    intensityTopRight =
    pSpecularIntensities[mapAddress+(addr2+1)*range+addr1+1];

20     bottom = intensityRight - intensityBase;
    bottom *= weight1;
    bottom += intensityBase;

    top = intensityTopRight - intensityTopLeft;
25     top *= weight1;
    top += intensityTopLeft;

    specularIntensity = top - bottom;
    specularIntensity *= weight2;
    specularIntensity += bottom;
30
    }
    else{
        specularIntensity =
        pSpecularIntensities[mapAddress+addr2*range+addr1];
35
    }
}

:::::::::::::
cube4/ReflectanceMap.h
:::::::::::::
40 // ReflectanceMap.h
// Ingmar Bitter '97 / Urs Kanus '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.
45 #ifndef _ReflectanceMap_h_    // prevent multiple includes
#define _ReflectanceMap_h_

#include "Misc.h"
50
55

```

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```

#include "Object.h"
#include "FixPointNumber.h"
#include "Vector3D.h"
5  #include "DynaArray.h"
#include "Light.h"

#define PI 3.1415927

10 class ReflectanceMap : virtual public Object {
public:

    static void      Demo ();

15     // constructors & destructors
    ReflectanceMap ();
    ~ReflectanceMap ();

    // show/set data & data properties
    // - class Object requirements
20     virtual ostream & Ostream (ostream & ) const;

    // - local show/set functions
    virtual void PerFrameSetup(const int newComponentAddressBits,

25     const int newMapWeightBits,

    const bool constantAngularResolution,

    const bool refVectorLookup,

30     const Vector3D<double> & newViewVector,

    const DynaArray<Light> & newLightSource,

    const double newSpecularExponent);

35     virtual void ComputeLookupVector(const Vector3D<FixPointNumber> vectorXYZ,

        FixPointNumber & index1,

        FixPointNumber & index2,

40     int & mapAddress);

    virtual void DiffuseLookUp(const Vector3D<FixPointNumber> gradientXYZ,

45     const bool interpolateReflMap,

    const bool distortionCompensation,

    Vector3D<FixPointNumber> & diffuseIntensity);

50

55

```

```

5      virtual void SpecularLookUp(const Vector3D<FixPointNumber> vectorXYZ,
      const bool interpolateRefMap,
      const bool distortionCompensation,
      Vector3D<FixPointNumber> & specularIntensity);

10
      virtual void WriteTable(const char * fileName);
      virtual void ReadTable (const char * fileName);
      virtual Vector3D<double> DiffuseIntensity( const Vector3D<double> & norm);
      virtual Vector3D<double> SpecularIntensity(const Vector3D<double> & norm,

15
      const bool
      refVectorLookup);

      void ShowValues( const char * fileName, int color ); // 0-red 1-green
20 2-blue
      void ShowMapImage( const bool refVectorLookup,
      const bool
      refMapInterpolation);

      protected:
25      int      componentAddressBits;
      int      mapWeightBits;
      Vector3D<double> viewVector;
      Vector3D<double> IAmbient;
      DynaArray<Light> lightSource;
      double    specularExponent;

30
      typedef Vector3D<FixPointNumber> rgb;
      rgb*      pDiffuseIntensities;
      rgb*      pSpecularIntensities;
    );

35
#endif // _ReflectanceMap_h_
:::::::::::::
cube4/Shadel.C
:::::::::::::
// Shadel.C
40 // (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include "Shadel.h"

45
Shadel::Shadel(FixPointNumber setR, FixPointNumber setG, FixPointNumber setB,
               FixPointNumber setA)
    : r(setR),g(setG),b(setB),a(setA)
{
50

```

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```

} // constructor

5
Shadel::Shadel(const Shadel & shadel)
    : r(shadel.r),g(shadel.g),b(shadel.b),a(shadel.a)
{
} // constructor

10
// friend output function
ostream & operator << (ostream & os, const Shadel & s)
{ return os<< "("<<s.r<<","<<s.g<<","<<s.b<<","<<s.a<<")"; }
::::::::::::
15
cube4/Shadel.h
::::::::::::
// Shadel.h
// (c) Ingmar Bitter '97

20
// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#ifndef _Shadel_h_ // prevent multiple includes
#define _Shadel_h_

25
#include <iostream.h> // cout
#include "FixPointNumber.h"

class Shadel {
public: // data
30
    FixPointNumber r,g,b,a;
public: // member functions
    Shadel(FixPointNumber r=0, FixPointNumber g=0, FixPointNumber b=0,
           FixPointNumber a=0);
    Shadel(const Shadel & shadel);
35
public: // friend functions
    friend ostream & operator << (ostream & os, const Shadel & shadel);
}; // Shadel

#endif // _Shadel_h_
::::::::::::
40
cube4/ShaderPipeline.C
::::::::::::
// ShaderPipeline.C
// (c) Ingmar Bitter '97 / Urs Kanus '97

45
// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include "ShaderPipeline.h"

50
void ShaderPipeline::Demo()
{
    ShaderPipeline shader;

55

```

```

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    cout << endl << "Demo of class " << typeid(shader).name();
    cout << endl << "size : " << sizeof(ShaderPipeline) << " Bytes";
5    cout << endl << "public member functions:";
    cout << endl << "ShaderPipeline shader; = " << shader;
    cout << endl << "End of demo of class " << typeid(shader).name() << endl;
} // Demo

10 //////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
// constructors & destructors

// static first init
int ShaderPipeline::numOfChips = 0;
15 int ShaderPipeline::numOfPipelinesPerChip = 0;
Cube4 *ShaderPipeline::cube4 = 0;

ShaderPipeline::ShaderPipeline()
{
} // constructor

20 ShaderPipeline::~ShaderPipeline()
{
} // destructor

25 //////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
// show/set data & data properties

ostream & ShaderPipeline::Ostream(ostream & os) const
30 {
    // append ShaderPipeline info to os
    os << typeid(*this).name() << "@" << (void *) this;
    os << endl << "    numOfChips          = " << numOfChips;
    os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
35    os << endl << "    chipIndex            = " << chipIndex;

    // return complete os
    return os;

40 } // Ostream

////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
// show/set data & data properties
//
45 // - local show/set functions

void ShaderPipeline::GlobalSetup(const int setNumOfChips,
    const int setNumOfPipelinesPerChip)
50

```

55

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```

{
    numOfChips          = setNumOfChips;
5    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
} // GlobalSetup

void ShaderPipeline::LocalSetup(const int setChipIndex,
10    const int setPipelineIndex,
    ShaderStage & shaderStage)
{
    chipIndex = setChipIndex;
15    pipelineIndex = setPipelineIndex;

    inputs.voxel = &(shaderStage.inputs.voxel[pipelineIndex]);
    inputs.gx = &(shaderStage.inputs.gx[pipelineIndex]);
    inputs.gy = &(shaderStage.inputs.gy[pipelineIndex]);
    inputs.gz = &(shaderStage.inputs.gz[pipelineIndex]);
20    inputs.weightsXYZ = &(shaderStage.inputs.weightsXYZ[pipelineIndex]);
    inputs.perChipControlFlags
        = shaderStage.inputs.perChipControlFlags;
    inputs.perPipelineControlFlags
        = &(shaderStage.inputs.perPipelineControlFlags[pipelineIndex]);
25    results.shadel = &(shaderStage.results.shadel[pipelineIndex]);
    results.weightsXYZ = &(shaderStage.results.weightsXYZ[pipelineIndex]);
    results.perPipelineControlFlags
        = &(shaderStage.results.perPipelineControlFlags[pipelineIndex]);
    results.perChipControlFlags
30    = &(shaderStage.results.perChipControlFlags);

    cube4 = shaderStage.cube4;

    reflectanceMap = &(shaderStage.reflectanceMap);
    colorLUT = &(shaderStage.colorLUT);
35 } // LocalSetup

void ShaderPipeline::PerFrameSetup()
{
40    // reset pipeline registers already done in ShaderStage
} // PerFrameSetup

////////////////////////////////////
45 // local computation functions

void ShaderPipeline::RunForOneClockCycle()
{
    /*
    // get inputs and transform to 0 ... 1 range
50    int index      = inputs.voxel->raw16bit;

```

55

```

293
double gx      = *inputs.gx / 255.0;
double gy      = *inputs.gy / 255.0;
5 double gz      = *inputs.gz / 255.0;

// color transferfunction
double red = double((colorLUT->Red(index))/255.0);
double green = double((colorLUT->Green(index))/255.0);
10 double blue = double((colorLUT->Blue(index))/255.0);

//double gradientMagnitude = sqrt(gx*gx + gy*gy + gz*gz);
//double noiseLevel(0.05);
//double signalToNoiseGradientMagnitude =
15 //Min(1.0, gradientMagnitude / noiseLevel);

Vector3D<double> viewVector;
Vector3D<double> diffuseIntensity;
Vector3D<double> specularIntensity;

20 if (cube4->shaderMode == Phong) {

    // Phong shading, assumes lightsource and eyepoint at infinite
    distance

    //Vector3D<double> halfway;
25 Vector3D<double> lightReflection;
    Vector3D<double> surfaceNormal;
    Vector3D<double> lightVector;
    //double norm;

    surfaceNormal(-gx, -gy, -gz);
30 surfaceNormal /= surfaceNormal.Norm();

    // viewVector is inverse of sightRay
    viewVector( (double) cube4->viewPointXYZ.X() - (double) cube4-
>datasetSizeXYZ.X() / 2.0,
35 (double) cube4->viewPointXYZ.Y()
- (double) cube4->datasetSizeXYZ.Y() / 2.0,
(double) cube4->viewPointXYZ.Z() -
(double) cube4->datasetSizeXYZ.Z() / 2.0);
    viewVector /= viewVector.Norm();

40 diffuseIntensity = 0;
    specularIntensity = 0;

    for (int light=0; light<cube4->lightSourceXYZ.Size(); ++light) {

        lightVector = cube4->lightSourceXYZ[light].Direction();
45 lightVector /= lightVector.Norm();

        //halfway = lightVector + viewVector; // skip /2.0 because
normalization
        //norm = halfway.Norm();

50

55

```

```

294
//if (norm > 0)           halfway /= norm; else
halfway(0,0,0);

5      double NL = surfaceNormal * lightVector;

      lightReflection = surfaceNormal;
      lightReflection *= (2*NL);
      lightReflection = lightReflection - lightVector;

10     if (NL < 0)
        NL = 0;
    else
        NL = pow(NL, cube4->lightSourceXYZ[light].Sharpness());

15     double phongComponent;

        //double NH = surfaceNormal*halfway;
        //if (NH < 0)
        //    phongComponent = 0;
        //else
20        phongComponent = pow(NH, cube4->phongExponent);

        double RV = lightReflection * viewVector;
        if (RV < 0)
            phongComponent = 0;
25        else
            phongComponent = pow(RV, cube4->phongExponent);

        diffuseIntensity +=
            cube4->lightSourceXYZ[light].Intensity() * NL;
        specularIntensity +=
30        cube4->lightSourceXYZ[light].Intensity() *
phongComponent;
    }
    else if (cube4->shaderMode == RefMap) {

35    Vector3D<FixPointNumber> diff, spec;
    Vector3D<FixPointNumber> gradient(-(*inputs.gx),

                                    -(*inputs.gy),
40                                    -(*inputs.gz));

        reflectanceMap->DiffuseLookUp(gradient,

45        cube4->reflectanceMapIP,

        cube4->distortionCompensation,

        diff);

50

55

```



```

295
reflectanceMap->SpecularLookUp(gradient,
5      cube4->reflectanceMapIP,
      cube4->distortionCompensation,
      spec);
10      diffuseIntensity( diff.R(), diff.G(), diff.B());
      specularIntensity( spec.R(), spec.G(), spec.B());
    }
    else if (cube4->shaderMode == RefVector) {
15      Vector3D<FixPointNumber> diff, spec;
      Vector3D<FixPointNumber> gradient(-(*inputs.gx),
      -(*inputs.gy),
      -(*inputs.gz));
20      Vector3D<FixPointNumber> eyeReflection, refNormal, refView;

      // viewVector is inverse of sightRay
      Vector3D<FixPointNumber> viewVectorFixP(cube4->viewPointXYZ.X()
25      - cube4-
      >datasetSizeXYZ.X() / 2.0,
      cube4->viewPointXYZ.Y()
30      - cube4-
      >datasetSizeXYZ.Y() / 2.0,
      cube4->viewPointXYZ.Z()
35      - cube4-
      >datasetSizeXYZ.Z() / 2.0);

      FixPointNumber gradientDotProduct = gradient * gradient;
      FixPointNumber gradientViewVectorDotProduct = gradient *
40      viewVectorFixP;

      refNormal = gradient;
      refNormal *= (2 * gradientViewVectorDotProduct);
      refView = viewVectorFixP;
      refView *= gradientDotProduct;
45      eyeReflection = refNormal - refView;

      reflectanceMap->DiffuseLookUp(gradient,
50      cube4->reflectanceMapIP,
55

```

```

5         cube4->distortionCompensation,
           diff);

           reflectanceMap->SpecularLookUp(eyeReflection,
10         cube4->reflectanceMapIP,
           cube4->distortionCompensation,
           spec);

15         diffuseIntensity( diff.R(), diff.G(), diff.B());
           specularIntensity( spec.R(), spec.G(), spec.B());
           }

           // The following lines contain the functionality of a color blending unit

20         // adjust the surface illumination to the degree of which a surface
           // is present at the current sample position
           //diffuseIntensity *= signalToNoiseGradientMagnitude;
           //specularIntensity *= signalToNoiseGradientMagnitude;

           // adjust the surface illumination to the degree specified by Kd and Ks
25         diffuseIntensity *= cube4->Kd;
           specularIntensity *= cube4->Ks;

           // add ambient light (surface independent)
           diffuseIntensity += cube4->IAmbient * cube4->Ka;

30         // combine color transfer function result with illumination result
           if (cube4->shaderMode == NoShading){
               results.shadel->r = red;
               results.shadel->g = green;
               results.shadel->b = blue;
35         }
           else{
               results.shadel->r = red * diffuseIntensity.X() +
           specularIntensity.X();
               results.shadel->g = green * diffuseIntensity.Y() +
           specularIntensity.Y();
40               results.shadel->b = blue * diffuseIntensity.Z() +
           specularIntensity.Z();
           }

           // clip too large color intensities
           results.shadel->r = (Min(1, results.shadel->r));
45           results.shadel->g = (Min(1, results.shadel->g));
           results.shadel->b = (Min(1, results.shadel->b));

           // clip too small color intensities
           results.shadel->r = (Max(0, results.shadel->r));
50
55

```

```

297
results.shadel->g = (Max(0, results.shadel->g));
results.shadel->b = (Max(0, results.shadel->b));
5
// Levoy classification

//double offset = ABS(cube4->threshold - intensity);

//double currHalfWidth = cube4->maxWidth/2.0 * gradientMagnitude;
10 //double extHalfWidth = currHalfWidth + 1.0/255.0;
//double alpha = 0;
//if (offset < currHalfWidth)
//alpha = cube4->mulAlpha * (extHalfWidth - offset) / (extHalfWidth);

15 //if (alpha > 1.0)
//alpha = 1.0;
//results.shadel->a = alpha;

// assign alpha
20 results.shadel->a = double(colorLUT->Alpha(index)/255.0);

// premultiply rgb with a
results.shadel->r *= results.shadel->a;
25 results.shadel->g *= results.shadel->a;
results.shadel->b *= results.shadel->a;

if (inputs.perPipelineControlFlags->invalid) {
    results.shadel->r = 0;
    results.shadel->g = 0;
30 results.shadel->b = 0;
    results.shadel->a = 0;
}
*/
results.shadel->r = inputs.voxel->raw16bit % 32;
35 results.shadel->g = inputs.voxel->raw16bit / 32 % 32;
results.shadel->b = inputs.voxel->raw16bit / 32 / 32 % 32;
// results.shadel->a = inputs.perPipelineControlFlags->voxelPosXYZ.Z();
results.shadel->a = inputs.voxel->raw16bit;

40 } // RunForOneClockCycle

////////////////////////////////////
// internal utility functions

45
// end of ShaderPipeline.C
:::::::::::::
cube4/ShaderPipeline.h
:::::::::::::
50 // ShaderPipeline.h
// (c) Ingmar Bitter '97

55

```

```

5 // Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#ifndef _ShaderPipeline_h_ // prevent multiple includes
#define _ShaderPipeline_h_

10 #include "Misc.h"
#include "Object.h"
#include "Voxel.h"
#include "Shadel.h"
#include "Control.h"
#include "FixPointNumber.h"
15 #include "ReflectanceMap.h"
#include "ColorLUT.h"

class ShaderStage;
class Cube4;

20 class ShaderPipelineInputs {
public: // pointers
    Voxel *voxel;
    ScalarGradient *gx, *gy, *gz;
    Vector3D<FixPointNumber> *weightsXYZ;
25 PerChipControlFlags *perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

30 class ShaderPipelineResults {
public: // pointers
    Shadel *shadel;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags *perChipControlFlags;
35 PerPipelineControlFlags *perPipelineControlFlags;
};

class ShaderPipeline : virtual public Object {
40 public:

    static void Demo ();

    // constructors & destructors
    ShaderPipeline ();
45 ~ShaderPipeline ();

    // show/set data & data properties
    // - class Object requirements
    virtual ostream & Ostream (ostream & ) const;

50 // - local show/set functions
    static void GlobalSetup (const int setNumOfChips,

55

```

299

[illegible]

```

300
// static first init
int ShaderStage::numOfChips      = 0;
5 int ShaderStage::numOfPipelinesPerChip = 0;
Cube4 *ShaderStage::cube4 = 0;

ShaderStage::ShaderStage()
{
    shaderPipeline = new ShaderPipeline [numOfPipelinesPerChip];
10 results.shadel = new Shadel [numOfPipelinesPerChip];
    results.weightsXYZ = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];
    results.perPipelineControlFlags = new PerPipelineControlFlags
[numOfPipelinesPerChip];
} // default constructor

15 ShaderStage::~ShaderStage()
{
    if (shaderPipeline) { delete shaderPipeline; shaderPipeline=0; }
    if (results.shadel) { delete results.shadel; results.shadel=0; }
20 if (results.weightsXYZ) { delete results.weightsXYZ; results.weightsXYZ=0; }
    if (results.perPipelineControlFlags) {
        delete results.perPipelineControlFlags;
        results.perPipelineControlFlags=0;
    }
25 } // destructor

////////////////////////////////////
// show/set data & data properties

30 ostream & ShaderStage::Ostream(ostream & os) const
{
    // append ShaderStage info to os
    os << typeid(*this).name() << "@" << (void *) this;
    os << endl << "    numOfChips      = " << numOfChips;
35 os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
    os << endl << "    chipIndex      = " << chipIndex;

    // return complete os
    return os;

40 } // Ostream

////////////////////////////////////
// show/set data & data properties
//
45 // - local show/set functions

void ShaderStage::GlobalSetup(const int setNumOfChips,
50
55

```

```

const int setNumOfPipelinesPerChip,
5      Cube4 *setCube4)
{
    numOfChips      = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    ShaderPipeline::GlobalSetup(numOfChips, numOfPipelinesPerChip);
10    cube4 = setCube4;
} // GlobalSetup

void ShaderStage::LocalSetup(const int setChipIndex)
{
15    chipIndex = setChipIndex;
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        shaderPipeline[p].LocalSetup(chipIndex,p,*this);
    }
} // LocalSetup

20 void ShaderStage::PerFrameSetup()
{
    int p;
    // reset pipeline registers
    for (p=0; p<numOfPipelinesPerChip; ++p) {
25        results.shadel[p].r = results.shadel[p].g = results.shadel[p].b = 0;
        results.shadel[p].a = 0;
        results.weightsXYZ[p](0.0,0);
        results.perPipelineControlFlags[p].Reset();
    }
    results.perChipControlFlags.Reset();
30
    for (p=0; p<numOfPipelinesPerChip; ++p) {
        shaderPipeline[p].PerFrameSetup();
    }

35    //cout << endl << cube4->shaderMode;

    if (cube4->shaderMode == RefMap) {
        // setup parallel viewVector
        Vector3D<double> viewVector;
        viewVector( (double) cube4->viewPointXYZ.X() - (double) cube4-
40 >datasetSizeXYZ.X() / 2.0,
                                (double) cube4->viewPointXYZ.Y()
- (double) cube4->datasetSizeXYZ.Y() / 2.0,
                                (double) cube4->viewPointXYZ.Z() -
(double) cube4->datasetSizeXYZ.Z() / 2.0);
        viewVector /= viewVector.Norm();
45
        // setup reflectance map

        cout << endl << "start computing reflectance table";

```

50

55

```

5      Timer timer;
      reflectanceMap.PerFrameSetup(cube4->reflectanceMapBits,
          cube4->mapWeightBits,
          cube4->constantAngularResolution,
10         false,
          viewVector,
          cube4->lightSourceXYZ,
15         cube4->phongExponent);
      cout << endl << "done computing reflectance table " << timer <<
endl;
    }

20     else if (cube4->shaderMode == RefVector){
        // setup dummy viewVector
        Vector3D<double> viewVector(0, 0, 0);

25         // setup reflectance map
        cout << endl << "start computing reflectance table";
        Timer timer;
        reflectanceMap.PerFrameSetup(cube4->reflectanceMapBits,
30         cube4->mapWeightBits,
          cube4->constantAngularResolution,
          true,
35         viewVector,
          cube4->lightSourceXYZ,
          cube4->phongExponent);
40         cout << endl << "done computing reflectance table " << timer <<
endl;
    }

    // cout << endl << "load lookup table";
45    colorLUT.ReadTable(cube4->colorTableFileName);

    // print debug info
    //static bool first(true); if (first) { cout<<this<<endl; first=false; }
    } // PerFrameSetup

```

50

55


```

5  ////////////////////////////////////////////////////////////////////
   // local computation functions

void ShaderStage::RunForOneClockCycle()
{
    // computation
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
10         shaderPipeline[p].RunForOneClockCycle();
           results.weightsXYZ[p] = inputs.weightsXYZ[p];
           results.perPipelineControlFlags[p] =
inputs.perPipelineControlFlags[p];
    }
15     results.perChipControlFlags = *(inputs.perChipControlFlags);
} // RunForOneClockCycle

   ////////////////////////////////////////////////////////////////////
20  // internal utility functions

// end of ShaderStage.C
:::::::::::::
cube4/ShaderStage.h
25  :::::::::::::::
// ShaderStage.h
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
30  // America, Inc., 1997, All rights reserved.

#ifdef _ShaderStage_h_ // prevent multiple includes
#define _ShaderStage_h_

#include "Misc.h"
35  #include "Object.h"
#include "Voxel.h"
#include "Shadel.h"
#include "Control.h"
#include "ShaderPipeline.h"
#include "FixPointNumber.h"
40  #include "Cube4.h"
#include "ReflectanceMap.h"
#include "ColorLUT.h"

class Cube4;
45

class ShaderStageInputs {
public: // pointers
    Voxel *voxel;
    ScalarGradient *gx, *gy, *gz;
50  Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags      *perChipControlFlags;

55

```

```

                                304
    PerPipelineControlFlags      *perPipelineControlFlags;
};

5

class ShaderStageResults {
public: // arrays
    Shadel *shadel;
    Vector3D<FixPointNumber> *weightsXYZ;
10    PerChipControlFlags      perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

15
class ShaderStage : virtual public Object {
public:

    static void      Demo ();

20    // constructors & destructors
    ShaderStage ();
    ~ShaderStage ();

    // show/set data & data properties
    // - class Object requirements
25    virtual ostream & Ostream (ostream & )    const;

    // - local show/set functions
    static void GlobalSetup (const int setNumOfChips,

30    const int setNumOfPipelinesPerChip,

    Cube4 *setCube4);
    virtual void LocalSetup (const int setChipIndex);
    virtual void PerFrameSetup ();
35    // local computation functions
    virtual void RunForOneClockCycle();

public:
    ShaderPipeline *shaderPipeline;
    ShaderStageInputs inputs;
40    ShaderStageResults results;

protected:
    static int      numOfChips, numOfPipelinesPerChip;
    static Cube4 *cube4;
45    int      chipIndex; // only for debugging purpose
    ReflectanceMap reflectanceMap;
    ColorLUT colorLUT;

    friend class ShaderPipeline;
50 };

#endif // _ShaderStage_h_

```

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```

5  : : : : : : : : : :
   cube4/SliceVoxelFiFoPipeline.C
   : : : : : : : : : :
   // SliceVoxelFiFoPipeline.C
   // (c) Ingmar Bitter '97

   // Copyright, Mitsubishi Electric Information Technology Center
   // America, Inc., 1997, All rights reserved.

10  #include "SliceVoxelFiFoPipeline.h"

   void SliceVoxelFiFoPipeline::Demo()
   {
15      SliceVoxelFiFoPipeline sliceVoxelFiFo;
      cout << endl <<"Demo of class " << typeid(sliceVoxelFiFo).name();
      cout << endl <<"size : " << sizeof(SliceVoxelFiFoPipeline) << " Bytes";
      cout << endl <<"public member functions:";
      cout << endl <<"SliceVoxelFiFoPipeline sliceVoxelFiFo; = " <<
   sliceVoxelFiFo;
20      cout << endl << "End of demo of class " << typeid(sliceVoxelFiFo).name() <<
   endl;
   } // Demo

   //////////////////////////////////////
25  // constructors & destructors

   // static first init
   int SliceVoxelFiFoPipeline::numOfChips      = 0;
   int SliceVoxelFiFoPipeline::numOfPipelinesPerChip = 0;
   int SliceVoxelFiFoPipeline::blockSize      = 0;
30  int SliceVoxelFiFoPipeline::maxDatasetSizeX = 256;
   int SliceVoxelFiFoPipeline::maxDatasetSizeY = 256;
   Cube4 *SliceVoxelFiFoPipeline::cube4 = 0;

   SliceVoxelFiFoPipeline::SliceVoxelFiFoPipeline()
   {
35      // step delay for a z-step within a block
      blockSliceDelay = (maxDatasetSizeX*blockSize

                                   ) /

   (numOfChips*numOfPipelinesPerChip);

      // step delay for a z-step between blocks
40  volumeSliceDelay = (maxDatasetSizeX*maxDatasetSizeY

                                   ) /

   (numOfChips*numOfPipelinesPerChip);

      blockSliceVoxelFiFo.SetSize(blockSliceDelay);
      blockSliceWeightsFiFo.SetSize(blockSliceDelay);
45  blockSlicePerPipelineControlFlagsFiFo.SetSize(blockSliceDelay);
      blockSlicePerChipControlFlagsFiFo.SetSize(blockSliceDelay);

      volumeSliceVoxelFiFo.SetSize(volumeSliceDelay);

50

```

55

```

5         volumeSliceWeightsFiFo.SetSize(volumeSliceDelay);
        volumeSlicePerPipelineControlFlagsFiFo.SetSize(volumeSliceDelay);
        volumeSlicePerChipControlFlagsFiFo.SetSize(volumeSliceDelay);
    } // constructor

SliceVoxelFiFoPipeline::~SliceVoxelFiFoPipeline()
10 {
    } // destructor

////////////////////////////////////
15 // show/set data & data properties

ostream & SliceVoxelFiFoPipeline::Ostream(ostream & os) const
{
    // append SliceVoxelFiFoPipeline info to os
20     os << typeid(*this).name() << "@" << (void *) this;
        os << endl << "    numOfChips          = " << numOfChips;
        os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
        os << endl << "    chipIndex            = " << chipIndex;

    // return complete os
25     return os;

} // Ostream

////////////////////////////////////
30 // show/set data & data properties
//
// - local show/set functions

35 void SliceVoxelFiFoPipeline::GlobalSetup(const int setNumOfChips,
                                           const int setNumOfPipelinesPerChip,
                                           const int setBlockSize,
                                           Cube4 *setCube4)
40 {
    numOfChips          = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    blockSize           = setBlockSize;
    cube4 = setCube4;
45 } // GlobalSetup

void SliceVoxelFiFoPipeline::LocalSetup(const int setChipIndex,

```

50

55

```

const int setPipelineIndex,

5 SliceVoxelFiFoStage & sliceVoxelFiFoStage)
{
    chipIndex = setChipIndex;
    pipelineIndex = setPipelineIndex;
    sliceVoxelFiFoStageChip = sliceVoxelFiFoStage.sliceVoxelFiFoStageChip;
10 startReadWriteCounters = sliceVoxelFiFoStage.startReadWriteCounters;

    inputs.voxel = &(sliceVoxelFiFoStage.inputs.voxel[pipelineIndex]);
    inputs.weightsXYZ =
&(sliceVoxelFiFoStage.inputs.weightsXYZ[pipelineIndex]);
    inputs.perChipControlFlags
15     = sliceVoxelFiFoStage.inputs.perChipControlFlags;
    inputs.perPipelineControlFlags
    =
&(sliceVoxelFiFoStage.inputs.perPipelineControlFlags[pipelineIndex]);

20     results.voxel = &(sliceVoxelFiFoStage.results.voxel[pipelineIndex]);
    results.weightsXYZ =
&(sliceVoxelFiFoStage.results.weightsXYZ[pipelineIndex]);
    results.perPipelineControlFlags
    =
25     &(sliceVoxelFiFoStage.results.perPipelineControlFlags[pipelineIndex]);
    results.perChipControlFlags
    = &(sliceVoxelFiFoStage.results.perChipControlFlags);
} // LocalSetup

30 void SliceVoxelFiFoPipeline::PerFrameSetup()
{
    // reset pipeline registers already done in SliceVoxelFiFoStage

    // resize fifo's according to dataset size
    // step delay for a z-step within a block
35     blockSliceDelay = (cube4->datasetSizeXYZ.X()*blockSize
                        ) /
(numOfChips*numOfPipelinesPerChip);

    // step delay for a z-step between blocks
40     volumeSliceDelay = (cube4->datasetSizeXYZ.X()*cube4->datasetSizeXYZ.Y()
                        ) /
(numOfChips*numOfPipelinesPerChip);

    blockSliceVoxelFiFo.SetSize(blockSliceDelay);
45     blockSliceWeightsFiFo.SetSize(blockSliceDelay);
    blockSlicePerPipelineControlFlagsFiFo.SetSize(blockSliceDelay);
    blockSlicePerChipControlFlagsFiFo.SetSize(blockSliceDelay);

    volumeSliceVoxelFiFo.SetSize(volumeSliceDelay);
50     volumeSliceWeightsFiFo.SetSize(volumeSliceDelay);

```

```

5      volumeSlicePerPipelineControlFlagsFiFo.SetSize(volumeSliceDelay);
      volumeSlicePerChipControlFlagsFiFo.SetSize(volumeSliceDelay);

      blockSliceVoxelFiFo.Preset(*(inputs.voxel));
      blockSliceWeightsFiFo.Preset(*(inputs.weightsXYZ));
      blockSlicePerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineControlFl
10     ags));
      blockSlicePerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFlags));

      volumeSliceVoxelFiFo.Preset(*(inputs.voxel));
      volumeSliceWeightsFiFo.Preset(*(inputs.weightsXYZ));
      volumeSlicePerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineControlF
15     lags));
      volumeSlicePerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFlags));

      readBigFiFoCounter = readSmallFiFoCounter =
          writeBigFiFoCounter = writeSmallFiFoCounter = -1;
    } // PerFrameSetup

20    ////////////////////////////////////////
    // local computation functions

    void SliceVoxelFiFoPipeline::RunForOneClockCycle()
    {
25        // reset counters
        if (*startReadWriteCounters ||
            ((readBigFiFoCounter == 0) &&
             (readSmallFiFoCounter == 0) &&
             (writeBigFiFoCounter == 0) &&
             (writeSmallFiFoCounter == 0))) {
30            readBigFiFoCounter = blockSliceDelay;
            readSmallFiFoCounter = (blockSize-1) * readBigFiFoCounter;

            writeBigFiFoCounter = readBigFiFoCounter;
            writeSmallFiFoCounter = readSmallFiFoCounter;
35        }

        ////////////////////////////////////////
        // first read from FiFos into results register

40        // at start of block read from big FiFo
        if (readBigFiFoCounter > 0) {
            volumeSliceVoxelFiFo.Read(*(results.voxel));
            volumeSliceWeightsFiFo.Read(*(results.weightsXYZ));

            volumeSlicePerPipelineControlFlagsFiFo.Read(*(results.perPipelineControlFl
45            ags));

            volumeSlicePerChipControlFlagsFiFo.Read(*(results.perChipControlFlags));
            --readBigFiFoCounter;

```

50

55

```

309
    // if (this == &cube4-
>sliceVoxelFiFo1[0].sliceVoxelFiFoPipeline[0])
5      cout<<"R"<<*(results.voxel)<<volumeSliceVoxelFiFo<<endl;
    }

    // in middle and at end of block read from small FiFo
    else if (readSmallFiFoCounter > 0) {
        blockSliceVoxelFiFo.Read(*(results.voxel));
10      blockSliceWeightsFiFo.Read(*(results.weightsXYZ));

        blockSlicePerPipelineControlFlagsFiFo.Read(*(results.perPipelineControlFla
gs));

        blockSlicePerChipControlFlagsFiFo.Read(*(results.perChipControlFlags));
15      --readSmallFiFoCounter;
        // if (this == &cube4->sliceVoxelFiFo0[0].sliceVoxelFiFoPipeline[0])
        cout<<"r";
    }

20      //////////////////////////////////////
    // now write to FiFos from inputs register

    // at start and in middle of block write to small FiFo
    if (writeSmallFiFoCounter > 0) {
        blockSliceVoxelFiFo.Write( *(inputs.voxel) );
25      blockSliceWeightsFiFo.Write(*(inputs.weightsXYZ) );

        blockSlicePerPipelineControlFlagsFiFo.Write(*(inputs.perPipelineControlFla
gs));

        blockSlicePerChipControlFlagsFiFo.Write(
30      *(inputs.perChipControlFlags));
        --writeSmallFiFoCounter;
        // if (this == &cube4->sliceVoxelFiFo0[0].sliceVoxelFiFoPipeline[0])
        cout<<"w";
    }

35      // at end of block write to big FiFo of next chip
    else if (writeBigFiFoCounter > 0) {
        ModInt c(chipIndex+1, numOfChips);
        int p(pipelineIndex);
        SliceVoxelFiFoPipeline
            *next(&sliceVoxelFiFoStageChip[c].sliceVoxelFiFoPipeline[p]);
40      next->volumeSliceVoxelFiFo.Write(*(inputs.voxel) );
        next->volumeSliceWeightsFiFo.Write(*(inputs.weightsXYZ) );
        next-
>volumeSlicePerPipelineControlFlagsFiFo.Write(*(inputs.perPipelineControlFlags))
;
        next-
45 >volumeSlicePerChipControlFlagsFiFo.Write(*(inputs.perChipControlFlags));
        --writeBigFiFoCounter;
        //if (this == &cube4->sliceVoxelFiFo1[0].sliceVoxelFiFoPipeline[0])
        cout<<"W";

```

50

55

```

    }

5   } // RunForOneClockCycle

////////////////////////////////////
// internal utility functions

10

// end of SliceVoxelFiFoPipeline.C
::::::::::::
cube4/SliceVoxelFiFoPipeline.h
::::::::::::
15 // SliceVoxelFiFoPipeline.h
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

20 #ifndef _SliceVoxelFiFoPipeline_h_ // prevent multiple includes
#define _SliceVoxelFiFoPipeline_h_

#include "Misc.h"
#include "Object.h"
25 #include "FiFo.h"
#include "Voxel.h"
#include "Coxel.h"
#include "Control.h"
#include "FixPointNumber.h"

30

typedef Vector3D<FixPointNumber> FixPointVector3D;

class SliceVoxelFiFoStage;
class Cube4;

35

class SliceVoxelFiFoPipelineInputs {
public: // pointers
    Voxel *voxel;
    Vector3D<FixPointNumber> *weightsXYZ;
40     PerChipControlFlags *perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

45

class SliceVoxelFiFoPipelineResults {
public: // pointers
    Voxel *voxel;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags *perChipControlFlags;
50     PerPipelineControlFlags *perPipelineControlFlags;
};

55

```



```

class SliceVoxelFiFoPipeline : virtual public Object {
5 public:

    static void      Demo ();

    // constructors & destructors
    SliceVoxelFiFoPipeline ();
10 ~SliceVoxelFiFoPipeline ();

    // show/set data & data properties
    // - class Object requirements
    virtual ostream & Ostream (ostream & ) const;
15

    // - local show/set functions
    static void GlobalSetup (const int setNumOfChips,

        const int setNumOfPipelinesPerChip,
20 const int setBlockSize,

        Cube4 *setCube4);

    virtual void LocalSetup(const int setChipIndex,
25 const int setPipelineIndex,

        SliceVoxelFiFoStage & sliceVoxelFiFoStage);
    virtual void PerFrameSetup();
30 // local computation functions
    virtual void RunForOneClockCycle();

public:
    SliceVoxelFiFoPipelineInputs inputs;
35 SliceVoxelFiFoPipelineResults results;

protected:
    bool *startReadWriteCounters;
    FiFo<Voxel>          blockSliceVoxelFiFo;
    FiFo<FixPointVector3D> blockSliceWeightsFiFo;
40 FiFo<PerPipelineControlFlags> blockSlicePerPipelineControlFlagsFiFo;
    FiFo<PerChipControlFlags> blockSlicePerChipControlFlagsFiFo;

    FiFo<Voxel>          volumeSliceVoxelFiFo;
    FiFo<FixPointVector3D> volumeSliceWeightsFiFo;
45 FiFo<PerPipelineControlFlags> volumeSlicePerPipelineControlFlagsFiFo;
    FiFo<PerChipControlFlags> volumeSlicePerChipControlFlagsFiFo;

    int blockSliceDelay, volumeSliceDelay;

50 int  readSmallFiFoCounter, readBigFiFoCounter;
    int writeSmallFiFoCounter, writeBigFiFoCounter;
55

```

```

312
    SliceVoxelFiFoStage    *sliceVoxelFiFoStageChip; // to access
neighbor chips
5      static int    numOfChips, numOfPipelinesPerChip, blockSize;
      static int    maxDatasetSizeX, maxDatasetSizeY;
      static Cube4 *cube4;
      int           chipIndex, pipelineIndex;

      friend class Cube4;
10  }; // class SliceVoxelFiFoPipeline

#include "SliceVoxelFiFoStage.h"
#include "Cube4.h"

#ifdef    // _SliceVoxelFiFoPipeline_h_
15  :::::::::::::::
cube4/SliceVoxelFiFoStage.C
:::::::::::::
// SliceVoxelFiFoStage.C
// (c) Ingmar Bitter '97

20  // Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include "SliceVoxelFiFoStage.h"

void SliceVoxelFiFoStage::Demo()
25  {
    SliceVoxelFiFoStage sliceVoxelFiFo;
    cout << endl << "Demo of class " << typeid(sliceVoxelFiFo).name();
    cout << endl << "size : " << sizeof(SliceVoxelFiFoStage) << " Bytes";
    cout << endl << "public member functions:";
    cout << endl << "SliceVoxelFiFoStage sliceVoxelFiFo; = " << sliceVoxelFiFo;
30  cout << endl << "End of demo of class " << typeid(sliceVoxelFiFo).name() <<
endl;
} // Demo

////////////////////////////////////
35  // constructors & destructors

// static first init
int SliceVoxelFiFoStage::numOfChips          = 0;
int SliceVoxelFiFoStage::numOfPipelinesPerChip = 0;
int SliceVoxelFiFoStage::blockSize           = 0;
40  Cube4 *SliceVoxelFiFoStage::cube4 = 0;

SliceVoxelFiFoStage::SliceVoxelFiFoStage()
{
    sliceVoxelFiFoPipeline = new SliceVoxelFiFoPipeline
45  [numOfPipelinesPerChip];
    results.voxel = new Voxel [numOfPipelinesPerChip];
    results.weightsXYZ = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];

50

55

```

```

313
    results.perPipelineControlFlags = new PerPipelineControlFlags
[numOfPipelinesPerChip];
5   } // defaultconstructor

SliceVoxelFiFoStage::~SliceVoxelFiFoStage()
{
    if (sliceVoxelFiFoPipeline) { delete sliceVoxelFiFoPipeline;
10 sliceVoxelFiFoPipeline=0; }
    if (results.voxel) { delete results.voxel; results.voxel=0; }
    if (results.weightsXYZ) { delete results.weightsXYZ; results.weightsXYZ=0;
    }
    if (results.perPipelineControlFlags) {
        delete results.perPipelineControlFlags;
15     results.perPipelineControlFlags=0;
    }
} // destructor

20 ///////////////////////////////////////////////////////////////////
// show/set data & data properties

ostream & SliceVoxelFiFoStage::Ostream(ostream & os) const
{
    // append SliceVoxelFiFoStage info to os
25   os << typeid(*this).name() << "@" << (void *) this;
    os << endl << "    numOfChips          = " << numOfChips;
    os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
    os << endl << "    chipIndex            = " << chipIndex;

30   // return complete os
    return os;
} // Ostream

35 ///////////////////////////////////////////////////////////////////
// show/set data & data properties
//
// - local show/set functions

40 void SliceVoxelFiFoStage::GlobalSetup(const int setNumOfChips,
                                        const int setNumOfPipelinesPerChip,
                                        const int setBlockSize,
45   Cube4 *setCube4)
{
    numOfChips          = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
50
55

```

```

                                314
        blockSize              =      setBlockSize;
        cube4 = setCube4;
5      SliceVoxelFiFoPipeline::GlobalSetup(numOfChips, numOfPipelinesPerChip,

                                blockSize, cube4);

    } // GlobalSetup

10     void SliceVoxelFiFoStage::LocalSetup(const int setChipIndex,

        SliceVoxelFiFoStage *setSliceVoxelFiFoStageChip)
    {
        chipIndex = setChipIndex;
        sliceVoxelFiFoStageChip = setSliceVoxelFiFoStageChip;
15     for (int p=0; p<numOfPipelinesPerChip; ++p) {
            sliceVoxelFiFoPipeline[p].LocalSetup(chipIndex,p,*this);
        }
    } // LocalSetup

20     void SliceVoxelFiFoStage::PerFrameSetup()
    {
        int p;
        // reset pipeline registers
        for (p=0; p<numOfPipelinesPerChip; ++p) {
25         results.voxel[p].raw16bit = 0;
            results.weightsXYZ[p](0,0,0);
            results.perPipelineControlFlags[p].Reset();
        }
        results.perChipControlFlags.Reset();

30     for (p=0; p<numOfPipelinesPerChip; ++p) {
            sliceVoxelFiFoPipeline[p].PerFrameSetup();
        }

        // print debug info
35     //static bool first(true); if (first) { cout<<this<<endl; first=false; }
    } // PerFrameSetup

    //////////////////////////////////////
40    // local computation functions

    void SliceVoxelFiFoStage::RunForOneClockCycle()
    {
        // computation
        for (int p=0; p<numOfPipelinesPerChip; ++p) {
45         sliceVoxelFiFoPipeline[p].RunForOneClockCycle();
        }
    } // RunForOneClockCycle

    //////////////////////////////////////
50

```

55

315

```

5 // internal utility functions

// end of SliceVoxelFiFoStage.C
:~::~:~::~:~::~:~::~:~::~:
cube4/Test.C
:~::~:~::~:~::~:~::~:~::~:
10 // Test.C
// (c) Ingmar Bitter '96

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

15 #include "Test.h"

void Test::Run(int argc, char *argv[])
{
20     Cube4 cube4(argc,argv);
    cube4.RenderAnimation();
} // Run

// end of Test.C
:~::~:~::~:~::~:~::~:~::~:
25 cube4/SliceVoxelFiFoStage.h
:~::~:~::~:~::~:~::~:~::~:
// SliceVoxelFiFoStage.h
// (c) Ingmar Bitter '97

30 // Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#ifdef _SliceVoxelFiFoStage_h_ // prevent multiple includes
#define _SliceVoxelFiFoStage_h_

35 #include "Misc.h"
#include "Object.h"
#include "Voxel.h"
#include "Control.h"
40 #include "SliceVoxelFiFoPipeline.h"
#include "FixPointNumber.h"
#include "Cube4.h"

class Cube4;

45 class SliceVoxelFiFoStageInputs {
public: // pointers
    Voxel *voxel;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags *perChipControlFlags;
50     PerPipelineControlFlags *perPipelineControlFlags;
};

55

```

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```

class SliceVoxelFiFoStageResults {
public: // arrays
    Voxel *voxel;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags      perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

class SliceVoxelFiFoStage : virtual public Object {
public:

    static void      Demo ();

    // constructors & destructors
    SliceVoxelFiFoStage ();
    ~SliceVoxelFiFoStage ();

    // show/set data & data properties
    // - class Object requirements
    virtual ostream & Ostream (ostream & )    const;

    // - local show/set functions
    static void GlobalSetup (const int setNumOfChips,
        const int setNumOfPipelinesPerChip,
        const int setBlockSize,
        Cube4 *setCube4);
    virtual void LocalSetup (const int setChipIndex,
        SliceVoxelFiFoStage *setSliceVoxelFiFoStageArray);
    virtual void PerFrameSetup ();
    // local computation functions
    virtual void RunForOneClockCycle();

public:
    SliceVoxelFiFoPipeline *sliceVoxelFiFoPipeline;
    SliceVoxelFiFoStageInputs inputs;
    SliceVoxelFiFoStageResults results;
    bool *startReadWriteCounters;

protected:
    SliceVoxelFiFoStage *sliceVoxelFiFoStageChip; // to access neighbor chips
    static int      numOfChips, numOfPipelinesPerChip, blockSize;
    static Cube4 *cube4;
    int      chipIndex; // only for debugging purpose

    friend class Cube4;
    friend class SliceVoxelFiFoPipeline;
};

```

55

```

5      // Delay for communication: 16 bits, 4 bits / cycle, double frequency => 2
cycles
      int communicationDelay = 2;

      partialBeamVoxelFiFo.SetSize(partialBeamDelay);
      partialBeamWeightsFiFo.SetSize(partialBeamDelay);
      partialBeamPerPipelineControlFlagsFiFo.SetSize(partialBeamDelay);
10     partialBeamPerChipControlFlagsFiFo.SetSize(partialBeamDelay);

      communicationDelayVoxelFiFo.SetSize(communicationDelay);
      communicationDelayWeightsFiFo.SetSize(communicationDelay);
      communicationDelayPerPipelineControlFlagsFiFo.SetSize(communicationDelay);
      communicationDelayPerChipControlFlagsFiFo.SetSize(communicationDelay);
15  } // constructor

TriLinXPipeline::~TriLinXPipeline()
{
20  } // destructor

////////////////////////////////////
// show/set data & data properties

25  ostream & TriLinXPipeline::Ostream(ostream & os) const
{
    // append TriLinXPipeline info to os
    os << typeid(*this).name() << "@" << (void *) this;
    os << endl << "    numOfChips          = " << numOfChips;
30    os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
    os << endl << "    chipIndex            = " << chipIndex;

    // return complete os
    return os;
35  } // Ostream

////////////////////////////////////
// show/set data & data properties
//
40  // - local show/set functions

void TriLinXPipeline::GlobalSetup(const int setNumOfChips,
                                  const int setNumOfPipelinesPerChip,
                                  const int setBlockSize)
{
    numOfChips          = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
    blockSize           = setBlockSize;
50

```

55

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```

    } // GlobalSetup

5   void TriLinXPipeline::LocalSetup(const int setChipIndex,
                                   const int setPipelineIndex,
                                   TriLinXStage & triLinXStage)
    {
10      chipIndex = setChipIndex;
      pipelineIndex = setPipelineIndex;

      inputs.voxelA = &(triLinXStage.computation.voxel[pipelineIndex]);
      inputs.voxelB = &(triLinXStage.computation.voxel[pipelineIndex+1]);
      inputs.weightsXYZ = &(triLinXStage.computation.weightsXYZ[pipelineIndex]);
      inputs.perChipControlFlags
15      = &(triLinXStage.computation.perChipControlFlags);
      inputs.perPipelineControlFlags
      = &(triLinXStage.computation.perPipelineControlFlags[pipelineIndex]);

      results.voxel = &(triLinXStage.results.voxel[pipelineIndex]);
      results.weightsXYZ = &(triLinXStage.results.weightsXYZ[pipelineIndex]);
20      results.perPipelineControlFlags
      = &(triLinXStage.results.perPipelineControlFlags[pipelineIndex]);
      results.perChipControlFlags
      = &(triLinXStage.results.perChipControlFlags);

      cube4 = triLinXStage.cube4;
25  } // LocalSetup

void TriLinXPipeline::PerFrameSetup()
{
30  // reset pipeline registers already done in TriLinXStage
      partialBeamVoxelFiFo.Preset(*(inputs.voxelA));
      partialBeamWeightsFiFo.Preset(*(inputs.weightsXYZ));
      partialBeamPerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineControlF
lags));
      partialBeamPerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFlags));
35
      communicationDelayVoxelFiFo.Preset(*(inputs.voxelA));
      communicationDelayWeightsFiFo.Preset(*(inputs.weightsXYZ));
      communicationDelayPerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineC
ontrolFlags));
      communicationDelayPerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFl
ags));
40  } // PerFrameSetup

////////////////////////////////////
// local computation functions
45

void TriLinXPipeline::RunForOneClockCycle()
{
    // Linear interpolation
50
55

```

320

```

// c = w(b-a)+a
//
5 // w=0 -> c=a
// w=1 -> c=b

if (cube4->cubeMode == Cube4Light) {
// just pick current voxel (as if w=0)
10 results.voxel->raw16bit = inputs.voxelA->raw16bit; // w=0;
// use weights later on in composing
}

else if (cube4->cubeMode == Cube4Classic) {
// do real interpolation
15 a((int)inputs.voxelA->raw16bit);
b((int)inputs.voxelB->raw16bit);
results.voxel->raw16bit = (short)(inputs.weightsXYZ->X()*(b-a) + a);
// assign control bits to weights to flow down the rest of the
// pipeline as weights
20 /*(results.weightsXYZ) = *(inputs.weightsXYZ);
//results.weightsXYZ->SetX(-1 * StepDirection[inputs.perChipControlFlags-
>xStep]);
}
} // RunForOneClockCycle

25

////////////////////////////////////
// internal utility functions

30 // end of TriLinXPipeline.C
::::::::::::
cube4/TriLinXPipeline.h
::::::::::::
// TriLinXPipeline.h
35 // (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#ifdef _TriLinXPipeline_h_ // prevent multiple includes
40 #define _TriLinXPipeline_h_

#include "Misc.h"
#include "Object.h"
#include "Voxel.h"
#include "FiFo.h"
45 #include "Coxel.h"
#include "Control.h"
#include "FixPointNumber.h"

typedef Vector3D<FixPointNumber> FixPointVector3D;

50

55

```

```

class TriLinXStage;
class Cube4;

5
class TriLinXPipelineInputs {
public: // pointers
    Voxel *voxelA;
    Voxel *voxelB;
10    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags      *perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

15
class TriLinXPipelineResults {
public: // pointers
    Voxel *voxel;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags      *perChipControlFlags;
20    PerPipelineControlFlags *perPipelineControlFlags;
};

class TriLinXPipeline : virtual public Object {
25 public:

    static void      Demo ();

    // constructors & destructors
30    TriLinXPipeline ();
    ~TriLinXPipeline ();

    // show/set data & data properties
    // - class Object requirements
35    virtual ostream & Ostream (ostream & ) const;

    // - local show/set functions
    static void GlobalSetup (const int setNumOfChips,
                             const int setNumOfPipelinesPerChip,
40                             const int setBlockSize);

    virtual void LocalSetup(const int setChipIndex,
                             const int setPipelineIndex,
                             TriLinXStage & triLinXStage);
    virtual void PerFrameSetup();
45    // local computation functions
    virtual void RunForOneClockCycle();

public:
    TriLinXPipelineInputs inputs;
50    TriLinXPipelineResults results;

protected:
    FixPointNumber          a, b;

55

```

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```

    FiFo<Voxel>                                partialBeamVoxelFiFo;
    FiFo<FixPointVector3D>                      partialBeamWeightsFiFo;
5    FiFo<PerPipelineControlFlags>              partialBeamPerPipelineControlFlagsFiFo;
    FiFo<PerChipControlFlags>                  partialBeamPerChipControlFlagsFiFo;

    FiFo<Voxel>                                communicationDelayVoxelFiFo;
    FiFo<FixPointVector3D>                      communicationDelayWeightsFiFo;
10   FiFo<PerPipelineControlFlags>              communicationDelayPerPipelineControlFlagsFiFo;
    FiFo<PerChipControlFlags>                  communicationDelayPerChipControlFlagsFiFo;

    static int    numOfChips, numOfPipelinesPerChip, blockSize;
    static Cube4 *cube4;
    int          chipIndex, pipelineIndex;

15   friend class TriLinXStage;
    friend class Cube4;
};

#include "TriLinXStage.h"
#include "Cube4.h"

20   #endif          // _TriLinXPipeline_h_
    : : : : : : : : : :
    cube4/TriLinXStage.C
    : : : : : : : : : :
    // TriLinXStage.C
25   // (c) Ingmar Bitter '97

    // Copyright, Mitsubishi Electric Information Technology Center
    // America, Inc., 1997, All rights reserved.

30   #include "TriLinXStage.h"

void TriLinXStage::Demo()
{
    TriLinXStage triLinX;
    cout << endl << "Demo of class " << typeid(triLinX).name();
35   cout << endl << "size : " << sizeof(TriLinXStage) << " Bytes";
    cout << endl << "public member functions:";
    cout << endl << "TriLinXStage triLinX; = " << triLinX;
    cout << endl << "End of demo of class " << typeid(triLinX).name() << endl;
} // Demo

40   ////////////////////////////////////////
    // constructors & destructors

    // static first init
    int TriLinXStage::numOfChips          = 0;
45   int TriLinXStage::numOfPipelinesPerChip = 0;
    Cube4 *TriLinXStage::cube4 = 0;

    TriLinXStage::TriLinXStage()

```

50

55

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```

{
    triLinXPipeline = new TriLinXPipeline [numOfPipelinesPerChip];
5
    computation.voxel = new Voxel [numOfPipelinesPerChip+1];
    computation.weightsXYZ = new Vector3D<FixPointNumber>
[numOfPipelinesPerChip];
    computation.perPipelineControlFlags = new PerPipelineControlFlags
[numOfPipelinesPerChip+1]; // +1 just for debugging
10
    results.voxel = new Voxel [numOfPipelinesPerChip];
    results.weightsXYZ = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];
    results.perPipelineControlFlags = new PerPipelineControlFlags
[numOfPipelinesPerChip];
    } // defaultconstructor
15

TriLinXStage::~TriLinXStage()
{
    if (triLinXPipeline) { delete triLinXPipeline; triLinXPipeline=0; }

20
    if (computation.voxel) { delete computation.voxel; computation.voxel=0; }
    if (computation.weightsXYZ) { delete computation.weightsXYZ;
computation.weightsXYZ=0; }
    if (computation.perPipelineControlFlags) {
        delete computation.perPipelineControlFlags;
25
        computation.perPipelineControlFlags=0;
    }

    if (results.voxel) { delete results.voxel; results.voxel=0; }
    if (results.weightsXYZ) { delete results.weightsXYZ; results.weightsXYZ=0;
    }

30
    if (results.perPipelineControlFlags) {
        delete results.perPipelineControlFlags;
        results.perPipelineControlFlags=0;
    }
    } // destructor

35
    //////////////////////////////////////
    // show/set data & data properties

    ostream & TriLinXStage::Ostream(ostream & os) const
40
    {
        // append TriLinXStage info to os
        os << typeid(*this).name() << "@" << (void *) this;
        os <<endl<< "    numOfChips          = " << numOfChips;
        os <<endl<< "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
        os <<endl<< "    chipIndex            = " << chipIndex;
45

        // return complete os
        return os;

50

55

```

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```

    } // Ostream

5  //////////////////////////////////////////////////
    // show/set data & data properties
    //
    // - local show/set functions

10 void TriLinXStage::GlobalSetup(const int setNumOfChips,

        const int setNumOfPipelinesPerChip,

15        Cube4 *setCube4)
    {
        numOfChips          = setNumOfChips;
        numOfPipelinesPerChip = setNumOfPipelinesPerChip;
        cube4                = setCube4;
20    TriLinXPipeline::GlobalSetup(numOfChips, numOfPipelinesPerChip, cube4-
>blockSize);
    } // GlobalSetup

    void TriLinXStage::LocalSetup(const int setChipIndex)
25    {
        chipIndex(setChipIndex, numOfChips);
        for (int p=0; p<numOfPipelinesPerChip; ++p) {
            triLinXPipeline[p].LocalSetup(chipIndex, p, *this);
        }
30    } // LocalSetup

    void TriLinXStage::PerFrameSetup()
    {
35        int p;
        // reset pipeline registers
        readBufferVoxel.raw16bit = 0;
        communicationVoxel.raw16bit = 0;
        for (p=0; p<numOfPipelinesPerChip; ++p) {
40            computation.voxel[p].raw16bit = 0;
            computation.weightsXYZ[p](0,0,0);
            computation.perPipelineControlFlags[p].Reset();
        }
        computation.voxel[numOfPipelinesPerChip].raw16bit = 0;

45        for (p=0; p<numOfPipelinesPerChip; ++p) {
            results.voxel[p].raw16bit = 0;
            results.weightsXYZ[p](0,0,0);
            results.perPipelineControlFlags[p].Reset();
        }
        results.perChipControlFlags.Reset();
50        for (p=0; p<numOfPipelinesPerChip; ++p) {

55

```

```

    triLinXPipeline[p].PerFrameSetup();
}

// print debug info
//static bool first(true); if (first) { cout<<this<<endl; first=false; }
} // PerFrameSetup

// local computation functions

void TriLinXStage::CommunicateForOneClockCycle()
{
    // fill communication register

    // only sent data at beginning of a block
    if (inputs.perChipControlFlags->xBlockStart) {

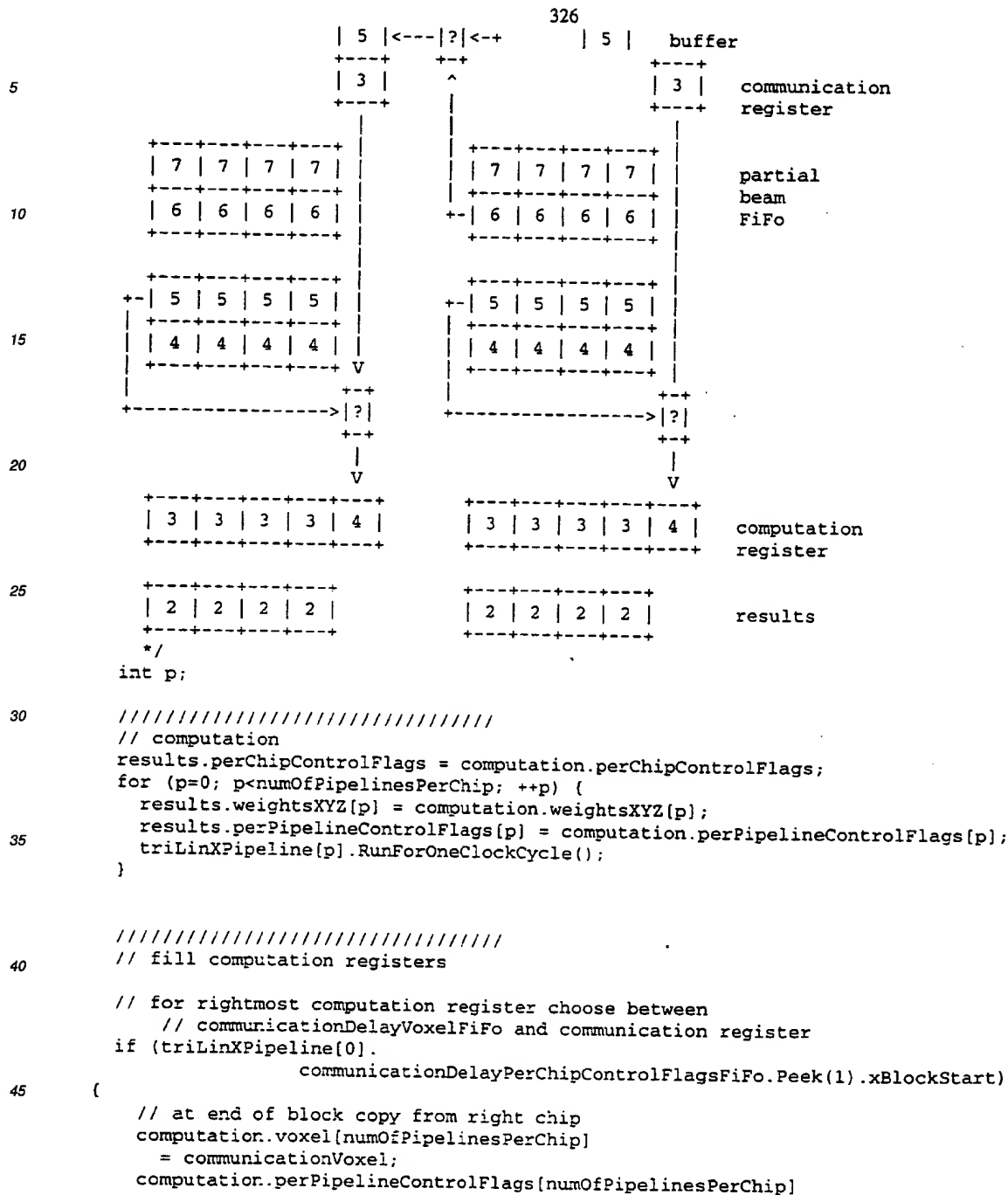
        // write readbuffer to communication register
        cube4->triLinX[chipIndex-1].communicationVoxel =
            cube4->triLinX[chipIndex-1].readBufferVoxel;
        cube4->triLinX[chipIndex-1].communicationPerPipelineControlFlags =
            cube4->triLinX[chipIndex-1].readBufferPerPipelineControlFlags;

        // leftmost chip sends data as early as possible
        if (inputs.perChipControlFlags->leftmostChip) {
            cube4->triLinX[chipIndex-1].readBufferVoxel =
                inputs.voxel[0];
            cube4->triLinX[chipIndex-1].readBufferPerPipelineControlFlags =
                inputs.perPipelineControlFlags[0];
        }
        // remaining chips send (blockSize/numOfPipelinesPerChip) later
        else {
            cube4->triLinX[chipIndex-1].readBufferVoxel =
                triLinXPipeline[0].partialBeamVoxelFiFo.Peek(0);
            cube4->triLinX[chipIndex-1].readBufferPerPipelineControlFlags =
                triLinXPipeline[0].partialBeamPerPipelineControlFlagsFiFo.Peek(0);
        }
    }
}

} // CommunicateForOneClockCycle

void TriLinXStage::RunForOneClockCycle()
{
    /*
    +-----+-----+
    | 8 | 8 | 8 | 8 |      +-----+-----+      inputs
    +-----+-----+      +-----+-----+
                                |
                                +-----+-----+      read
    +-----+ +--+
    */

```




```

327
    = communicationPerPipelineControlFlags;
}
5 else (
    // within block copy from leftmost pipeline
    computation.voxel[numOfPipelinesPerChip]
    = triLinXPipeline[0].communicationDelayVoxelFifo.Peek(1);
    computation.perPipelineControlFlags[numOfPipelinesPerChip]
    =
10 triLinXPipeline[0].communicationDelayPerPipelineControlFlagsFifo.Peek(1);
}

// always copy communicationDelayFifo to remaining computation registers
for (p=0; p<numOfPipelinesPerChip; ++p) {
15     computation.voxel[p]
        = triLinXPipeline[p].communicationDelayVoxelFifo.Read();
    computation.weightsXYZ[p]
        = triLinXPipeline[p].communicationDelayWeightsFifo.Read();
    computation.perPipelineControlFlags[p]
        =
20 triLinXPipeline[p].communicationDelayPerPipelineControlFlagsFifo.Read();
}

    computation.perChipControlFlags
    =
    triLinXPipeline[0].communicationDelayPerChipControlFlagsFifo.Read();

25 ///////////////////////////////////////////////////
// Write to communication delay Fifo
for (p=0; p<numOfPipelinesPerChip; ++p) {
    triLinXPipeline[p].communicationDelayVoxelFifo.Write
        (triLinXPipeline[p].partialBeamVoxelFifo.Read());
    triLinXPipeline[p].communicationDelayWeightsFifo.Write
30     (triLinXPipeline[p].partialBeamWeightsFifo.Read());
    triLinXPipeline[p].communicationDelayPerPipelineControlFlagsFifo.Write
        (triLinXPipeline[p].partialBeamPerPipelineControlFlagsFifo.Read());
}

    triLinXPipeline[0].communicationDelayPerChipControlFlagsFifo.Write
        (triLinXPipeline[0].partialBeamPerChipControlFlagsFifo.Read());

35 ///////////////////////////////////////////////////
// Write to partial beam Fifo
for (p=0; p<numOfPipelinesPerChip; ++p) {
    triLinXPipeline[p].partialBeamVoxelFifo.Write
        (inputs.voxel[p]);
40     triLinXPipeline[p].partialBeamWeightsFifo.Write
        (inputs.weightsXYZ[p]);
    triLinXPipeline[p].partialBeamPerPipelineControlFlagsFifo.Write
        (inputs.perPipelineControlFlags[p]);
}

    triLinXPipeline[0].partialBeamPerChipControlFlagsFifo.Write
45     (*inputs.perChipControlFlags);
} // RunForOneClockCycle

```


329

```

// constructors & destructors
TriLinXStage ();
5 ~TriLinXStage ();

// show/set data & data properties
// - class Object requirements
virtual ostream & Ostream (ostream & ) const;

10 // - local show/set functions
static void GlobalSetup (const int setNumOfChips,
                        const int setNumOfPipelinesPerChip,
                        Cube4 *setCube4);
virtual void LocalSetup (const int setChipIndex);
15 virtual void PerFrameSetup ();
// local computation functions
virtual void CommunicateForOneClockCycle();
virtual void RunForOneClockCycle();

20 public:
TriLinXPipeline *triLinXPipeline;
TriLinXStageInputs inputs;
TriLinXStageResults computation;
TriLinXStageResults results;

25 protected:
static int numOfChips, numOfPipelinesPerChip;
static Cube4 *cube4;
ModInt chipIndex;
Voxel readBufferVoxel;
30 PerPipelineControlFlags readBufferPerPipelineControlFlags; // only for
debugging
Voxel communicationVoxel;
PerPipelineControlFlags communicationPerPipelineControlFlags; // only for
debugging

35 friend class TriLinXPipeline;
friend class Cube4;
};

#endif // _TriLinXStage_h_
40 :::::::::::::::
cube4/TriLinYPipeline.C
:::::::::::::
// TriLinYPipeline.C
// (c) Ingmar Bitter '97

45 // Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include "TriLinYPipeline.h"

50 void TriLinYPipeline::Demo()
{

```

55

330

```

TriLinYPipeline triLinY;
cout << endl << "Demo of class " << typeid(triLinY).name();
5  cout << endl << "size : " << sizeof(TriLinYPipeline) << " Bytes";
    cout << endl << "public member functions:";
    cout << endl << "TriLinYPipeline triLinY; = " << triLinY;
    cout << endl << "End of demo of class " << typeid(triLinY).name() << endl;
} // Demo

10  //////////////////////////////////////
    // constructors & destructors

    // static first init
int TriLinYPipeline::numOfChips          = 0;
15  int TriLinYPipeline::numOfPipelinesPerChip = 0;
    int TriLinYPipeline::blockSize        = 0;
    int TriLinYPipeline::maxDatasetSizeX  = 256;
    Cube4 *TriLinYPipeline::cube4        = 0;

20  TriLinYPipeline::TriLinYPipeline()
    {
        // step delay for a y-step within a block
        int beamDelay = (maxDatasetSizeX

                                ) /
        (numOfChips*numOfPipelinesPerChip);

25  // step delay for a y-step between blocks
    int blockBeamDelay = beamDelay * blockSize;

    beamVoxelFiFo.SetSize(beamDelay);
    beamWeightsFiFo.SetSize(beamDelay);
30  beamPerPipelineControlFlagsFiFo.SetSize(beamDelay);
    beamPerChipControlFlagsFiFo.SetSize(beamDelay);

    blockBeamVoxelFiFo.SetSize(blockBeamDelay);
    blockBeamWeightsFiFo.SetSize(blockBeamDelay);
    blockBeamPerPipelineControlFlagsFiFo.SetSize(blockBeamDelay);
35  blockBeamPerChipControlFlagsFiFo.SetSize(blockBeamDelay);
} // constructor

TriLinYPipeline::~TriLinYPipeline()
{
40  } // destructor

    //////////////////////////////////////
    // show/set data & data properties

45  ostream & TriLinYPipeline::Ostream(ostream & os) const
    {
        // append TriLinYPipeline info to os

50
55

```

```

331
os << typeid(*this).name() << "@" << (void *) this;
os <<endl<< "  numOfChips          = " << numOfChips;
5  os <<endl<< "  numOfPipelinesPerChip = " << numOfPipelinesPerChip;
os <<endl<< "  chipIndex          = " << chipIndex;

// return complete os
return os;

10 } // Ostream

////////////////////////////////////
// show/set data & data properties
//
15 // - local show/set functions

void TriLinYPipeline::GlobalSetup(const int setNumOfChips,
20 const int setNumOfPipelinesPerChip,
const int setBlockSize)
{
numOfChips          = setNumOfChips;
numOfPipelinesPerChip = setNumOfPipelinesPerChip;
25 blockSize        = setBlockSize;
} // GlobalSetup

void TriLinYPipeline::LocalSetup(const int setChipIndex,
30 const int setPipelineIndex,
TriLinYStage & triLinYStage)
{
chipIndex = setChipIndex;
35 pipelineIndex = setPipelineIndex;

inputs.voxel = &(triLinYStage.inputs.voxel[pipelineIndex]);
inputs.weightsXYZ = &(triLinYStage.inputs.weightsXYZ[pipelineIndex]);
inputs.perChipControlFlags
= triLinYStage.inputs.perChipControlFlags;
40 inputs.perPipelineControlFlags
= &(triLinYStage.inputs.perPipelineControlFlags[pipelineIndex]);

results.voxel = &(triLinYStage.results.voxel[pipelineIndex]);
results.weightsXYZ = &(triLinYStage.results.weightsXYZ[pipelineIndex]);
45 results.perPipelineControlFlags
= &(triLinYStage.results.perPipelineControlFlags[pipelineIndex]);
results.perChipControlFlags
= &(triLinYStage.results.perChipControlFlags);

50 cube4 = triLinYStage.cube4;

55

```

332

} // LocalSetup

```

5 void TriLinYPipeline::PerFrameSetup()
{
    // reset pipeline registers already done in TriLinYStage

    //////////////////////////////////////
10 // resize fifo's according to dataset size

    // step delay for a y-step within a block
    beamDelay = (cube4->datasetSizeXYZ.X()

                                ) /
15 (numOfChips*numOfPipelinesPerChip);

    // step delay for a y-step between blocks
    blockBeamDelay = beamDelay * blockSize;

    beamVoxelFiFo.SetSize(beamDelay);
    beamWeightsFiFo.SetSize(beamDelay);
20 beamPerPipelineControlFlagsFiFo.SetSize(beamDelay);
    beamPerChipControlFlagsFiFo.SetSize(beamDelay);

    blockBeamVoxelFiFo.SetSize(blockBeamDelay);
    blockBeamWeightsFiFo.SetSize(blockBeamDelay);
25 blockBeamPerPipelineControlFlagsFiFo.SetSize(blockBeamDelay);
    blockBeamPerChipControlFlagsFiFo.SetSize(blockBeamDelay);

    beamVoxelFiFo.Preset(*(inputs.voxel));
    beamWeightsFiFo.Preset(*(inputs.weightsXYZ));
    beamPerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineControlFlags));
30 beamPerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFlags));

    blockBeamVoxelFiFo.Preset(*(inputs.voxel));
    blockBeamWeightsFiFo.Preset(*(inputs.weightsXYZ));
    blockBeamPerPipelineControlFlagsFiFo.Preset(*(inputs.perPipelineControlFla
35 gs));
    blockBeamPerChipControlFlagsFiFo.Preset(*(inputs.perChipControlFlags));

    readBigFiFoCounter = readSmallFiFoCounter =
        writeBigFiFoCounter = writeSmallFiFoCounter = -1;
} // PerFrameSetup

40 //////////////////////////////////////
// local computation functions

void TriLinYPipeline::RunForOneClockCycle()
{
45 // buffer reading

    // reset counters
50
55

```

```

333
    if (inputs.perChipControlFlags- >volumeStart ||
        ((readBigFiFoCounter == 0) &&
         (readSmallFiFoCounter == 0) &&
         (writeBigFiFoCounter == 0) &&
         (writeSmallFiFoCounter == 0))) {
5
        readBigFiFoCounter = beamDelay;
        readSmallFiFoCounter = (blockSize-1) * readBigFiFoCounter;
10
        writeBigFiFoCounter = readBigFiFoCounter;
        writeSmallFiFoCounter = readSmallFiFoCounter;
    }

    //////////////////////////////////////
15    // first read from FiFos into results register

    // at start of block read from big FiFo
    if (readBigFiFoCounter > 0) {
        blockBeamVoxelFiFo.Read(outFiFo);
        blockBeamWeightsFiFo.Read(*(results.weightsXYZ));
20
        blockBeamPerPipelineControlFlagsFiFo.Read(*(results.perPipelineControlFlag
s));
        blockBeamPerChipControlFlagsFiFo.Read(*(results.perChipControlFlags));
        --readBigFiFoCounter;
25
        // if (chipIndex == 0 && pipelineIndex == 0)
        cout<<"R"<<*(results.voxel)<<volumeSliceGradientFiFo<<endl;
    }

    // in middle and at end of block read from small FiFo
30    else if (readSmallFiFoCounter > 0) {
        beamVoxelFiFo.Read(outFiFo);
        beamWeightsFiFo.Read(*(results.weightsXYZ));

        beamPerPipelineControlFlagsFiFo.Read(*(results.perPipelineControlFlags));
        beamPerChipControlFlagsFiFo.Read(*(results.perChipControlFlags));
35
        --readSmallFiFoCounter;
        // if (chipIndex == 0 && pipelineIndex == 0)    cout<<"r";
    }

    //////////////////////////////////////
40    // computation

    // Linear interpolation
    // c = w(b-a)+a
    //
    // w=0 -> c=a
    // w=1 -> c=b
45

    if (cube4->cubeMode == Cube4Light) {
        // just pick current voxel (as if w=0)
50
55

```

```

334
results.voxel->raw16bit = outFiFo.raw16bit; // w=0;
// use weights later on in composing
5      }

else if (cube4->cubeMode == Cube4Classic) {
    // do real interpolation
    a((int)outFiFo.raw16bit);
    b((int)inputs.voxel->raw16bit);
10
    // use results-weight (they are generated relative to (0,0,0) pos
    results.voxel->raw16bit = (short) ((results.weightsXYZ->Y())*(b-a) +
a);

    // assign control bits to weights to flow down the rest of the
15    // pipeline as weights
    results.weightsXYZ->SetY(-1 *
StepDirection[results.perChipControlFlags->yStep]);
}

20    //////////////////////////////////////
    // buffer writing

    //////////////////////////////////////
    // now write to FiFos from inputs register

25    // at start and in middle of block write to small FiFo
    if (writeSmallFiFoCounter > 0) {
        beamVoxelFiFo.Write(*(inputs.voxel));
        beamWeightsFiFo.Write(*(inputs.weightsXYZ) );

        beamPerPipelineControlFlagsFiFo.Write(*(inputs.perPipelineControlFlags));
        beamPerChipControlFlagsFiFo.Write(
30    *(inputs.perChipControlFlags));
        --writeSmallFiFoCounter;
        // if (chipIndex == 0 && pipelineIndex == 0) cout<<"w";
    }

35    // at end of block write to big FiFo of next chip
    else if (writeBigFiFoCounter > 0) {
        ModInt c(chipIndex+1, numOfChips);
        int p(pipelineIndex);
        TriLinYPipeline *next(&cube4->triLinY[c].triLinYPipeline[p]);
        next->blockBeamVoxelFiFo.Write(*(inputs.voxel));
40        next->blockBeamWeightsFiFo.Write(*(inputs.weightsXYZ) );
        next->blockBeamPerPipelineControlFlagsFiFo.Write(*(inputs.perPipelineControlFlags));
        next->blockBeamPerChipControlFlagsFiFo.Write(*(inputs.perChipControlFlags));
        --writeBigFiFoCounter;
45        //if (chipIndex == 0 && pipelineIndex == 0) cout<<"W";
    }
} // RunForOneClockCycle

```

50

55


```

5  //////////////////////////////////////
   // internal utility functions

   // end of TriLinYPipeline.C
   ::::::::::::::
10  cube4/TriLinYPipeline.h
   ::::::::::::::
   // TriLinYPipeline.h
   // (c) Ingmar Bitter '97

   // Copyright, Mitsubishi Electric Information Technology Center
15  // America, Inc., 1997, All rights reserved.

   #ifndef _TriLinYPipeline_h_ // prevent multiple includes
   #define _TriLinYPipeline_h_

20  #include "Misc.h"
   #include "Object.h"
   #include "FiFo.h"
   #include "Voxel.h"
   #include "Coxel.h"
25  #include "Control.h"
   #include "FixPointNumber.h"

   typedef Vector3D<FixPointNumber> FixPointVector3D;

   class TriLinYStage;
30  class Cube4;

   class TriLinYPipelineInputs {
   public: // pointers
       Voxel *voxel;
35       Vector3D<FixPointNumber> *weightsXYZ;
       PerChipControlFlags *perChipControlFlags;
       PerPipelineControlFlags *perPipelineControlFlags;
   };

40  class TriLinYPipelineResults {
   public: // pointers
       Voxel *voxel;
       Vector3D<FixPointNumber> *weightsXYZ;
       PerChipControlFlags *perChipControlFlags;
45       PerPipelineControlFlags *perPipelineControlFlags;
   };

   class TriLinYPipeline : virtual public Object {
50  public:

       static void Demo ();

55

```

```

// constructors & destructors
5   TriLinYPipeline ();
   ~TriLinYPipeline ();

// show/set data & data properties
// - class Object requirements
10  virtual ostream & Ostream (ostream & ) const;

// - local show/set functions
static void GlobalSetup (const int setNumOfChips,

15  const int setNumOfPipelinesPerChip,

const int setBlockSize);

virtual void LocalSetup(const int setChipIndex,

20  const int setPipelineIndex,

TriLinYStage & triLinYStage);
virtual void PerFrameSetup();
// local computation functions
25  virtual void RunForOneClockCycle();

public:
TriLinYPipelineInputs inputs;
TriLinYPipelineResults results;

30  protected:
FiFo<Voxel> beamVoxelFiFo;
FiFo<FixPointVector3D> beamWeightsFiFo;
FiFo<PerPipelineControlFlags> beamPerPipelineControlFlagsFiFo;
FiFo<PerChipControlFlags> beamPerChipControlFlagsFiFo;

35  FiFo<Voxel> blockBeamVoxelFiFo;
FiFo<FixPointVector3D> blockBeamWeightsFiFo;
FiFo<PerPipelineControlFlags> blockBeamPerPipelineControlFlagsFiFo;
FiFo<PerChipControlFlags> blockBeamPerChipControlFlagsFiFo;

40  Voxel outFiFo;
FixPointNumber a,b;

int beamDelay, blockBeamDelay;

45  int readSmallFiFoCounter, readBigFiFoCounter;
int writeSmallFiFoCounter, writeBigFiFoCounter;

static int numOfChips, numOfPipelinesPerChip, blockSize;
static int maxDatasetSizeX;
50  static Cube4 *cube4;
int chipIndex, pipelineIndex;

55

```

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```

    friend class Cube4;
};

5  #include "TriLinYStage.h"
    #include "Cube4.h"

    #endif // _TriLinYPipeline_h_
    ::::::::::::::
10  cube4/TriLinYStage.C
    ::::::::::::::
    // TriLinYStage.C
    // (c) Ingmar Bitter '97

    // Copyright, Mitsubishi Electric Information Technology Center
15  // America, Inc., 1997, All rights reserved.

    #include "TriLinYStage.h"

    void TriLinYStage::Demo()
    {
20      TriLinYStage triLinY;
        cout << endl <<"Demo of class " << typeid(triLinY).name();
        cout << endl <<"size : " << sizeof(TriLinYStage) << " Bytes";
        cout << endl <<"public member functions:";
        cout << endl <<"TriLinYStage triLinY; = " << triLinY;
        cout << endl <<"End of demo of class " << typeid(triLinY).name() << endl;
25    } // Demo

    //////////////////////////////////////
    // constructors & destructors

30  // static first init
    int TriLinYStage::numOfChips = 0;
    int TriLinYStage::numOfPipelinesPerChip = 0;
    Cube4 *TriLinYStage::cube4 = 0;

    TriLinYStage::TriLinYStage()
35  {
        triLinYPipeline = new TriLinYPipeline [numOfPipelinesPerChip];
        results.voxel = new Voxel [numOfPipelinesPerChip];
        results.weightsXYZ = new Vector3D<FixPointNumber> [numOfPipelinesPerChip];
        results.perPipelineControlFlags = new PerPipelineControlFlags
40  [numOfPipelinesPerChip];
    } // defaultconstructor

    TriLinYStage::~TriLinYStage()
    {
45      if (triLinYPipeline) { delete triLinYPipeline; triLinYPipeline=0; }
        if (results.voxel) { delete results.voxel; results.voxel=0; }
        if (results.weightsXYZ) { delete results.weightsXYZ; results.weightsXYZ=0; }
    }

```

50

55

```

338
        if (results.perPipelineControlFlags) {
            delete results.perPipelineControlFlags;
            results.perPipelineControlFlags=0;
5        }
    } // destructor

10 // show/set data & data properties

ostream & TriLinYStage::Ostream(ostream & os) const
{
    // append TriLinYStage info to os
15    os << typeid(*this).name() << "@" << (void *) this;
        os << endl << "    numOfChips          = " << numOfChips;
        os << endl << "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
        os << endl << "    chipIndex            = " << chipIndex;

20    // return complete os
    return os;

} // Ostream

25 // show/set data & data properties
//
// - local show/set functions

30 void TriLinYStage::GlobalSetup(const int setNumOfChips,
                                const int setNumOfPipelinesPerChip,
                                const int setBlockSize,
35                                Cube4 *setCube4)
{
    numOfChips          = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
40    TriLinYPipeline::GlobalSetup(numOfChips, numOfPipelinesPerChip,
                                setBlockSize);
    cube4 = setCube4;
} // GlobalSetup

45 void TriLinYStage::LocalSetup(const int setChipIndex)
{
    chipIndex = setChipIndex;
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
50        triLinYPipeline[p].LocalSetup(chipIndex,p,*this);

```

55

```

    )
} // LocalSetup

5
void TriLinYStage::PerFrameSetup()
{
    int p;
    // reset pipeline registers
10    for (p=0; p<numOfPipelinesPerChip; ++p) {
        results.voxel[p].raw16bit = 0;
        results.weightsXYZ[p](0,0,0);
        results.perPipelineControlFlags[p].Reset();
    }
    results.perChipControlFlags.Reset();
15
    for (p=0; p<numOfPipelinesPerChip; ++p) {
        triLinYPipeline[p].PerFrameSetup();
    }

    // print debug info
20    //static bool first(true); if (first) { cout<<this<<endl; first=false; }
} // PerFrameSetup

////////////////////////////////////
25 // local computation functions

void TriLinYStage::RunForOneClockCycle()
{
    // communication

30    // computation
    for (int p=0; p<numOfPipelinesPerChip; ++p) {
        triLinYPipeline[p].RunForOneClockCycle();
    }
} // RunForOneClockCycle

35
////////////////////////////////////
// internal utility functions

40 // end of TriLinYStage.C
:~::~:~::~:~::~:~::~:~::~:
cube4/TriLinYStage.h
:~::~:~::~:~::~:~::~:~::~:
// TriLinYStage.h
45 // (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#ifdef _TriLinYStage_h_ // prevent multiple includes
50
55

```

```

#define _TriLinYStage_h_

#include "Misc.h"
#include "Object.h"
#include "Vector3D.h"
#include "Voxel.h"
#include "Control.h"
#include "TriLinYPipeline.h"
#include "FixPointNumber.h"
#include "Cube4.h"

class Cube4;

class TriLinYStageInputs {
public: // pointers
    Voxel *voxel;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags      *perChipControlFlags;
    PerPipelineControlFlags  *perPipelineControlFlags;
};

class TriLinYStageResults {
public: // arrays
    Voxel *voxel;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags      perChipControlFlags;
    PerPipelineControlFlags  *perPipelineControlFlags;
};

class TriLinYStage : virtual public Object {
public:

    static void      Demo ();

    // constructors & destructors
    TriLinYStage ();
    ~TriLinYStage ();

    // show/set data & data properties
    // - class Object requirements
    virtual ostream & Ostream (ostream & )    const;

    // - local show/set functions
    static void GlobalSetup (const int setNumOfChips,

        const int setNumOfPipelinesPerChip,

        const int setBlockSize,

        Cube4 *setCube4);
    virtual void LocalSetup (const int setChipIndex);

```

```

341
    virtual void PerFrameSetup ();
    // local computation functions
5    virtual void RunForOneClockCycle();

public:
    TriLinYPipeline *triLinYPipeline;
    TriLinYStageInputs inputs;
    TriLinYStageResults results;
10

protected:
    static int    numOfChips, numOfPipelinesPerChip;
    static Cube4 *cube4;
    int          chipIndex; // only for debugging purpose
15

    friend class TriLinYPipeline;
};

#ifdef _TriLinYStage_h_
::::::::::::::::::
20 cube4/TriLinZPipeline.C
::::::::::::::::::
// TriLinZPipeline.C
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
25 // America, Inc., 1997, All rights reserved.

#include "TriLinZPipeline.h"

void TriLinZPipeline::Demo()
{
30    TriLinZPipeline triLinZ;
    cout << endl << "Demo of class " << typeid(triLinZ).name();
    cout << endl << "size : " << sizeof(TriLinZPipeline) << " Bytes";
    cout << endl << "public member functions:";
    cout << endl << "TriLinZPipeline triLinZ; = " << triLinZ;
35    cout << endl << "End of demo of class " << typeid(triLinZ).name() << endl;
} // Demo

/////////////////////////////////////////////////////////////////
// constructors & destructors
40

// static first init
int TriLinZPipeline::numOfChips      = 0;
int TriLinZPipeline::numOfPipelinesPerChip = 0;
Cube4 *TriLinZPipeline::cube4      = 0;

45 TriLinZPipeline::TriLinZPipeline()
{
} // constructor

50

55

```

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```

TriLinZPipeline::~TriLinZPipeline()
{
5   } // destructor

////////////////////////////////////
// show/set data & data properties

10

ostream & TriLinZPipeline::Ostream(ostream & os) const
{
    // append TriLinZPipeline info to os
    os << typeid(*this).name() << "@" << (void *) this;
15     os <<endl<< "    numOfChips          = " << numOfChips;
        os <<endl<< "    numOfPipelinesPerChip = " << numOfPipelinesPerChip;
        os <<endl<< "    chipIndex            = " << chipIndex;

    // return complete os
20     return os;
} // Ostream

////////////////////////////////////
25 // show/set data & data properties
//
// - local show/set functions

void TriLinZPipeline::GlobalSetup(const int setNumOfChips,
30                                const int setNumOfPipelinesPerChip)
{
    numOfChips          = setNumOfChips;
    numOfPipelinesPerChip = setNumOfPipelinesPerChip;
35 } // GlobalSetup

void TriLinZPipeline::LocalSetup(const int setChipIndex,
40                                const int setPipelineIndex,
                                TriLinZStage & triLinZStage)
{
    chipIndex = setChipIndex;
    pipelineIndex = setPipelineIndex;
45     inputs.voxel0 = &(triLinZStage.inputs.voxel0[pipelineIndex]);
    inputs.voxel1 = &(triLinZStage.inputs.voxel1[pipelineIndex]);
    inputs.weightsXYZ = &(triLinZStage.inputs.weightsXYZ[pipelineIndex]);
    inputs.perChipControlFlags
50     = triLinZStage.inputs.perChipControlFlags;
    inputs.perPipelineControlFlags

```

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```

=
&(triLinZStage.inputs.perPipelineControlFlags[pipelineIndex]);
5
    results.voxel = &(triLinZStage.results.voxel[pipelineIndex]);
    results.perPipelineControlFlags
        = &(triLinZStage.results.perPipelineControlFlags[pipelineIndex]);

    cube4 = triLinZStage.cube4;
10 } // LocalSetup

void TriLinZPipeline::PerFrameSetup()
{
15     // reset pipeline registers already done in TriLinZStage
} // PerFrameSetup

////////////////////////////////////
// local computation functions

20 void TriLinZPipeline::RunForOneClockCycle()
{
    /*
        / (z)
25     /voxB (seen late (recently) during processing => take from FiFo0 )
        /
        /voxA (seen early (long ago) during processing => take from FiFo1 )
        /
        +----->(x)
30     |
        |
        V(y)

    */
35
    // Linear interpolation
    // c = w(b-a)+a
    //
    // w=0 -> c=a
40     // w=1 -> c=b

    if (cube4->cubeMode == Cube4Light) {
        // just pick current voxel (as if w=0)
        results.voxel->raw16bit = inputs.voxell->raw16bit; // w=0;
45         // use weights later on in composing
    }

    else if (cube4->cubeMode == Cube4Classic) {
        // do real interpolation
50         a((int)inputs.voxell->raw16bit);
    }
}

```

55

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345

```

public: // pointers
    Voxel *voxel;
5    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags *perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
};

10 class TriLinZPipeline : virtual public Object {
public:

    static void      Demo ();

15    // constructors & destructors
    TriLinZPipeline ();
    ~TriLinZPipeline ();

    // show/set data & data properties
    // - class Object requirements
20    virtual ostream & Ostream (ostream & ) const;

    // - local show/set functions
    static void GlobalSetup (const int setNumOfChips,

25    const int setNumOfPipelinesPerChip);

    virtual void LocalSetup(const int setChipIndex,

    const int setPipelineIndex,

30    TriLinZStage & triLinZStage);
    virtual void PerFrameSetup();
    // local computation functions
    virtual void RunForOneClockCycle();

35 public:
    TriLinZPipelineInputs inputs;
    TriLinZPipelineResults results;

protected:
40    Voxel delayVoxel0; // delay voxel from SliceVoxelFiFo0 for one extra
    cycle
    FixPointNumber a,b;
    static int      numOfChips, numOfPipelinesPerChip;
    static Cube4 *cube4;
    int            chipIndex, pipelineIndex;

45    friend class Cube4;
};

#include "TriLinZStage.h"
50 #include "Cube4.h"

```

55

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```

#endif          // _TriLinZPipeline_h_
:
:
:cube4/TriLinZStage.C
:
:
// TriLinZStage.C
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include "TriLinZStage.h"

void TriLinZStage::Demo()
{
    TriLinZStage triLinZ;
    cout << endl << "Demo of class " << typeid(triLinZ).name();
    cout << endl << "size : " << sizeof(TriLinZStage) << " Bytes";
    cout << endl << "public member functions:";
    cout << endl << "TriLinZStage triLinZ; = " << triLinZ;
    cout << endl << "End of demo of class " << typeid(triLinZ).name() << endl;
} // Demo

////////////////////////////////////
// constructors & destructors

// static first init
int TriLinZStage::numOfChips          = 0;
int TriLinZStage::numOfPipelinesPerChip = 0;
Cube4 *TriLinZStage::cube4 = 0;

TriLinZStage::TriLinZStage()
{
    triLinZPipeline = new TriLinZPipeline {numOfPipelinesPerChip};
    results.voxel = new Voxel {numOfPipelinesPerChip};
    results.weightsXYZ = new Vector3D<FixPointNumber> {numOfPipelinesPerChip};
    results.perPipelineControlFlags = new PerPipelineControlFlags
[numOfPipelinesPerChip];
} // default constructor

TriLinZStage::~TriLinZStage()
{
    if (triLinZPipeline) { delete triLinZPipeline; triLinZPipeline=0; }
    if (results.voxel) { delete results.voxel; results.voxel=0; }
    if (results.weightsXYZ) { delete results.weightsXYZ; results.weightsXYZ=0; }

    if (results.perPipelineControlFlags) {
        delete results.perPipelineControlFlags;
        results.perPipelineControlFlags=0;
    }
} // destructor

```

```

5  //////////////////////////////////////
   // show/set data & data properties

   ostream & TriLinZStage::Ostream(ostream & os) const
   {
10    // append TriLinZStage info to os
       os << typeid(*this).name() << "@" << (void *) this;
       os << endl << "   numOfChips           = " << numOfChips;
       os << endl << "   numOfPipelinesPerChip = " << numOfPipelinesPerChip;
       os << endl << "   chipIndex           = " << chipIndex;

15    // return complete os
       return os;

   } // Ostream

20  //////////////////////////////////////
   // show/set data & data properties
   //
   // - local show/set functions

25  void TriLinZStage::GlobalSetup(const int setNumOfChips,

                                   const int setNumOfPipelinesPerChip,

                                   Cube4 *setCube4)
30  {
       numOfChips           = setNumOfChips;
       numOfPipelinesPerChip = setNumOfPipelinesPerChip;
       TriLinZPipeline::GlobalSetup(numOfChips, numOfPipelinesPerChip);
       cube4 = setCube4;
35  } // GlobalSetup

   void TriLinZStage::LocalSetup(const int setChipIndex)
   {
40     chipIndex = setChipIndex;
       for (int p=0; p<numOfPipelinesPerChip; ++p) {
           triLinZPipeline[p].LocalSetup(chipIndex,p,*this);
       }
   } // LocalSetup

45  void TriLinZStage::PerFrameSetup()
   {
       int p;
       // reset pipeline registers
50     for (p=0; p<numOfPipelinesPerChip; ++p) {
           results.voxel[p].raw16bit = 0;

55

```

```

                                348
                                results.weightsXYZ[p](0,0,0);
                                results.perPipelineControlFlags[p].Reset();
5      }
      results.perChipControlFlags.Reset();

      for (p=0; p<numOfPipelinesPerChip; ++p) {
          triLinZPipeline[p].PerFrameSetup();
      }
10
      // print debug info
      //static bool first(true); if (first) { cout<<this<<endl; first=false; }
      } // PerFrameSetup

15
      ///////////////////////////////////////////////////////////////////
      // local computation functions

      void TriLinZStage::RunForOneClockCycle()
      {
20          // computation
          for (int p=0; p<numOfPipelinesPerChip; ++p) {
              results.weightsXYZ[p] = inputs.weightsXYZ[p];
              results.perPipelineControlFlags[p] =
              inputs.perPipelineControlFlags[p];
              triLinZPipeline[p].RunForOneClockCycle();
25          }
          results.perChipControlFlags = *(inputs.perChipControlFlags);
      } // RunForOneClockCycle

30
      ///////////////////////////////////////////////////////////////////
      // internal utility functions

      // end of TriLinZStage.C
      ::::::::::::::
35      cube4/Voxel.C
      ::::::::::::::
      // Voxel.C
      // (c) Ingmar Bitter '97

      // Copyright, Mitsubishi Electric Information Technology Center
40      // America, Inc., 1997, All rights reserved.

      #include "Voxel.h"

      ostream & operator << (ostream & os, const Voxel & v)
      {
45          short s(v.raw16bit);

          os << "[" << s << "|" << s%32 << "," << s/32%32 << "," << s/32/32%32 <<
          "]"<<";
50
55

```

```

    return os;
} // operator <<

5

// end of Voxel.C
::::::::::::
cube4/TriLinZStage.h
10 ::::::::::::::
// TriLinZStage.h
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.
15

#ifndef _TriLinZStage_h_      // prevent multiple includes
#define _TriLinZStage_h_

#include "Misc.h"
20 #include "Object.h"
#include "Voxel.h"
#include "Control.h"
#include "TriLinZPipeline.h"
#include "FixPointNumber.h"
25 #include "Cube4.h"

class Cube4;

class TriLinZStageInputs {
30 public: // pointers
    Voxel *voxel0; // from SliceVoxelFiFo0
    Voxel *voxel1; // from SliceVoxelFiFo1
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags      *perChipControlFlags;
35     PerPipelineControlFlags *perPipelineControlFlags;
};

class TriLinZStageResults {
40 public: // arrays
    Voxel *voxel;
    Vector3D<FixPointNumber> *weightsXYZ;
    PerChipControlFlags      perChipControlFlags;
    PerPipelineControlFlags *perPipelineControlFlags;
45 };

class TriLinZStage : virtual public Object {
public:

50     static void      Demo ();

    // constructors & destructors
    TriLinZStage ();

55

```

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```

351
    cout << endl << "VoxMem::Demo()" << endl;
} // Demo

5

////////////////////////////////////
// constructors & destructors

VoxMem::VoxMem()
10     : size(0), mem(0)
{
} // constructor

VoxMem::~VoxMem()
15 {
    if (mem) { delete mem; mem=0; }
} // destructor

20
////////////////////////////////////
// show/set data & data properties

ostream & VoxMem::Ostream(ostream & os) const
{
    // append Control info to os
25     os << typeid(*this).name() << "@" << (void *) this;
        os << endl << "  size = " << size;

    // return complete os
    return os;

30 } // Ostream

//
// - local show/set functions

35 bool VoxMem::Init (unsigned int setSize)
{
    size = setSize;
    if (mem) delete mem;
    mem = new Voxel [size];
40     if (!mem) ERROR("OutOfMemoryError");

    // print debug info
    //static bool first(true); if (first) { cout<<this<<endl; first=false; }

    return true;
45 } // Init

Voxel & VoxMem::operator () (unsigned int index)
{
50

55

```

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```

// subscript a array value
// check that index is valid
5   if (index >= size) {
        cout <<index<<"index:size"<<size;
        ERROR("TooLargeArrayIndexError!");
    }

10      // return reference to requested element
        return mem[index];
    } // operator ()

15  // end of VoxMem.C
    ::::::::::::::
    cube4/VoxMem.h
    ::::::::::::::
    // VoxMem.h
    // (c) Ingmar Bitter '97

20  // Copyright, Mitsubishi Electric Information Technology Center
    // America, Inc., 1997, All rights reserved.

    // DRAM Voxel Memory of one pipeline
25  // in : 1/numOfChips fraction of the dataset
    // out: bustmode access to blocks of voxels

    #ifndef _VoxMem_h_      // prevent multiple includes
    #define _VoxMem_h_

30  #include "Object.h"
    #include "Misc.h"
    #include "Voxel.h"

    class VoxMem : virtual public Object {
35  public:

        static void      Demo ();

        // constructors & destructors
40  VoxMem();
        virtual ~VoxMem();

        // show/set data & data properties
        // - class Object requirements
45  virtual      ostream &  Ostream (ostream & )    const;

        virtual      bool   Init      (unsigned int setSize);
        virtual /*inline*/ Voxel & operator () (unsigned int index);

50  // local computation functions

    protected:
        Voxel *mem;

55

```

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```

    unsigned int size;
};
5
#endif      // _VoxMem_h_
:
:
cube4/Voxel.h
:
:
10 // Voxel.h
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

15 #ifndef _Voxel_h_ // prevent multiple includes
#define _Voxel_h_

#include <iostream.h> // cout
#include "Global.h" // cout

20 union Voxel {
    unsigned char  raw8bit;
    unsigned short raw16bit;
    struct test {
25         unsigned x      : 5;
         unsigned y      : 5;
         unsigned z      : 5;
    };
    struct Format0 {
30         unsigned data      : 8;
    };
    struct Format1 {
         unsigned data      : 16;
    };
    struct Density12_Index4 {
35         unsigned data      : 12;
         unsigned segmentIndex : 4;
    };

    // Voxel (unsigned char c) { raw8bit = c; };
    // Voxel (unsigned short s) { raw16bit = s; };
40 Voxel (unsigned short i=0) { raw16bit = i; };
    friend ostream & operator << (ostream & os, const Voxel & v);
}; // union Voxel

45 #endif      // _Voxel_h_
:
:
cube4/doc/CoordinateSystems.doc
:
:
Frist of all, from now on we would like to use the following conventions
for the coordinate systems we discuss in Cube-4, to make the discussions
50 easier and the explanations clearer.

Abbreviations:

```

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=====

5 n : # samples along one axis of the dataset
 p : # parallel pipelines

 Ns : Slice number
 NB : Beam number
 Nb : Partial beam number

10 (i,k) : Memory Space coordinates
 (u,v,w) = (Ud,Vd,Wd) : Dataset Space coordinates (righthanded)
 (x,y,z) = (Xp,Yp,Zp) : Pipeline Space coordinates (righthanded)
 (u,v,w) = (Ub,Vb,Wb) : Baseplane Space coordinates (righthanded)
 (x,y,z) = (Xi,Yi,Zi) : Image Space coordinates (righthanded)

Memory Space:

=====

20 i ^ Conversions from dataset coordinates (Ud,Vd,Wd):

a		<	>	<	>	<	>	full parallel pipeline (p == n):
d		< R	>	< R	>	< R	>	i = v + w*n
d		< A	>	< A	>	< A	>	k = (u+v+w) % n
r		< M	>	< M	>	< M	>	
25 e		<	>	<	>	<	>	partial beam partitioned pipeline (p < n):
s		+++		+++		+++		i = Nb + NB * (n/p) + Ns * (n^2/p)
s		----->		----->		----->		k = (u+v+w) % p

 memory bank number k

30 eg: 4x4x4 dataset stored in 4 memory modules (full parallel)
 the entries below represent [wvu] dataset coordinates

 i ^

15		332 333 330 331
14		323 320 321 322
35 13		310 311 312 313
12		301 302 303 300
11		233 230 231 232
10		220 221 222 223
40 9		211 212 213 210
8		202 203 200 201
7		130 131 132 133
a 6		121 122 123 120
d 5		112 113 110 111
45 d 4		103 100 101 102
r		
e 3		031 032 033 030
s 2		022 023 020 021
s 1		013 010 011 012
50 0		000 001 002 003

 +----->

55

355

```

0  1  2  3
memory bank number k

```

Dataset Space:
=====
$$(u, v, w) == (Ud, Vd, Vd)$$

Conversion from pipeline coordinates to Dataset coordinates

$$\frac{\bar{w}}{/}$$
$$\begin{pmatrix} U_d \\ V_d \\ W_d \\ 1 \end{pmatrix} = M_{pd} * \begin{pmatrix} X_p \\ Y_p \\ Z_p \\ 1 \end{pmatrix}$$

Mpd = 4x4 matrix

$$M_{pd} = M_{dp}^{-1}$$

Origin always at upper left corner of storage order frontmost slice.
Unit length == distance between samples along one axes.

```
Pipeline Space:
=====
```

$$(x, y, z) == (X_p, Y_p, Z_p)$$

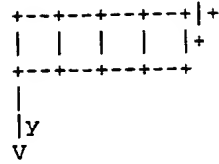
Conversion from dataset coordinates to pipeline coordinates

$$\frac{\bar{z}}{z}$$
$$\begin{pmatrix} X_p \\ Y_p \\ Z_p \\ 1 \end{pmatrix} = M_{dp} * \begin{pmatrix} U_d \\ V_d \\ W_d \\ 1 \end{pmatrix}$$

Conversion from baseplane coordinates to pipeline coordinates

$$\begin{pmatrix} X_p \\ Y_p \\ Z_p \\ 1 \end{pmatrix} = M_{bp} * \begin{pmatrix} U_b \\ V_b \\ W_b \\ 1 \end{pmatrix}$$

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Mpd, Mbp = 4x4 matrices

Mpd = Mdp⁽⁻¹⁾

Mpb = Mbp⁽⁻¹⁾

Origin always at upper left corner of view direction frontmost slice.
Unit length == distance between samples along one axes.

Baseplane Space:

=====

(u,v,w) == (Ub,Vb,Vb)

Conversion from pipeline coordinates
to baseplane coordinates

(Ub) (Xp)

(Vb) = Mpb * (Yp)

(Wb) (Zp)

(1) (1)

Conversion from image coordinates
to baseplane coordinates

(Ub) (Xi)

(Vb) = Mib * (Yi)

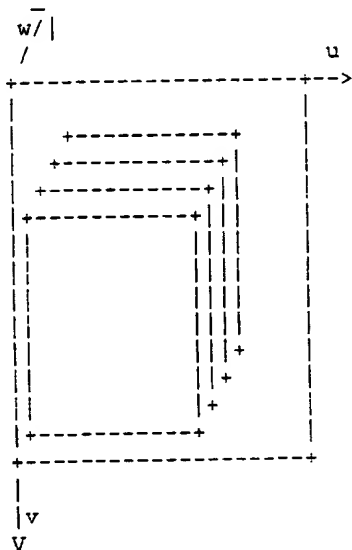
(Wb) (Zi)

(1) (1)

Mpb, Mib = 4x4 matrices

Mpb = Mbp⁽⁻¹⁾

Mib = Mbi⁽⁻¹⁾



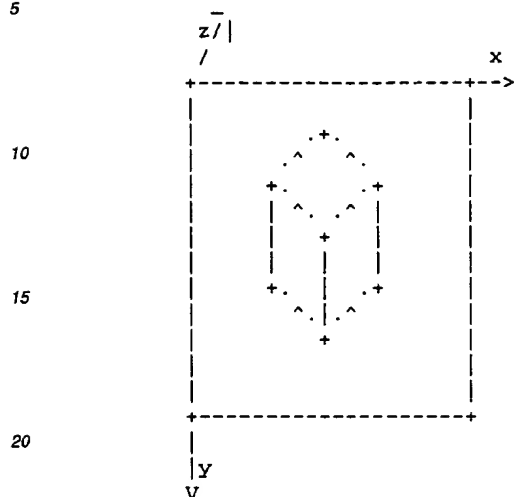
Unit length == distance between samples along one axes.

Image Space:

=====

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5 (x,y,z) == (Xp,Yp,Zp)



Conversions from baseplane coordinates
to image coordinates

(Xi) (Ub)
(Yi) = Mbi * (Vb)
(Zi) (Wb)
(1) (1)

Conversions from dataset coordinates
to image coordinates

(Xi) (Ub)
(Yi) = T * (Vb)
(Zi) (Wb)
(1) (1)

Mbi, T = 4x4 matrices

Mbi = Mib⁻¹

Global transformation matrix Dataset->Image:

T = Mbi * Mpb * Mdp
 | | |
 V V V
 Warp Shear Coordinate relabeling

Unit length == distance between image pixels along one axes.

30 :::::::::::::::
 cube4/doc/HOWTO-addNewPipeStage.doc
 :::::::::::::::
 HOWTO-addNewPipelineStage
 =====

35 Ingmar Bitter 4-23-97

New Pipeline stage: Foo

40 o Take an existing Pipeline stage Bar with similar in/outputs

o copy BarStage.C to FooStage.C
 o copy BarStage.h to FooStage.h
 o copy BarPipeline.C to FooPipeline.C
 o copy BarPipeline.h to FooPipeline.h

45 o search and replace all bar's by foo's and Bar's by Foo's in the new
 files

FooStage.h:

50 o update class FooStageInputs // pointers to previous results

55

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o update class FooStageResults // (dynamic) arrays of results
 o put(delete) (un)necessary class variables in protected section

5 FooPipeline.h:

o update class FooStageInputs // pointers to Stage array
 o update class FooStageResults // pointers to Stage array
 o put(delete) (un) necessary class variables in protected section

10 FooStage.C:

o check for completeness: // static first init
 o constructor/destructor: make updates according to updates of
 inputs/results class, keep array of pipelines !
 o check in SetupFunctions, that all local variables + in/output are
 15 initialized
 o RunForOneClockCycle(): do the copy stuff and communication stuff
 here, real computation is done in the pipelines

20 FooPipeline.C:

o check for completeness: // static first init
 o check in SetupFunctions, that all local variables + in/output are
 initialized
 o in LocalSetup() connect input/output pointers to appropriate members
 of Stage class
 25 o RunForOneClockCycle(): do the real computation of this pipeline

Cube4.h:

o #include "Foo*.h"
 o protected:
 30 ... DebugFoo(...) ...
 Foo *foo;

Cube4Debug.C:

o Add a FooDebug() function

35 Cube4.C:

o constructor
 // allocate memory for pipeline objects:
 ...
 40 Foo::GlobalSetup()
 ...
 foo = new Foo [numOfChips];
 ...
 // setup pipeline connections
 ...
 45 foo[c].inputs. ... = stageBeforeFoo[c].results. ...
 foo[c].LocalSetup(c);
 ...
 stageAfterFoo[c].inputs. ... = foo[c].results. ...
 ...

50 o destructor

if (foo) { delete foo; foo =0; }

55

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```

o PerFrameSetup()
...
5      for (c=0; c<numOfChips; ++c) { foo[c].PerFrameSetup(); }
...

o RunPipeline()
...
10     for (c=0; c<numOfChips; ++c) { foo[c].RunForOneClockCycle(); }
      DebugFoo(clk);
...

Makefile:
15  o Add "FooStage.C FooPipeline.C" to the SRC line
    o type make depend
    o type make all

:::
20  cube4/doc/blocking.doc
:::
Cube-4 Blocking
=====

25  (A) driver interface implications
-----

The complete volume of at most  $256^3$  voxels is grouped into  $8^3$  blocks
which are distributed skewed across the memory modules.

30  Each  $8^3$  block is subdivided into 64 mini-blocks of size  $2^3$ . All
mini-blocks belonging to a particular block reside in the same memory
module and occupy a contiguous chunk of linear memory. There is no
skewing inside blocks.

35  The one board implementation will have 4 VoxMem DRAMs holding 32 MB, 4
CoxMem DRAMs holding 0.5 MB and 4 Cube-4 chips with 4 rendering
pipelines per chip. Therefore, volume management has to keep the size
of the to be rendered dataset a multiple of  $4 \times 8 = 32$  in the horizontal
axis (in pipeline coordinate system). In y direction any multiple of 2
40  (mini-block granularity) is ok while in z it has to be a multiple of
4 (FinalCoxelBuffer readout delay). However, the horizontal axis in
the pipeline coordinate system could be any of the major axis in the
dataset coordinate system, so the easiest is to keep all dataset
dimensions a multiple of 32.

45  Using tiling of partial beams of mini-blocks across the volume allows
horizontally oversized datasets. Using horizontal sectioning allows
vertically oversized datasets. Finally using the slice buffers allows
for really deep volumes. So big long sticks can be computed in only
one pass without change of the algorithm. Unfortunately, some of the
50  internal buffers grow. The maximum values are:
    256 wide (no extra storage for y- and z-step buffers)
    512 wide (16KB extra storage for y- and z-step buffers)

55

```

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1024 wide (33KB extra storage for y- and z-step buffers)
 16K high (no extra storage on Cube-4 chip, CoxMem grows by 1 MB)
 16K deep (no extra storage on Cube-4 chip, CoxMem grows by 1 MB)
 Thus, y and z oversizes up to 32x32x16K can be handled by the
 hardware without modifications, x oversizes probably require the
 driver to split the rendering into 256 wide chunks, which will then be
 composited in 2D by the driver.

Really huge volumes are best cut up into 256 wide, 32 high (one
 section) and 2048 deep bricks, combining those bricks has to be done
 by the driver (using 3D (polygon) graphics board).

Sub volumes -- a zoomed-in region of a big dataset (e.g. tumor in
 brain), or initially small datasets (e.g. leg of game figure) should
 be at least 32^3 to use the full available bandwidth. If the
 sub volume is a zoom of a big volume, it can be positioned with the
 granularity of the 8^3 blocks. Finer changes can be achieved by
 specifying additional axis aligned cutting planes.

6 axis aligned cutting planes + one arbitrary cutting plane can be
 supported by the hardware.

Dynamically growing volumes generated by a phantom operated clay spray
 tool keep most of their data constant. Only small regions have to be
 updated. If the to-be-updated region exceeds the current volume a new
 slice of 8^3 blocks has to be allocated and filled with zeros and data
 from the new region. If the slice is not perpendicular to the view
 and the complete object is to be rendered, an increase by 4 slices of
 8^3 blocks is necessary (keep horizontal volume extend a multiple of
 32).

(B) internal buffer size implications (#copies x depth x width)

2x	8x2 bytes	mini-block read buffer
4x	256x2	beam of mini-blocks buffer
4x	2x2	TriLinX
4x	2x2	GradX
4x	2x2	GradZLinX
4x	2x4	ComposSelX
4x	2x4	ComposLinX
4x	64x2	TriLinY
4x	64x2	GradZLinY
8x	64x2	GradY
4x	64x4	ComposSelY
4x	64x4	ComposLinY
8x	16x2	2 SliceVoxelFiFo (inside slabs)
8x	512x2	2 SliceVoxelFiFo (between slabs)

EP 0 903 694 A1

```

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4x 16x2      GradZLinZ (inside   slabs)
4x512x2      GradZLinZ (between slabs)
5
4x512x4      ComposBuffer
3x 64x4      FinalCoxelBuffer
10
total: 26 K bytes

(C) Urs' requirements for on chip shader storage
-----
6x512x3 bytes reflectance tables (RGB intensities)
2x256x1       distortion compensation table (ROM)
15

total: 9.5 K bytes
:::::::::::::
cube4/linramp.txt
20
:::::::::::::
0 0 0 0 0
1 1 1 1 1
2 2 2 2 2
3 3 3 3 3
25
4 4 4 4 4
5 5 5 5 5
6 6 6 6 6
7 7 7 7 7
8 8 8 8 8
9 9 9 9 9
30
10 10 10 10 10
11 11 11 11 11
12 12 12 12 12
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15 15 15 15 15
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29 29 29 29 29
50
30 30 30 30 30
31 31 31 31 31
32 32 32 32 32
33 33 33 33 33
55

```

	34	34	34	34	34
	35	35	35	35	35
5	36	36	36	36	36
	37	37	37	37	37
	38	38	38	38	38
	39	39	39	39	39
	40	40	40	40	40
10	41	41	41	41	41
	42	42	42	42	42
	43	43	43	43	43
	44	44	44	44	44
	45	45	45	45	45
15	46	46	46	46	46
	47	47	47	47	47
	48	48	48	48	48
	49	49	49	49	49
	50	50	50	50	50
20	51	51	51	51	51
	52	52	52	52	52
	53	53	53	53	53
	54	54	54	54	54
	55	55	55	55	55
25	56	56	56	56	56
	57	57	57	57	57
	58	58	58	58	58
	59	59	59	59	59
	60	60	60	60	60
	61	61	61	61	61
30	62	62	62	62	62
	63	63	63	63	63
	64	64	64	64	64
	65	65	65	65	65
	66	66	66	66	66
35	67	67	67	67	67
	68	68	68	68	68
	69	69	69	69	69
	70	70	70	70	70
	71	71	71	71	71
40	72	72	72	72	72
	73	73	73	73	73
	74	74	74	74	74
	75	75	75	75	75
	76	76	76	76	76
	77	77	77	77	77
45	78	78	78	78	78
	79	79	79	79	79
	80	80	80	80	80
	81	81	81	81	81
	82	82	82	82	82
50	83	83	83	83	83
	84	84	84	84	84
	85	85	85	85	85
	86	86	86	86	86
55					

	87 87 87 87 87
	88 88 88 88 88
5	89 89 89 89 89
	90 90 90 90 90
	91 91 91 91 91
	92 92 92 92 92
	93 93 93 93 93
10	94 94 94 94 94
	95 95 95 95 95
	96 96 96 96 96
	97 97 97 97 97
	98 98 98 98 98
	99 99 99 99 99
15	100 100 100 100 100
	101 101 101 101 101
	102 102 102 102 102
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35	225	225	225	225	225
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40	230	230	230	230	230
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	232	232	232	232	232
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	234	234	234	234	234
45	235	235	235	235	235
	236	236	236	236	236
	237	237	237	237	237
	238	238	238	238	238
	239	239	239	239	239
50	240	240	240	240	240
	241	241	241	241	241
	242	242	242	242	242
	243	243	243	243	243
	244	244	244	244	244
55	245	245	245	245	245

55


```

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    cout << endl <<" numbers.SetSize(2) : " << numbers.SetSize(2) << " numbers
= "<< numbers;
5   DynaArray<int> nums(numbers);
    cout << endl <<" DynaArray<int> nums(numbers): nums = " << nums << &nums;
    cout << endl <<" numbers.Flush() : " << numbers.Flush() << "
numbers = "<< numbers;
    cout << endl <<" numbers(nums) : " << numbers(nums) << " numbers
= "<< numbers;
10   cout << endl <<" numbers.Flush() : " << numbers.Flush() << "
numbers = "<< numbers;
    cout << endl <<" numbers=nums : " << (numbers=nums) << " numbers
= "<< numbers;

    cout << endl <<"End of demo of class " << typeid(numbers).name() << endl;
15 } // Demo

////////////////////////////////////
// constructors & destructors

20
template <class T> DynaArray<T>::DynaArray(unsigned int setSize)
    : size(setSize), space(setSize)
{
    // make space for elements
25   elements = new T[space];
    assert(elements);

    // set all elements to 0
    Flush();

30 } // constructor

template <class T> DynaArray<T>::DynaArray(const DynaArray<T> & source)
    : size(source.size), space(source.size)
{
35   // make space for elements
    elements = new T[size];
    assert(elements);

    // set each element to the initial value
    for (unsigned int k = 0; k<size; ++k)
40     elements[k] = source.elements[k];

    // copy-constructor

45
template <class T> DynaArray<T>::~DynaArray()
{
    // free datastructures
    assert(elements);
    delete [] elements;

50

55

```

```

        elements = 0;

5      } // destructor

        ///////////////////////////////////////////////////////////////////
        // show/set data & data properties
        //
10     // - class Object requirements

template <class T> ostream & DynaArray<T>::Ostream(ostream & os) const
{
15     // append array info to os
    os << "( ";
    if (!size)
        os << "empty DynaArray";
    else
20     os << elements[0];
    for (unsigned int k=1; k<size; ++k) {
        os << "," << elements[k];
    }
    os << " )";

25     // return complete os
    return os;

} // Ostream

30     ///////////////////////////////////////////////////////////////////
    // show/set data & data properties
    //
    // - local show/set functions

35     template <class T> unsigned int DynaArray<T>::Size() const
    {
        return size;
    } // Size

40     template <class T> unsigned int DynaArray<T>::SetSize (unsigned int setSize)
    {
        // dynamic change of array size
        unsigned int k;

45         if (space/4 < setSize && setSize <= space) {
            size = setSize;
            return size;
        }

50         space = 2*setSize;

```

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```

// allocate memory for new array
T * newElements = new T[space];
5  assert(newElements);

if ( space < size ) {

    // copy the first setSize elements into smaller array
    for (k=0; k<space; ++k)
10      newElements[k] = elements[k];
}
else {
    // space > size

15    // copy all size elements into bigger array
    for (k=0; k<size; ++k)
        newElements[k] = elements[k];

    // initialize the remaining ones to 0
20    for (k=size; k<space; ++k)
        newElements[k] = 0;
}

// delete the old array
assert(elements);
25 delete [] elements;

// update the data member fields
size = setSize;
elements = newElements;

30 // return new size
return size;
} // SetSize

35
template <class T> DynaArray<T> & DynaArray<T>::Flush()
{
    // set each element to 0
    for (unsigned int k = 0; k<space; ++k)
40     elements[k] = 0;

    return *this;
} // Flush

45
template <class T> T & DynaArray<T>::operator [] (unsigned int index) const
{
    // subscript a array value
    // check that index is valid
    assert(index < size);
50

    // return requested element

```

55

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```

    return elements[index];

5      } // operator []

template <class T> DynaArray<T> & DynaArray<T>::operator =
    (const DynaArray<T> & source)
10  {
    // match sizes
    if (size != source.size) {
        // allocate memory for new array
        space = source.size;
        T * newElements = new T[space];
15        assert(newElements);

        // delete the old array
        assert(elements);
        delete [] elements;
20

        // update the data member fields
        size = space;
        elements = newElements;
    }

25    // copy the elements
    for (unsigned int k=0; k<size; ++k)
        elements[k] = source.elements[k];

30    return *this;
} // operator =

template <class T> DynaArray<T> & DynaArray<T>::operator ()
35  (const DynaArray<T> & source)
{
    *this = source;

    return *this;
40 } // operator ()

// end of DynaArray.C
:::::::::::::
oop/DynaArray/DynaArray.h
45 :::::::::::::::
// DynaArray.h
// (c) Ingmar Bitter '97

// Copyright, Mitsubishi Electric Information Technology Center
50 // America, Inc., 1997, All rights reserved.

// dynamic array ADT
55

```

```

371
#ifndef _DynaArray_h_ // prevent multiple includes
#define _DynaArray_h_

5
#include "assert.h"
#include "Object.h"

template <class T> class DynaArray : public virtual Object {
10
public:
    static void      Demo      ();

    // constructors & destructors
    DynaArray  (unsigned int setSize=0);
15    DynaArray  (const DynaArray<T> &);
    virtual ~DynaArray  ();

    // show/set data & data properties
    // - class Object requirements
    virtual ostream &  Ostream (ostream & )    const;

20
    // - local show/set functions
    virtual /*inline*/ unsigned int  Size      ( ) const;
    virtual      unsigned int  SetSize      (unsigned int
setSize);
    virtual /*inline*/ DynaArray<T> & Flush      ( ); // set all
25 elements to 0
    virtual /*inline*/ T &      operator [] (unsigned int index)
const;
    virtual      DynaArray<T> & operator = (const DynaArray<T> &);
    virtual      DynaArray<T> & operator () (const DynaArray<T> &);

30
protected:
    unsigned int size; // reported by Size()
    unsigned int space; // really allocated memory
    T * elements;

}; // class DynaArray

35
#endif // _DynaArray_h_
::::::::::::
oop/DynaArray/Makefile
::::::::::::
40 # Makefile for C++ programs (c) Ingmar Bitter '97
#
# make      : compile only changed files and their depend
files
# make all      : recompile all
# make clean : recompile all and remove unnecessary files
45 #

EXECUTABLE = go

SRC = main.C Test.C Object.C DynaArray.C

```

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```

RM = /bin/rm -fs

#
#   put -g here | to add debugging info to executable
#               V
CDEBUGFLAGS = -O3
CCOPTIONS    = -n32

10  CC = CC

INCLUDES     =
LIBS         =
CFLAGS       = $(CCOPTIONS) $(CDEBUGFLAGS) $(INCLUDES)

15  OFILES = $(SRC:.C=.o)

$(EXECUTABLE): $(OFILES)
                $(CC) $(OFILES) $(CFLAGS) $(LIBS) -o $(EXECUTABLE)

20  #
#   target: dependency \n tab rule
#
.C.o:
                $(CC) $(CFLAGS) -c $<

25  #
#   switch:: ; \n tab rule
#
clean:
                ;

30  find . -name "*.o" -print -exec mv {} ~/dumpster \; ;
    find . -name "*" -print -exec mv {} ~/dumpster \; ;
    find . -name "go" -print -exec mv {} ~/dumpster \; ;
    find . -name "core" -print -exec mv {} ~/dumpster \; ;

all: ;

35  pmake -u

depend:
                makedepend -- $(CFLAGS) -- $(SRC)

# DO NOT DELETE

40  main.o: Test.h DynaArray.h /usr/include/assert.h Object.h
    main.o: /usr/include/string.h /usr/include/standards.h Global.h
    main.o: /usr/include/stdlib.h /usr/include/sgidefs.h
    Test.o: Test.h DynaArray.h /usr/include/assert.h Object.h
    Test.o: /usr/include/string.h /usr/include/standards.h Global.h
45  Test.o: /usr/include/stdlib.h /usr/include/sgidefs.h
    Object.o: Object.h /usr/include/string.h /usr/include/standards.h Global.h
    Object.o: /usr/include/assert.h /usr/include/stdlib.h /usr/include/sgidefs.h
    DynaArray.o: DynaArray.h /usr/include/assert.h Object.h /usr/include/string.h
    DynaArray.o: /usr/include/standards.h Global.h /usr/include/stdlib.h
50  DynaArray.o: /usr/include/sgidefs.h

```

55

```

5  ::::::::::::::
   oop/DynaArray/Test.C
   ::::::::::::::
   // Test.cpp    testclass for OOP-classes
   // (c) Ingmar Bitter '96

   #include "Test.h"

10  void Test::Run()          { DynaArray<int>::Demo(); }

   // end of Test.cpp
   ::::::::::::::
   oop/DynaArray/Test.h
15  ::::::::::::::
   // Test.h        test class for OOP-classes
   // (c) Ingmar Bitter '96

   #ifndef _Test_h_          // prevent multiple includes
20  #define _Test_h_

   #include "DynaArray.h"

   class Test { public: static void Run(); };

25  #endif          // _Test_h_
   ::::::::::::::
   oop/FiFo/FiFo.C
   ::::::::::::::
   // FiFo.C
30  // (c) Ingmar Bitter '97 / Urs Kanus '97

   // Copyright, Mitsubishi Electric Information Technology Center
   // America, Inc., 1997, All rights reserved.

35  #include "FiFo.h"
   #include "ModInt.h"

   template <class T> void FiFo<T>::Demo()
   {
40     FiFo<T> fifo;
        T a(1),b(2),c(3),d(4),e(5),f(6),out;
        cout << endl <<"Demo of class " << typeid(fifo).name();
        cout << endl <<"size : " << sizeof(FiFo<T>) << " Bytes";
        cout << endl <<"public member functions:";

45     cout << endl <<"  Size() => " << fifo.Size();
        cout << endl <<Object::BoolStr[fifo.Size()==1];
        cout << "SetSize("<<c<<" )"; fifo.SetSize(3);
        cout << endl <<Object::BoolStr[fifo.Size()==3];
        cout << "Preset("<<a<<" ) => "; fifo.Preset(a); cout << fifo;
50     cout << endl <<Object::BoolStr[fifo.mem[0]==a && fifo.mem[1]==a &&
        fifo.mem[2]==a];

```

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```

cout << "Read(out); => ";                                fifo.Read(out);
cout << "out="<<out<<"; fifo="<<fifo;
5 cout << endl <<Object::BoolStr[out==a];
cout << "Read(out); => ";    fifo.Read(out);
cout << "out="<<out<<"; fifo="<<fifo;
cout << endl <<Object::BoolStr[out==a];
cout << "Read(out); => ";    fifo.Read(out);
10 cout << "out="<<out<<"; fifo="<<fifo;
cout << endl <<Object::BoolStr[out==a];

cout << "Write("<<b<<") => ";    fifo.Write(b); cout<<"fifo="<<fifo;
cout << endl <<Object::BoolStr[fifo.mem[0]==b && fifo.mem[1]==a &&
15 fifo.mem[2]==a];
cout << "Write("<<c<<") => ";    fifo.Write(c); cout<<"fifo="<<fifo;
cout << endl <<Object::BoolStr[fifo.mem[0]==b && fifo.mem[1]==c &&
fifo.mem[2]==a];
cout << "Write("<<d<<") => ";    fifo.Write(d); cout<<"fifo="<<fifo;
20 cout << endl <<Object::BoolStr[fifo.mem[0]==b && fifo.mem[1]==c &&
fifo.mem[2]==d];

cout << "Peek(0); => "; out = fifo.Peek(0);
cout << "out="<<out<<"; fifo="<<fifo;
cout << endl <<Object::BoolStr[out==b];
25 cout << "Peek(1); => "; out = fifo.Peek(1);
cout << "out="<<out<<"; fifo="<<fifo;
cout << endl <<Object::BoolStr[out==c];
cout << "Peek(2); => "; out = fifo.Peek(2);
cout << "out="<<out<<"; fifo="<<fifo;
30 cout << endl <<Object::BoolStr[out==d];
cout << "Peek(-1); => "; out = fifo.Peek(-1);
cout << "out="<<out<<"; fifo="<<fifo;
cout << endl <<Object::BoolStr[out==d];

cout << "Read(); => "; out = fifo.Read();
35 cout << "out="<<out<<"; fifo="<<fifo;
cout << endl <<Object::BoolStr[out==b];
cout << "Read(); => "; out = fifo.Read();
cout << "out="<<out<<"; fifo="<<fifo;
40 cout << endl <<Object::BoolStr[out==c];
cout << "Read(); => "; out = fifo.Read();
cout << "out="<<out<<"; fifo="<<fifo;
cout << endl <<Object::BoolStr[out==d];

cout << "Exchange("<<e<<",out) => ";    fifo.Exchange(e,out);
45 cout << "out="<<out<<"; fifo="<<fifo;
cout << endl <<Object::BoolStr[out==b];
cout << "Exchange("<<f<<",out) => ";    fifo.Exchange(f,out);
cout << "out="<<out<<"; fifo="<<fifo;
cout << endl <<Object::BoolStr[out==c];

50 cout << "Read(out); => ";    fifo.Read(out);
cout << "out="<<out<<"; fifo="<<fifo;
cout << endl <<Object::BoolStr[out==d];

```

55

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```

    cout << endl << "End of demo of class " << typeid(fifo).name() << endl;
} // Demo
5

////////////////////////////////////
// constructors & destructors

10 template <class T> FiFo<T>::FiFo(int setSize)
    : size(setSize), writePointer(0), readPointer(0), fifoFull(false)
    {

        mem = new T [size];

15     if (!mem) ERROR("OutOfMemoryError");
    } // constructor

    template <class T> FiFo<T>::~~FiFo()
20     {
        if (mem) { delete mem; mem = 0;    }
    } // destructor

    //////////////////////////////////////
25 // show/set data & data properties
    //
    // - class Object requirements

    template <class T> ostream & FiFo<T>::Ostream(ostream & os) const
30     {
        // append FiFo info to os
        os << "writePointer=" << writePointer;
        os << "; readPointer=" << readPointer;
        /*
35         << "; data=[";
        for (int k=0; k<size-1; ++k) {
            os << &mem[k] << ", ";
        }
        os << &mem[size-1] << "]"
        */
40         os << " ";

        // return complete os
        return os;

45     } // Ostream

    //////////////////////////////////////
    // show/set data & data properties
    //
50 // - local show/set functions

```

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```

template <class T> bool                               FiFo<T>::SetSize(const int& setSize)
{
5   size = setSize;
    if (mem) delete mem;
    mem = new T [size];
    if (!mem) ERROR("OutOfMemoryError");

    writePointer = readPointer = 0;
10   fifoFull = false;

    return true;
} // SetSize

15 template <class T> int FiFo<T>::Size() const
{
    return size;
} // Size

template <class T> void FiFo<T>::Preset(const T& value )
20 {
    if (size>0) {
        for (int i=0; i<size; i++)
            mem[i] = value;
    }
    writePointer = readPointer = 0;
25   fifoFull = false;
}
// ////////////////////////////////////////
// local computation functions

30 template <class T> bool FiFo<T>::Write( const T& in )
{
    if ( fifoFull )
        ERROR( "FiFo is full" );

    mem[writePointer] = in;
35   writePointer = (writePointer + 1) % size;

    if ( writePointer == readPointer )
        fifoFull = true;

    return true;
40 } // Write

template <class T> bool FiFo<T>::Read(T& out)
{
45   if ( fifoFull ) fifoFull = false;

    out = mem[readPointer];
    readPointer = (readPointer + 1) % size;

    return true;
50 }

```

55

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```

    } // Read

5   template <class T> T FiFo<T>::Read()
    {
        T out;

        if ( fifoFull ) fifoFull = false;

10      out = mem[readPointer];
        readPointer = (readPointer + 1) % size;

        return out;
    } // Read

15   template <class T> T FiFo<T>::Peek( const int offsetFromReadPointer )
    {
        T out;
        ModInt peekPointer(0, size);

20      peekPointer = readPointer + offsetFromReadPointer;
        out = mem[peekPointer];

        return out;
    } // Read

25

    template <class T> bool FiFo<T>::Exchange( const T& in, T& out)
    {
        if (size>0) {
30          Read(out);
          Write(in);
        }
        else {
            out=in;
35          }

        return true;
    } // Exchange

40

    //////////////////////////////////////
    // internal utility functions

    // end of FiFo.C
45  ::::::::::::::
    oop/FiFo/FiFo.h
    ::::::::::::::
    // FiFo.h
    // (c) Ingmar Bitter '97 / Urs Kanus '97

50

    // Copyright, Mitsubishi Electric Information Technology Center
    // America, Inc., 1997, All rights reserved.

55

```

```

5 // FiFo (Write, Read, Exchange)

#ifndef _FiFo_h_ // prevent multiple includes
#define _FiFo_h_

#include "Object.h"

10 template <class T> class FiFo : virtual public Object {
public:

    static void      Demo ();

15 // constructors & destructors
    FiFo(int setSize=1);
    virtual ~FiFo();

    // show/set data & data properties
    // - class Object requirements
20 virtual      ostream &      Ostream (ostream & )      const;

    // - local show/set functions
    virtual      bool          SetSize( const int& setSize );
    virtual      int           Size() const;
25 virtual      void           Preset( const T& value );

    // local computation functions
    virtual      bool          Write( const T& in );
    virtual      bool          Read ( T& out );
30 virtual      T              Read ();
    virtual      T              Peek ( const int offsetFromReadPointer );
    virtual      bool          Exchange( const T& in, T& out );

protected:
    T *mem;
35 int size, writePointer, readPointer;
    bool fifoFull;
};

#endif // _FiFo_h_
40 ::::::::::::::
oop/FiFo/Makefile
::::::::::::
# Makefile for C++ programs (c) Ingmar Bitter '97
#
# make : compile only changed files and their depend
45 files
# make all : recompile all
# make clean : recompile all and remove unnecessary files
#

50 EXECUTABLE = go

```

```

                                379
SRC    = main.C Test.C Object.C FiFo.C      ModInt.C

5  RM = /bin/rm -fs

#
#    put -g here | to add debugging info to executable
#                V
CDEBUGFLAGS = -g
10 CCOPTIONS  = -n32

CC = CC

INCLUDES =
LIBS      =
15 CFLAGS   = $(CCOPTIONS) $(CDEBUGFLAGS) $(INCLUDES)

OFILES = $(SRC:.C=.o)

$(EXECUTABLE): $(OFILES)
20      $(CC) $(OFILES) $(CFLAGS) $(LIBS) -o $(EXECUTABLE)

#
#    target: dependency \n tab rule
#
.C.o:
25      $(CC) $(CFLAGS) -c $<

#
#    switch:: ; \n tab rule
#
clean:
30      find . -name "*.o" -print -exec mv {} ~/dumpster \; ;
      find . -name "*~" -print -exec mv {} ~/dumpster \; ;
      find . -name "go" -print -exec mv {} ~/dumpster \; ;
      find . -name "core" -print -exec mv {} ~/dumpster \; ;

35  all: ;

      pmake -u

depend:

      makedepend -- $(CFLAGS) -- $(SRC)

40  # DO NOT DELETE

main.o: Test.h FiFo.h Object.h /usr/include/string.h /usr/include/standards.h
main.o: Global.h /usr/include/assert.h /usr/include/stdlib.h
main.o: /usr/include/sgidefs.h
Test.o: Test.h FiFo.h Object.h /usr/include/string.h /usr/include/standards.h
45  Test.o: Global.h /usr/include/assert.h /usr/include/stdlib.h
Test.o: /usr/include/sgidefs.h
Object.o: Object.h /usr/include/string.h /usr/include/standards.h Global.h
Object.o: /usr/include/assert.h /usr/include/stdlib.h /usr/include/sgidefs.h
FiFo.o: FiFo.h Object.h /usr/include/string.h /usr/include/standards.h

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FiFo.o: Global.h /usr/include/assert.h /usr/include/stdlib.h
FiFo.o: /usr/include/sgidefs.h ModInt.h /usr/include/limits.h
5 ModInt.o: ModInt.h Object.h /usr/include/string.h /usr/include/standards.h
ModInt.o: Global.h /usr/include/assert.h /usr/include/stdlib.h
ModInt.o: /usr/include/sgidefs.h /usr/include/limits.h
::::::::::::
oop/FiFo/Test.C
::::::::::::
10 // Test.cpp      testclass for OOP-classes
// (c) Ingmar Bitter '96

#include "Test.h"

15 void Test::Run() { FiFo<int>::Demo(); }

// end of Test.cpp
::::::::::::
oop/FiFo/Test.h
::::::::::::
20 // Test.h      test class for OOP-classes
// (c) Ingmar Bitter '96

#ifdef _Test_h_          // prevent multiple includes
#define _Test_h_

25 #include "FiFo.h"

class Test { public: static void Run(); };

30 #endif          // _Test_h_
::::::::::::
oop/FixPointNumber/FixPointNumber.C
::::::::::::
// FixPointNumber.cpp      class FixPointNumber
// (c) Ingmar Bitter '96 / Urs Kanus '97

35 // Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

#include "FixPointNumber.h"

40 char FixPointNumber::defaultFractionBits = 8;
char FixPointNumber::maxFractionBits = 32;

void FixPointNumber::Demo()
{
    double a(0.5);

    FixPointNumber k(2.5), m(k), n(k*k), p;
    FixPointNumber kp(2, 8), mp(kp), np(kp*kp);
50    FixPointNumber pp(2.5, 8);

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cout << endl <<"Demo of class " << typeid(k).name();
cout << endl <<"size : " << sizeof(FixPointNumber) << " Bytes";
cout << endl <<"public members:";
5 cout << endl <<"public member functions:";
cout << endl <<" double a(0.5) = "<<a;
cout << endl <<" FixPointNumber k(2.5), m(k), n(k*k), p = "<<k<<, "<<m<<,
"<<n<<", "<<p;
cout << endl <<"\t"<<Object::BoolStr[k==2.5 && m==2.5 && n==6.25 && p==0];
10 cout <<" k.FractionBits() = "<<(int)(k.FractionBits());
cout << endl
<<"\t"<<Object::BoolStr[(int)(k.FractionBits())==defaultFractionBits];
SetDefaultFractionBits(8); FixPointNumber test(2);
cout <<" SetDefaultFractionBits(8); FixPointNumber test(2);
test.FractionBits() = "<<(int)(test.FractionBits());
15 cout << endl <<"\t"<<Object::BoolStr[(int)(test.FractionBits())==8];
cout <<" FixPointNumber kp(2, 8), mp(kp), np(kp*kp), pp = "<<kp<<, "<<mp<<,
"<<np<<", "<<pp;
cout << endl <<"\t"<<Object::BoolStr[kp==2 && mp==2 && np==4 && pp==2.5];

cout <<" p(-8) = "<<p(-8);
20 cout << endl <<"\t"<<Object::BoolStr[p==8];

cout <<" k.Abs() = "<<k.Abs()<<"\tp.Abs() = "<<(p.Abs());
cout << endl <<"\t"<<Object::BoolStr[k.Abs()==2.5 && p.Abs()==8];

cout <<" k==k = "<<(k==k)<<"\tk==k = "<<(k==k)<<"\tk<k = "<<(k<k)
25 <<"\tk==9 = "<<(k==9)<<"\t9.<=k = "<<(9.<=k)<<"\tk<n =
"<<(k<n);
cout << endl <<"\t"<<Object::BoolStr[(k==k)==1 && (k<k)==1 && (k<k)==0 &&
(k==9)==0 && (9.<=k)==0 && (k<n)==1];

cout <<" k!=k = "<<(k!=k)<<"\tk>=k = "<<(k>=k)<<"\tk>k = "<<(k>k)
30 <<"\tk!=9 = "<<(k!=9)<<"\t9.>=k = "<<(9.>=k)<<"\tk>n =
"<<(k>n);
cout << endl <<"\t"<<Object::BoolStr[(k!=k)==0 && (k>=k)==1 && (k>k)==0 &&
(k!=9)==1 && (9.>=k)==1 && (k>n)==0];

cout <<" ++k = "<<(++k) <<"\tn+m = "<<(n+m);
35 cout <<"\tm+a = "<<(m+a) <<"\t\tp+=a = "<<(p+=a);
cout << endl <<"\t"<<Object::BoolStr[k==3.5 && (n+m)==8.75 && (m+a)==3 &&
p==7.5];

cout <<" k++ = "<<(k++) <<"\tn-m = "<<(n-m);
40 cout <<"\tm-a = "<<(m-a) <<"\t\tp-=a = "<<(p-=a);
cout << endl <<"\t"<<Object::BoolStr[k==4.5 && (n-m)==3.75 && (m-a)==2 &&
p==8];

cout <<" --k = "<<(--k) <<"\tn*m = "<<(n*m);
cout <<"\tm*a = "<<(m*a) <<"\tp*=a = "<<(p*=a);
45 cout << endl <<"\t"<<Object::BoolStr[k==3.5 && (n*m)==15.625 &&
(m*a)==1.25 && p==4];

cout <<" k-- = "<<(k--) <<"\tn/m = "<<(n/m);
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    cout << "\tm/a = " << (m/a) << "\t\tp/a = " << (p/a);
    cout << endl << "\t" << Object::BoolStr[k==2.5 && (n/m)==2.5 && (m/a)==5 &&
5 p==8];

    cout << " k+kp = " << (k+kp) << "\t k-kp = " << (k-kp);
    cout << "\t k*kp = " << (k*kp) << "\t k/kp = " << (k/kp);
    cout << endl << "\t" << Object::BoolStr[(k+kp)==4.5 && (k-kp)==0.5 && (k*kp)==5
&& (k/kp)==1.25];
10    cout << " k.Abs() = " << k.Abs() << "\tp.Abs() = " << p.Abs();
    cout << endl << "\t" << Object::BoolStr[k.Abs()==2.5 && p.Abs()==8];

    cout << " kp==kp = " << (kp==kp) << "\tkp<=kp = " << (kp<=kp) << "\tkp>kp = " << (kp>kp)
<< "\tkp==9 = " << (kp==9) << "\t9.<=kp = " << (9.<=kp) << "\tkp<np =
" << (kp<np);
15    cout << endl << "\t" << Object::BoolStr[(kp==kp)==1 && (kp<=kp)==1 &&
(kp>kp)==0 && (kp==9)==0 && (9.<=kp)==0 && (kp<np)==1];

    cout << " kp!=kp = " << (kp!=kp) << "\tkp>=kp = " << (kp>=kp) << "\tkp>kp = " << (kp>kp)
<< "\tkp!=9 = " << (kp!=9) << "\t9.>=kp = " << (9.>=kp) << "\tkp>np =
" << (kp>np);
20    cout << endl << "\t" << Object::BoolStr[(kp!=kp)==0 && (kp>=kp)==1 &&
(kp>kp)==0 && (kp!=9)==1 && (9.>=kp)==1 && (kp>np)==0];

    cout << " ++kp = " << (++kp) << "\tnp+mp = " << (np+mp);
    cout << "\tmp+a = " << (mp+a) << "\t\tp+a = " << (pp+a);
    cout << endl << "\t" << Object::BoolStr[kp==3 && (np+mp)==6 && (mp+a)==2.5 &&
25 pp==3];

    cout << " kp++ = " << (kp++) << "\tnp-mp = " << (np-mp);
    cout << "\tmp-a = " << (mp-a) << "\t\tp-a = " << (pp-a);
    cout << endl << "\t" << Object::BoolStr[kp==4 && (np-mp)==2 && (mp-a)==1.5 &&
30 pp==2.5];

    cout << " --kp = " << (--kp) << "\tnp*mp = " << (np*mp);
    cout << "\tmp*a = " << (mp*a) << "\tpp*a = " << (pp*a);
    cout << endl << "\t" << Object::BoolStr[kp==3 && (np*mp)==8 && (mp*a)==1 &&
35 pp==1.25];

    cout << " kp-- = " << (kp--) << "\tnp/mp = " << (np/mp);
    cout << "\tmp/a = " << (mp/a) << "\t\tp/a = " << (pp/a);
    cout << endl << "\t" << Object::BoolStr[kp==2 && (np/mp)==2 && (mp/a)==4 &&
40 pp==2.5];

    cout << " kp+=k = " << (kp+=k) << "\tk+=kp = " << (k+=kp);
    cout << endl << "\t" << Object::BoolStr[kp==4.5 && k==7];

    FixPointNumber round1(0.4,16), round2(0.5,16), round3(0.6,16);

    cout << " round1(0.4,16) = " << round1 << "\tround2(0.5,16) =
" << round2 << "\tround3(0.6,16) = " << round3;
    cout << endl << "\t" << Object::BoolStr[round1==round1 && round2>=round? &&
round3>=round3];
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    cout << " round1.Round(0) =
    "<<round1.Round(0)<<"\t\tround2.Round(0) =
5    "<<round2.Round(0)<<"\t\tround3.Round(0) = "<<round3.Round(0);
    cout << endl << "\t"<<Object::BoolStr[round1.Round(0)==0 && round2.Round(0)==1
    && round3.Round(0)==1];
    cout << " round1.Round(1) = "<<round1.Round(1)<<"\t\tround2.Round(1) =
    "<<round2.Round(1)<<"\t\tround3.Round(1) = "<<round3.Round(1);
    cout << endl << "\t"<<Object::BoolStr[round1.Round(1)==0.5 &&
10    round2.Round(1)==0.5 && round3.Round(1)==0.5];
    cout << " round1.Round(2) = "<<round1.Round(2)<<"\t\tround2.Round(2) =
    "<<round2.Round(2)<<"\t\tround3.Round(2) = "<<round3.Round(2);
    cout << endl << "\t"<<Object::BoolStr[round1.Round(2)==0.5 &&
    round2.Round(2)==0.5 && round3.Round(2)==0.5];
    cout << " round1.Round(3) = "<<round1.Round(3)<<"\t\tround2.Round(3) =
15    "<<round2.Round(3)<<"\t\tround3.Round(3) = "<<round3.Round(3);
    cout << endl << "\t"<<Object::BoolStr[round1.Round(3)==0.375 &&
    round2.Round(3)==0.5 && round3.Round(3)==0.625];

    FixPointNumber s( 255, 8);
20    cout << " FixPointNumber s( 255, 8); s>>8 = "<<(s>>8);
    cout << endl << "\t"<<Object::BoolStr[((s>>8) - 0.996094) < 0.00001];
    cout << " s<<8 = "<<(s<<8);
    cout << endl << "\t"<<Object::BoolStr[(s<<8)==65280];

    FixPointNumber doubleToFixP(0.847656 , 12);
25    cout << endl << " FixPointNumber doubleToFixP(0.847656 , 12) =
    "<<doubleToFixP;
    cout << endl << " double(doubleToFixP) = "<<double(doubleToFixP);
    FixPointNumber doubleToFix2(double(doubleToFixP), 8);
    cout << endl << " FixPointNumber doubleToFix2(double(doubleToFixP), 8) =";
    cout <<doubleToFix2;
30    cout << endl << "End of demo of class " << typeid(k).name() << endl;
    } // Demo

    ////////////////////////////////////////
35    // constructors & destructors

    FixPointNumber::FixPointNumber (const int k)
        : n(((FixPointData) k)<<defaultFractionBits),
        fractionBits(defaultFractionBits) { }

40    FixPointNumber::FixPointNumber (const int k, const char p)
        : n(((FixPointData) k)<<p), fractionBits(p) { }

    FixPointNumber::FixPointNumber (const FixPointData k)
        : n(k<<defaultFractionBits), fractionBits(defaultFractionBits) { }

45    FixPointNumber::FixPointNumber (const double x)
        : n(((FixPointData) (x * (1<<defaultFractionBits))),
        fractionBits(defaultFractionBits) { }

    FixPointNumber::FixPointNumber (const double x, const char p)
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                                384
        : n((FixPointData) (x * (1<<p))), fractionBits(p) { }

5      FixPointNumber::FixPointNumber      (const FixPointNumber & k)
        : n(k.n), fractionBits(k.fractionBits) { }

////////////////////////////////////
10     // show/set data & data properties
        //
        // - class Object requirements

        ostream & FixPointNumber::Ostream (ostream & os) const
            //{ return os << double(*this) << "." << int(fractionBits); }
15     { return os << double(*this); }

////////////////////////////////////
        // casts to other data types

20     FixPointNumber::operator double ( ) const { return double(n) / (1 <<
        fractionBits); }

////////////////////////////////////
        // show/set data & data properties
25     //
        // - class Object requirements

        double FixPointNumber::Norm ( ) const { return double(*this); }

30     //////////////////////////////////////
        // show/set data & data properties
        //
        // - local show/set functions

35     void FixPointNumber::SetDefaultFractionBits( const char p )
        { defaultFractionBits = p; }

        FixPointNumber FixPointNumber::Round ( const char p) const
        {
40         FixPointNumber temp;
            int fractionBitsDiff = fractionBits - p;
            bool round = false;
            int cutoffBit;
            if (fractionBitsDiff > 0) {
45                 cutoffBit = 1<<(fractionBitsDiff-1);
                    round = ((cutoffBit & n) == cutoffBit);
                    temp.n = (n>>fractionBitsDiff)+(int)round;
                    temp.fractionBits = p;
            }
            else {
50                 temp.n = n<<fractionBitsDiff;
                    temp.fractionBits = p;
            }
        }

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    }

    return temp;
5   }

    FixPointNumber FixPointNumber::Abs ( ) const
    { if (n<0) return FixPointNumber(((double)(-n))/(1<<fractionBits),
      fractionBits); else return *this; }

10   FixPointNumber & FixPointNumber::operator ( )      (const int k)
    {
        n=(k<<defaultFractionBits);
        fractionBits=defaultFractionBits;
        return *this;
15   }
    FixPointNumber & FixPointNumber::operator ( )      (const double x)
    {
        n=(FixPointData) (x * (1<<defaultFractionBits));
        fractionBits=defaultFractionBits;
        return *this;
20   }

    FixPointNumber  FixPointNumber::operator +      ( ) const
    { return FixPointNumber(n); }
    FixPointNumber  FixPointNumber::operator -      ( ) const
    { return FixPointNumber(-double(*this)); }
25   FixPointNumber & FixPointNumber::operator ++      ( ) { n += (1<<fractionBits);
    return *this; }
    FixPointNumber & FixPointNumber::operator ++      (int) { n += (1<<fractionBits);
    return *this; }
    FixPointNumber & FixPointNumber::operator --      ( ) { n -= (1<<fractionBits);
    return *this; }
    FixPointNumber & FixPointNumber::operator --      (int) { n -= (1<<fractionBits);
    return *this; }

    // change +=, -=, *=, /=
35   FixPointNumber & FixPointNumber::operator +=      (const FixPointNumber& k)
    {
        int fractionBitsDiff = fractionBits - k.fractionBits;

        if (fractionBitsDiff > 0)
            n += (k.n<<fractionBitsDiff);
40   else if (fractionBitsDiff < 0)
            n += (k.n>>(-fractionBitsDiff));
        else n += k.n;
        return *this;
    }
    FixPointNumber & FixPointNumber::operator -=      (const FixPointNumber& k)
45   { n -= k.n; return *this; }
    FixPointNumber & FixPointNumber::operator *=      (const FixPointNumber& k)
    { n=FixPointNumber(double(*this) * double(k)).n; return *this; }
    FixPointNumber & FixPointNumber::operator /=      (const FixPointNumber& k)

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{ n=FixPointNumber(double(*this) /      double(k)).n; return *this; }

5  FixPointNumber & FixPointNumber::operator +=      (const double& k)
   { n += FixPointNumber(k, fractionBits).n; return *this; }
   FixPointNumber & FixPointNumber::operator -=      (const double& k)
   { n -= FixPointNumber(k, fractionBits).n; return *this; }
   FixPointNumber & FixPointNumber::operator *=      (const double& k)
   { n=FixPointNumber(double(*this) * k, fractionBits).n; return *this; }
10  FixPointNumber & FixPointNumber::operator /=      (const double& k)
   { n=FixPointNumber(double(*this) / k, fractionBits).n; return *this; }

   FixPointNumber  FixPointNumber::operator +      (const FixPointNumber& k) const
   {
15     char resultFractionBits;

       if (fractionBits >= k.fractionBits)
           resultFractionBits = fractionBits;
       else
           resultFractionBits = k.fractionBits;

20     return FixPointNumber(double(*this) + double(k), resultFractionBits);
   }
   FixPointNumber  FixPointNumber::operator -      (const FixPointNumber& k) const
   {
25     char resultFractionBits;

       if (fractionBits >= k.fractionBits)
           resultFractionBits = fractionBits;
       else
           resultFractionBits = k.fractionBits;

30     return FixPointNumber(double(*this) - double(k), resultFractionBits);
   }

   FixPointNumber  FixPointNumber::operator *      (const FixPointNumber& k) const
   {
35     char resultFractionBits = fractionBits + k.fractionBits;

       if (resultFractionBits > maxFractionBits)
           return FixPointNumber(double(*this) * double(k), maxFractionBits);
       else
           return FixPointNumber(double(*this) * double(k),
40     resultFractionBits);
   }

   FixPointNumber  FixPointNumber::operator /      (const FixPointNumber& k) const
   {
45     char resultFractionBits;

       if (fractionBits >= k.fractionBits)
           resultFractionBits = fractionBits;
       else
           resultFractionBits = k.fractionBits;

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5      }
      return FixPointNumber(double(*this) / double(k), resultFractionBits);

      FixPointNumber    FixPointNumber::operator +      (const double& k) const
      {
          return FixPointNumber(double(*this) + k);
      }

10     FixPointNumber    FixPointNumber::operator -      (const double& k) const
      {
          return FixPointNumber(double(*this) - k);
      }

      FixPointNumber    FixPointNumber::operator *      (const double& k) const
15     {
          return FixPointNumber(double(*this) * k);
      }

      FixPointNumber    FixPointNumber::operator /      (const double& k) const
      {
          return FixPointNumber(double(*this) / k);
20     }

      int FixPointNumber::operator &      (const int k) const
      { FixPointNumber temp(*this); return (temp.n & k); }

      FixPointNumber    FixPointNumber::operator <<      (const int k) const
25     { FixPointNumber temp(*this); temp.n = temp.n<<k; return temp; }

      FixPointNumber    FixPointNumber::operator >>      (const int k) const
      { FixPointNumber temp(*this); temp.n = temp.n>>k; return temp; }

30     char              FixPointNumber::FractionBits( ) const { return fractionBits; }

      // end of FixPointNumber

      ::::::::::::::
35     oop/FixPointNumber/FixPointNumber.h
      ::::::::::::::
      // FixPointNumber.h          class FixPointNumber
      // (c) Ingmar Bitter '96 / Urs Kanus '97

      // Copyright, Mitsubishi Electric Information Technology Center
40     // America, Inc., 1997, All rights reserved.

      // Policy for determining precision of division results:
      // Use precision of the higher precision operand

45     #ifndef _FixPointNumber_h_          // prevent multiple includes
      #define _FixPointNumber_h_

      #include "Object.h"
      typedef long FixPointData;

```

```

class FixPointNumber : virtual public Object {
5 public:
    virtual void MoveRight() { n = n >> fractionBits; }

    static void      Demo ();

10    // constructors & destructors
    FixPointNumber (const int k);
    FixPointNumber (const int k, const char p);
    FixPointNumber (const FixPointData k=0);
    FixPointNumber (const double x);
    FixPointNumber (const double x, const char p);
15    FixPointNumber (const FixPointNumber & k);

    // casts to other data types
    virtual /*inline*/ operator double () const;

20    // show/set data & data properties
    // - class Object requirements
    virtual      ostream &  Ostream (ostream & ) const;

    // - class CmpObj requirements
    virtual double      Norm      ( )          const;
25    // - local show/set functions

    /*inline*/ static void SetDefaultFractionBits(const char p );

30    /*inline*/ virtual FixPointNumber Round (const char p) const;

    /*inline*/ virtual FixPointNumber Abs ( ) const;

    /*inline*/ virtual FixPointNumber & operator () (const int      k);
    /*inline*/ virtual FixPointNumber & operator () (const double x);
35    /*inline*/ virtual FixPointNumber      operator + ( ) const;
    /*inline*/ virtual FixPointNumber      operator - ( ) const;

    /*inline*/ virtual FixPointNumber & operator ++ ( );
    /*inline*/ virtual FixPointNumber & operator ++ (int);
40    /*inline*/ virtual FixPointNumber & operator -- ( );
    /*inline*/ virtual FixPointNumber & operator -- (int);

    /*inline*/ virtual FixPointNumber & operator += (const FixPointNumber& k);
    /*inline*/ virtual FixPointNumber & operator -= (const FixPointNumber& k);
45    /*inline*/ virtual FixPointNumber & operator *= (const FixPointNumber& k);
    /*inline*/ virtual FixPointNumber & operator /= (const FixPointNumber& k);

    /*inline*/ virtual FixPointNumber & operator += (const double& k);
    /*inline*/ virtual FixPointNumber & operator -= (const double& k);
50    /*inline*/ virtual FixPointNumber & operator *= (const double& k);
    /*inline*/ virtual FixPointNumber & operator /= (const double& k);

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5  /*inline*/ virtual FixPointNumber operator + (const FixPointNumber& k)
const;
/*inline*/ virtual FixPointNumber operator - (const FixPointNumber& k)
const;
/*inline*/ virtual FixPointNumber operator * (const FixPointNumber& k)
const;
10 /*inline*/ virtual FixPointNumber operator / (const FixPointNumber& k)
const;

/*inline*/ virtual FixPointNumber operator + (const double& k) const;
/*inline*/ virtual FixPointNumber operator - (const double& k) const;
/*inline*/ virtual FixPointNumber operator * (const double& k) const;
15 /*inline*/ virtual FixPointNumber operator / (const double& k) const;

/*inline*/ virtual int operator & (const int k) const;

/*inline*/ virtual FixPointNumber operator << (const int k) const;
20 /*inline*/ virtual FixPointNumber operator >> (const int k) const;

/*inline*/ virtual char FractionBits() const;

protected:
FixPointData n; // actual data
char fractionBits;
static char defaultFractionBits; // global default Precision
static char maxFractionBits;
}; // class FixPointNumber

30 #endif // _FixPointNumber_h_

::::::::::::
oop/FixPointNumber/Makefile
::::::::::::
35 # Makefile for C++ programs (c) Ingmar Bitter '97
#
# make : compile only changed files and their depend
files
# make all : recompile all
# make clean : recompile all and remove unnecessary files
40 #

EXECUTABLE = go

45 SRC = main.C Test.C Object.C FixPointNumber.C

RM = /bin/rm -fs

#
# put -g here | to add debugging info to executable
#
V
CDEBUGFLAGS = -O -OPT:Olimit=2299
55

```

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oop/FixPointNumber/Test.h
::::::::::::
5 // Test.h      test class for OOP-classes
// (c) Ingmar Bitter '96

#ifndef _Test_h_      // prevent multiple includes
#define _Test_h_

10 #include "FixPointNumber.h"

class Test { public: static void Run(); };

#endif      // _Test_h_
::::::::::::
15 oop/Int/Global.h
::::::::::::
// Global.h      Global definitions
// (c) Ingmar Bitter '96

// Copyright, Mitsubishi Electric Information Technology Center
20 // America, Inc., 1997, All rights reserved.

#ifndef _Global_h_      // prevent multiple includes
#define _Global_h_

#include <assert.h>
25 #include <iostream.h> // ostream
#include <typeinfo.h> // typeid(obj).name()
#include <stdlib.h> // exit()

//const unsigned char true      = 1
30 //const unsigned char false   = 0

#define Max(a,b) ((a) > (b)) ? (a) : (b)
#define Min(a,b) ((a) < (b)) ? (a) : (b)
#define ABS(a) ((a) < 0) ? -(a) : (a)

35 // #define ERROR(str) { cerr << endl << (str) << " exiting ..." << endl; int
k=999999, a[1]={1}; cout << a[k]; }
#define ERROR(msg) { cerr << endl << "###Error### in file " << __FILE__ << " at
line " << __LINE__ << endl; cerr << (msg) << endl; cerr << "Exiting ..." <<
endl; abort(); }

40 // avoid following warning
// "/usr/include/CC/iostream.h", line 675: remark(1174):
// variable "iostream_init" was declared but never referenced
// } iostream_init ;
#include <iostream.h>
static void Dummy () { static void * dummy = &iostream_init; cout << dummy;
45 Dummy(); }

#endif      // _Global_h_
::::::::::::

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Int::operator int() const { return n; }

5 //////////////////////////////////////////////////
// show/set data & data properties
//
// - class Object requirements

ostream & Int::Ostream (ostream & os) const { return os << n; }

10 //////////////////////////////////////////////////
// show/set data & data properties
//
// - class Object requirements

15 double Int::Norm ( ) const { return double(n); }

//////////////////////////////////////////////////
// show/set data & data properties
20 //
// - local show/set functions

Int Int::Abs ( ) const { return Int((n<0) ? -n : n); }

25 Int & Int::operator () (const int k) { n=k; return *this; }

Int Int::operator + ( ) const { return Int(n); }
Int Int::operator - ( ) const { return Int(-n); }

Int Int::operator ++ ( ) { ++n; return *this; }
30 Int Int::operator ++ (int) { ++n; return *this; }
Int Int::operator -- ( ) { --n; return *this; }
Int Int::operator -- (int) { --n; return *this; }

Int & Int::operator += (const Int& k) { n+=k.n; return *this; }
Int & Int::operator -= (const Int& k) { n-=k.n; return *this; }
35 Int & Int::operator *= (const Int& k) { n*=k.n; return *this; }
Int & Int::operator /= (const Int& k) { n/=k.n; return *this; }

Int Int::operator + (const Int& k) const { return Int(n+k.n); }
Int Int::operator - (const Int& k) const { return Int(n-k.n); }
Int Int::operator * (const Int& k) const { return Int(n*k.n); }
40 Int Int::operator / (const Int& k) const { return Int(n/k.n); }

double Int::operator + (const double& x) const { return (n+x); }
double Int::operator - (const double& x) const { return (n-x); }
double Int::operator * (const double& x) const { return (n*x); }
45 double Int::operator / (const double& x) const { return (n/x); }

// define friend functions
double operator + (const double& x, const Int& k) { return x+k.n; }
}

```

```

                                394
double      operator - (const double& x, const Int& k) {      return x-k.n;
    }
5 double      operator * (const double& x, const Int& k)      {      return x*k.n;
    }
double      operator / (const double& x, const Int& k)      {      return x/k.n;
    }

10 Int      operator + (const int n,                          const Int& k)      {
    return n+k.n;      }
Int      operator - (const int n,                          const Int& k)      {
    return n-k.n;      }
Int      operator * (const int n,                          const Int& k)      {
    return n*k.n;      }
15 Int      operator / (const int n,                          const Int& k)      {
    return n/k.n;      }

double & operator += (double& x, const Int& k)      {      return x+=k.n; }
double & operator -= (double& x, const Int& k)      {      return x-=k.n; }
double & operator *= (double& x, const Int& k)      {      return x*=k.n; }
20 double & operator /= (double& x, const Int& k)      {      return x/=k.n; }

int &      operator += (int n,                          const Int& k)      {
    return n+=k.n; }
int &      operator -= (int n,                          const Int& k)      {      return
25 n-=k.n; }
int &      operator *= (int n,                          const Int& k)      {      return
n*=k.n; }
int &      operator /= (int n,                          const Int& k)      {      return
n/=k.n; }

30 // end of Int

:::
oop/Int/Int.h
:::
// Int.h      class Int
35 // (c) Ingmar Bitter '96

#ifdef _Int_h_      // prevent multiple includes
#define _Int_h_

40 #include "Object.h"

class Int : virtual public Object {
public:
    static void      Demo ();

45 // constructors & destructors
    inline Int (const int k=0);
    inline Int (const Int & k);
    inline Int (const Int * k);

50

55

```

```

5      // casts to other data types
      virtual inline operator int() const;

      // show/set data & data properties
      // - class Object requirements
      virtual ostream &   Ostream (ostream & )   const;

10     // - class CmpObj requirements
      virtual double      Norm      ( )          const;

      // - local show/set functions
      virtual inline Int Abs ( ) const;

15     virtual inline Int &      operator () (const int k); // set function
      virtual inline Int      operator +  ( ) const;
      virtual inline Int      operator -  ( ) const;
      virtual inline Int      operator ++ ( );
20     virtual inline Int      operator ++ (int);
      virtual inline Int      operator -- ( );
      virtual inline Int      operator -- (int);
      virtual inline Int &      operator += (const Int& k);
      virtual inline Int &      operator -= (const Int& k);
25     virtual inline Int &      operator *= (const Int& k);
      virtual inline Int &      operator /= (const Int& k);
      virtual inline Int      operator +  (const Int& k)      const;
      virtual inline Int      operator -  (const Int& k)      const;
      virtual inline Int      operator *   (const Int& k)      const;
      virtual inline Int      operator /   (const Int& k)      const;
30     virtual inline double    operator +  (const double& x)  const;
      virtual inline double    operator -  (const double& x)  const;
      virtual inline double    operator *   (const double& x)  const;
      virtual inline double    operator /   (const double& x)  const;

35     friend double    operator +  (const double& x, const Int& k);
      friend double    operator -  (const double& x, const Int& k);
      friend double    operator *   (const double& x, const Int& k);
      friend double    operator /   (const double& x, const Int& k);
      friend Int       operator +  (const int n, const Int& k);
40     friend Int       operator -  (const int n, const Int& k);
      friend Int       operator *   (const int n, const Int& k);
      friend Int       operator /   (const int n, const Int& k);
      friend double &   operator += (double& x, const Int& k);
      friend double &   operator -= (double& x, const Int& k);
45     friend double &   operator *= (double& x, const Int& k);
      friend double &   operator /= (double& x, const Int& k);
      friend int &      operator += (int n, const Int& k);
      friend int &      operator -= (int n, const Int& k);
      friend int &      operator *= (int n, const Int& k);
      friend int &      operator /= (int n, const Int& k);

50     protected:
      int n;
}; // class INT

```

55

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```

// Object.h      class Object      abstract base class for
everything
5 // (c) Ingmar Bitter '96

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

10 #ifndef _Object_h_      // prevent multiple includes
#define _Object_h_

#include <string.h>    // strcmp
#include <iostream.h>
#include "Global.h"

15 class Object {
public:
    static void      Demo ( );

    // show/set data & data properties
20     virtual /*inline*/ ostream & Ostream (ostream & os) const;
    friend ostream & operator << (ostream & os, const Object & obj);
    friend ostream & operator << (ostream & os, const Object * obj);

public:
25     static const char * BoolStr[];

}; // class Object

#ifdef      // _Object_h_
30 :::::::::::::::
oop/Int/Test.C
:::::::::::::
// Test.cpp      testclass for OOP-classes
// (c) Ingmar Bitter '96

35 #include "Test.h"

void Test::Run() { Int::Demo(); }

// end of Test.cpp
40 :::::::::::::::
oop/Int/Test.h
:::::::::::::
// Test.h      test class for OOP-classes
// (c) Ingmar Bitter '96

45 #ifndef _Test_h_      // prevent multiple includes
#define _Test_h_

#include "Int.h"

50 class Test { public: static void Run(); };

```

55

```

5      #endif          // _Test__h_
      : : : : : : : : : :
      oop/Int/main.C
      : : : : : : : : : :
      // main.cpp
      // (c) Ingmar Bitter '97

10     #include "Test.h"

      main() { Test::Run(); } // main

      // end of main.cpp
15     : : : : : : : : : :
      oop/Int/main.h
      : : : : : : : : : :
      // main.h

      // Copyright, Mitsubishi Electric Information Technology Center
20     // America, Inc., 1997, All rights reserved.

      : : : : : : : : : :
      oop/Matrix4x4/Makefile
      : : : : : : : : : :
25     #      Makefile for C++ programs (c) Ingmar Bitter '97
      #
      #      make                  : compile only changed files and their depend
      files
      #      make all              : recompile all
30     #      make clean          : recompile all and remove unnecessary files
      #

      EXECUTABLE = go

      SRC      = main.C Test.C Object.C Vector3D.C Matrix4x4.C
35     RM = /bin/rm -fs

      #
      #      put -g here | to add debugging info to executable
      #                  V
40     CDEBUGFLAGS = -O
      CCOPTIONS   = -64

      CC = CC

45     INCLUDES    =
      LIBS        = -lm
      CFLAGS      = $(CCOPTIONS) $(CDEBUGFLAGS) $(INCLUDES)

      OFILES =      $(SRC:.C=.o)

50     $(EXECUTABLE): $(OFILES)

```

55


```

399
$(CC) $(OFILES) $(CFLAGS) $(LIBS) -o $(EXECUTABLE)

5  #
  # target: dependency \n tab rule
  #
  .C.o:
        $(CC) $(CFLAGS) -c $<

10  #
  # switch:: ; \n tab rule
  #
  clean:
        ;
        find . -name "*.o" -print -exec mv {} ~/dumpster \; ;
        find . -name "*" -print -exec mv {} ~/dumpster \; ;
15  find . -name "go" -print -exec mv {} ~/dumpster \; ;
        find . -name "core" -print -exec mv {} ~/dumpster \; ;

  all:
        ;
        pmake -u

20  depend:
        makedepend -- $(CFLAGS) -- $(SRC)

  # DO NOT DELETE

25  main.o: Test.h Matrix4x4.h /usr/include/math.h /usr/include/sgidefs.h
  main.o: /usr/include/standards.h Object.h /usr/include/string.h Global.h
  main.o: /usr/include/assert.h Vector3D.h
  Test.o: Test.h Matrix4x4.h /usr/include/math.h /usr/include/sgidefs.h
  Test.o: /usr/include/standards.h Object.h /usr/include/string.h Global.h
30  Test.o: /usr/include/assert.h Vector3D.h
  Object.o: Object.h /usr/include/string.h /usr/include/standards.h Global.h
  Object.o: /usr/include/assert.h
  Vector3D.o: Vector3D.h /usr/include/math.h /usr/include/sgidefs.h
  Vector3D.o: /usr/include/standards.h Object.h /usr/include/string.h Global.h
  Vector3D.o: /usr/include/assert.h
35  Matrix4x4.o: Matrix4x4.h /usr/include/math.h /usr/include/sgidefs.h
  Matrix4x4.o: /usr/include/standards.h Object.h /usr/include/string.h Global.h
  Matrix4x4.o: /usr/include/assert.h Vector3D.h
  .....
  oop/Matrix4x4/Matrix4x4.C
  .....
40  // Matrix4x4.cpp
  // (c) Ingmar Bitter '96

  // Copyright, Mitsubishi Electric Information Technology Center
  // America, Inc., 1997, All rights reserved.

45  #include "Matrix4x4.h"

  template <class _T_> void Matrix4x4<_T_>::Demo()
  {
    Matrix4x4<_T_> a, b(1,0,0,0, 0,2,0,0, 0,0,3,0, 0,0,0,1);

50

55

```

```

400
    cout << endl << "Demo of class " << typeid(a).name();
    cout << endl << "size : " << sizeof(Matrix4x4<_T_>) << " Bytes";
5    cout << endl << "public member functions:";
    cout << endl << " "<<typeid(a).name()<<" a, b(3,2,1); == " << a << ", "<<
    &b;
    /*
        cout << endl << " a<b;\t== " << (a<b) << "\t a<=b;\t== " <<
        (a<=b)<< "\ta==b;\t== " << (a==b);
10    cout << endl << " a>b;\t== " << (a>b) << "\t a>=b;\t== " <<
        (a>=b)<< "\ta!=b;\t== " << (a!=b);
    */
        cout << endl << " a=b;\t== " << (a=b);
        cout << endl << " +a;\t== " << (+a) ; // << "\t a+b;\t== " << (a+b);
        cout << endl << " -a;\t== " << (-a) ; // << "\t a-b;\t== " << (a-b);
15    /*
        cout << endl << " a+=b;\t== " << (a+=b);
        cout << endl << " a-=b;\t== " << (a-=b);
        _T_ s; s = (_T_) 2.5;
        cout << endl << " "<<typeid(s).name()<<" s(2.5);\t== "<< s;
        cout << endl << " a*s;\t== " << (a*s) << "\t a*=s;\t== " << (a*=s);
20    */
        Vector3D<_T_> v(2.5,2.5,2.5);
        cout << endl << " "<<typeid(v).name()<<" v(2.5,2.5,2.5);\t== "<< v ;
        cout << endl << " a*v;\t== " << (a*v);
    /*
25    cout << endl << " a.Determinant();\t== " << a.Determinant();
        cout << endl << " a.Det();\t== " << a.Det();
        cout << endl << " a.D();\t== " << a.D();
        cout << endl << " a.Transpose();\t== " << a.Transpose();
        cout << endl << " a.Trans();\t== " << a.Trans();
        cout << endl << " a.T();\t== " << a.T();
30    cout << endl << " a.Inverse();\t== " << a.Inverse();
        cout << endl << " a.Inv();\t== " << a.Inv();
        cout << endl << " a.I();\t== " << a.I();
    */

        cout << endl << "End of demo of class " << typeid(a).name() << endl;
35    } // Demo

    //////////////////////////////////////
    // constructors & destructors

40

template <class _T_> Matrix4x4<_T_>::Matrix4x4 ()
{
    element[0][0] = 1; element[1][0] = 0; element[2][0] = 0; element[3][0]
= 0;
45    element[0][1] = 0; element[1][1] = 1; element[2][1] = 0; element[3][1]
= 0;
    element[0][2] = 0; element[1][2] = 0; element[2][2] = 1; element[3][2]
= 0;

50

55

```

```

401
    element[0][3] = 0; element[1][3] = 0; element[2][3] = 0; element[3][3]
= 1;
5   } // constructor

template <class _T_> Matrix4x4<_T_>::Matrix4x4 (const _T_ & ax, const _T_ & bx,
const _T_ & cx, const _T_ & dx,
10   const _T_ &
ay, const _T_ & by, const _T_ & cy, const _T_ & dy,
const _T_ &
15   const _T_ &
az, const _T_ & bz, const _T_ & cz, const _T_ & dz,
const _T_ &
15   const _T_ &
aw, const _T_ & bw, const _T_ & cw, const _T_ & dw)
{
    element[0][0] = ax; element[1][0] = bx; element[2][0] = cx;
element[3][0] = dx;
    element[0][1] = ay; element[1][1] = by; element[2][1] = cy;
20   element[3][1] = dy;
    element[0][2] = az; element[1][2] = bz; element[2][2] = cz;
element[3][2] = dz;
    element[0][3] = aw; element[1][3] = bw; element[2][3] = cw;
element[3][3] = dw;
25   } // constructor

template <class _T_> Matrix4x4<_T_>::Matrix4x4(const Matrix4x4<_T_> & matrix)
{
    register int m,k;
30   for (m=0; m<4; ++m)
        for (k=0; k<4; ++k)
            element[m][k] = matrix.element[m][k];
} // copy-constructor

35   ////////////////////////////////////////
// casts to other data types

template <class _T_> Matrix4x4<_T_>::operator double() const { return Norm(); }

40   ////////////////////////////////////////
// show/set data & data properties
//
// - class Object requirements

45   template <class _T_> ostream & Matrix4x4<_T_>::Ostream(ostream & os) const
{
    os << "{ ";
    for (int m=0; m<4; ++m) {
50
55

```

402

```

5         os << "(";
        for (int k=0; k<4; ++k) {
            os << element[m][k];
            if (k<3) os << ",";
        }
        os << ")^T";
        if (m<3) os << ", ";
10    } os << " )";
        return os;
    } // Ostream

//////////////////////////////////////
15    // show/set data & data properties
    //
    // - class CmpObj requirements

20    template <class _T_> double Matrix4x4<_T_>::Norm() const
    {
        return Determinant();
    } // Norm

25    ////////////////////////////////////////
    // show/set data & data properties
    //
    // - local show/set functions

30    template <class _T_> Matrix4x4<_T_> & Matrix4x4<_T_>::operator ()
        (const _T_ & ax, const _T_ & bx, const _T_ & cx, const _T_ & dx,
         const _T_ & ay, const _T_ & by, const _T_ & cy, const _T_ & dy,
         const _T_ & az, const _T_ & bz, const _T_ & cz, const _T_ & dz,
         const _T_ & aw, const _T_ & bw, const _T_ & cw, const _T_ & dw)
35    {
        element[0][0] = ax;  element[1][0] = bx;  element[2][0] = cx;
        element[3][0] = dx;
        element[0][1] = ay;  element[1][1] = by;  element[2][1] = cy;
        element[3][1] = dy;
        element[0][2] = az;  element[1][2] = bz;  element[2][2] = cz;
40    element[3][2] = dz;
        element[0][3] = aw;  element[1][3] = bw;  element[2][3] = cw;
        element[3][3] = dw;
        return *this;
    } // operator ()

45

    template <class _T_> Matrix4x4<_T_>  Matrix4x4<_T_>::operator + () const {
        return Matrix4x4(*this);
    }
    template <class _T_> Matrix4x4<_T_>  Matrix4x4<_T_>::operator - () const
50    {

```

55

```

403
    return Matrix4x4( -element[0][0], -element[1][0], -element[2][0], -
element[3][0],
5
    -element[0][1], -
    element[1][1], -element[2][1], -element[3][1],
    -element[0][2], -
    element[1][2], -element[2][2], -element[3][2],
    -element[0][3], -
    element[1][3], -element[2][3], -element[3][3]);
10
} // // operator +

template <class _T_> Matrix4x4<_T_> Matrix4x4<_T_>::operator + (const
Matrix4x4<_T_> & m) const
{ cerr <<m<< "\n\n sorry, + not implemented \n\n"; return Matrix4x4();
15
} // operator +
template <class _T_> Matrix4x4<_T_> Matrix4x4<_T_>::operator - (const
Matrix4x4<_T_> & m) const
{ cerr <<m<< "\n\n sorry, - not implemented \n\n"; return Matrix4x4();
} // operator -

20
template <class _T_> Matrix4x4<_T_> & Matrix4x4<_T_>::operator +=(const
Matrix4x4<_T_> & m)
{ cerr <<m<< "\n\n sorry, += not implemented \n\n"; return *this;
} // operator +=
template <class _T_> Matrix4x4<_T_> & Matrix4x4<_T_>::operator -=(const
Matrix4x4<_T_> & m)
25
{ cerr <<m<< "\n\n sorry, -= not implemented \n\n"; return *this;
} // operator -=
/*
template <class _T_> Matrix4x4<_T_> Matrix4x4<_T_>::operator * (const _T_ & a)
const
{ cerr << "\n\n sorry, * not implemented \n\n"; return Matrix4x4();
30
} // operator *
*/
template <class _T_> Matrix4x4<_T_> Matrix4x4<_T_>::operator / (const _T_ & a)
const
{ cerr <<a<< "\n\n sorry, / not implemented \n\n"; return Matrix4x4();
35
} // operator /

template <class _T_> Matrix4x4<_T_> & Matrix4x4<_T_>::operator *=(const _T_ & a)
{ cerr <<a<< "\n\n sorry, *= not implemented \n\n"; return *this;
} // operator *=
template <class _T_> Matrix4x4<_T_> & Matrix4x4<_T_>::operator /=(const _T_ & a)
40
{ cerr <<a<< "\n\n sorry, /= not implemented \n\n"; return *this;
} // operator /=
/*
template <class _T_> Matrix4x4<_T_> Matrix4x4<_T_>::operator * (const
Matrix4x4<_T_> & m) const
{ cerr <<m<< "\n\n sorry, * not implemented \n\n"; return Matrix4x4();
45
} // operator *
*/
template <class _T_> Matrix4x4<_T_> & Matrix4x4<_T_>::operator *=(const
Matrix4x4<_T_> & m)

```

50

55

```

404
{ cerr << "sorry, *= not implemented\n\n"; return *this;
} // operator *=

5
template <class _T_> Vector3D<_T_> Matrix4x4<_T_>::operator * (const
Vector3D<_T_> &v) const
{
    _T_ w(element[0][3]*v.X() + element[1][3]*v.Y() + element[2][3]*v.Z() +
    element[3][3]);
10
    return Vector3D<_T_>((element[0][0]*v.X() + element[1][0]*v.Y() +
    element[2][0]*v.Z() + element[3][0])/w,

    (element[0][1]*v.X() + element[1][1]*v.Y() + element[2][1]*v.Z() +
    element[3][1])/w,

15
    (element[0][2]*v.X() + element[1][2]*v.Y() + element[2][2]*v.Z() +
    element[3][2])/w);
} // operator *

template <class _T_> Vector3D<double> Matrix4x4<_T_>::operator * (const
Vector3D<double> &v) const
20
{
    double w(element[0][3]*v.X() + element[1][3]*v.Y() + element[2][3]*v.Z() +
    element[3][3]);
    return Vector3D<double>((element[0][0]*v.X() + element[1][0]*v.Y() +
    element[2][0]*v.Z() + element[3][0])/w,

25
    (element[0][1]*v.X() + element[1][1]*v.Y() + element[2][1]*v.Z() +
    element[3][1])/w,

    (element[0][2]*v.X() + element[1][2]*v.Y() + element[2][2]*v.Z() +
    element[3][2])/w);
30
} // operator *

template <class _T_> Vector3D<FixPointNumber> Matrix4x4<_T_>::operator * (const
Vector3D<FixPointNumber> &v) const
{
    FixPointNumber w(element[0][3]*v.X() + element[1][3]*v.Y() +
    element[2][3]*v.Z() + element[3][3]);
35
    return Vector3D<FixPointNumber>((element[0][0]*v.X() + element[1][0]*v.Y()
    + element[2][0]*v.Z() + element[3][0])/w,

    (element[0][1]*v.X() + element[1][1]*v.Y() +
    element[2][1]*v.Z() + element[3][1])/w,

40
    (element[0][2]*v.X() + element[1][2]*v.Y() +
    element[2][2]*v.Z() + element[3][2])/w);
} // operator *

template <class _T_> _T_ Matrix4x4<_T_>::Determinant( ) const { return D(); } //
Determinant
45
template <class _T_> _T_ Matrix4x4<_T_>::Det( ) const { return D(); } //
Det
template <class _T_> _T_ Matrix4x4<_T_>::D( ) const

```

```

405
{ cerr << "\n\n sorry, Det() not      implemented \n\n"; return _T();
5   } // D

template <class _T> Matrix4x4<_T> Matrix4x4<_T>::Transpose ( ) const {
return T(); } // Transpose
template <class _T> Matrix4x4<_T> Matrix4x4<_T>::Trans      ( ) const {
return T(); } // Trans
10  template <class _T> Matrix4x4<_T> Matrix4x4<_T>::T          ( ) const
{ cerr << "\n\n sorry, Trans() not implemented \n\n"; return Matrix4x4();
} // T

template <class _T> Matrix4x4<_T> Matrix4x4<_T>::Inverse ( ) const { return
T(); } // Inverse
15  template <class _T> Matrix4x4<_T> Matrix4x4<_T>::Inv      ( ) const { return
T(); } // Inv
template <class _T> Matrix4x4<_T> Matrix4x4<_T>::I          ( ) const
{ cerr << "\n\n sorry, Inv() not implemented \n\n"; return Matrix4x4();
} // I

20  // end of Matrix4x4.cpp
:::::::::::
oop/Matrix4x4/Matrix4x4.h
:::::::::::
25  // Matrix4x4.h
// (c) Ingmar Bitter '96

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

30  #ifndef _Matrix4x4_h_ // prevent multiple includes
#define _Matrix4x4_h_

#include <math.h>
#include "Object.h"
#include "Vector3D.h"
35  #include "FixPointNumber.h"

template <class _T> class Matrix4x4 : public virtual Object {
public:
40  static void Demo ();

// constructors & destructors
/*inline*/ Matrix4x4 ();
/*inline*/ Matrix4x4 (const _T_ & ax, const _T_ & bx, const _T_ & cx,
const _T_ & dx,
45  const _T_ & ay,
const _T_ & by, const _T_ & cy, const _T_ & dy,
const _T_ & az,
const _T_ & bz, const _T_ & cz, const _T_ & dz,
50
55

```

406

const _T_ & aw,

```

const _T_ & bw, const _T_ & cw, const _T_ & dw);
5      /*inline*/ Matrix4x4 (const Matrix4x4<_T_> & matrix);

      // casts to other data types
      virtual /*inline*/ operator double() const;

      // show/set data & data properties
10     // - class Object requirements
      virtual          ostream &  Ostream (ostream & )    const;

      // - class CmpObj requirements
      virtual /*inline*/ double Norm ( ) const;

15     // - local show/set functions
      virtual /*inline*/ Matrix4x4<_T_> & operator ( ) (const _T_ & ax, const _T_
& bx, const _T_ & cx, const _T_ & dx,
                                                    const _T_ & ay, const _T_
20     & by, const _T_ & cy, const _T_ & dy,
                                                    const _T_ & az, const _T_
& bz, const _T_ & cz, const _T_ & dz,
                                                    const _T_ & aw, const _T_
25     & bw, const _T_ & cw, const _T_ & dw);

      virtual /*inline*/ Matrix4x4<_T_>  operator +  ( ) const;
      virtual /*inline*/ Matrix4x4<_T_>  operator -  ( ) const;

      virtual /*inline*/ Matrix4x4<_T_>  operator +  (const Matrix4x4<_T_> &)
30     const;
      virtual /*inline*/ Matrix4x4<_T_>  operator -  (const Matrix4x4<_T_> &)
const;
      virtual /*inline*/ Matrix4x4<_T_> & operator += (const Matrix4x4<_T_> &);
      virtual /*inline*/ Matrix4x4<_T_> & operator -= (const Matrix4x4<_T_> &);

35     // virtual /*inline*/ Matrix4x4<_T_>  operator *  (const _T_ &) const;
      virtual /*inline*/ Matrix4x4<_T_>  operator /  (const _T_ &) const;
      virtual /*inline*/ Matrix4x4<_T_> & operator *= (const _T_ &);
      virtual /*inline*/ Matrix4x4<_T_> & operator /= (const _T_ &);

      // virtual          Matrix4x4<_T_>  operator *  (const Matrix4x4<_T_> &) const;
40     virtual          Matrix4x4<_T_> & operator *= (const Matrix4x4<_T_> &);
      virtual          Vector3D<_T_>  operator *  (const Vector3D<_T_> &) const;
      virtual          Vector3D<double> operator *  (const Vector3D<double> &) const;
      virtual          Vector3D<FixPointNumber> operator *  (const
Vector3D<FixPointNumber> &) const;

45     virtual /*inline*/ _T_          Determinant ( ) const;
      virtual /*inline*/ _T_          Det          ( ) const;
      virtual          _T_          D              ( ) const;
      virtual /*inline*/ Matrix4x4<_T_>  Transpose   ( ) const;

```

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                                407
virtual /*inline*/ Matrix4x4<_T_>      Trans      ( ) const;
virtual      Matrix4x4<_T_>      T      ( ) const;
5 virtual /*inline*/ Matrix4x4<_T_>      Inverse      ( ) const;
virtual /*inline*/ Matrix4x4<_T_>      Inv      ( ) const;
virtual      Matrix4x4<_T_>      I      ( ) const;
protected:
    _T_ element[4][4];
}; // class Matrix4x4

10 #endif      // _Matrix4x4_h_
    ::::::::::::::
oop/Matrix4x4/Test.C
    ::::::::::::::
// Test.cpp      testclass for OOP-classes
15 // (c) Ingmar Bitter '96

#include "Test.h"

void Test::Run() { Matrix4x4<int>::Demo(); }

20 // end of Test.cpp
    ::::::::::::::
oop/Matrix4x4/Test.h
    ::::::::::::::
// Test.h      test class for OOP-classes
// (c) Ingmar Bitter '96

25 #ifndef _Test_h_      // prevent multiple includes
#define _Test_h_

#include "Matrix4x4.h"

30 class Test { public: static void Run(); };

#endif      // _Test_h_
    ::::::::::::::
oop/ModInt/Int.C
    ::::::::::::::
35 // Int.cpp      class Int
// (c) Ingmar Bitter '96

#include "Int.h"

40 void Int::Demo()
{
    double a(2.2);
    Int k(3), m(k), n(k*k), p;
    cout << endl <<"Demo of class " << typeid(k).name();
    cout << endl <<"size : " << sizeof(Int) << " Bytes";
45    cout << endl <<"public members: - none";
    cout << endl <<"public member functions:";
    cout << endl <<" double a(2.2) = "<<a;
    cout << endl <<" Int k(3), m(k), n(k*k), p = "<<k<<, "<<m<<, "<<n<<, "<<p;

```

50

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```

    cout << endl << "  p(-8) = "<<p(- 8);
    cout << endl << "  k.Abs() = "<< k.Abs()<<"\tp.Abs() = "<< p.Abs();

5    cout << endl << "  k==k = "<<(k==k)<<"\tk==k = "<<(k==k)<<"\tk<k = "<<(k<k)
    <<"\tk==9 = "<<(k==9)<<"\t9.<=k = "<<(9.<=k)<<"\tk<n =
    "<<(k<n);
    cout << endl << "  k!=k = "<<(k!=k)<<"\tk>=k = "<<(k>=k)<<"\tk>k = "<<(k>k)
    <<"\tk!=9 = "<<(k!=9)<<"\t9.>=k = "<<(9.>=k)<<"\tk>n =
10    "<<(k>n);

    cout << endl << "  ++k = "<<(++k) <<"\tm+n = "<<(m+n);
    cout << endl << "  <<"\tm+a = "<<(m+a) <<"\tp+=n = "<<(p+=n);
    cout << endl << "  k++ = "<<(k++) <<"\tm-n = "<<(m-n);
    cout << endl << "  <<"\tm-a = "<<(m-a) <<"\tp-=n = "<<(p-=n);
15    cout << endl << "  --k = "<<(--k) <<"\tm*n = "<<(m*n);
    cout << endl << "  <<"\tm*a = "<<(m*a) <<"\ta*=p = "<<(a*=p);
    cout << endl << "  k-- = "<<(k--) <<"\tm/n = "<<(m/n);
    cout << endl << "  <<"\tm/a = "<<(m/a)<<"\ta/=p = "<<(a/=p);

20    Int array[5]; cout<< endl;
    for (k(0); k<5; ++k)
        cout << " array["<<k<<"] = "<<(array[k] = k);
    cout << endl <<"End of demo of class " << typeid(k).name() << endl;
}    //    Demo

25

////////////////////////////////////
// constructors & destructors

Int::Int    (const int    k) : n(k)    { }
30 Int::Int    (const Int & k) : n(k.n)    { }
Int::Int    (const Int * k) : n(k->n) { }

////////////////////////////////////
// casts to other data types

35 Int::operator int() const { return n; }

////////////////////////////////////
// show/set data & data properties
//
40 // - class Object requirements

ostream &    Int::Ostream (ostream & os) const { return os << n; }

////////////////////////////////////
45 // show/set data & data properties
//
// - class Object requirements

double Int::Norm ( ) const { return double(n); }

50

55

```

```

5 ///////////////////////////////////////////////////////////////////
// show/set data & data properties
//
// - local show/set functions

Int Int::Abs ( ) const { return Int((n<0) ? -n : n); }

10 Int & Int::operator ( ) (const int k) { n=k; return *this; }

Int Int::operator + ( ) const { return Int(n); }
Int Int::operator - ( ) const { return Int(-n); }

15 Int Int::operator ++ ( ) { ++n; return *this; }
Int Int::operator ++ (int) { ++n; return *this; }
Int Int::operator -- ( ) { --n; return *this; }
Int Int::operator -- (int) { --n; return *this; }

20 Int Int::operator += (const Int& k) { n+=k.n; return *this; }
Int Int::operator -= (const Int& k) { n-=k.n; return *this; }
Int Int::operator *= (const Int& k) { n*=k.n; return *this; }
Int Int::operator /= (const Int& k) { n/=k.n; return *this; }

Int Int::operator + (const Int& k) const { return Int(n+k.n); }
Int Int::operator - (const Int& k) const { return Int(n-k.n); }
25 Int Int::operator * (const Int& k) const { return Int(n*k.n); }
Int Int::operator / (const Int& k) const { return Int(n/k.n); }

double Int::operator + (const double& x) const { return (n+x); }
double Int::operator - (const double& x) const { return (n-x); }
double Int::operator * (const double& x) const { return (n*x); }
30 double Int::operator / (const double& x) const { return (n/x); }

// define friend functions
double operator + (const double& x, const Int& k) { return x+k.n; }
double operator - (const double& x, const Int& k) { return x-k.n; }
35 double operator * (const double& x, const Int& k) { return x*k.n; }
double operator / (const double& x, const Int& k) { return x/k.n; }

40 Int operator + (const int n, const Int& k) {
return n+k.n; }
Int operator - (const int n, const Int& k) {
return n-k.n; }
Int operator * (const int n, const Int& k) {
45 return n*k.n; }
Int operator / (const int n, const Int& k) {
return n/k.n; }

double & operator += (double& x, const Int& k) { return x+=k.n; }

```

50

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```

                                410
double & operator -= (double& x,      const Int& k)      {      return x-=k.n;
}
5  double & operator *= (double& x, const Int& k)      {      return x*=k.n; }
double & operator /= (double& x, const Int& k)      {      return x/=k.n; }

int  &      operator += (int n,      const Int& k)      {
    return n+=k.n; }
int  &      operator -= (int n,      const Int& k)      {      return
10  n-=k.n; }
int  &      operator *= (int n,      const Int& k)      {      return
n*=k.n; }
int  &      operator /= (int n,      const Int& k)      {      return
n/=k.n; }

15

// end of Int

:::::::::::::
oop/ModInt/Int.h
:::::::::::::
20 // Int.h      class Int
// (c) Ingmar Bitter '96

#ifdef _Int_h_      // prevent multiple includes
#define _Int_h_

25

#include "Object.h"
#include <typeinfo.h>

class Int : virtual public Object {
30 public:
    static void      Demo ();

    // constructors & destructors
    inline Int (const int      k=0);
    inline Int (const Int & k);
35  inline Int (const Int * k);

    // casts to other data types
    virtual inline operator int() const;

    // show/set data & data properties
    // - class Object requirements
40  virtual ostream &      Ostream (ostream & )      const;

    // - class CmpObj requirements
    virtual double      Norm      ( )      const;

45  // - local show/set functions
    virtual inline Int Abs ( ) const;

    virtual inline Int &      operator () (const int k); // set function

50

55

```

```

411
virtual inline Int      operator + ( ) const;
virtual inline Int      operator - ( ) const;
5 virtual inline Int      operator ++ ( );
virtual inline Int      operator ++ (int);
virtual inline Int      operator -- ( );
virtual inline Int      operator -- (int);
virtual inline Int      operator += (const Int& k);
10 virtual inline Int      operator -= (const Int& k);
virtual inline Int      operator *= (const Int& k);
virtual inline Int      operator /= (const Int& k);
    virtual inline Int      operator + (const Int& k)          const;
virtual inline Int      operator - (const Int& k)          const;
15 virtual inline Int      operator * (const Int& k)          const;
virtual inline Int      operator / (const Int& k)          const;
    virtual inline double  operator + (const double& x)      const;
virtual inline double  operator - (const double& x)      const;
virtual inline double  operator * (const double& x)      const;
20 virtual inline double  operator / (const double& x)      const;

    friend double  operator + (const double& x, const Int& k);
friend double  operator - (const double& x, const Int& k);
friend double  operator * (const double& x, const Int& k);
25 friend double  operator / (const double& x, const Int& k);
friend Int      operator + (const int n, const Int& k);
friend Int      operator - (const int n, const Int& k);
friend Int      operator * (const int n, const Int& k);
friend Int      operator / (const int n, const Int& k);
friend double & operator += (double& x, const Int& k);
30 friend double & operator -= (double& x, const Int& k);
friend double & operator *= (double& x, const Int& k);
friend double & operator /= (double& x, const Int& k);
friend int & operator += (int n, const Int& k);
friend int & operator -= (int n, const Int& k);
35 friend int & operator *= (int n, const Int& k);
friend int & operator /= (int n, const Int& k);
protected:
    int n;
}; // class INT

40

#endif // _Int_h_

:::::::::::::
oop/ModInt/Makefile
45 :::::::::::::::
#      Makefile for C++ programs (c) Ingmar Bitter '97
#
#      make          : compile only changed files and their depend files
#      make all       : recompile all
#      make clean     : recompile all and remove unnecessary files
50 #
EXECUTABLE = go

```

```

SRC  = main.C Test.C Object.C ModInt.C
5
RM = /bin/rm -fs

#
#   put -g here | to add debugging info to executable
#               V
10
CDEBUGFLAGS = -O
#CCOPTIONS  = -64
CCOPTIONS    = -n32 -mips4 -r10000

CC = CC
15
INCLUDES    =
LIBS        =
CFLAGS      = $(CCOPTIONS) $(CDEBUGFLAGS) $(INCLUDES)

20
OFILES = $(SRC:.C=.o)

$(EXECUTABLE): $(OFILES)
                $(CC) $(OFILES) $(CFLAGS) $(LIBS) -o $(EXECUTABLE)

#
#   target: dependency \n tab rule
#
.C.o:
                $(CC) $(CFLAGS) -c $<

30
#
#   switch:: ; \n tab rule
#
clean:
                ;
                find . -name "*.o" -print -exec rm {} \; ;
                find . -name "*~" -print -exec rm {} \; ;
35
                find . -name "go" -print -exec rm {} \; ;
                find . -name "core" -print -exec rm {} \; ;

all:
                ;
                pmake -u

40
depend:
                makedepend -- $(CFLAGS) -- $(SRC)

# DO NOT DELETE

45
main.o: Test.h ModInt.h Object.h /usr/include/string.h
main.o: /usr/include/standards.h Global.h /usr/include/assert.h
main.o: /usr/include/stdlib.h /usr/include/sgidefs.h /usr/include/limits.h
Test.o: Test.h ModInt.h Object.h /usr/include/string.h
Test.o: /usr/include/standards.h Global.h /usr/include/assert.h
Test.o: /usr/include/stdlib.h /usr/include/sgidefs.h /usr/include/limits.h
50
Object.o: Object.h /usr/include/string.h /usr/include/standards.h Global.h

```

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```

Object.o: /usr/include/assert.h          /usr/include/stdlib.h
/usr/include/sgidefs.h
5  ModInt.o: ModInt.h Object.h /usr/include/string.h /usr/include/standards.h
ModInt.o: Global.h /usr/include/assert.h /usr/include/stdlib.h
ModInt.o: /usr/include/sgidefs.h /usr/include/limits.h
::::::::::::
oop/ModInt/ModInt.C
::::::::::::
10 // ModInt.C class ModInt
// (c) Hanspeter Pfister '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

15 #include "ModInt.h"

void ModInt::Demo()
{
    ModInt k(3), l(5,3), m(1), n;

20     cout << endl << "Demo of class " << typeid(k).name();
    cout << endl << "size : " << sizeof(ModInt) << " Bytes";
    cout << endl << "public members: - none";
    cout << endl << "public member functions:";

25     cout << endl << "Constructors";

    cout << endl << "  ModInt k(3), l(5,3), m(1), n = "<<k<< ", "<<l<< ", "<<m<< ",
"<<n;
        cout << endl << Object::BoolStr[k==3 && l==2 && m==2 && n==0];

30     cout << endl << "  k(0,3), k(1,3), k(2,3), k(3,3), k(4,3) = "
        <<k(0,3)<< ", "<<k(1,3)<< ", "<<k(2,3)<< ", "<<k(3,3)<< ", "<<k(4,3);
        cout << endl << Object::BoolStr[k(0,3)==0 && k(1,3)==1 && k(2,3)==2 &&
k(3,3)==0 && k(4,3)==1];

        cout << endl << "  k(0,4), k(1,4), k(2,4), k(3,4), k(4,4) = "
35         <<k(0,4)<< ", "<<k(1,4)<< ", "<<k(2,4)<< ", "<<k(3,4)<< ", "<<k(4,4);
        cout << endl << Object::BoolStr[k(0,4)==0 && k(1,4)==1 && k(2,4)==2 &&
k(3,4)==3 && k(4,4)==0];

        cout << endl << "  k(-1,3), k(-2,3), k(-3,3), k(-4,3) = "
        <<k(-1,3)<< ", "<<k(-2,3)<< ", "<<k(-3,3)<< ", "<<k(-4,3);
40     cout << endl << Object::BoolStr[k(-1,3)==2 && k(-2,3)==1 && k(-3,3)==0 &&
k(-4,3)==2];

        cout << endl << "  k.Abs() = "<< k.Abs();
        cout << endl << Object::BoolStr[k.Abs()==2];

45     cout << endl << "Comparisons";

    cout << endl << "  k==k = "<<(k==k)<< "\tk==k = "<<(k==k)<< "\tk<k = "<<(k<k)
        << "\tk==9 = "<<(k==9)<< "\tk9.<=k = "<<(9.<=k)<< "\tk<n = "<<(k<n);

```

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    cout << endl <<
    && (k<k)==0 && (k==9)==0
    && (9.<=k)==0 && (k<n)==0];

    cout << endl << " k!=k = "<<(k!=k)<<"\tk>=k = "<<(k>=k)<<"\tk>k = "<<(k>k)
    <<"\tk!=9 = "<<(k!=9)<<"\t9.>=k = "<<(9.>=k)<<"\tk>n = "<<(k>n);
    cout << endl << Object::BoolStr[(k!=k)==0 && (k>=k)==1 && (k>k)==0 &&
    (k!=9)==1
    && (9.>=k)==1 && (k>n)==1];

    cout << endl << "Unary Operators";

    cout << endl << " ++k = "<<(++k);
    cout << endl << Object::BoolStr[k==0];
    cout << endl << " k++ = "<<(k++);
    cout << endl << Object::BoolStr[k==1];
    cout << endl << " --k = "<<(--k);
    cout << endl << Object::BoolStr[k==0];
    cout << endl << " k-- = "<<(k--);
    cout << endl << Object::BoolStr[k==2];
    cout << endl << " k-- = "<<(k--);
    cout << endl << Object::BoolStr[k==1];
    cout << endl << " k-- = "<<(k--);
    cout << endl << Object::BoolStr[k==0];
    cout << endl << " k-- = "<<(k--);
    cout << endl << Object::BoolStr[k==2];
    cout << endl << " k-- = "<<(k--);
    cout << endl << Object::BoolStr[k==1];

    cout << endl << "ModInt op ModInt";
    k(1,5);
    n(2,5);
    cout << endl << " k = " << k << "\tn = " << n;

    cout << endl << " k+=n = "<<(k+=n);
    cout << endl << Object::BoolStr[k==3];
    cout << endl << " k*=n = "<<(k*=n);
    cout << endl << Object::BoolStr[k==1];
    cout << endl << " k-=n = "<<(k-=n);
    cout << endl << Object::BoolStr[k==4];
    cout << endl << " k/=n = "<<(k/=n);
    cout << endl << Object::BoolStr[k==2];

    k(4,5);
    n(2,5);
    cout << endl << " k = " << k << "\tn = " << n;

    cout << endl << " k+n = "<<(k+n) <<"\tk-n = "<<(k-n);
    cout << endl << " \tk*n = "<<(k*n) <<"\tk/n = "<<(k/n);
    cout << endl << Object::BoolStr[(k+n)==1 && (k-n)==2 && (k*n)==3 &&
    (k/n)==2];

    cout << endl << "ModInt op double";

```


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k(4,5);
double a(2.2);
5  cout << endl << " k = " << k << "\ta = " << a;

    cout << endl << " k+=a = "<<(k+=a);
    cout << endl << Object::BoolStr[k==1];
    cout << endl << " k-=a = "<<(k-=a);
10   cout << endl << Object::BoolStr[k==4];
    cout << endl << " k*=a = "<<(k*=a);
    cout << endl << Object::BoolStr[k==3];
    cout << endl << " k/=a = "<<(k/=a);
    cout << endl << Object::BoolStr[k==1];

15   cout << endl << " k+a = "<<(k+a) << "\tk-a = "<<(k-a);
    cout << "\tk*a = "<<(k*a) << "\tk/a = "<<(k/a);
    cout << endl << Object::BoolStr[(k+a)==3 && (k-a)==4 &&
        (k*a)==2 && (k/a)==0];

20   cout << endl << "double op ModInt";
    k(4,5);
    cout << endl << " k = " << k << "\ta = " << a;

    cout << endl << " a+k = "<<(a+k) << "\ta-k = "<<(a-k);
    cout << "\ta*k = "<<(a*k) << "\ta/k = "<<(a/k);
25   cout << endl << Object::BoolStr[(a+k)==(2.2+4) && (a-k)==(2.2-4) &&
        (a*k)==(2.2*4) && (a/k)==(2.2/4)];

    cout << endl << " a+=k = "<<(a+=k);
    cout << endl << Object::BoolStr[a==6.2];
30   cout << endl << " a-=k = "<<(a-=k);
    cout << endl << Object::BoolStr[a==2.2];
    cout << endl << " a*=k = "<<(a*=k);
    cout << endl << Object::BoolStr[a==8.8];
    cout << endl << " a/=k = "<<(a/=k);
35   cout << endl << Object::BoolStr[a==2.2];

    ModInt array[6];
    int i = 0;
    for (k(0); i<10; ++k, ++i)
40     cout << endl << " array["<<k<<"] = "<<(array[k] = k);

    cout << endl << "End of demo of class " << typeid(k).name() << endl;
}    // Demo

//////////////////////////////////////
45 // MyMod: Calculate modulus for neg numbers, too.

int ModInt::MyMod (int n, unsigned int m)
{
    while ( n < 0 ) {
50       n += m;
    }
    return ( n % m );
}
55

```

```

}

5  //////////////////////////////////////////////////
  // constructors & destructors

  ModInt::ModInt (const int k, const unsigned int modulus)
    : n(MyMod(k, modulus)), m(modulus) { }
  ModInt::ModInt (const ModInt & k)
10  : n(MyMod(k.n, k.m)), m(k.m) { }
  ModInt::ModInt (const ModInt * k)
    : n(MyMod(k->n, k->m)), m(k->m) { }

  //////////////////////////////////////////////////
15  // casts to other data types

  ModInt::operator int() const { return n; }

  //////////////////////////////////////////////////
  // show/set data & data properties
20  //
  // - class Object requirements

  ostream & ModInt::Ostream (ostream & os) const { return (os << n << ":" << m); }

  //////////////////////////////////////////////////
25  // show/set data & data properties
  //
  // - class Object requirements

  double ModInt::Norm ( ) const { return double(n); }

30  //////////////////////////////////////////////////
  // show/set data & data properties
  //
  // - local show/set functions

35  ModInt ModInt::Abs ( ) const { return ModInt((n<0) ? -n : n); }

  ModInt & ModInt::operator () (const int k, const unsigned int modulus)
  {
40    n = MyMod(k, modulus);
    m = modulus;
    return *this;
  }

  ModInt & ModInt::operator () (const int k)
45  {
    n = MyMod(k, m);
    return *this;
  }

  //////////////////////////////////////////////////
50

```

55

```

// operators
//
5 // Unary operators
ModInt ModInt::operator + ( ) const { return ModInt(n); }
ModInt ModInt::operator - ( ) const { return ModInt(-n); }
ModInt & ModInt::operator ++ ( ) { n = ++n % m; return *this; }
ModInt & ModInt::operator ++ (int) { n = ++n % m; return *this; }
10 ModInt & ModInt::operator -- ( ) { n = MyMod(--n, m); return *this; }
ModInt & ModInt::operator -- (int) { n = MyMod(--n, m); return *this; }

// ModInt op ModInt
ModInt & ModInt::operator += (const ModInt& k) { n = MyMod((n+k.n), m); return
*this; }
15 ModInt & ModInt::operator -= (const ModInt& k) { n = MyMod((n-k.n), m); return
*this; }
ModInt & ModInt::operator *= (const ModInt& k) { n = MyMod((n*k.n), m); return
*this; }
ModInt & ModInt::operator /= (const ModInt& k) { n = MyMod((n/k.n), m); return
20 *this; }
ModInt ModInt::operator + (const ModInt& k) const { return ModInt(n+k.n, m);
}
ModInt ModInt::operator - (const ModInt& k) const { return ModInt(n-k.n, m);
}
ModInt ModInt::operator * (const ModInt& k) const { return ModInt(n*k.n, m);
25 }
ModInt ModInt::operator / (const ModInt& k) const { return ModInt(n/k.n, m);
}

// ModInt op double
30 ModInt & ModInt::operator += (const double& x) { n = MyMod((n+x), m); return
*this; }
ModInt & ModInt::operator -= (const double& x) { n = MyMod((n-x), m); return
*this; }
ModInt & ModInt::operator *= (const double& x) { n = MyMod((n*x), m); return
*this; }
35 ModInt & ModInt::operator /= (const double& x) { n = MyMod((n/x), m); return
*this; }
ModInt ModInt::operator + (const double& x) const { return ModInt(n+x, m); }
ModInt ModInt::operator - (const double& x) const { return ModInt(n-x, m); }
ModInt ModInt::operator * (const double& x) const { return ModInt(n*x, m); }
ModInt ModInt::operator / (const double& x) const { return ModInt(n/x, m); }
40

// double op ModInt
double & operator += (double& x, const ModInt& k) { return x+=k.n; }
double & operator -= (double& x, const ModInt& k) { return x-=k.n; }
double & operator *= (double& x, const ModInt& k) { return x*=k.n; }
double & operator /= (double& x, const ModInt& k) { return x/=k.n; }
45 double
operator + (const double& x, const ModInt& k) { return x+k.n;
}
double
operator - (const double& x, const ModInt& k) { return x-k.n;
}

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double      operator * (const double& x, const ModInt& k)      { return
x*k.n;      }
double      operator / (const double& x, const ModInt& k)      { return x/k.n;
5      }

// ModInt op int
ModInt & ModInt::operator =      (const int& i) { n = MyMod(i, m); return
*this; }
10 ModInt & ModInt::operator += (const int& i) { n = MyMod((n+i), m); return
*this; }
ModInt & ModInt::operator -= (const int& i) { n = MyMod((n-i), m); return
*this; }
ModInt & ModInt::operator *= (const int& i) { n = MyMod((n*i), m); return
*this; }
15 ModInt & ModInt::operator /= (const int& i) { n = MyMod((n/i), m); return
*this; }
ModInt ModInt::operator +      (const int& i) const { return ModInt(n+i, m); }
ModInt ModInt::operator -      (const int& i) const { return ModInt(n-i, m); }
ModInt ModInt::operator *      (const int& i) const { return ModInt(n*i, m); }
20 ModInt ModInt::operator /      (const int& i) const { return ModInt(n/i, m); }

// int op ModInt
int & operator += (int& i, const ModInt& k)      { return i+=k.n; }
int & operator -= (int& i, const ModInt& k)      { return i-=k.n; }
int & operator *= (int& i, const ModInt& k)      { return i*=k.n; }
25 int & operator /= (int& i, const ModInt& k)      { return i/=k.n; }
int operator + (const int& i, const ModInt& k)      { return i+k.n; }
int operator - (const int& i, const ModInt& k)      { return i-k.n; }
int operator * (const int& i, const ModInt& k)      { return i*k.n; }
int operator / (const int& i, const ModInt& k)      { return i/k.n; }

30 // ModInt op long
ModInt & ModInt::operator += (const long& i) { n = MyMod((n+i), m); return
*this; }
ModInt & ModInt::operator -= (const long& i) { n = MyMod((n-i), m); return
*this; }
ModInt & ModInt::operator *= (const long& i) { n = MyMod((n*i), m); return
35 *this; }
ModInt & ModInt::operator /= (const long& i) { n = MyMod((n/i), m); return
*this; }
ModInt ModInt::operator +      (const long& i) const { return ModInt(n+i, m); }
ModInt ModInt::operator -      (const long& i) const { return ModInt(n-i, m); }
ModInt ModInt::operator *      (const long& i) const { return ModInt(n*i, m); }
40 ModInt ModInt::operator /      (const long& i) const { return ModInt(n/i, m); }

// long op ModInt
long & operator +=      (long& i, const ModInt& k)      { return i+=k.n; }
long & operator -=      (long& i, const ModInt& k)      { return i-=k.n; }
45 long & operator *=      (long& i, const ModInt& k)      { return i*=k.n; }
long & operator /=      (long& i, const ModInt& k)      { return i/=k.n; }
long operator + (const long& i, const ModInt& k)      { return i+k.n; }
long operator - (const long& i, const ModInt& k)      { return i-k.n; }
long operator * (const long& i, const ModInt& k)      { return i*k.n; }

```

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long operator / (const long& i, const ModInt& k) { return i/k.n; }

5 // end of ModInt

:::
oop/ModInt/ModInt.h
:::
// ModInt.h      class ModInt
10 // (c) Hanspeter Pfister '97

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

15 #ifndef _ModInt_h_           // prevent multiple includes
#define _ModInt_h_

#include "Object.h"
#include <iostream.h>
#include <typeinfo.h>
20 #include <limits.h>

class ModInt : virtual public Object {
public:
    static void Demo ();
25
    // constructors & destructors
    ModInt (const int k=0, const unsigned int modulus=INT_MAX);
    ModInt (const ModInt & k);
    ModInt (const ModInt * k);

30
    // casts to other data types
    virtual operator int() const;

    // show/set data & data properties
    // - class Object requirements
35 virtual ostream & Ostream (ostream & os) const;

    // - class CmpObj requirements
    virtual double Norm ( ) const;

    // - local show/set functions
40 virtual ModInt Abs ( ) const;

    virtual ModInt & operator () (const int k); // set function
    virtual ModInt & operator () (const int k, const unsigned int modulus);

    // Unary operators
45 virtual ModInt operator + ( ) const;
    virtual ModInt operator - ( ) const;
    virtual ModInt & operator ++ ( );
    virtual ModInt & operator ++ (int);
    virtual ModInt & operator -- ( );
50

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```
virtual ModInt & operator -- (int);
```

```

5      // ModInt op ModInt
virtual ModInt & operator += (const ModInt& k);
virtual ModInt & operator -= (const ModInt& k);
virtual ModInt & operator *= (const ModInt& k);
virtual ModInt & operator /= (const ModInt& k);
10     virtual ModInt operator + (const ModInt& k)      const;
virtual ModInt operator - (const ModInt& k)      const;
virtual ModInt operator * (const ModInt& k)      const;
virtual ModInt operator / (const ModInt& k)      const;

15     // ModInt op double
virtual ModInt & operator += (const double& x);
virtual ModInt & operator -= (const double& x);
virtual ModInt & operator *= (const double& x);
virtual ModInt & operator /= (const double& x);
20     virtual ModInt operator + (const double& x)      const;
virtual ModInt operator - (const double& x)      const;
virtual ModInt operator * (const double& x)      const;
virtual ModInt operator / (const double& x)      const;

// double op ModInt
25     friend double & operator += (double& x, const ModInt& k);
friend double & operator -= (double& x, const ModInt& k);
friend double & operator *= (double& x, const ModInt& k);
friend double & operator /= (double& x, const ModInt& k);
30     friend double operator + (const double& x, const ModInt& k);
friend double operator - (const double& x, const ModInt& k);
friend double operator * (const double& x, const ModInt& k);
friend double operator / (const double& x, const ModInt& k);

// ModInt op int
35     virtual ModInt & operator = (const int& i);
virtual ModInt & operator += (const int& i);
virtual ModInt & operator -= (const int& i);
virtual ModInt & operator *= (const int& i);
virtual ModInt & operator /= (const int& i);
40     virtual ModInt operator + (const int& i)      const;
virtual ModInt operator - (const int& i)      const;
virtual ModInt operator * (const int& i)      const;
virtual ModInt operator / (const int& i)      const;

// int op ModInt
45     friend int & operator += (int& i, const ModInt& k);
friend int & operator -= (int& i, const ModInt& k);
friend int & operator *= (int& i, const ModInt& k);
friend int & operator /= (int& i, const ModInt& k);
50     friend int operator + (const int& i, const ModInt& k);
friend int operator - (const int& i, const ModInt& k);
friend int operator * (const int& i, const ModInt& k);
friend int operator / (const int& i, const ModInt& k);

```

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```

// ModInt op long
virtual ModInt & operator += (const long& i);
virtual ModInt & operator -= (const long& i);
virtual ModInt & operator *= (const long& i);
virtual ModInt & operator /= (const long& i);
virtual ModInt operator + (const long& i) const;
virtual ModInt operator - (const long& i) const;
virtual ModInt operator * (const long& i) const;
virtual ModInt operator / (const long& i) const;

// long op ModInt
friend long & operator += (long& i, const ModInt& k);
friend long & operator -= (long& i, const ModInt& k);
friend long & operator *= (long& i, const ModInt& k);
friend long & operator /= (long& i, const ModInt& k);
friend long operator + (const long& i, const ModInt& k);
friend long operator - (const long& i, const ModInt& k);
friend long operator * (const long& i, const ModInt& k);
friend long operator / (const long& i, const ModInt& k);

protected:
    int n;
    unsigned int m;

private:
    int MyMod(int n, unsigned int m);

}; // class MODINT

#endif // _ModInt_h_

:::
oop/ModInt/Test.C
:::
// Test.cpp testclass for OOP-classes
// (c) Ingmar Bitter '96

#include "Test.h"

void Test::Run() { ModInt::Demo(); }

// end of Test.cpp
:::
oop/ModInt/Test.h
:::
// Test.h test class for OOP-classes
// (c) Ingmar Bitter '96

#ifndef _Test_h_ // prevent multiple includes
#define _Test_h_

#include "ModInt.h"

```

```

class Test { public: static void Run(); };

5  #endif      // _Test__h_
   :::::::::::::
   oop/Timer/Makefile
   :::::::::::::
10  #      Makefile for C++ programs (c) Ingmar Bitter '97
   #
   #      make          : compile only changed files and their depend
   files
   #      make all      : recompile all
   #      make clean    : recompile all and remove unnecessary files
   #
15  EXECUTABLE = go

   SRC = main.C Test.C Object.C Timer.C

20  RM = /bin/rm -fs

   #
   #      put -g here | to add debugging info to executable
   #                      V
   CDEBUGFLAGS = -g
25  CCOPTIONS  = -64

   CC = CC

   INCLUDES =
   LIBS =
30  CFLAGS = $(CCOPTIONS) $(CDEBUGFLAGS) $(INCLUDES)

   OFILES = $(SRC:.C=.o)

   $(EXECUTABLE): $(OFILES)
35  $(CC) $(OFILES) $(CFLAGS) $(LIBS) -o $(EXECUTABLE)

   #
   #      target: dependency \n tab rule
   #
   .C.o:
40  $(CC) $(CFLAGS) -c $<

   #
   #      switch:: ; \n tab rule
   #
   clean:
45  ;
      find . -name "*.o" -print -exec mv {} ~/dumpster \; ;
      find . -name "*~" -print -exec mv {} ~/dumpster \; ;
      find . -name "go" -print -exec mv {} ~/dumpster \; ;
      find . -name "core" -print -exec mv {} ~/dumpster \; ;

```

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all: ;

                                pmake -u

5  depend:

                                make depend -- $(CFLAGS) -- $(SRC)

# DO NOT DELETE

10  main.o: Test.h Timer.h /usr/include/sys/time.h /usr/include/standards.h
    main.o: /usr/include/sgidefs.h /usr/include/sys/times.h
    main.o: /usr/include/sys/types.h /usr/include/unistd.h /usr/include/stdlib.h
    main.o: Object.h /usr/include/string.h Global.h /usr/include/assert.h
    Test.o: Test.h Timer.h /usr/include/sys/time.h /usr/include/standards.h
    Test.o: /usr/include/sgidefs.h /usr/include/sys/times.h
15  Test.o: /usr/include/sys/types.h /usr/include/unistd.h /usr/include/stdlib.h
    Test.o: Object.h /usr/include/string.h Global.h /usr/include/assert.h
    Object.o: Object.h /usr/include/string.h /usr/include/standards.h Global.h
    Object.o: /usr/include/assert.h
    Timer.o: Timer.h /usr/include/sys/time.h /usr/include/standards.h
20  Timer.o: /usr/include/sgidefs.h /usr/include/sys/times.h
    Timer.o: /usr/include/sys/types.h /usr/include/unistd.h /usr/include/stdlib.h
    Timer.o: Object.h /usr/include/string.h Global.h /usr/include/assert.h
    : : : : : : : : : :
    oop/Timer/Test.C
    : : : : : : : : : :
25  // Test.cpp      testclass for OOP-classes
    // (c) Ingmar Bitter '96

    #include "Test.h"

30  void Test::Run()          { Timer::Demo(); }

    // end of Test.cpp
    : : : : : : : : : :
    oop/Timer/Test.h
    : : : : : : : : : :
35  // Test.h          test class for OOP-classes
    // (c) Ingmar Bitter '96

    #ifndef _Test_h_          // prevent multiple includes
    #define _Test_h_

40  #include "Timer.h"

    class Test { public: static void Run(); };

    #endif          // _Test_h_
45  : : : : : : : : : :
    oop/Timer/Timer.C
    : : : : : : : : : :
    // Timer.C
    // (c) Ingmar Bitter '96

50

55

```

// Copyright, Mitsubishi Electric Information Technology Center
 // America, Inc., 1997, All rights reserved.

```

5  #include "Timer.h"

void Timer::Demo()
{
    // this demo only gives ok results with -g (-O optimizes the loops away)
10  Timer timer;
    cout << endl << "Demo of class " << typeid(timer).name();
    cout << endl << "size : " << sizeof(Timer) << " Bytes";
    cout << endl << "public member functions:";
        long k,n(10000000);
15  for (k=0; k<n; ++k) ;
    cout << endl << " This is a running Timer: " << timer;
    for (k=0; k<n; ++k) ;
    cout << endl << " ... still running: " << timer;
    for (k=0; k<n; ++k) ;
    cout << endl << " timer.Stop(): " << timer.Stop();
20  for (k=0; k<n; ++k) ;
    cout << endl << " ... still stopped: " << timer;
    cout << endl << " timer.Restart(): " << timer.Restart();
    for (k=0; k<n; ++k) ;
    cout << endl << " timer.ElapsedTime(): " << timer.ElapsedTime();
    cout << endl << " timer: " << timer;
25  cout << endl << "End of demo of class " << typeid(timer).name() << endl;
} // Demo

////////////////////////////////////
30 // constructors & destructors

Timer::Timer()
    : timerIsRunning(false)
{
    // start timer
35  Restart();
} // constructor

////////////////////////////////////
40 // show/set data & data properties
//
// - class Object requirements

ostream & Timer::Ostream(ostream & os) const
{
45  // append Timer info to os
        double t(ElapsedTime());

        double sec (t - int(t) + int(t)%60);
        double min (int(t)/60%60);
50  double hour(int(t)/60/60);

```

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```

5      os << "time:" <<t<< "s = "<<hour<<"h "<<min<<"min "<<sec<<"s";

      // return complete os
      return os;

} // Ostream

10  //////////////////////////////////////
// show/set data & data properties
//
// - local show/set functions

15  Timer & Timer::Restart()
{
    times(& startTime);
    timerIsRunning = true;
    return *this;
20 } // Restart

double Timer::ElapsedTime() const
{
    if (!timerIsRunning)
        return runningTime;

    // get current time for time snapshot
    struct tms currentTime, elapsedTime;
    times(& currentTime);
    elapsedTime.tms_utime = currentTime.tms_utime - startTime.tms_utime;
30  elapsedTime.tms_stime = currentTime.tms_stime - startTime.tms_stime;
    elapsedTime.tms_cutime = currentTime.tms_cutime - startTime.tms_cutime;
    elapsedTime.tms_cstime = currentTime.tms_cstime - startTime.tms_cstime;
    double seconds = elapsedTime.tms_utime + elapsedTime.tms_stime
        + elapsedTime.tms_cutime+ elapsedTime.tms_cstime;
35  seconds /= (double)CLK_TCK;
    return seconds;
} // ElapsedTime

40  Timer & Timer::Stop()
{
    runningTime = ElapsedTime();
    timerIsRunning = false;
    return *this;
45 } // Stop

// end of Timer.C
::::::::::::
oop/Timer/Timer.h
::::::::::::
50

```

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```

// Timer.h
// (c) Ingmar Bitter '96

5 // Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

// Timer to track program running time (only real system time, not wall clock
time)

10 #ifndef _Timer_h_ // prevent multiple includes
#define _Timer_h_

#include <sys/time.h>
15 #include <sys/times.h>
#include <unistd.h>

#include "Object.h"

20 class Timer : virtual public Object {
public:
    static void      Demo ();

    // constructors & destructors
    /*inline*/      Timer      ();

25 // show/set data & data properties
// - class Object requirements
    virtual /*inline*/ ostream & Ostream (ostream &) const;

    // - local show/set functions
30 virtual /*inline*/ Timer & Restart      ();
    virtual /*inline*/ double ElapsedTime () const;
    virtual /*inline*/ Timer & Stop      ();
protected:
    bool      timerIsRunning;
35 double      runningTime;
    struct tms      startTime;
};

#endif // _Timer_h_
40 ::::::::::::::
oop/Vector3D/Makefile
::::::::::::
# Makefile for C++ programs (c) Ingmar Bitter '97
#
# make : compile only changed files and their depend
45 files
# make all : recompile all
# make clean : recompile all and remove unnecessary files
#

EXECUTABLE = go
50

```

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```

SRC    = main.C Test.C Object.C Vector3D.C

5  RM = /bin/rm -fs

#
#    put -g here | to add debugging info to executable
#
10 CDEBUGFLAGS = -O
CCOPTIONS    = -64

CC = CC

INCLUDES    =
15 LIBS      = -lm
CFLAGS      = $(CCOPTIONS) $(CDEBUGFLAGS) $(INCLUDES)

OFILES = $(SRC:.C=.o)

20 $(EXECUTABLE): $(OFILES)
                        $(CC) $(OFILES) $(CFLAGS) $(LIBS) -o $(EXECUTABLE)

#
#    target: dependency \n tab rule
#
25 .C.o:
                        $(CC) $(CFLAGS) -c $<

#
#    switch:: ; \n tab rule
#
30 clean:
                        ;
                        find . -name "*.o" -print -exec mv {} ~/dumpster \; ;
                        find . -name "*~" -print -exec mv {} ~/dumpster \; ;
                        find . -name "go" -print -exec mv {} ~/dumpster \; ;
                        find . -name "core" -print -exec mv {} ~/dumpster \; ;

35 all: ;
                        pmake -u

depend:
                        makedepend -- $(CFLAGS) -- $(SRC)

40 # DO NOT DELETE

main.o: Test.h Vector3D.h /usr/include/math.h /usr/include/sgidefs.h
main.o: /usr/include/standards.h Object.h /usr/include/string.h Global.h
main.o: /usr/include/assert.h
45 Test.o: Test.h Vector3D.h /usr/include/math.h /usr/include/sgidefs.h
Test.o: /usr/include/standards.h Object.h /usr/include/string.h Global.h
Test.o: /usr/include/assert.h
Object.o: Object.h /usr/include/string.h /usr/include/standards.h Global.h
Object.o: /usr/include/assert.h

50

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```

```

Vector3D.o: Vector3D.h /usr/include/math.h
/usr/include/sgidefs.h
5 Vector3D.o: /usr/include/standards.h Object.h /usr/include/string.h Global.h
Vector3D.o: /usr/include/assert.h
::::::::::::
oop/Vector3D/Test.C
::::::::::::
// Test.cpp testclass for OOP-classes
10 // (c) Ingmar Bitter '96

#include "Test.h"

void Test::Run() { Vector3D<int>::Demo(); }

15 // end of Test.cpp
::::::::::::
oop/Vector3D/Test.h
::::::::::::
// Test.h test class for OOP-classes
// (c) Ingmar Bitter '96

20 #ifndef _Test_h // prevent multiple includes
#define _Test_h

#include "Vector3D.h"

25 class Test { public: static void Run(); };

#ifdef _Test_h
::::::::::::
oop/Vector3D/Vector3D.C
::::::::::::
30 // Vector3D.C
// (c) Ingmar Bitter '96

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

35 #include "Vector3D.h"

template <class T> void Vector3D<T>::Demo()
{
    Vector3D<T> a, b(3.5,2.5,1.5);
    cout << endl <<"Demo of class " << typeid(a).name();
40    cout << endl <<"size : " << sizeof(Vector3D<T>)/8 << " Bytes";
    cout << endl <<"public member functions:";
    cout << endl <<" "<<typeid(a).name()<<" a, b(3.5,2.5,1.5); == " << a <<"", "<<
    &b;
        cout << endl <<" a<b;\t== " << (a<b) <<"\t a<=b;\t== " <<
    (a<=b)<<"\ta==b;\t== " << (a==b);
        cout << endl <<" a>b;\t== " << (a>b) <<"\t a>=b;\t== " <<
    (a>=b)<<"\ta!=b;\t== " << (a!=b);
45

```

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```

5      cout << endl <<"  a=b;\t== " <<      (a=b);
      cout << endl <<"  a.X();\t== " << (a.X()) <<"\t a.U();\t== " << (a.U());
      cout << endl <<"  a.Y();\t== " << (a.Y()) <<"\t a.V();\t== " << (a.V());
      cout << endl <<"  a.Z();\t== " << (a.Z()) <<"\t a.W();\t== " << (a.W());

      cout << endl <<"  +a;\t== " << (+a) <<"\t a+b;\t== " << (a+b);
      cout << endl <<"  -a;\t== " << (-a) <<"\t a-b;\t== " << (a-b);
      cout << endl <<"  a+=b;\t== " << (a+=b);
10     cout << endl <<"  a-=b;\t== " << (a-=b);
      T s; s = (T) 2.5;
      cout << endl <<"  "<<typeid(s).name()<<" s(2.5);\t== "<< s;
      cout << endl <<"  a*s;\t== " << (a*s) <<"\t a*=s;\t== " << (a*=s);
      cout << endl <<"  a/s;\t== " << (a/s) <<"\t a/=s;\t== " << (a/=s);
      cout << endl <<"  a.DotProduct(b);\t== " << a.DotProduct(b);
15     cout << endl <<"  a.Dot(b);\t\t== " << a.Dot(b);
      cout << endl <<"  a*b;\t\t\t== " << (a*b);
      cout << endl <<"  a.CrossProduct(b);\t== " << a.CrossProduct(b);
      cout << endl <<"  a.Cross(b);\t\t== " << a.Cross(b);
      cout << endl <<"  a.X(b);\t\t== " << a.X(b);
20     cout << endl <<"  a/b;\t\t\t== " << (a/b);

      cout << endl <<"End of demo of class " << typeid(a).name() << endl;
    } // Demo

25     ////////////////////////////////////////
    // constructors & destructors

    template <class T> Vector3D<T>::Vector3D(const T & x, const T & y, const T & z)
    {
30         element[0] = x; element[1] = y; element[2] = z;
    } // constructor

    template <class T> Vector3D<T>::Vector3D(const Vector3D<T> & v)
    {
35         element[0] = v.element[0]; element[1] = v.element[1]; element[2] =
v.element[2];
    } // copy-constructor

    template <class T> Vector3D<T>::Vector3D(Vector3D<int> & v)
    {
40         element[0] = v.X(); element[1] = v.Y(); element[2] = v.Z();
    } // copy-constructor

    template <class T> Vector3D<T>::Vector3D(Vector3D<ModInt> & v)
    {
45         element[0] = v.X(); element[1] = v.Y(); element[2] = v.Z();
    } // copy-constructor

50

55

```

```

5  //////////////////////////////////////////////////
// casts to other data types

template <class T> Vector3D<T>::operator double() const { return Norm(); }

//////////////////////////////////////////////////
// show/set data & data properties
10 //
// - class Object requirements

template <class T> ostream & Vector3D<T>::Ostream(ostream & os) const
{
15     return os<<"(<<X()<<"<<"<<Y()<<"<<"<<Z()<<")";
} // Ostream

//////////////////////////////////////////////////
// show/set data & data properties
20 //
// - class CmpObj requirements

template <class T> double Vector3D<T>::Norm() const
25 {
    return sqrt(X()*X() + Y()*Y() + Z()*Z());
} // Norm

//////////////////////////////////////////////////
// show/set data & data properties
30 //
// - local show/set functions

template <class T> T Vector3D<T>::X() const { return element[0]; }
35 template <class T> T Vector3D<T>::Y() const { return element[1]; }
template <class T> T Vector3D<T>::Z() const { return element[2]; }

template <class T> T Vector3D<T>::U() const { return element[0]; }
template <class T> T Vector3D<T>::V() const { return element[1]; }
40 template <class T> T Vector3D<T>::W() const { return element[2]; }

template <class T> T Vector3D<T>::R() const { return element[0]; }
template <class T> T Vector3D<T>::G() const { return element[1]; }
template <class T> T Vector3D<T>::B() const { return element[2]; }

45 template <class T> Vector3D<T> & Vector3D<T>::SetX(const T & setX) {
    element[0]=setX; return *this; }
template <class T> Vector3D<T> & Vector3D<T>::SetY(const T & setY) {
    element[1]=setY; return *this; }
template <class T> Vector3D<T> & Vector3D<T>::SetZ(const T & setZ) {
50     element[2]=setZ; return *this; }

```

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template <class T> Vector3D<T> & Vector3D<T>::SetU(const T & setU) {
    element[0]=setU; return *this; }
5  template <class T> Vector3D<T> & Vector3D<T>::SetV(const T & setV) {
    element[1]=setV; return *this; }
    template <class T> Vector3D<T> & Vector3D<T>::SetW(const T & setW) {
    element[2]=setW; return *this; }

    template <class T> Vector3D<T> & Vector3D<T>::SetR(const T & setR) {
10  element[0]=setR; return *this; }
    template <class T> Vector3D<T> & Vector3D<T>::SetG(const T & setG) {
    element[1]=setG; return *this; }
    template <class T> Vector3D<T> & Vector3D<T>::SetB(const T & setB) {
    element[2]=setB; return *this; }

15  template <class T> Vector3D<T> & Vector3D<T>::operator () (const T & x, const T
    & y, const T & z)
    {
        element[0] = x; element[1] = y; element[2] = z;
        return *this;
    } // operator ()

20
    template <class T> T Vector3D<T>::operator [] (const int index) const
    {
        return element[index];
    } // operator []

25
    template <class T> bool Vector3D<T>::operator ==(const Vector3D<T> & a) const {
    return ( X()==a.X() && Y()==a.Y() && Z()==a.Z() ); }
    template <class T> bool Vector3D<T>::operator !=(const Vector3D<T> & a) const {
30  return ( X()!=a.X() || Y()!=a.Y() || Z()!=a.Z() ); }

    template <class T> Vector3D<T> Vector3D<T>::operator + () const { return
    Vector3D<T>(*this); }
    template <class T> Vector3D<T> Vector3D<T>::operator - () const { return
    Vector3D<T>(-element[0], -element[1], -element[2]); }

35
    template <class T> Vector3D<T> Vector3D<T>::operator + (const Vector3D<T> & a)
    const { return Vector3D<T>(X()+a.X(), Y()+a.Y(), Z()+a.Z()); }
    template <class T> Vector3D<T> Vector3D<T>::operator - (const Vector3D<T> & a)
    const { return Vector3D<T>(X()-a.X(), Y()-a.Y(), Z()-a.Z()); }
    template <class T> Vector3D<T> & Vector3D<T>::operator +=(const Vector3D<T> & a)
40  { element[0]+=a.X(); element[1]+=a.Y(); element[2]+=a.Z(); return *this; }
    template <class T> Vector3D<T> & Vector3D<T>::operator -=(const Vector3D<T> & a)
    { element[0]-=a.X(); element[1]-=a.Y(); element[2]-=a.Z(); return *this; }

    template <class T> Vector3D<T> Vector3D<T>::operator * (const T & a) const {
    return Vector3D<T>(X()*a, Y()*a, Z()*a); }
45  template <class T> Vector3D<T> Vector3D<T>::operator / (const T & a) const {
    return Vector3D<T>(X()/a, Y()/a, Z()/a); }
    template <class T> Vector3D<T> & Vector3D<T>::operator *=(const T & a) {
    element[0]*=a; element[1]*=a; element[2]*=a; return *this; }

50

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template <class T> Vector3D<T> & Vector3D<T>::operator /=(const T & a)
{ element[0]/=a; element[1]/=a; element[2]/=a; return *this; }

5
template <class T> T Vector3D<T>::DotProduct (const Vector3D<T> &
a) const { return *this * a; }
template <class T> T Vector3D<T>::Dot (const Vector3D<T> &
a) const { return *this * a; }
template <class T> T Vector3D<T>::operator * (const Vector3D<T> &
10 a) const { return (X()*a.X() + Y()*a.Y() + Z()*a.Z()); }

template <class T> Vector3D<T> Vector3D<T>::CrossProduct(const Vector3D<T> &
a) const { return *this / a; }
template <class T> Vector3D<T> Vector3D<T>::Cross (const Vector3D<T> &
a) const { return *this / a; }
15 template <class T> Vector3D<T> Vector3D<T>::X (const Vector3D<T> &
a) const { return *this / a; }
template <class T> Vector3D<T> Vector3D<T>::operator / (const Vector3D<T> &
a) const
{ return Vector3D(Y()*a.Z() - Z()*a.Y(), Z()*a.X() - X()*a.Z(), X()*a.Y() -
20 Y()*a.X()); }

// end of Vector3D.C
::::::::::::
oop/Vector3D/Vector3D.h
::::::::::::
// Vector3D.h
25 // (c) Ingmar Bitter '96

// Copyright, Mitsubishi Electric Information Technology Center
// America, Inc., 1997, All rights reserved.

30 // dynamic array ADT

#ifdef _Vector3D_h_ // prevent multiple includes
#define _Vector3D_h_

#include <math.h>
35 #include "Object.h"
#include "ModInt.h"

template <class T> class Vector3D : public virtual Object {
public:
40 static void Demo ();

// constructors & destructors
Vector3D (const T & x=0, const T & y=0, const T & z=0);
Vector3D (const Vector3D<T> &);
Vector3D (Vector3D<int> &);
45 Vector3D (Vector3D<ModInt> &);

// casts to other data types
virtual /*inline*/ operator double() const;

```

```

// show/set data & data properties
// - class Object requirements
5   virtual      ostream &   Ostream (ostream & )   const;

// - class CmpObj requirements
virtual /*inline*/ double Norm ( ) const;

10   // - local show/set functions
virtual /*inline*/ T X ( ) const;
virtual /*inline*/ T Y ( ) const;
virtual /*inline*/ T Z ( ) const;

15   virtual /*inline*/ T U ( ) const;
virtual /*inline*/ T V ( ) const;
virtual /*inline*/ T W ( ) const;

virtual /*inline*/ T R ( ) const;
virtual /*inline*/ T G ( ) const;
20   virtual /*inline*/ T B ( ) const;

virtual /*inline*/ Vector3D<T> & SetX (const T &);
virtual /*inline*/ Vector3D<T> & SetY (const T &);
virtual /*inline*/ Vector3D<T> & SetZ (const T &);

25   virtual /*inline*/ Vector3D<T> & SetU (const T &);
virtual /*inline*/ Vector3D<T> & SetV (const T &);
virtual /*inline*/ Vector3D<T> & SetW (const T &);

virtual /*inline*/ Vector3D<T> & SetR (const T &);
virtual /*inline*/ Vector3D<T> & SetG (const T &);
30   virtual /*inline*/ Vector3D<T> & SetB (const T &);

virtual /*inline*/ Vector3D<T> & operator () (const T & x, const T & y,
const T & z);
35   virtual /*inline*/ T operator [] (const int index) const;

// local computation functions
virtual /*inline*/ bool operator == (const Vector3D<T> &) const;
virtual /*inline*/ bool operator != (const Vector3D<T> &) const;

40   virtual /*inline*/ Vector3D<T> operator + ( ) const;
virtual /*inline*/ Vector3D<T> operator - ( ) const;

virtual /*inline*/ Vector3D<T> operator + (const Vector3D<T> &) const;
virtual /*inline*/ Vector3D<T> operator - (const Vector3D<T> &) const;
virtual /*inline*/ Vector3D<T> & operator += (const Vector3D<T> &);
45   virtual /*inline*/ Vector3D<T> & operator -= (const Vector3D<T> &);

virtual /*inline*/ Vector3D<T> operator * (const T &) const;
virtual /*inline*/ Vector3D<T> operator / (const T &) const;
virtual /*inline*/ Vector3D<T> & operator *= (const T &);

```

50

55

```

                                434
virtual /*inline*/ Vector3D<T> &      operator /= (const T &);

5   virtual /*inline*/ T      DotProduct (const Vector3D<T> &) const;
    virtual /*inline*/ T      Dot      (const Vector3D<T> &) const;
    virtual /*inline*/ T      operator * (const Vector3D<T> &) const;

    virtual /*inline*/ Vector3D<T> CrossProduct(const Vector3D<T> &) const;
10   virtual /*inline*/ Vector3D<T> Cross      (const Vector3D<T> &) const;
    virtual /*inline*/ Vector3D<T> X          (const Vector3D<T> &) const;
    virtual /*inline*/ Vector3D<T> operator / (const Vector3D<T> &) const;

protected:
    T element[3];
15   }; // class Vector3D

#ifdef _Vector3D_h_

20

```

Claims

- 25 1. Apparatus to enable real-time volume rendering, comprising:

a volume graphics rendering engine having a number of memory modules for storing an incoming volume data set and a like number of processing modules connected to respective memory modules and interconnected in a ring-like fashion; and,
 30

means for grouping voxels in said volume data set in such a way that said voxels from said groups can be fetched from consecutive memory addresses in said memory modules regardless of view direction, thereby to permit the use of memory modules of types that support high speed accesses from consecutive memory addresses.
 35
2. The apparatus of Claim 1 wherein said volume graphics rendering engine is applied to a personal computer.
3. The apparatus of Claim 1 wherein said volume graphics rendering engine is coupled to a desktop computer.
- 40 4. The apparatus of Claim 1 wherein said memory modules are Dynamic Random Access Memory modules equipped with the capability for accessing data from consecutive memory addresses in burst mode.
- 45 5. The apparatus of Claim 1 wherein said grouping means including means for grouping said voxels into blocks of contiguous voxels in three dimensions and means for skewing said blocks across said memory modules in such a way that adjacent blocks in any of the three dimensions of the volume data set are stored in adjacent memory modules to make possible for adjacent processing modules to concurrently and simultaneously fetch voxels of adjacent blocks in burst mode from respective adjacent memory modules.
- 50 6. The apparatus of Claim 5 wherein all of the voxels in a block are stored in the same memory module.
7. The apparatus of Claim 6 wherein within each block voxels are stored at consecutive memory addresses.
- 55 8. The apparatus of Claim 7 wherein said processing modules include means for rendering voxels within a block;

means for forwarding data to adjacent processing modules; and,

means for accumulating results of rendering individual blocks to produce resulting images.

9. The apparatus of Claim 8 and further including means for bi-directional communication between adjacent processing modules; and,

means for determining direction of communication for said forwarding data.

10. The apparatus of Claim 5 wherein said blocks are grouped into slices such that all blocks of a slice are equidistant from a face of the volume data set.

11. The apparatus of Claim 5 and further including means for rendering of said volume data set proceeds in groups of P adjacent blocks at a time, where P is the number of said processing modules in said volume graphics engine;

means for controlling the sequence of said rendering in groups of P blocks at a time so that all blocks of any slice of said volume data said are rendered before any blocks of any other slice more distant from the face of said volume data set than said slice; and,

means for accumulating results of rendering blocks a slice at a time.

12. The apparatus of Claim 1 and further including means for partitioning the volume data set into sections;

means for rendering said volume data set a section at a time; and,

means for storing results of rendered sections and for reapplying said results to the rendering of subsequent sections.

13. The apparatus of Claim 1 and further including means for reducing the amount of internal storage within each of said processing modules including means for sectioning said volume data set thus to permit rendering a section at a time, with each section requiring less storage than that associated with rendering the volume as a whole.

14. The apparatus of Claim 1 wherein said memory modules are Dynamic Random Access Memory semi-conductor arrays embedded within respective processing modules on one semi-conductor chip.

15. The apparatus of Claim 5 and further including means for transmitting data only from voxels on the face of each block to the adjacent processing pipeline, thereby to reduce by a factor of $1/B$ the amount of data transmitted between adjacent pipelines, where B is the number of voxels on an edge of a block.

16. The apparatus of Claim 7 and further including means for subdividing said blocks into mini-blocks such that all of the voxels of a mini-block are stored at consecutive memory addresses, thereby to reduce the amount of storage required in said processing modules.

17. The apparatus of Claim 13 and further including means for subdividing said blocks into mini-blocks such that all of the voxels of a mini-block are stored at consecutive memory addresses, thereby to reduce the amount of storage required in said processing modules, and means for reducing the amount of time needed to render a section including means for reducing the number of voxels needing to be read from a block at the boundary of said section from all of the voxels of the block at said boundary to only those voxels in mini-blocks at said boundary.

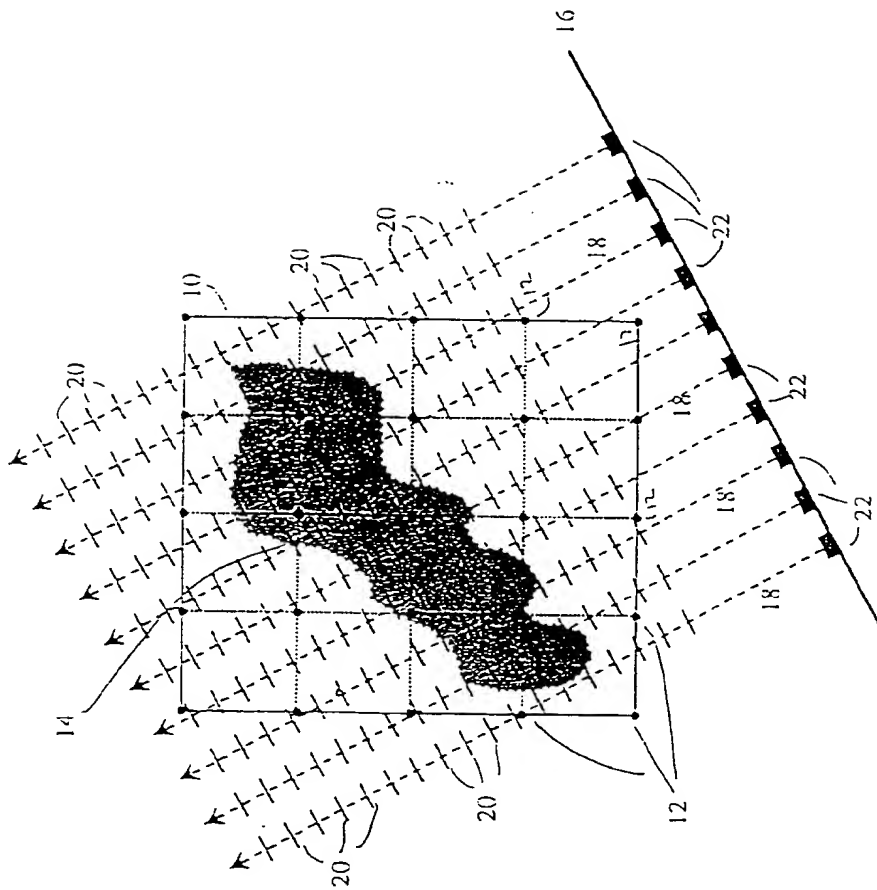


FIG. 1

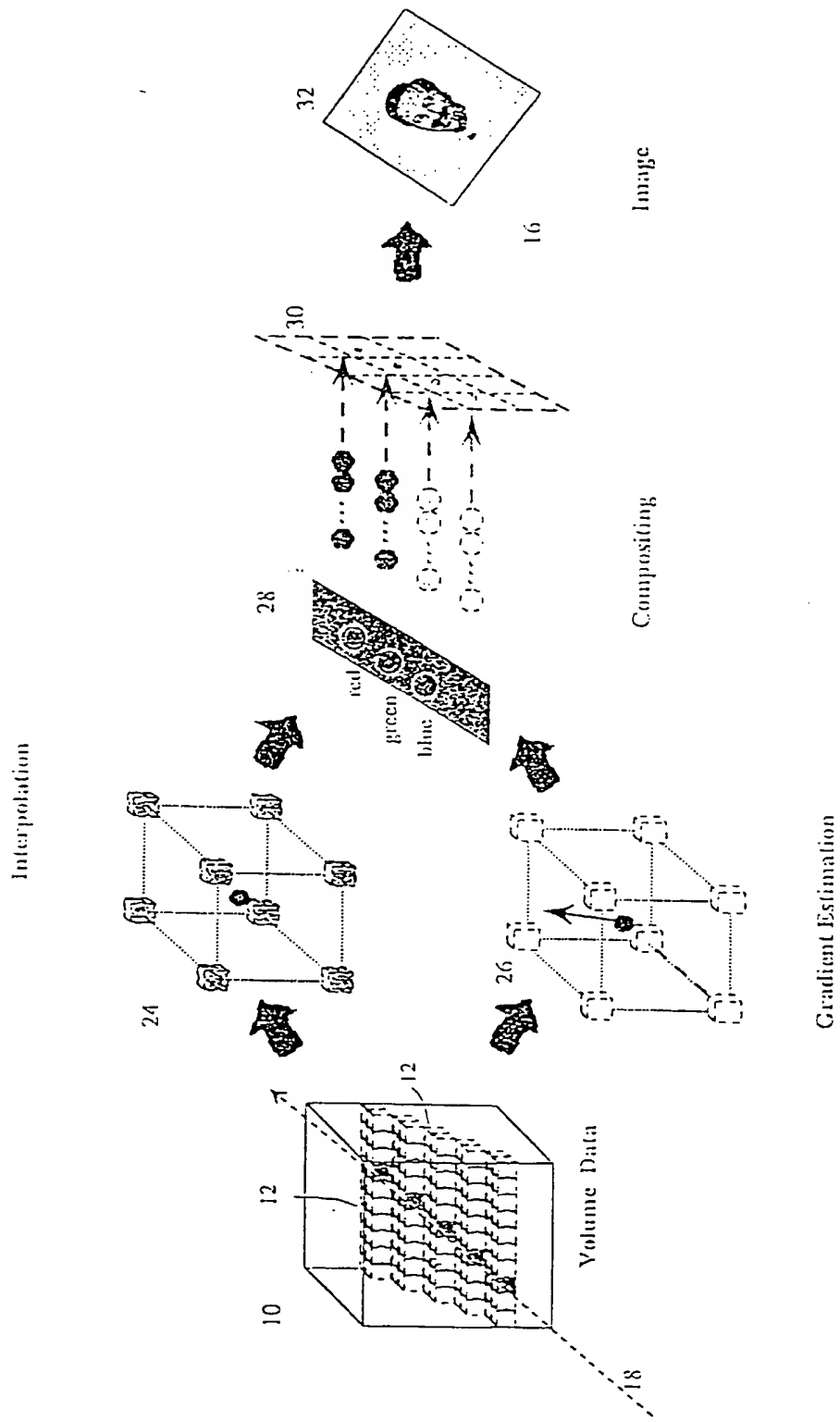


FIG. 2

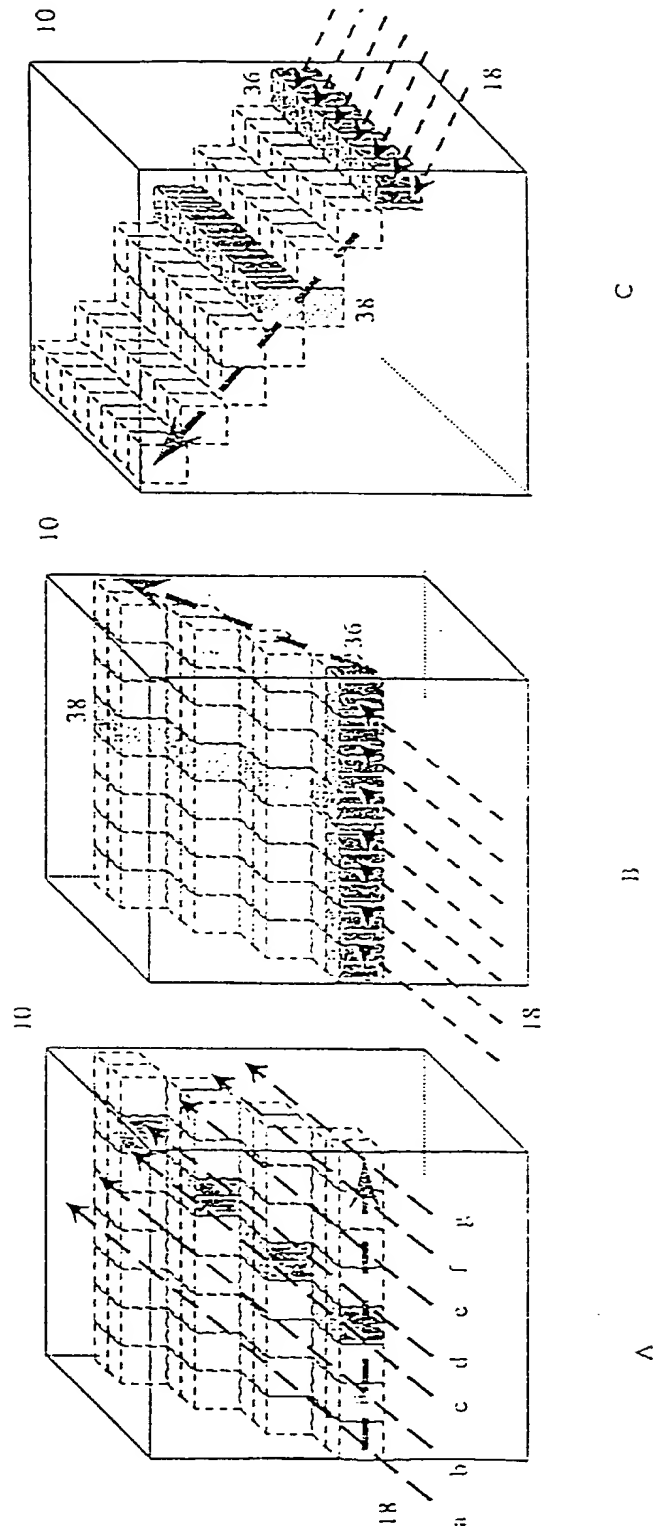


FIG. 3

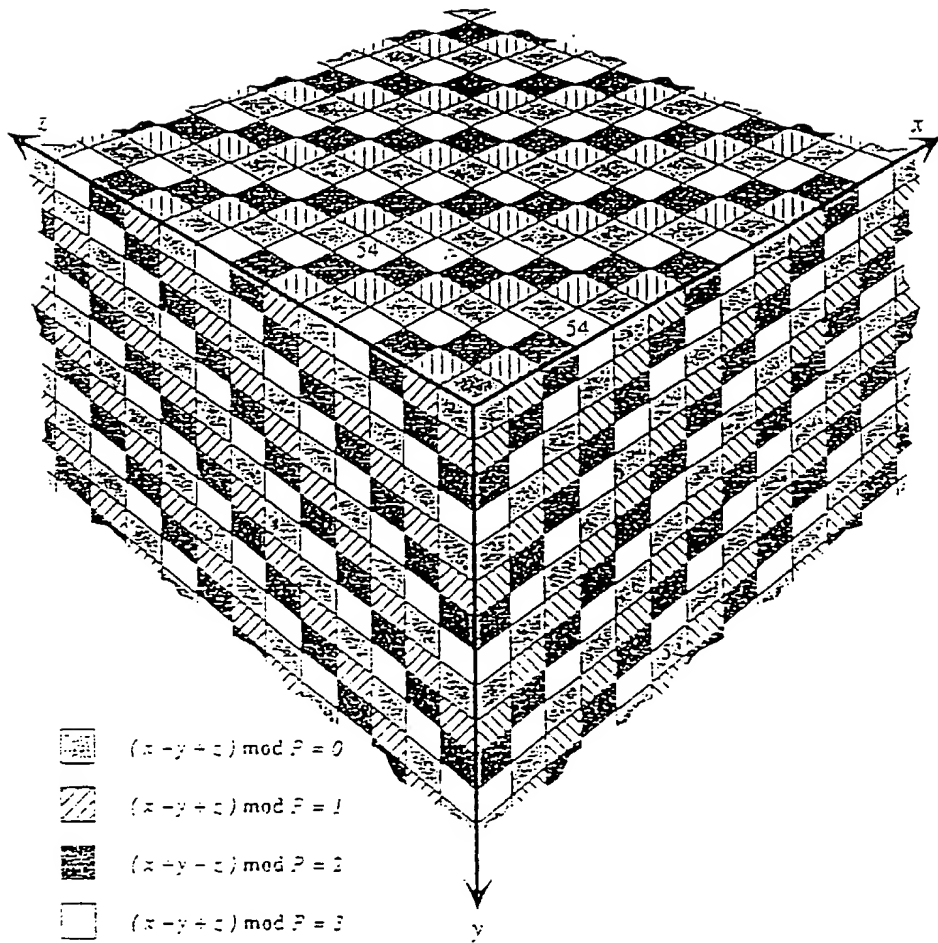


FIG. 4

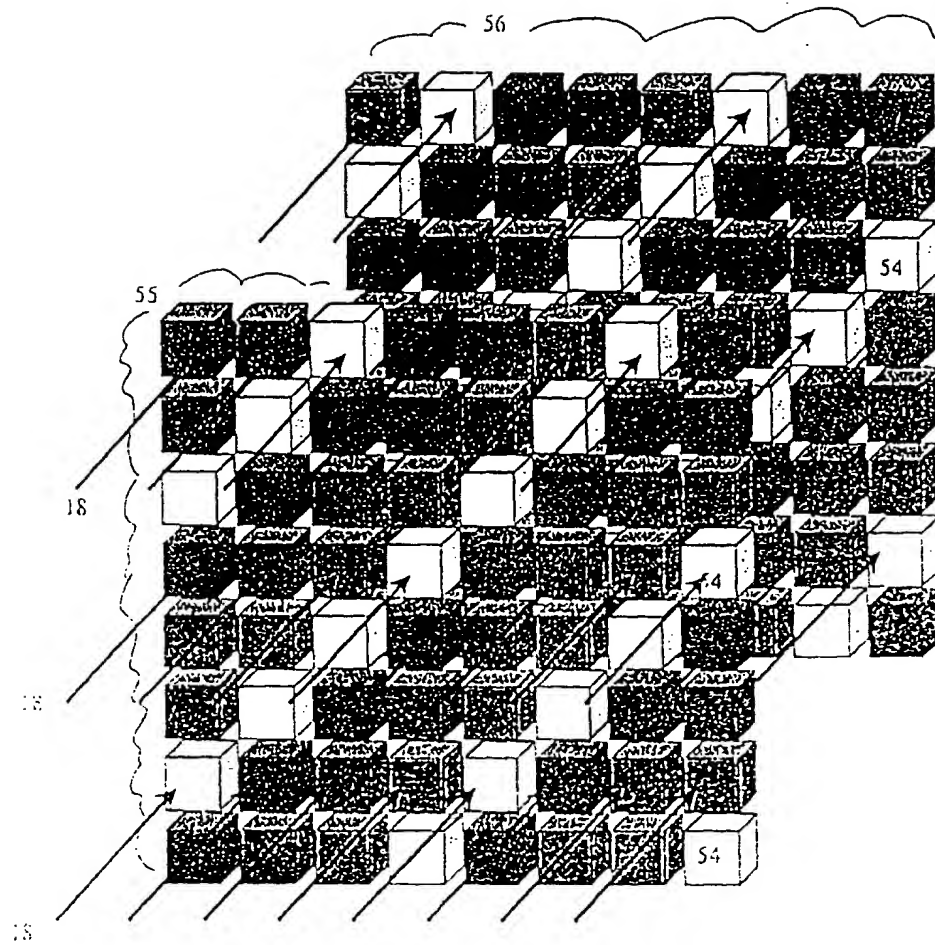


FIG. 5

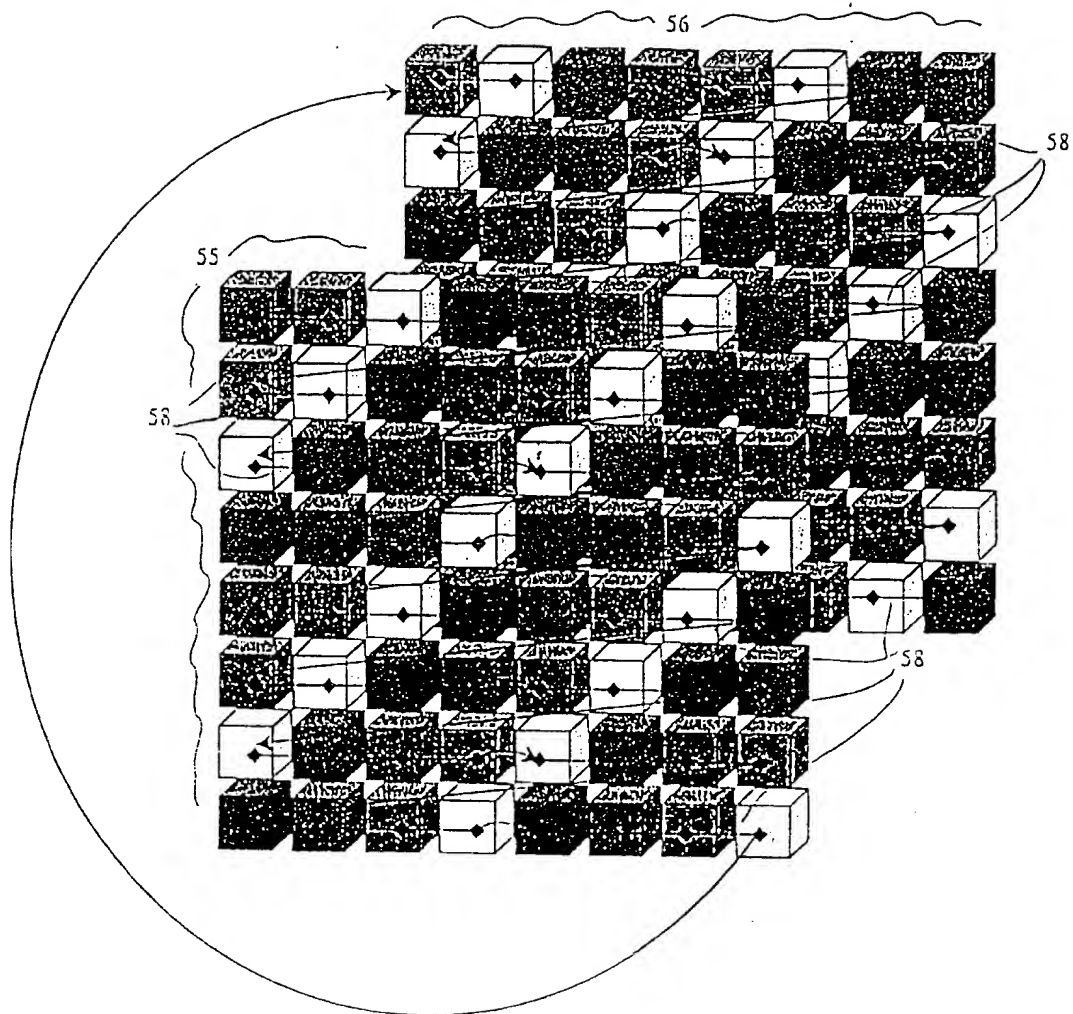
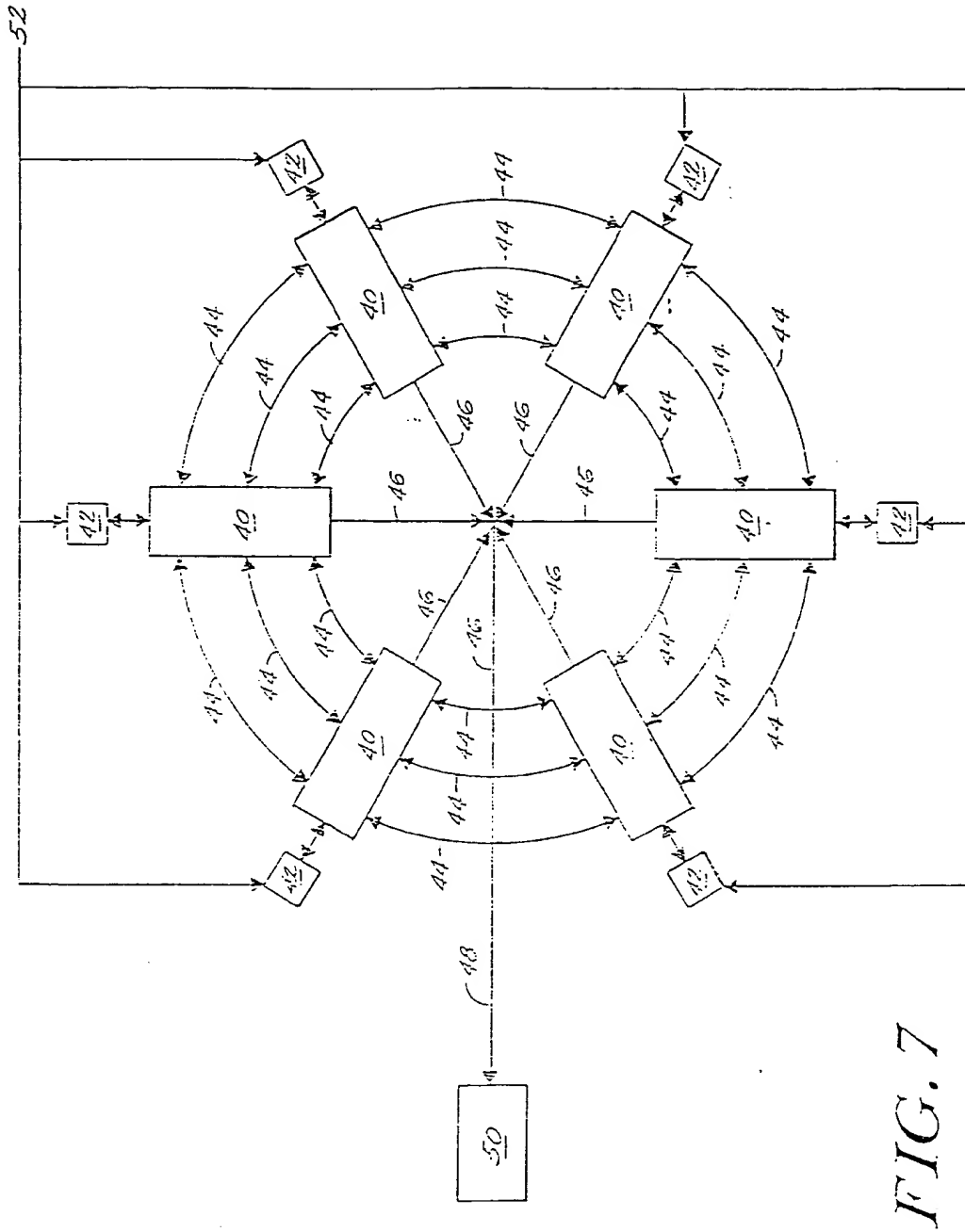


FIG. 6



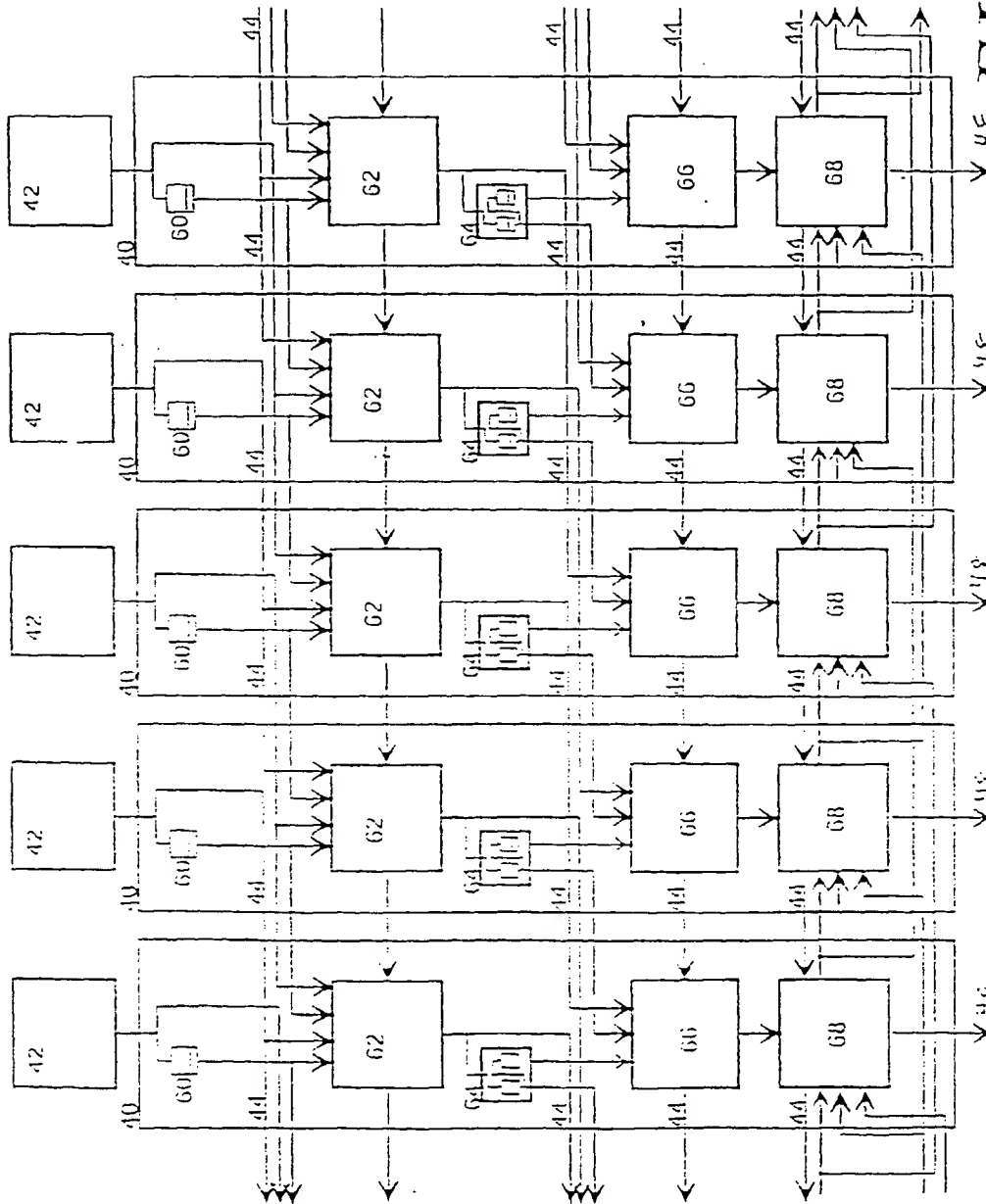


FIG. 8

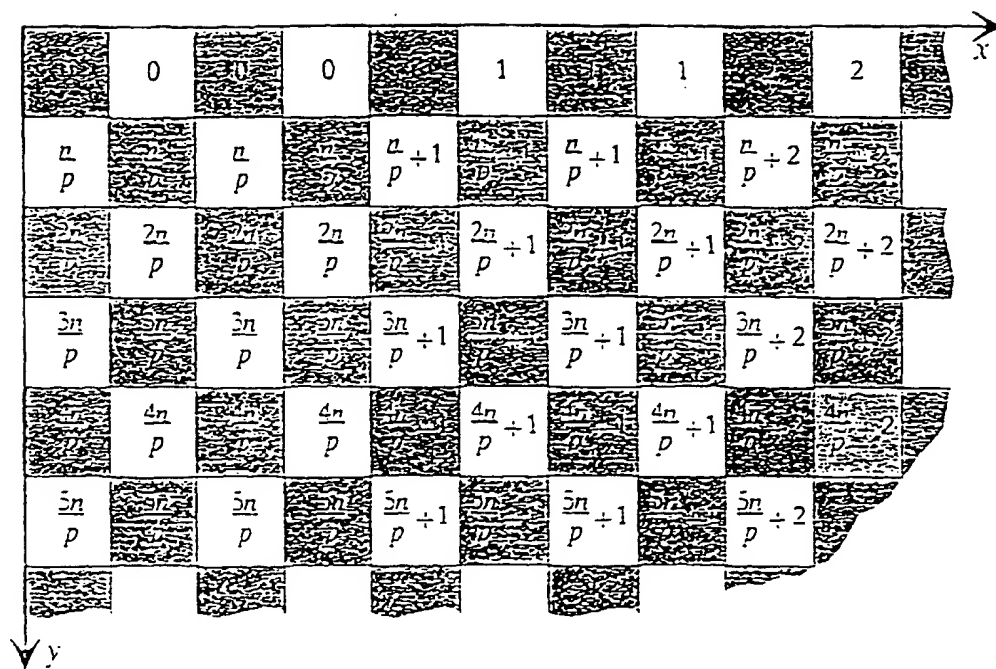


FIG. 9

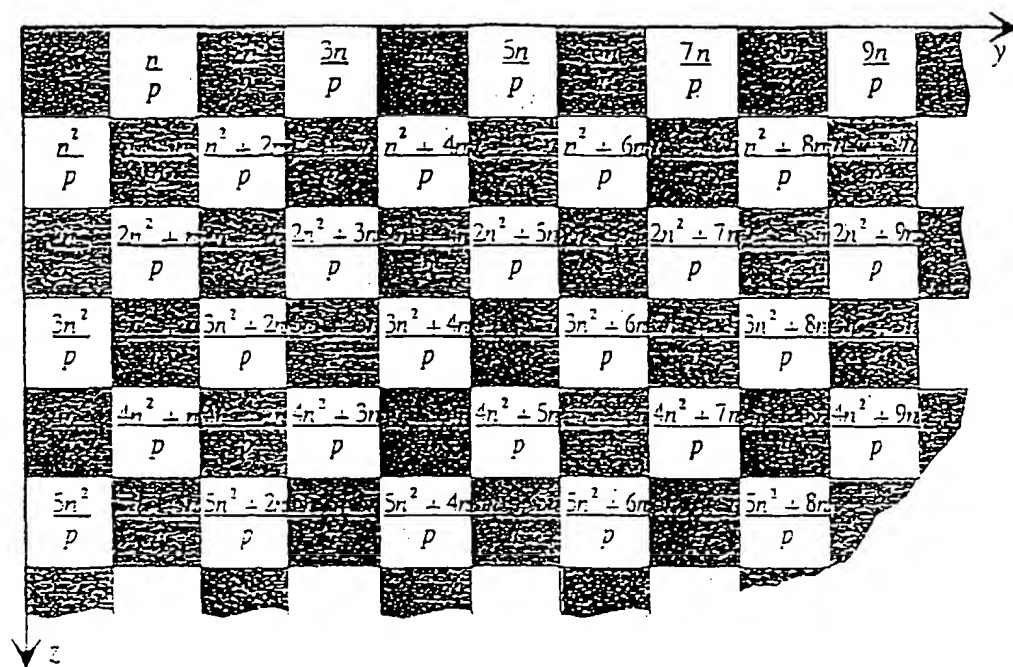


FIG. 10

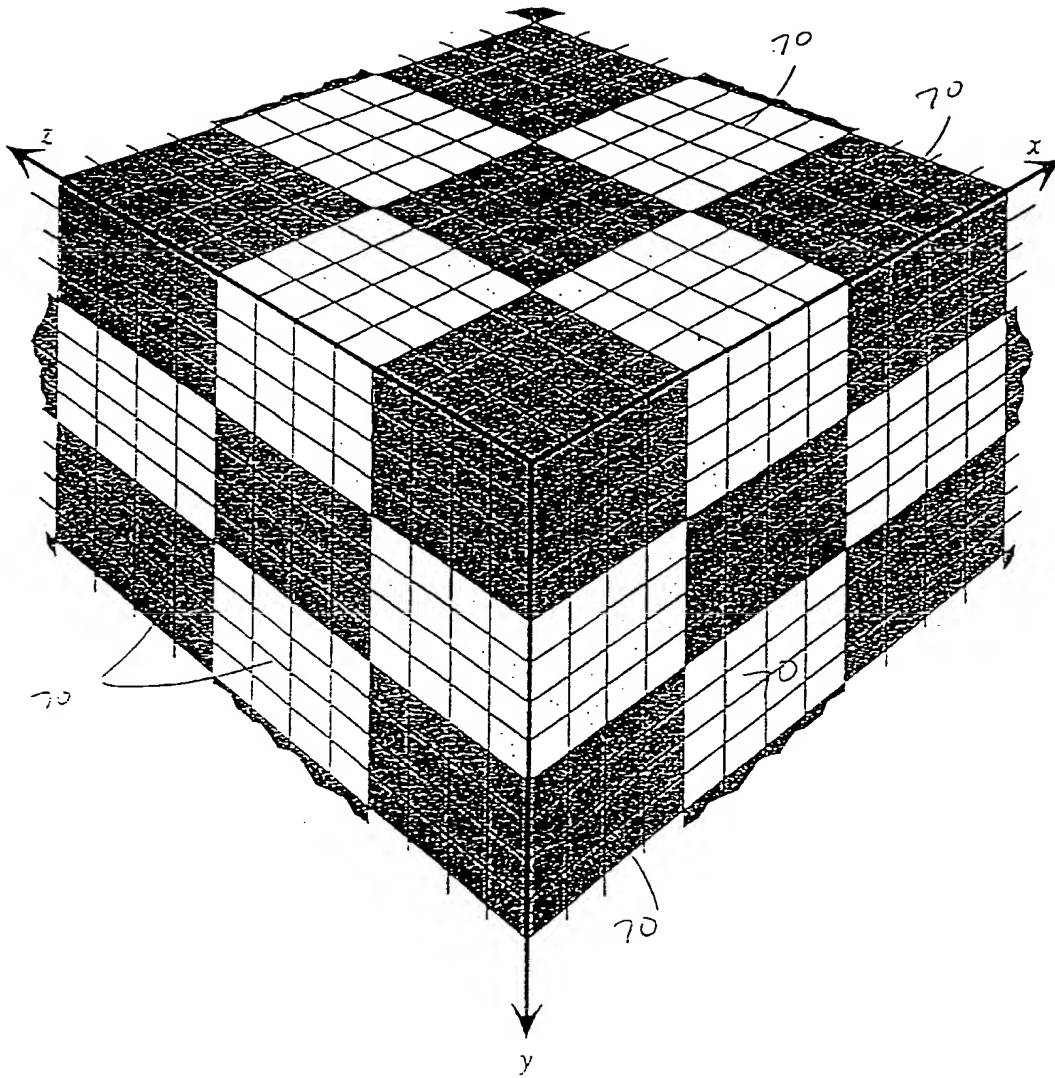


FIG. 11

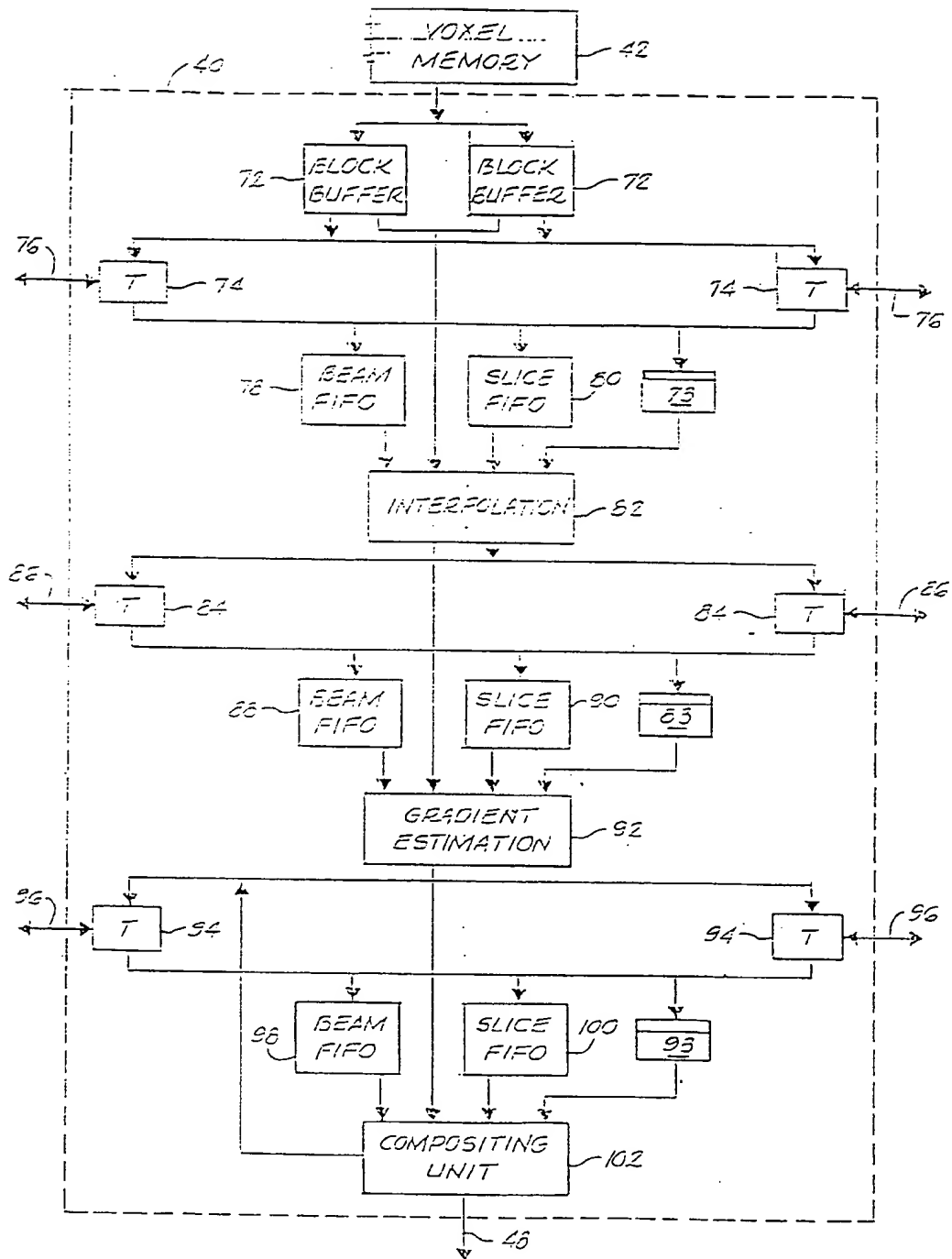


FIG. 12

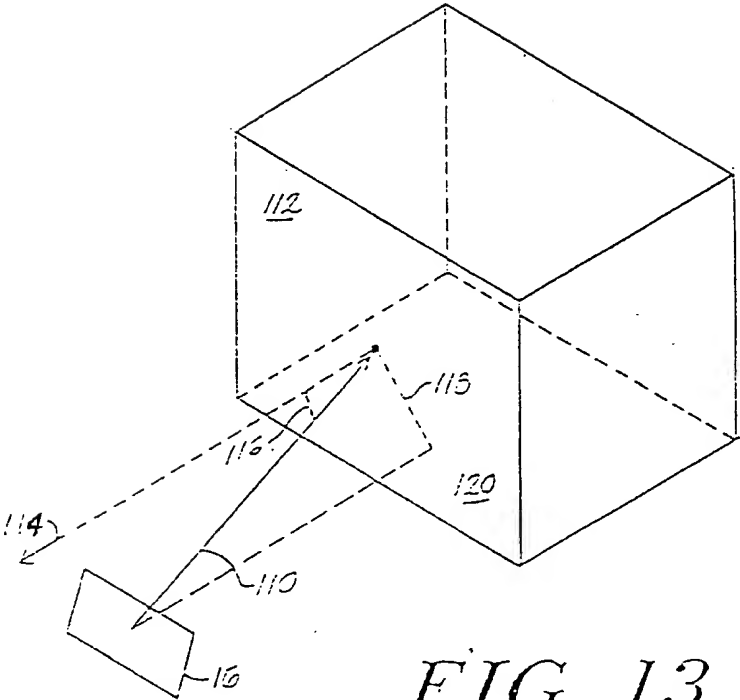


FIG. 13

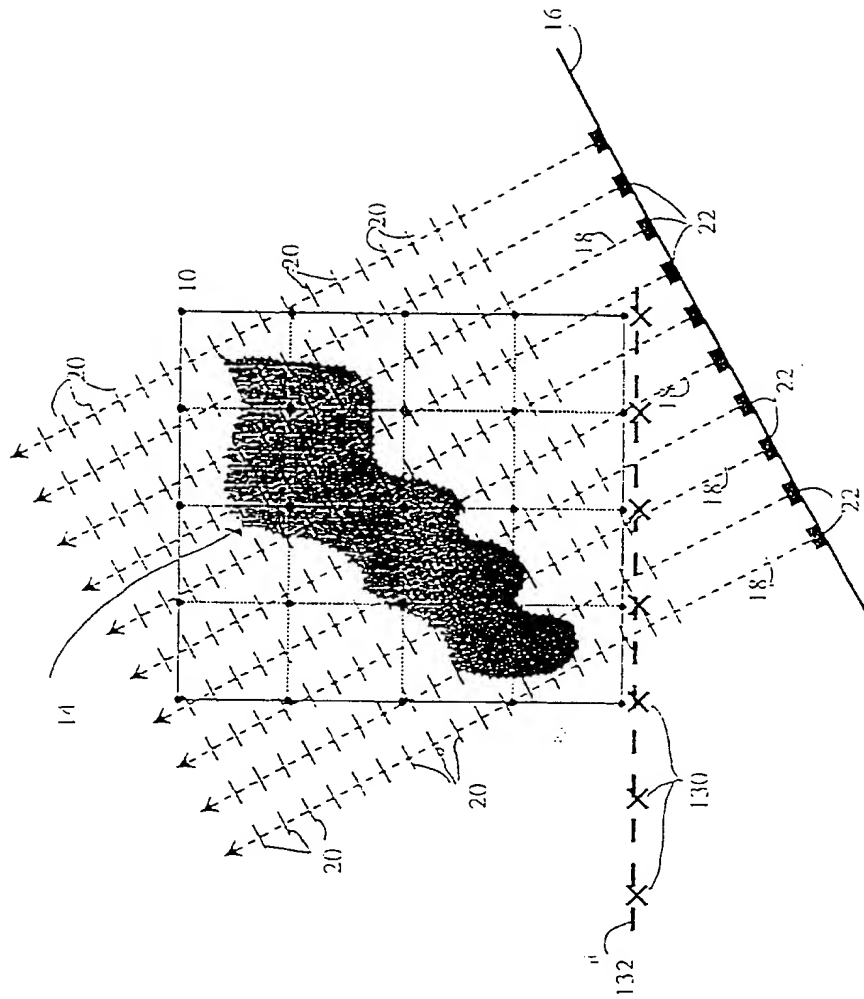


FIG. 14

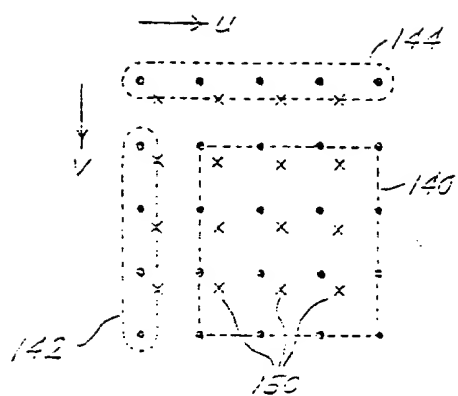


FIG. 15A

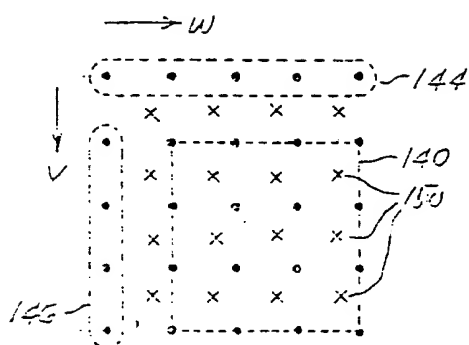


FIG. 15B

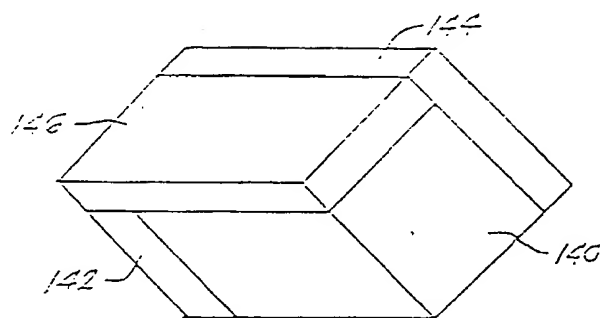


FIG. 15C

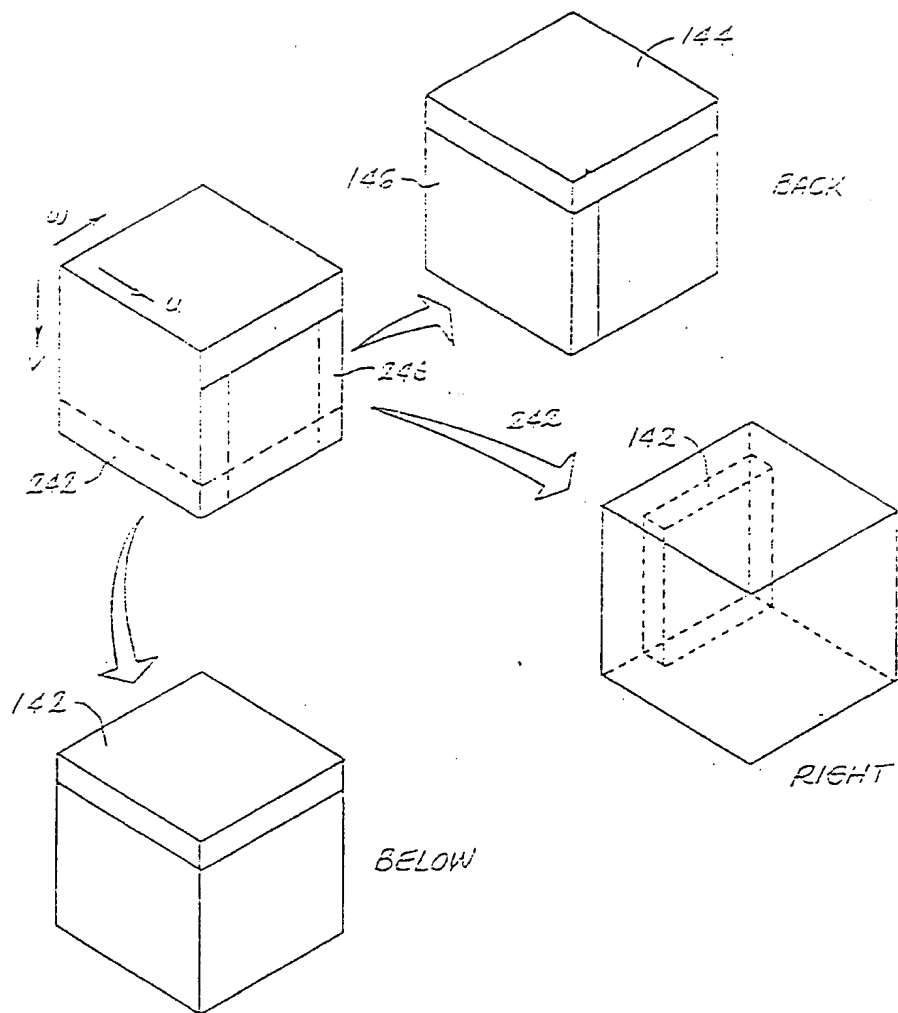


FIG. 16

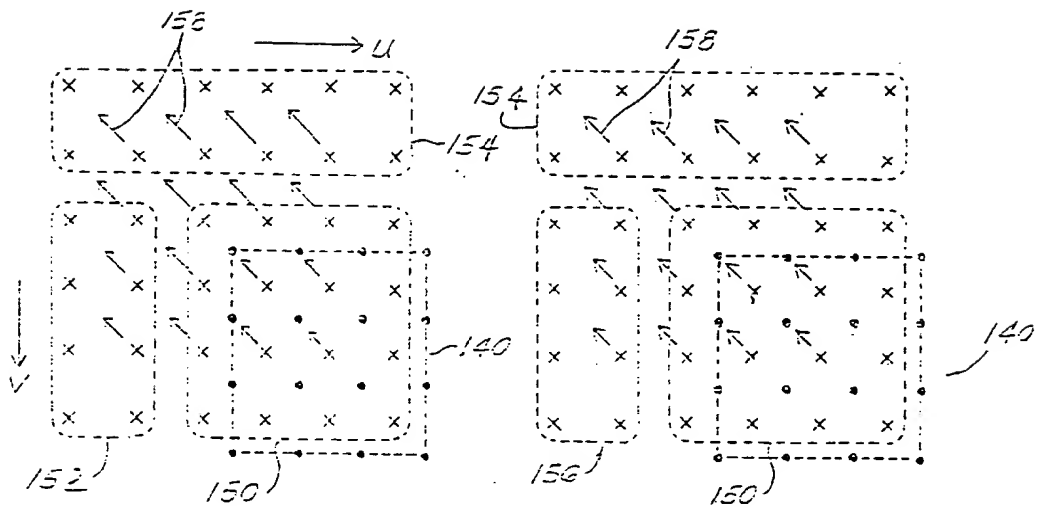


FIG. 17

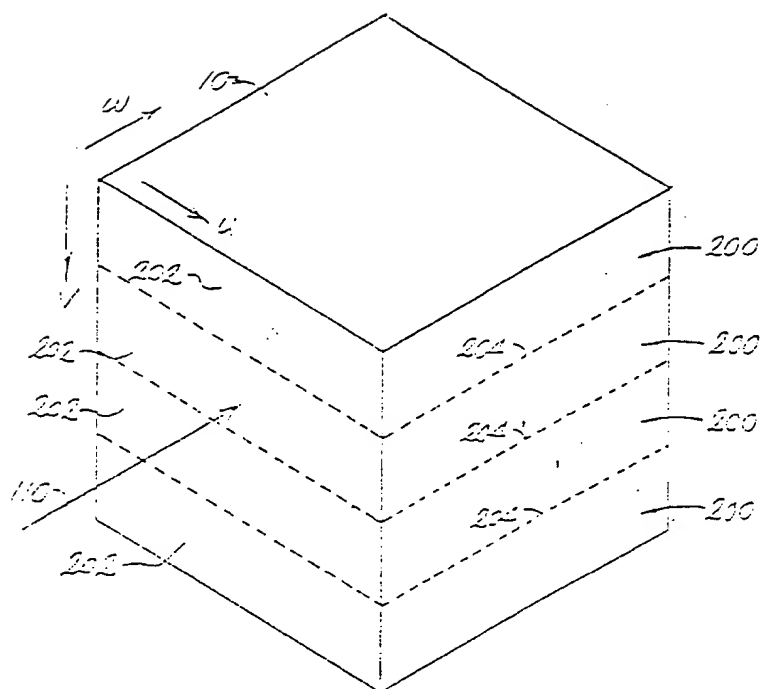


FIG. 18A

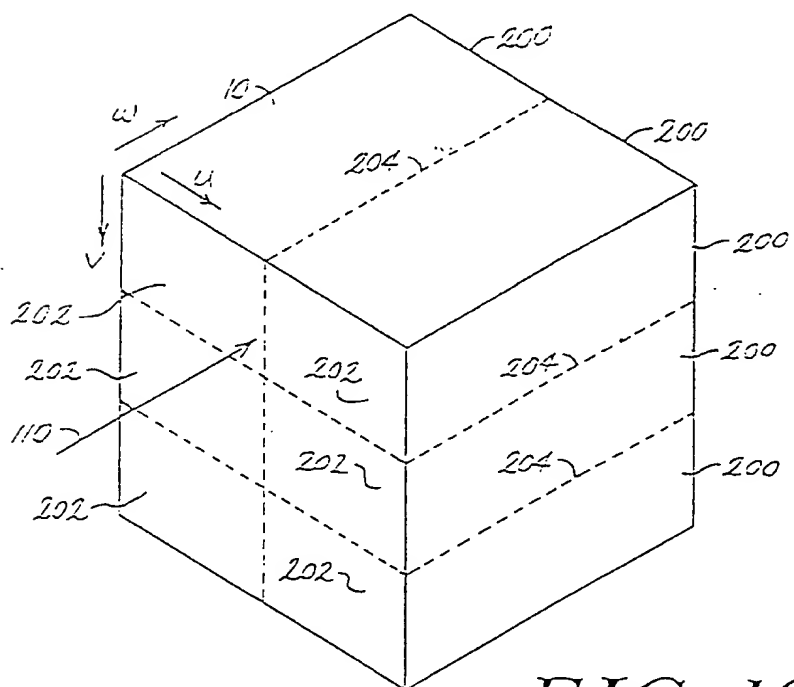


FIG. 18B

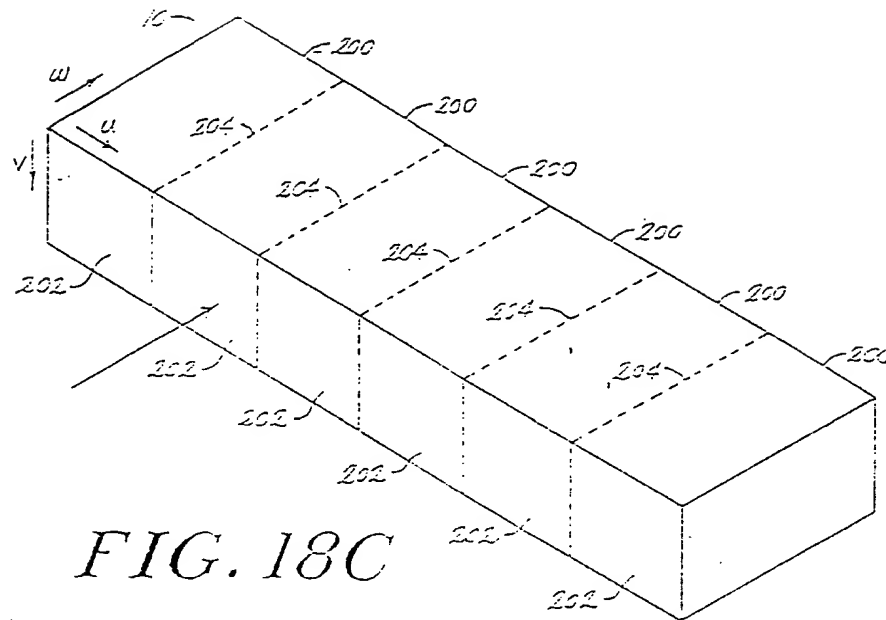


FIG. 18C

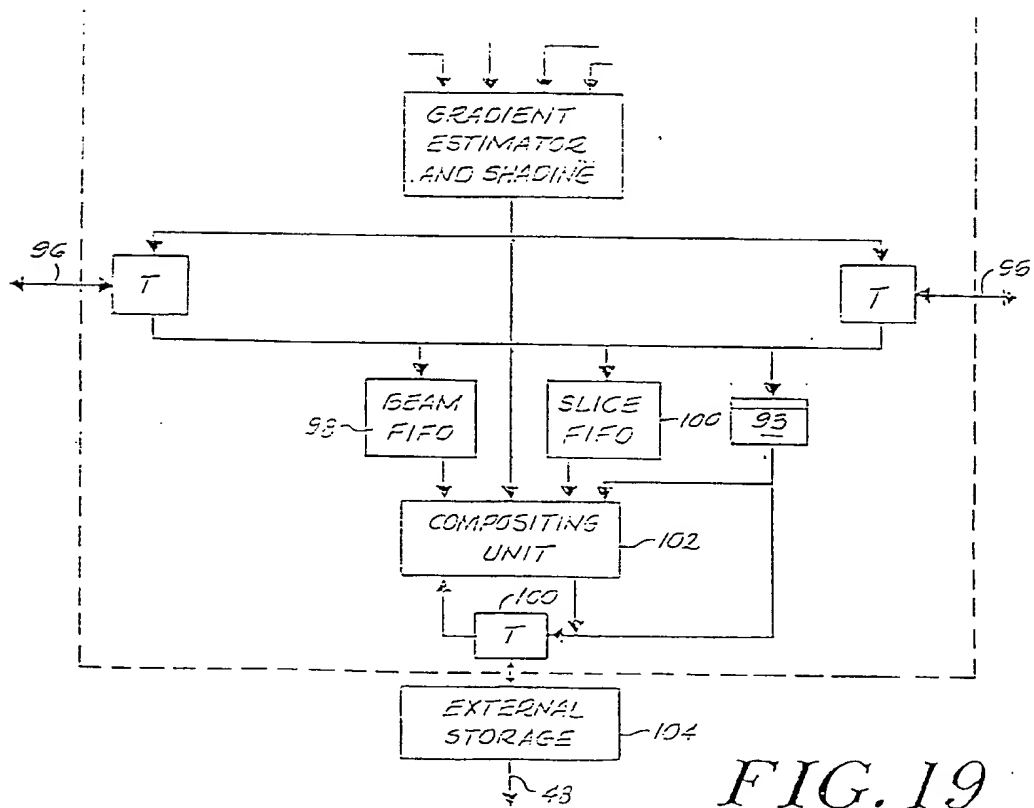


FIG. 19



European Patent
Office

EUROPEAN SEARCH REPORT

Application Number
EP 98 10 7592

DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int.Cl.6)
A	PFISTER H ET AL: "CUBE-4 - A SCALABLE ARCHITECTURE FOR REAL-TIME VOLUME RENDERING" PROCEEDINGS OF THE 1996 SYMPOSIUM ON VOLUME VISUALIZATION, SAN FRANCISCO, OCT. 28 - 29, 1996, 28 October 1996, pages 47-54, XP000724429 ASSOCIATION FOR COMPUTING MACHINERY * the whole document *	1-17	G06T15/00
A	ANIDO M L ET AL: "THE ARCHITECTURE OF RIG: A RISC FOR IMAGE GENERATION IN A MULTI-MICROPROCESSOR ENVIRONMENT" MICROPROCESSING AND MICROPROGRAMMING, vol. 24, no. 1 - 05, 1 August 1988, pages 581-588, XP000105698 * page 584, left-hand column, line 26 - line 31 *	1,4	
A	PHILLIPS D: "THE Z80000 MICROPROCESSOR" IEEE MICRO, vol. 5, no. 6, 1 December 1985, pages 23-36, XP000211949 * page 23, left-hand column, line 14 - line 24 * * page 27, left-hand column, line 5 - line 15 *	1,4	TECHNICAL FIELDS SEARCHED (Int.Cl.6) G06T
The present search report has been drawn up for all claims			
Place of search BERLIN		Date of completion of the search 5 November 1998	Examiner Burgaud, C
CATEGORY OF CITED DOCUMENTS X : particularly relevant if taken alone Y : particularly relevant if combined with another document of the same category A : technological background O : non-written disclosure P : intermediate document		T : theory or principle underlying the invention E : earlier patent document, but published on, or after the filing date D : document cited in the application L : document cited for other reasons & : member of the same patent family, corresponding document	

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